

① Optimal driving signal

② Forcing parameters

③ Time variable

a

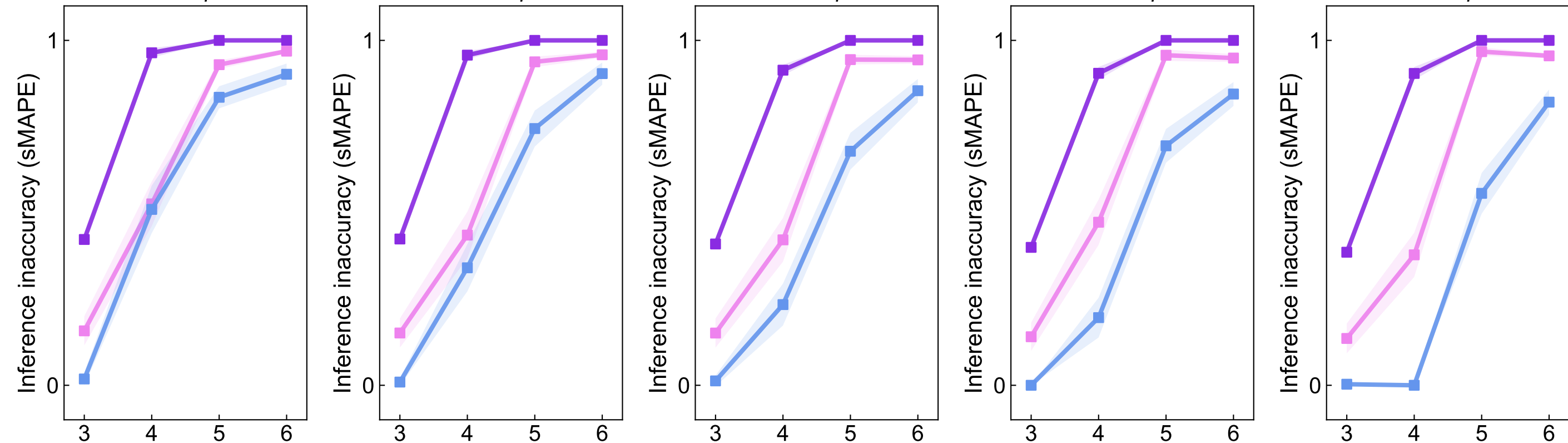
500 data points

550 data points

600 data points

650 data points

700 data points



b

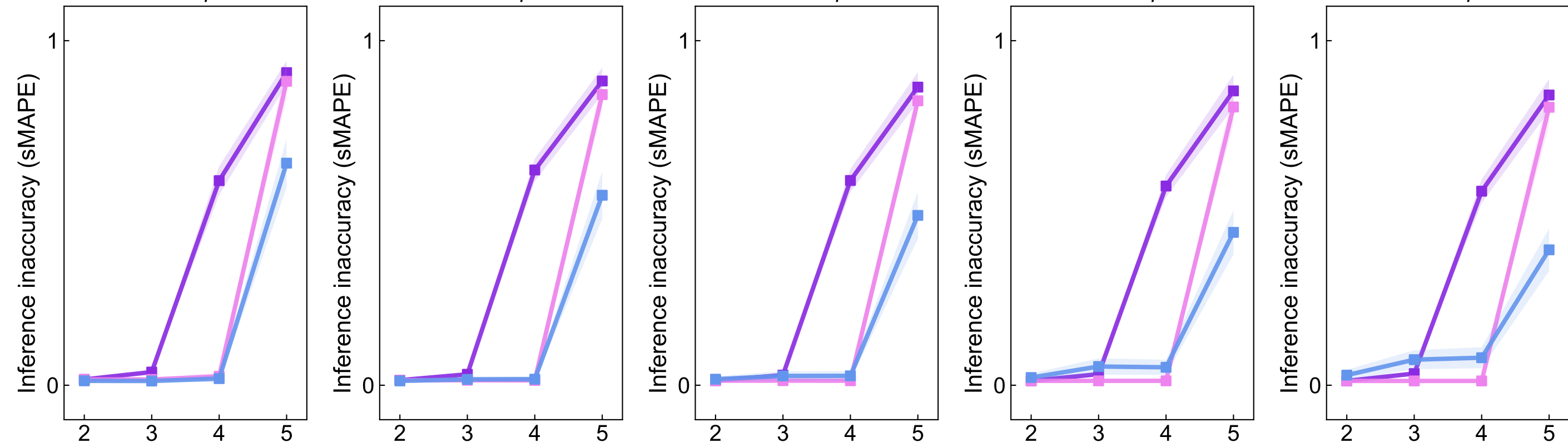
300 data points

350 data points

400 data points

450 data points

500 data points



Basis function library with degree k