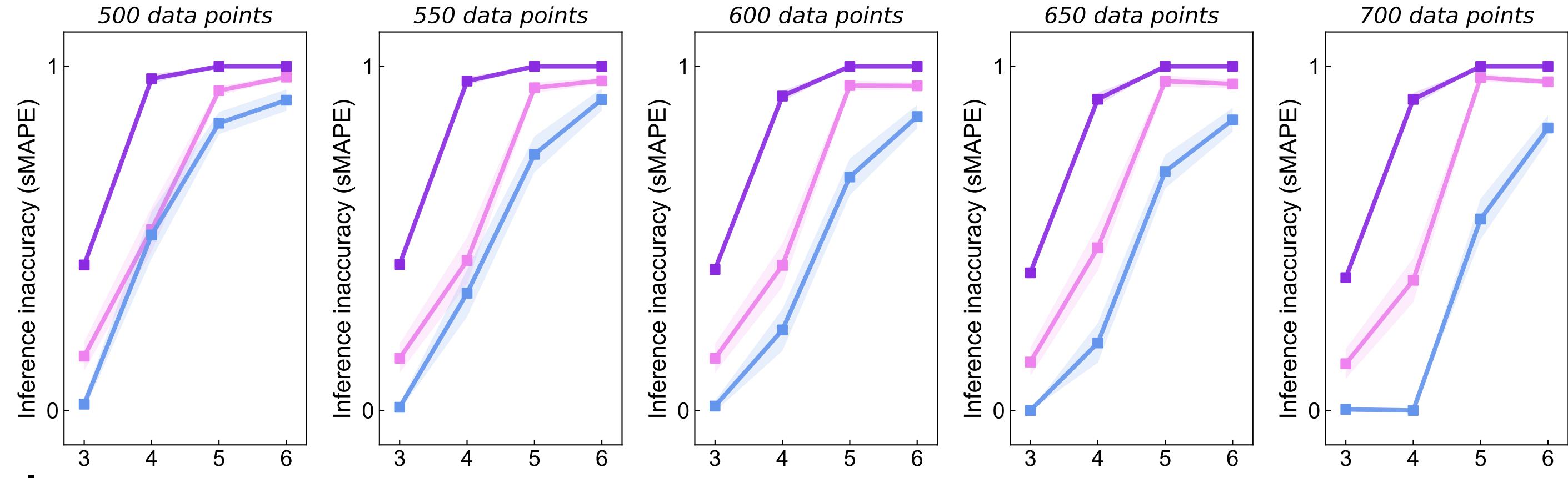
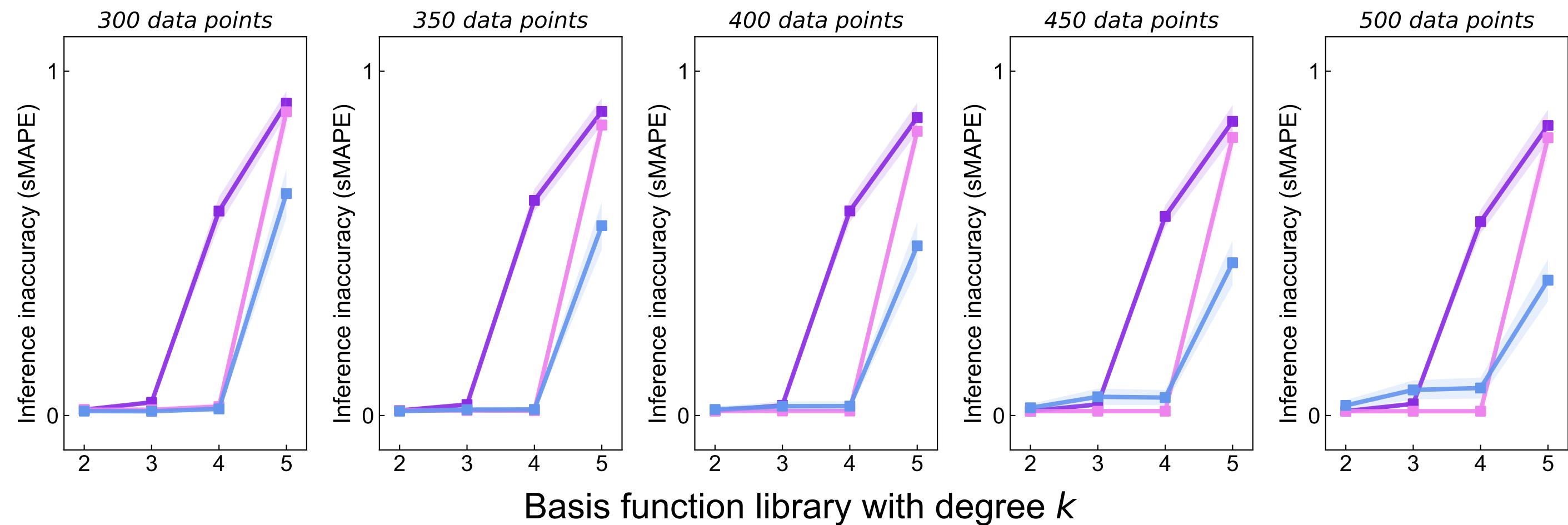


① Optimal driving signal    ② Forcing parameters    ③ Time variable

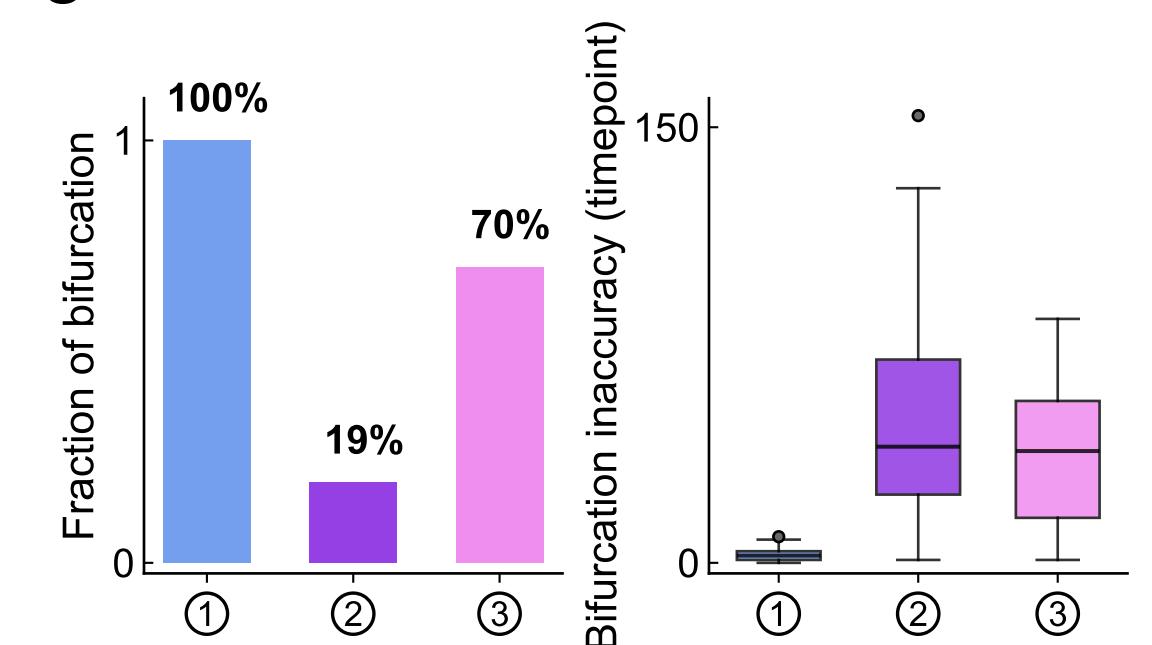
**a**



**b**



**c**



**d**

