# HW 2 Solution

## 1 Problem 1 (10 points)

a) 5 points

$$\frac{\partial (U^T A V)}{\partial X} = \frac{\partial V}{\partial X} A^T U + \frac{\partial (A^T U)}{\partial X} V$$
$$= \frac{\partial V}{\partial X} A^T U + \frac{\partial U}{\partial X} A V$$

The first equality is the result of applying the chain rule and the second one holds due to the fact that A is not a function of X.

**3 points** for applying the chain rule, and **2 points** for simplification in the second step.

b) 5 points

$$\begin{split} \frac{\partial (U^T A V)}{\partial X} &= \underbrace{\frac{\partial U}{\partial X}}_{=0} A V + \frac{\partial (A V)}{\partial X} U \\ &= \underbrace{\frac{\partial V}{\partial X}}_{=0} A^T U + \left[ \left[ \left( \frac{\partial A}{\partial X} \right)^{M \times N \times K} V^{K \times 1} \right]^{M \times N} U^{N \times 1} \right]^{M \times 1} \\ &= \sum_i \sum_j U_i V_j \frac{\partial A_{ij}}{\partial X} \end{split}$$

**2 points** for applying the chain rule, **1 point** for recognizing the zero terms, and **2 points** for finding the final answer with the correct dimension.

### 2 Problem 2 (10 points)

#### a) 5 points

The sigmoid function  $\sigma(z)$  can be written as:

$$\sigma(z) = \frac{1}{1 + \exp(-z)} \tag{1}$$

Taking derivative of the sigmoid function with respect to z, we can get:

$$\frac{\partial \sigma(z)}{\partial z} = \frac{\exp(-z)}{(1 + \exp(-z))^2} = \frac{\exp(-z)}{1 + \exp(-z)} * \frac{1}{1 + \exp(-z)}$$

$$= \sigma(z)(1 - \sigma(z))$$
(2)

**4 points** for calculating the derivative correctly, and **1 point** for writing the final answer in terms of sigmoid functions.

#### b) 5 points

The multiclass sigmoid function can be expressed as:

$$\sigma_M(z_k) = \frac{\exp(z_k)}{\sum_{i=1}^K \exp(z_i)}$$
(3)

Taking derivative of the multiclass sigmoid function with respect to  $z_k$ , we can get:

$$\frac{\partial \sigma_M(z_k)}{\partial z_k} = \frac{\exp(z_k)(\sum_{i=1}^K \exp(z_i)) - \exp(z_k) \exp(z_k)}{(\sum_{i=1}^K \exp(z_i))^2}$$

$$= \frac{\exp(z_k)}{\sum_{i=1}^K \exp(z_i)} - (\frac{\exp(z_k)}{\sum_{i=1}^K \exp(z_i)})^2$$

$$= \sigma_M(z_k)(1 - \sigma_M(z_k))$$
(4)

**4 points** for calculating the derivative correctly, **2 points** for each of the numerator and denominator, and **1 points** for writing the final answer in terms of sigmoid functions.

## 3 Problem 3 (10 points)

Assume there are m training samples  $\mathcal{D}_{m=1}^M = \{x[m], y[m]\}$ . Construct the data matrix A:

$$\mathbf{A}^{M \times (N+1)} = \begin{bmatrix} A[1] \\ A[2] \\ \vdots \\ A[M] \end{bmatrix}$$
 (5)

with mth row composed of:  $A[m] = \begin{bmatrix} \boldsymbol{x}[m] & 1 \end{bmatrix}^{1 \times (N+1)}$ . And the output data matrix  $\boldsymbol{y}$ :

$$\mathbf{y}^{M \times 2} = \begin{bmatrix} y_1[1] & y_2[1] \\ y_1[2] & y_2[2] \\ \vdots \\ y_1[M] & y_2[M] \end{bmatrix} = \begin{bmatrix} \mathbf{y}_1 & \mathbf{y}_2 \end{bmatrix}$$
(6)

So the predicted output matrix  $\hat{y}$  can be expressed as:

$$\hat{\boldsymbol{y}} = \boldsymbol{A}^{M \times (N+1)} W^{(N+1) \times 2} 
= \boldsymbol{A}^{M \times (N+1)} \left[ W_1^{(N+1) \times 1} \quad W_2^{(N+1) \times 1} \right]$$
(7)

The mean squared errors are:

$$L_{MSE}(D:W) = \frac{1}{M} [(\mathbf{A}W_1 - \mathbf{y}_1)^t (\mathbf{A}W_1 - \mathbf{y}_1) + (\mathbf{A}W_2 - \mathbf{y}_2)^t (\mathbf{A}W_2 - \mathbf{y}_2)]$$
(8)

Taking derivative of the mean squared error with respect to  $W_1$ , we can get:

$$\nabla_{W_1} L_{MSE} = \frac{\partial L_{MSE}}{\partial W_1}$$

$$= \frac{\partial \frac{1}{M} [(\mathbf{A}W_1 - \mathbf{y}_1)^t (\mathbf{A}W_1 - \mathbf{y}_1) + (\mathbf{A}W_2 - \mathbf{y}_2)^t (\mathbf{A}W_2 - \mathbf{y}_2)]}{\partial W_1}$$

$$= \frac{2}{M} \mathbf{A}^t (\mathbf{A}W_1 - \mathbf{y}_1)$$
(9)

Following the same procedure, we can get:

$$\nabla_{W_2} L_{MSE} = \frac{2}{M} \boldsymbol{A}^t (\boldsymbol{A}W_2 - \boldsymbol{y}_2) \tag{10}$$

Setting the gradient equal to zero, we can get:

$$W = \begin{bmatrix} W_1 & W_2 \end{bmatrix} = (\boldsymbol{A}^t \boldsymbol{A})^{-1} \boldsymbol{A} \boldsymbol{y}$$
 (11)

while 
$$\boldsymbol{y} = \begin{bmatrix} \boldsymbol{y}_1 & \boldsymbol{y}_2 \end{bmatrix}$$
.

2 points for forming the augmented input matrix and the output matrix, 2 points for writing the total cost functions in matrix format, 3 points for correctly calculating the gradient, and 3 points for finding the closed-from for the final solution.

# 4 Problem 4 (10 points)

By using the same notations as in the class, we have vector

$$y[m] = [y[m][1], y[m][2], y[m][3]]^T$$

as the output for data point m, where y[m][i] = 1 when y[m] = i, and define  $X[m] = [x[m], 1]^T$  as the augmented input, where x[m] is the feature vector for data point m. We know that when we use softmax, the conditional likelihood of the output vector is

$$p(y[m]|X[m], \boldsymbol{\theta}) = \prod_{k=1}^{3} \left( \sigma_3(\boldsymbol{\theta}_k^T X[m]) \right)^{y[m][k]}.$$

Therefore, the overall cost function, which is the negative log conditional likelihood added by the L-1 norm, is

$$\begin{split} L(\boldsymbol{D}:\boldsymbol{\theta}) &= -\sum_{m=1}^{N} \log p(y[m] \big| X[m], \boldsymbol{\theta}) + \lambda R(\boldsymbol{\theta}) \\ &= -\sum_{m=1}^{N} \log \prod_{k=1}^{3} \left( \sigma_{3}(\boldsymbol{\theta}_{k}^{T} X[m]) \right)^{y[m][k]} + \lambda R(\boldsymbol{\theta}) \\ &= -\sum_{m=1}^{N} \sum_{k=1}^{3} y[m][k] \log \left( \sigma_{3}(\boldsymbol{\theta}_{k}^{T} X[m]) \right) + \lambda R(\boldsymbol{\theta}) \\ &= -\sum_{m=1}^{N} \sum_{k=1}^{3} y[m][k] \log \frac{\exp\{\boldsymbol{\theta}_{k}^{T} X[m]\}}{\sum_{\ell=1}^{3} \exp\{\boldsymbol{\theta}_{\ell}^{T} X[m]\}} + \lambda R(\boldsymbol{\theta}) \\ &= -\sum_{m=1}^{N} \sum_{k=1}^{3} y[m][k] \left[ \boldsymbol{\theta}_{k}^{T} X[m] - \log \sum_{\ell=1}^{3} \exp\{\boldsymbol{\theta}_{\ell}^{T} X[m]\} \right] + \lambda R(\boldsymbol{\theta}) \end{split}$$

Now, the gradient equation for any  $\theta_k$ ,  $k \in \{1, 2, 3\}$  can be obtained from the fact that only *one* of the elements of y[m] is 1 for any m and the rests are 0, and also the derivative of the L-1 norm is the sign function, where

here we assume that it is applied element-wise on any vector

$$\begin{split} \frac{\partial L(\boldsymbol{D}:\boldsymbol{\theta})}{\partial \boldsymbol{\theta}_{k}} &= -\sum_{m=1}^{N} \sum_{j=1}^{3} \frac{\partial}{\partial \boldsymbol{\theta}_{k}} \left[ y[m][j] \left[ \boldsymbol{\theta}_{j}^{T} X[m] - \log \sum_{\ell=1}^{3} \exp\{\boldsymbol{\theta}_{\ell}^{T} X[m]\} \right] \right] + \lambda \frac{\partial R(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}_{k}} \\ &= -\sum_{m=1}^{N} \left[ y[m][k] X[m] - \frac{\partial}{\partial \boldsymbol{\theta}_{k}} \sum_{j=1}^{3} y[m][j] \log \sum_{\ell=1}^{3} \exp\{\boldsymbol{\theta}_{\ell}^{T} X[m]\} \right] + \lambda \mathrm{sign}(\boldsymbol{\theta}_{k}) \\ &= -\sum_{m=1}^{N} \left[ y[m][k] X[m] - \frac{\partial}{\partial \boldsymbol{\theta}_{k}} \log \sum_{\ell=1}^{3} \exp\{\boldsymbol{\theta}_{\ell}^{T} X[m]\} \right] + \lambda \mathrm{sign}(\boldsymbol{\theta}_{k}) \\ &= -\sum_{m=1}^{N} \left[ y[m][k] X[m] - \frac{X[m] \exp\{\boldsymbol{\theta}_{\ell}^{T} X[m]\}}{\sum_{\ell=1}^{3} \exp\{\boldsymbol{\theta}_{\ell}^{T} X[m]\}} \right] + \lambda \mathrm{sign}(\boldsymbol{\theta}_{k}) \\ &= -\sum_{m=1}^{N} X[m] \left[ y[m][k] - \frac{\exp\{\boldsymbol{\theta}_{\ell}^{T} X[m]\}}{\sum_{\ell=1}^{3} \exp\{\boldsymbol{\theta}_{\ell}^{T} X[m]\}} \right] + \lambda \mathrm{sign}(\boldsymbol{\theta}_{k}) \\ &= -\sum_{m=1}^{N} X[m] \left[ y[m][k] - \sigma_{3}(\boldsymbol{\theta}_{k}^{T} X[m]) \right] + \lambda \mathrm{sign}(\boldsymbol{\theta}_{k}) \end{split}$$

**2 points** for forming the negative log conditional likelihood, **2 points** for calculating the derivative of the *L*-1 norm correctly, **3 points** for correctly identifying the relevant term for taking the derivatives, and **3 points** for finding the closed-from for the final solution.