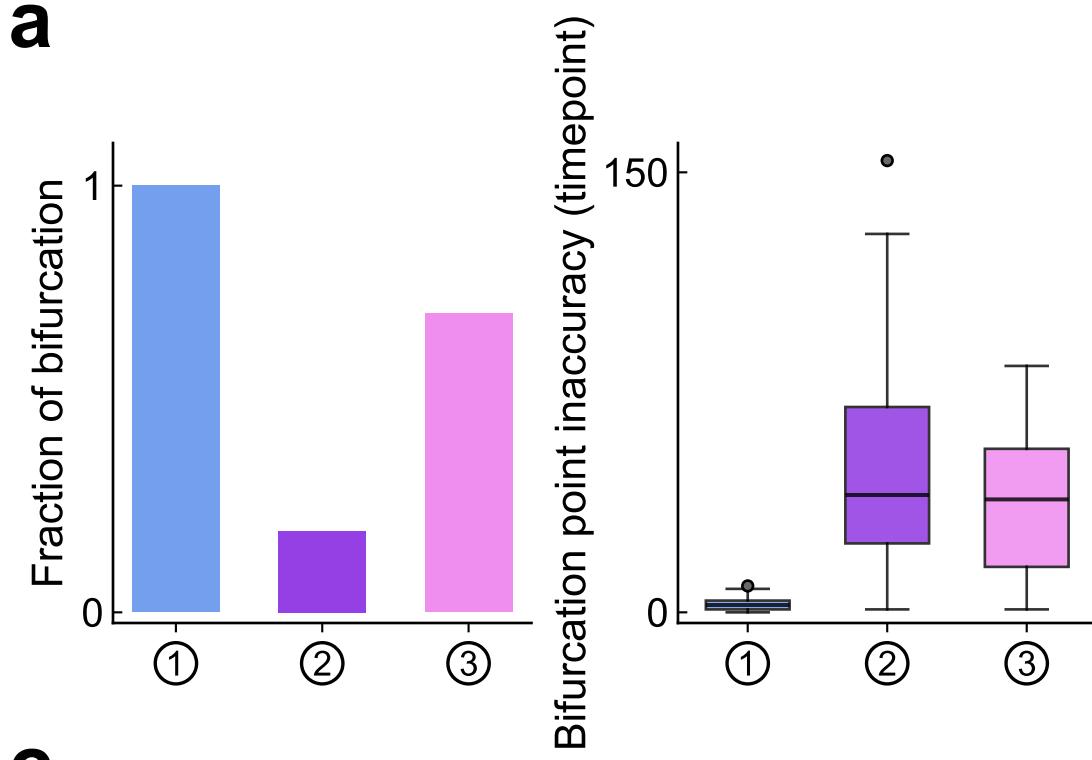
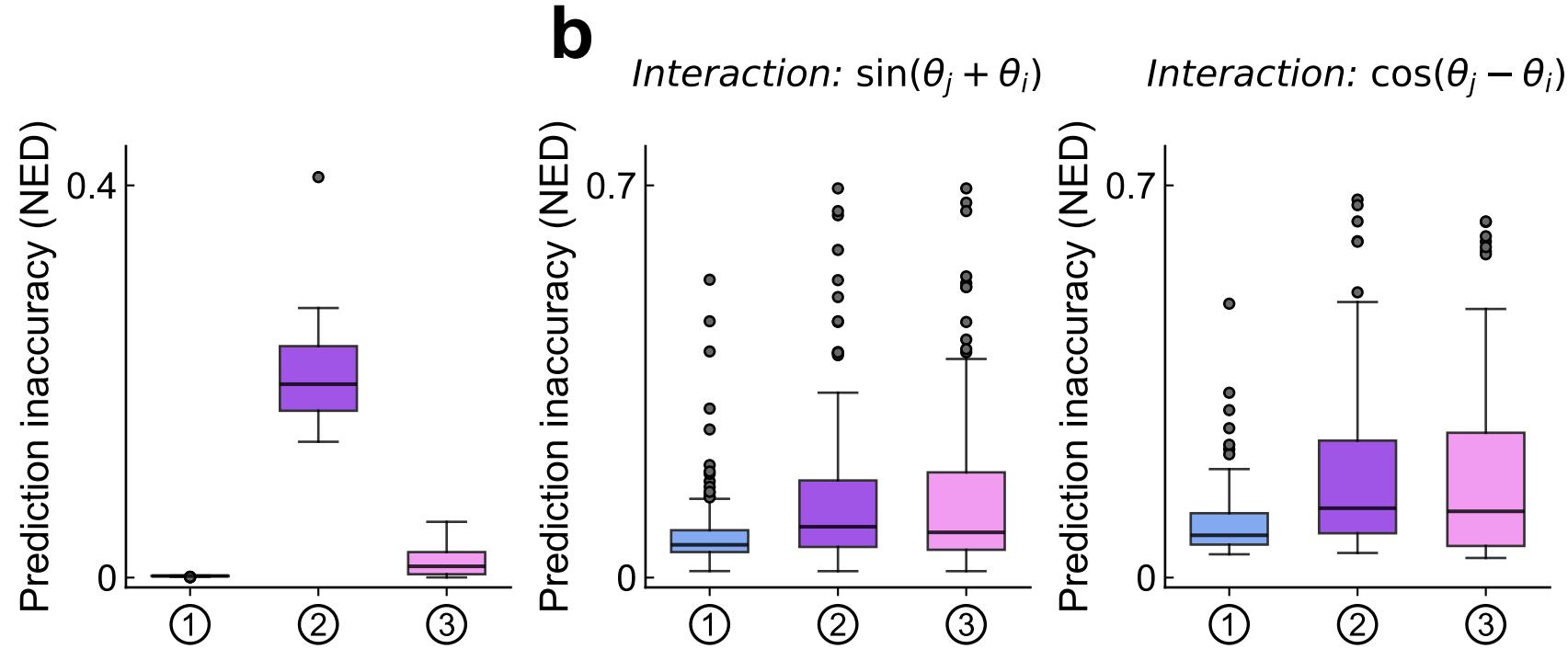


① Optimal driving signal ② Forcing parameters ③ Time variable

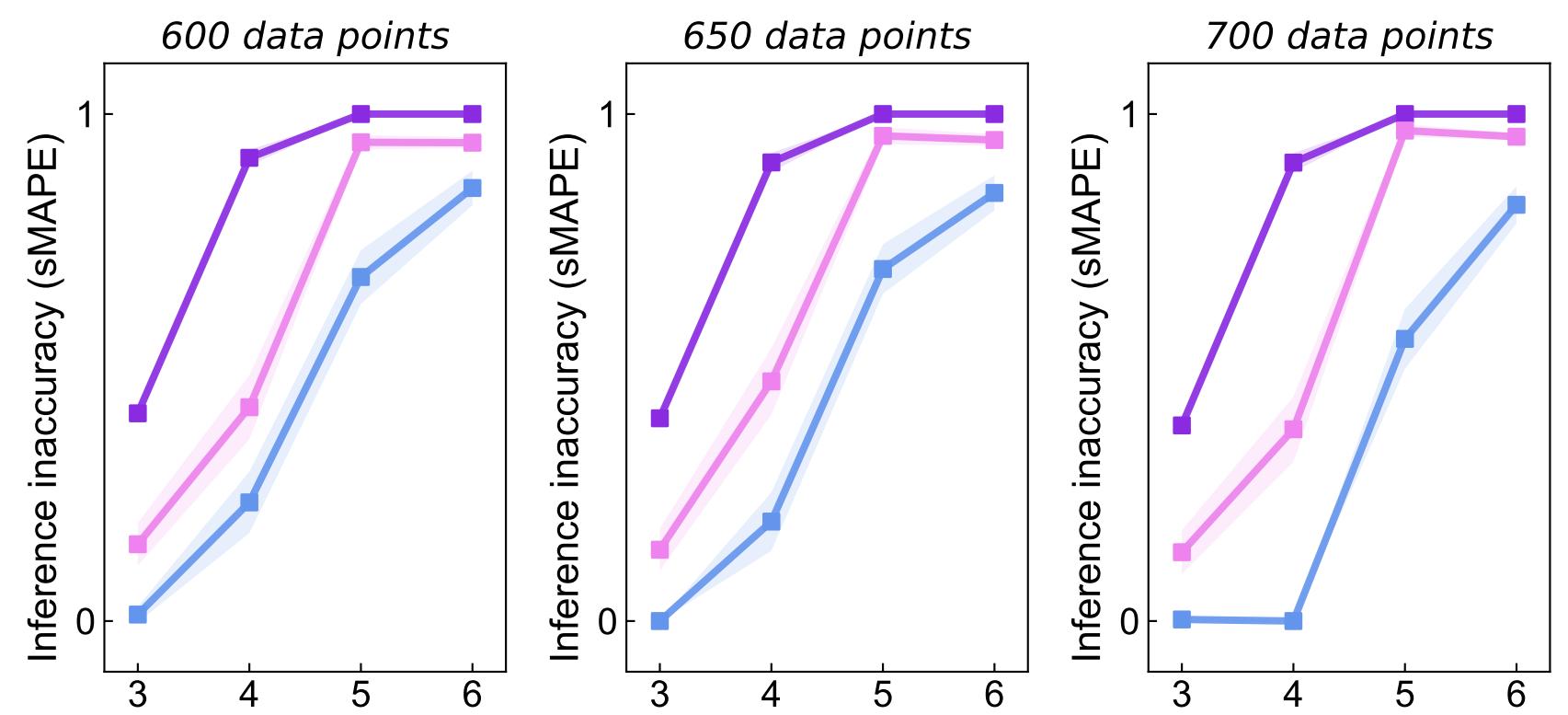
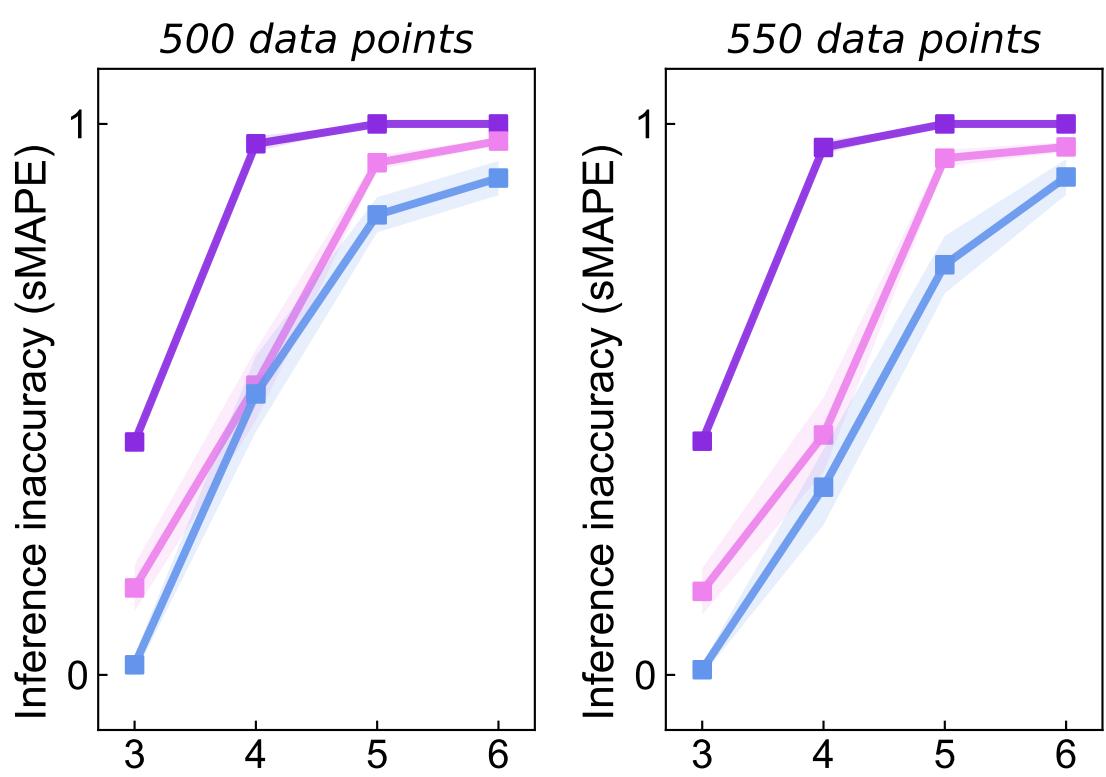
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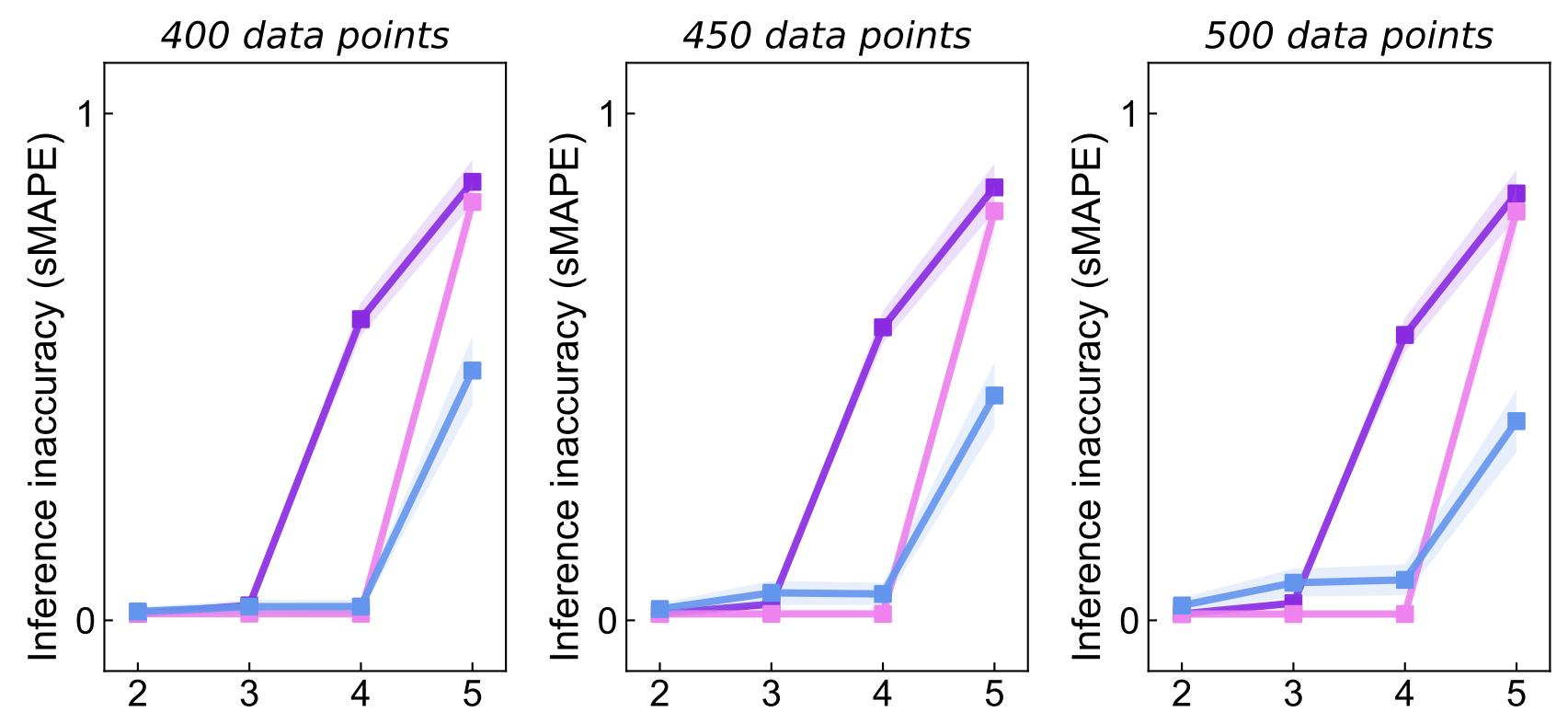
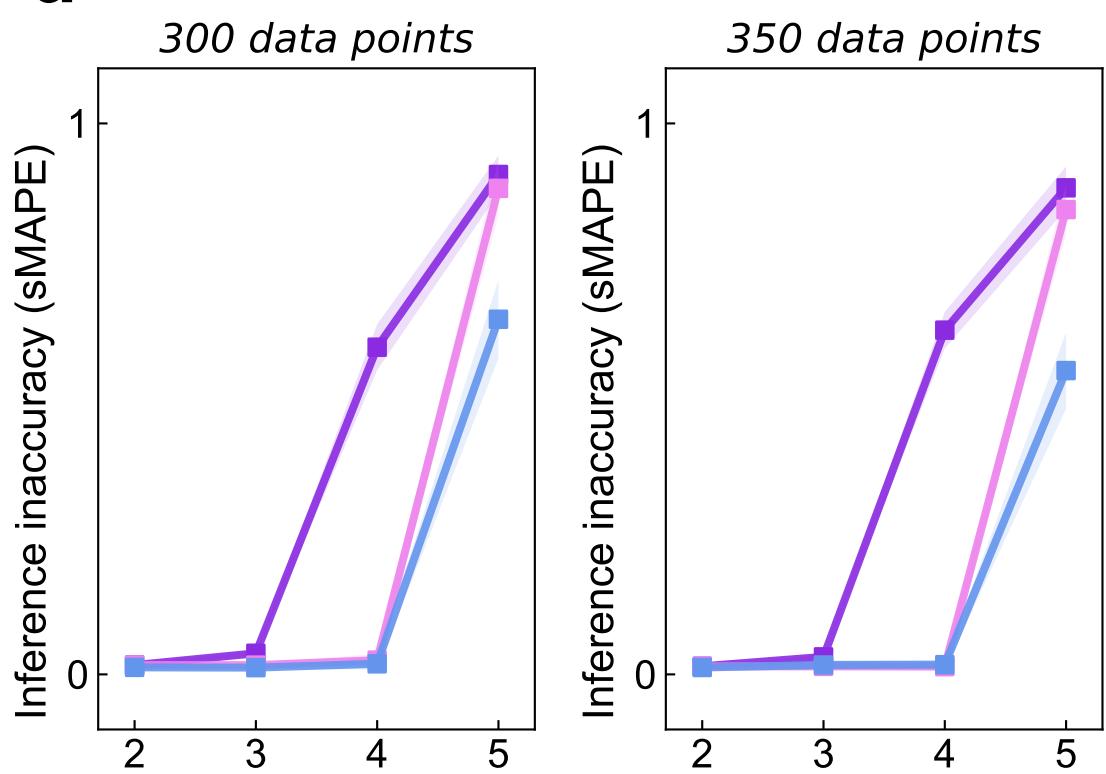
b



c



d



Basis function library with degree k