NCTU Pattern Recognition, Homework 5

Deadline: June 12, 23:59

Coding (100%):

In this coding assignment, you need to implement the deep neural network by any deep learning fr amework, e.g., Pytorch, TensorFlow, or Keras, then train the DNN model by the Cifar-10 dataset a nd try to beat the baseline performance.

Download dataset HERE.

Please note that you should only train and evaluate your model on the provided dataset. **DO NOT** download the data from other resources.

If you are a newbie in a deep learning framework, we recommend learning Keras or Pytorch.

- Pytorch tutorial
- Keras tutorial
- TensorFlow tutorial
- 1. (100%) Show your accuracy of your model on the provided test data by screenshot the results of your code and paste them on your report

/home/user/anaconda3/envs/DNN_tzuchichen/lib/python3.5/site-packages/keras/engine/savconfiguration found in save file: the model was *not* compiled. Compile it manually. warnings.warn('No training configuration found in save file: '(10000, 10)
Accuracy of my model on test set: 0.8702

Evaluation:

Accuracy	Your scores
acc >= 0.95	100 points
0.9 <= acc < 0.95	90 points
0.80 <= acc < 0.90	80 points
0.75 <= acc < 0.80	70 points
0.65 <= acc < 0.75	60 points
0.6 <= acc < 0.65	50 points
acc <0.6	No points

Note: Keyword to boost your model performance

- 1. Data augmentation
- 2. Hyperparameter searches for model structure (number of filters, number of

convolution/dense layer) and optimizer (learning rate)

3. Regularization

Note: If your result is bad, check this tutorial first to debug your model

NOTE: 如果助教需要測試程式,請手動安裝以下這些套件(或參考requirements.txt)

tensorflow

numpy

matplotlib

keras

h5py

sklearn

Pillow

只要讓它自動選擇最新版本即可(例如: conda install tensorflow)。

以下為我增加效能的小方法

1.Data augmentation:

```
# set up image augmentation
datagen = ImageDataGenerator(
rotation_range=15,
horizontal_flip=True,
#vertical_flip=True,
width_shift_range=0.1,
height_shift_range=0.1
#zoom_range=0.3
)
```

旋轉15度、左右翻轉、左右平移0.1倍的width、上下平移0.1倍的height。

Regularization:

```
model = Sequential()

model.add(Conv2D(num_filters, (3, 3), activation=ac kernel_regularizer=reg, input_shape=(img_r model.add(BatchNormalization(axis=-1))

model.add(Conv2D(num_filters, (3, 3), activation=ac kernel_regularizer=reg, adding='same'))

model.add(BatchNormalization(axis=-1))

model.add(MaxPooling2D(pool_size=(2, 2)))  # reduces to 16x16x3xnum_filters

model.add(Dropout(drop_conv))

model.add(Conv2D(2*num_filters, (3, 3), activation=ac kernel_regularizer=reg, adding='same'))

model.add(Conv2D(2*num_filters, (3, 3), activation=ac kernel_regularizer=reg, adding='same'))

model.add(Conv2D(2*num_filters, (3, 3), activation=ac kernel_regularizer=reg, adding='same'))

model.add(MaxPooling2D(pool_size=(2, 2)))  # reduces to 8x8x3x(2*num_filters)

model.add(Dropout(drop_conv))

model.add(Conv2D(4*num_filters, (3, 3), activation=ac kernel_regularizer=reg, adding='same'))

model.add(Conv2D(4*num_filters, (3, 3), activation=ac kernel_regularizer=reg, adding='same'))

model.add(BatchNormalization(axis=-1))

model.add(Conv2D(4*num_filters, (3, 3), activation=ac kernel_regularizer=reg, adding='same'))
```

```
model.add(BatchNormalization(axis=-1))
model.add(Conv2D(4*num_filters, (3, 3), activation=ac, kernel_regularizer=reg padding='same'))
model.add(BatchNormalization(axis=-1))
model.add(MaxPooling2D(pool_size=(2, 2))) # reduces to 4x4x3x(4*num_filters)
model.add(Dropout(drop_conv))

model.add(Flatten())
model.add(Dense(512, activation=ac kernel_regularizer=reg))
model.add(BatchNormalization())
model.add(Dropout(drop_dense))
model.add(Dropout(drop_dense))
model.add(Dense(num_classes, activation='softmax'))

#model.compile(loss='categorical_crossentropy', metrics=['accuracy'], optimizer='Adam')
model.compile(loss='categorical_crossentropy', metrics=['accuracy'], optimizer=keras.optimizers.ad
```

每一層都加上regularizer來防止overfitting。

另外,因為訓練時間太長,我沒有使用Hyperparameter searches。我直接選用推薦的opti mizer (learning rate): keras.optimizers.adamax(lr=5e-3)。

我選擇參考VGG模型架構,架構如下:

Layer (type)	Output Shape Pa	ram #		
conv2d_1 (Conv2D)	(None, 32, 32, 32)	896	=======================================	======
batch_normalization_1	(Batch (None, 32, 32, 32)	128		
conv2d_2 (Conv2D)	(None, 32, 32, 32)	9248		
batch_normalization_2	2 (Batch (None, 32, 32, 32)	128		
max_pooling2d_1 (Ma	axPooling2 (None, 16, 16, 3	2) 0		
dropout_1 (Dropout)	(None, 16, 16, 32)	0		
conv2d_3 (Conv2D)	(None, 16, 16, 64)	18496		
batch_normalization_3	3 (Batch (None, 16, 16, 64)	256		
conv2d_4 (Conv2D)	(None, 16, 16, 64)	36928		
batch_normalization_4	1 (Batch (None, 16, 16, 64)	256		
max_pooling2d_2 (Ma	axPooling2 (None, 8, 8, 64)	0		

dropout_2 (Dropout)	(None, 8, 8, 64)	0	
conv2d_5 (Conv2D)	(None, 8, 8, 128) 73856	
batch_normalization_5	5 (Batch (None, 8, 8, 12	28) 512	
conv2d_6 (Conv2D)	(None, 8, 8, 128)) 147584	
batch_normalization_6	6 (Batch (None, 8, 8, 12	28) 512	
max_pooling2d_3 (Ma	axPooling2 (None, 4, 4	, 128) 0	
dropout_3 (Dropout)	(None, 4, 4, 128)	0	
flatten_1 (Flatten)	(None, 2048)	0	
dense_1 (Dense)	(None, 512)	1049088	
batch_normalization_7	7 (Batch (None, 512)	2048	
dropout_4 (Dropout)	(None, 512)	0	
dense_2 (Dense)	(None, 10)	5130	

Total params: 1,345,066 Trainable params: 1,343,146 Non-trainable params: 1,920

我的架構比VGG簡單一些,一般VGG16有13層Convolution layer、5層Maxpooling layer、3層Fully connected layer。VGG16或VGG19太多層,訓練時間太長,因此我縮短成6層Convolution layer、3層Maxpooling layer、1層Fully connected layer。每兩層Convolution layer後面都有一層3層Maxpooling layer,最後再攤平完成Fully connected layer。