目标点 1 ：

frame\_id: "map"

pose:

position:

x: 1.84500110149

y: -0.883078575134

z: 0.0

orientation:

x: 0.0

y: 0.0

z: -0.306595935327

w: 0.951839761956

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目标点 2 ：

frame\_id: "map"

pose:

position:

x: 3.24358606339

y: 0.977679371834

z: 0.0

orientation:

x: 0.0

y: 0.0

z: 0.647871240469

w: 0.761749864308

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目标点 3 ：

frame\_id: "map"

pose:

position:

x: 2.41693687439

y: 1.64631867409

z: 0.0

orientation:

x: 0.0

y: 0.0

z: 0.988149484601

w: 0.153494612555

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目标点 4：

frame\_id: "map"

pose:

position:

x: -0.970185279846

y: 0.453477025032

z: 0.0

orientation:

x: 0.0

y: 0.0

z: 0.946238058267

w: -0.323471076121

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