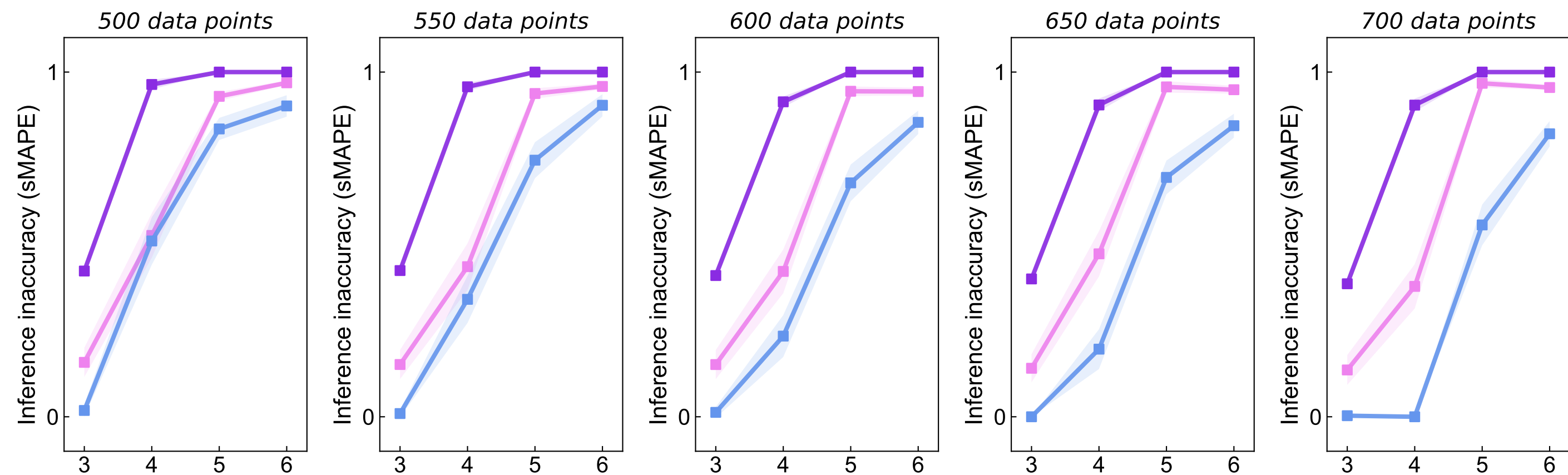


① Optimal driving signal

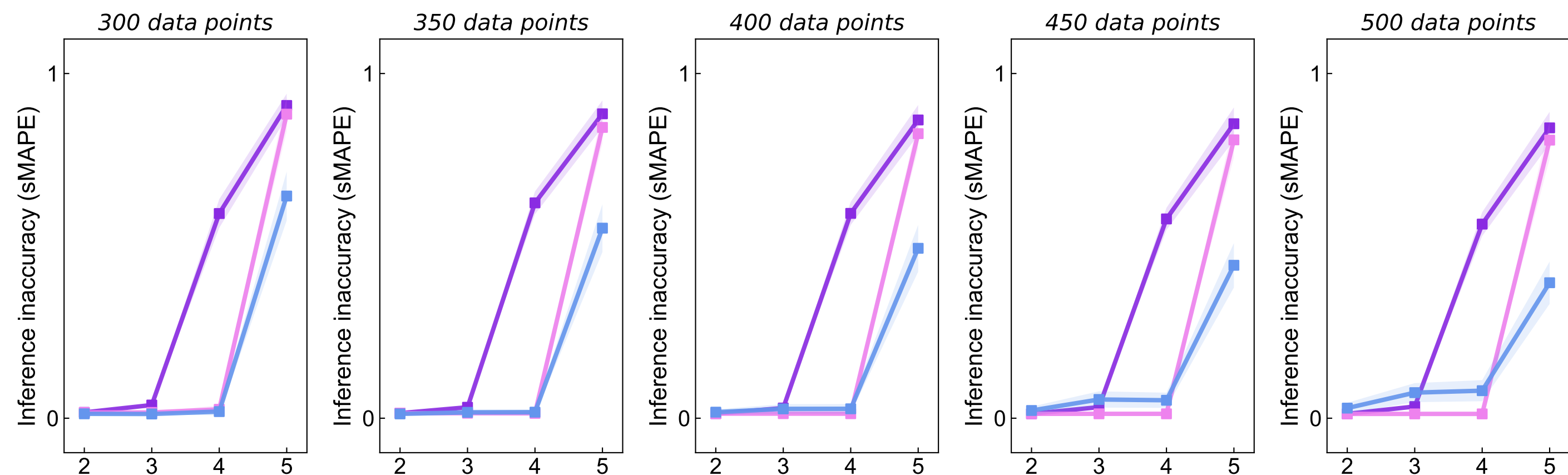
② Forcing parameters

③ Time variable

a



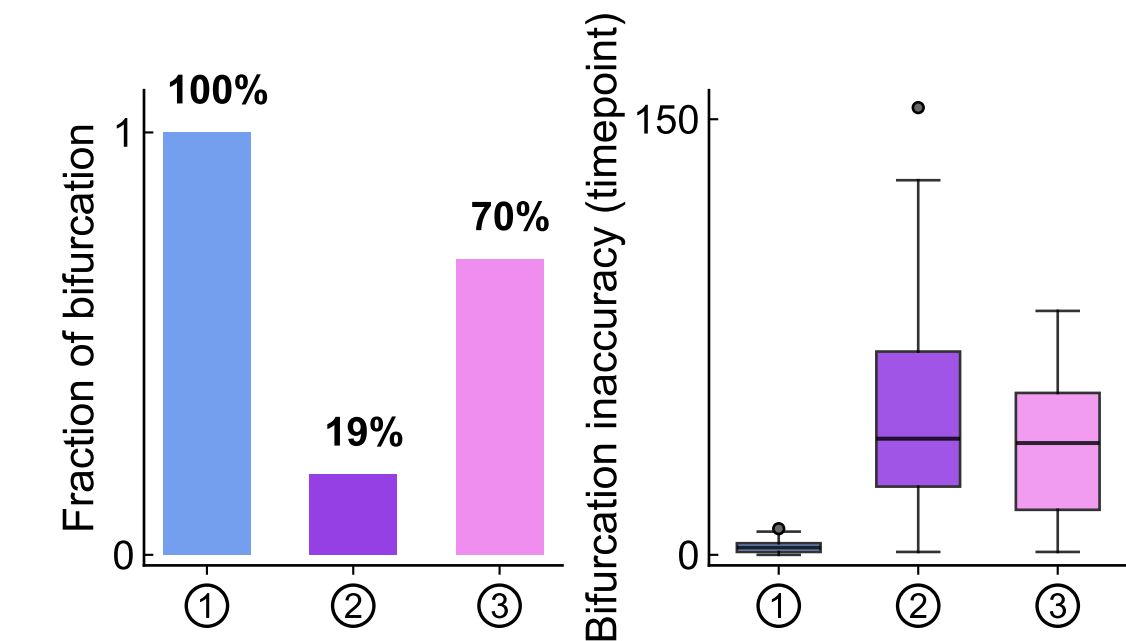
b



Basis function library with degree k

Cusp bifurcation

c



Kuramoto oscillators

d

