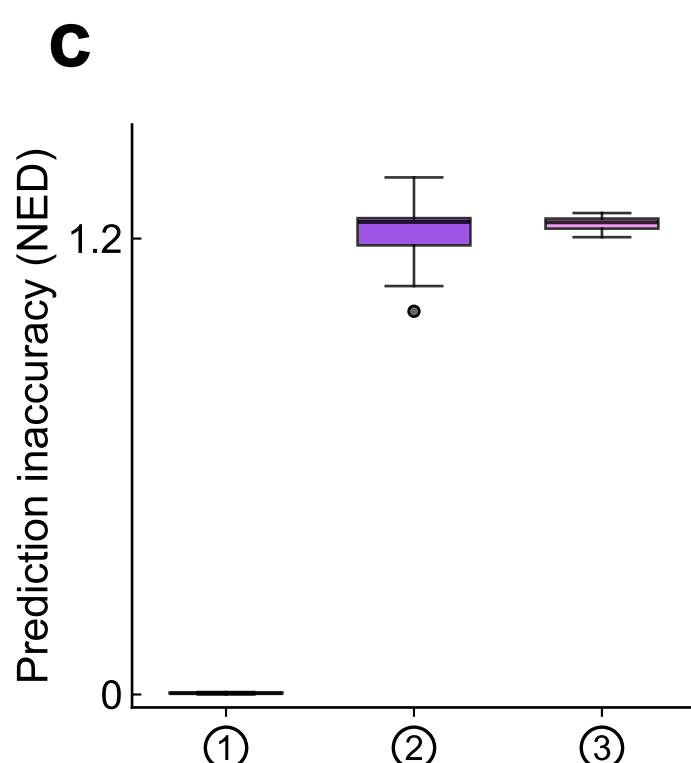
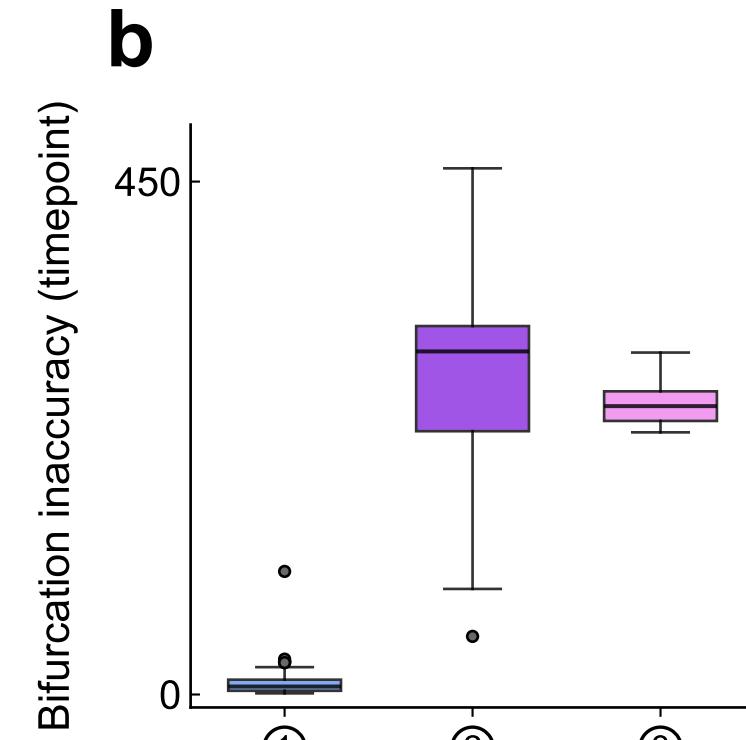
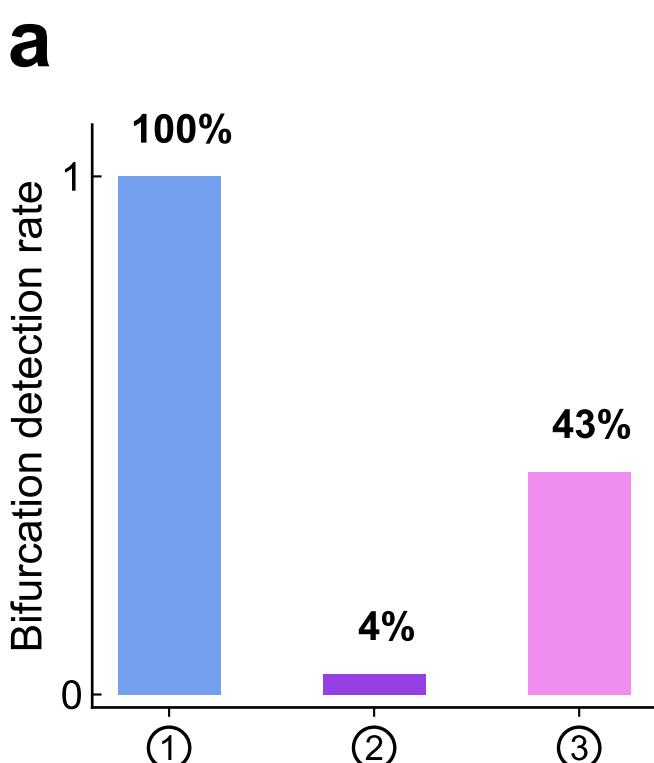


① Optimal driving variable

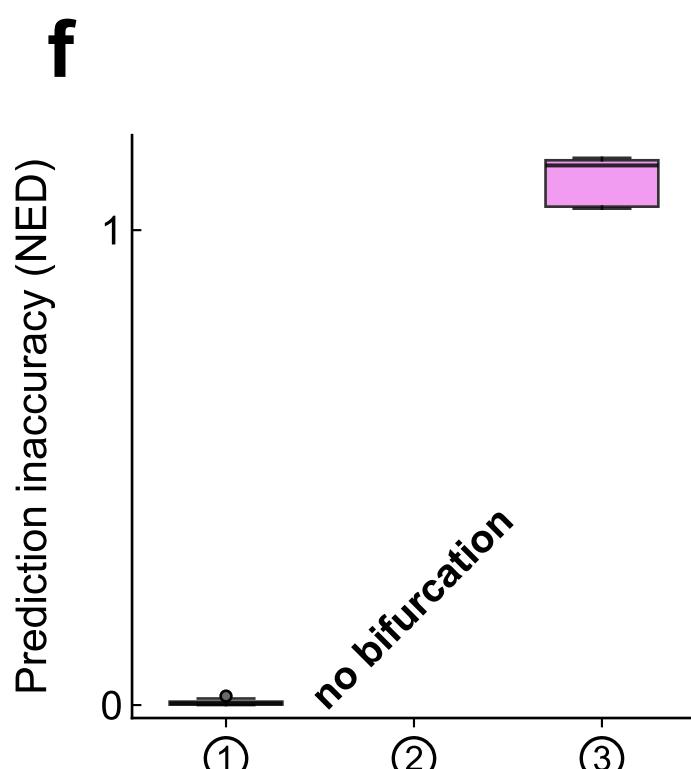
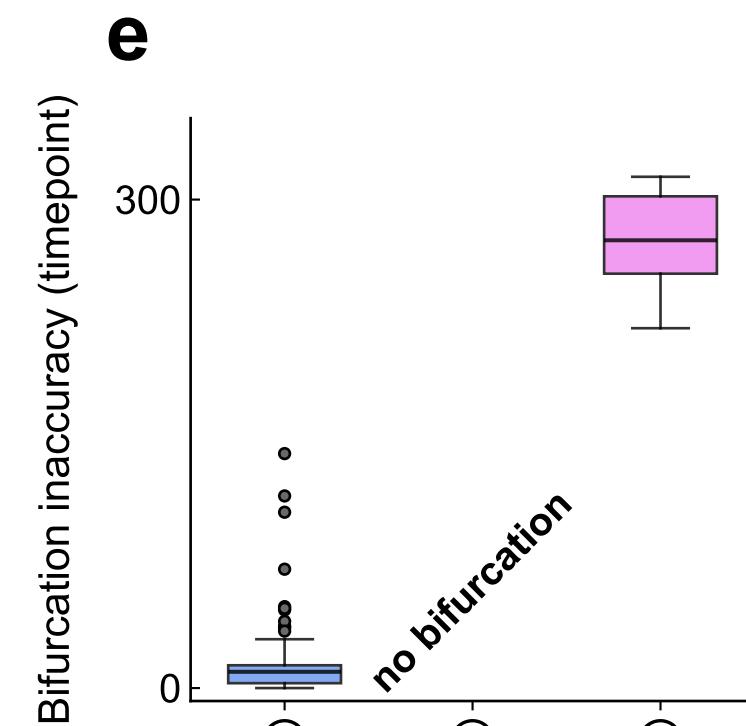
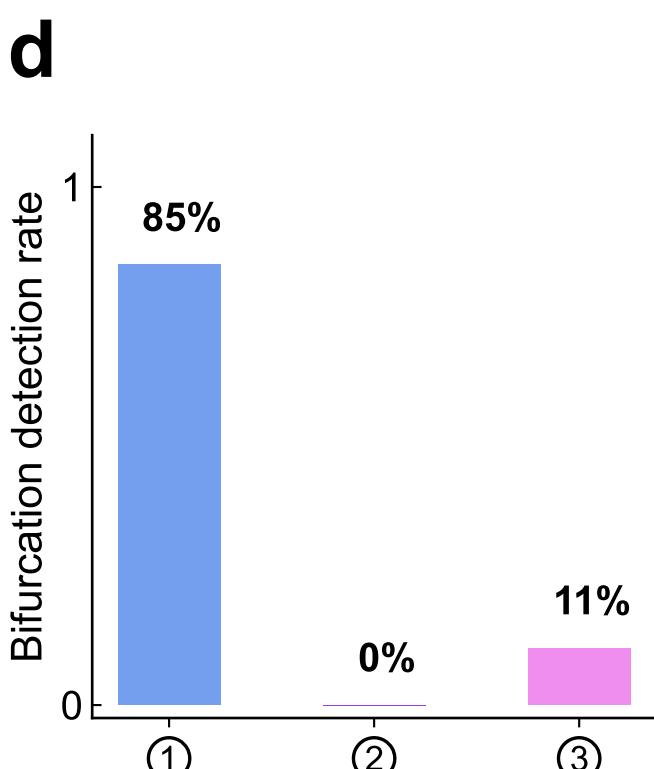
② Forcing parameters

③ Time variable

Degree-4 basis function library



Degree-5 basis function library



Degree-6 basis function library

