Stochastic Signal Processing

Lesson 3:

Functions of one and two random variables

Weize Sun

Review Examples from last week

1: Assume that the waiting time of a bus follows an $\lambda = 0.1$ exponential distribution. (Time: minutes) What is the probability that you will be able to get on the bus in 10 minutes?

$$f(x) = \begin{cases} \lambda e^{-\lambda x}, & x \ge 0 \\ 0, & x < 0 \end{cases}$$
$$F(x) = 1 - e^{-\lambda x}, & x \ge 0$$

Solution:

$$Pr(X \le 10) = F(10) = 1 - e^{-1} = 0.6321$$

Review Examples from last week

2: Let B represent the event $\{a < X(\xi) \le b\}$ with b > a. For a given $F_X(x)$, determine $F_X(x|B)$ and $f_X(x|B)$

Solution:

$$F_X(x|B) = P\{X(\xi) \le x | B\} = \frac{P\{(X(\xi) \le x) \cap (a < X(\xi) \le b)\}}{P(a < X(\xi) \le b)}$$
$$= \frac{P\{(X(\xi) \le x) \cap (a < X(\xi) \le b)\}}{F_X(b) - F_X(a)}.$$

For x < a, we have $\{X(\xi) \le x\} \cap \{a < X(\xi) \le b\} = \emptyset$, hence $F_X(x|B) = 0$.

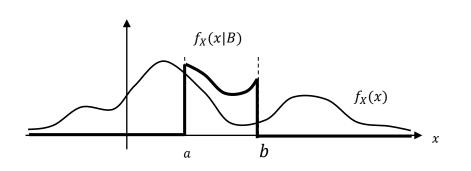
For $a \le x < b$,we have $\{X(\xi) \le x\} \cap \{a < X(\xi) \le b\} = \{a < X(\xi) \le x\}$, hence

$$F_X(x|B) = \frac{P(a < X(\xi) \le x)}{F_X(b) - F_X(a)} = \frac{F_X(x) - F_X(a)}{F_X(b) - F_X(a)}.$$

Review Examples from last week

2: Let B represent the event $\{a < X(\xi) \le b\}$ with b > a. For a given $F_X(x)$, determine $F_X(x|B)$ and $f_X(x|B)$.

For $x \ge b$, we have $\{X(\xi) \le x\} \cap \{a < X(\xi) \le b\} = \{a\}$



- The shape of the conditional pdf is the same as the shape of original pdf, for a < x < b
- Otherwise, pdf becomes 0

• Let X be a r.v and suppose g(x) is a function of the variable x. Define

$$Y = g(X)$$

 Clearly Y is a r.v (there are some conditions, see Page 87 of the text book, but here we will not discuss it), In particular

$$F_Y(y) = P(Y(\xi) \le y) = P(g(X(\xi)) \le y)$$
$$= P(X(\xi) \le g^{-1}(-\infty, y])$$

- Thus the CDF and pdf of Y can be determined in terms of that of X.
- Usually, we start with the CDF $F_Y(y)$, then take the derivative of it to get the pdf.
- We will start with some examples

• Quick Example 1: Y = aX + b, compute $f_Y(y)$.

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Suppose a > 0.

$$F_Y(y) = P(Y(\xi) \le y) = P(aX(\xi) + b \le y) = P(X(\xi) \le \frac{y - b}{a})$$
$$= F_X(\frac{y - b}{a})$$

and
$$f_Y(y) = \frac{1}{a} f_X(\frac{y-b}{a})$$

On the other hand if a < 0, then

$$F_Y(y) = P(Y(\xi) \le y) = P(aX(\xi) + b \le y) = P\left(X(\xi) > \frac{y - b}{a}\right)$$
$$= 1 - F_X\left(\frac{y - b}{a}\right),$$

and hence
$$f_Y(y) = -\frac{1}{a} f_X\left(\frac{y-b}{a}\right)$$

Generally speaking,
$$f_Y(y) = \frac{1}{|a|} f_X\left(\frac{y-b}{a}\right)$$
 for all a

• Quick Example 2: $Y = X^2$, compute $f_Y(y)$.

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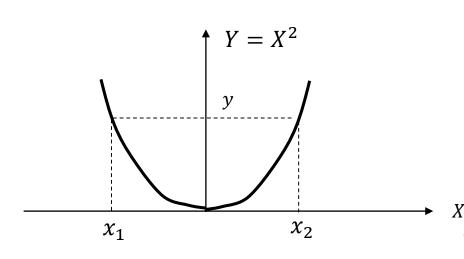
$$F_Y(y) = P(Y(\xi) \le y) = P(X^2(\xi) \le y)$$
.

If y < 0, then the event $\{X^2(\xi) \le y\} = \emptyset$, and hence

$$F_Y(y) = 0, \qquad y < 0.$$

For y > 0, from the below figure, the event $\{Y(\xi) \le y\} = \{X^2(\xi) \le y\}$ is equivalent to

$$\{x_1 < X(\xi) \le x_2\}$$



Hence

$$F_Y(y) = P(x_1 < X(\xi) \le x_2) = F_X(x_2) - F_X(x_1)$$

= $F_X(\sqrt{y}) - F_X(-\sqrt{y}), y > 0$.

By direct differentiation, we get

$$f_Y(y) = \begin{cases} \frac{1}{2\sqrt{y}} \left(f_X(\sqrt{y}) + f_X(-\sqrt{y}) \right), & y > 0, \\ 0, & \text{otherwise.} \end{cases}$$

Is there a general solution?

The random variable g(X) – general solution – discrete type r.v

• Assume that there are n different function values x_i (i = 1, 2, ..., n) map to the same value y, then

$$P(Y = y) = \sum_{i=1}^{n} P(X = x_n) = \sum_{i=1}^{n} P(X = g_n^{-1}(y))$$

- where $g_n^{-1}(y)$ represents different values x mapped to the same y value
- Example: Given $X = \{-2, -1, 0, 1, 2\}$ with probabilities $\{0.1, 0.15, 0.25, 0.3, 0.2\}$, respectively, and the distribution of $Y = X^2$ is:

The random variable g(X) – general solution – continuous type r.v

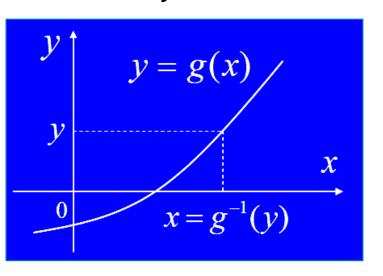
• Assume that g(x) is a derivable monotone function (可导的单调函数) whose inverse function is $g^{-1}(y)$, and it is monotonically increasing

$$\rightarrow$$
 $F_Y(y) = P(Y \le y) = P\{g(X) \le y\} = P\{X \le g^{-1}(y)\} = F_X(g^{-1}(y))$

Take the derivative of both sides

$$f_Y(y) = f_X(g^{-1}(y)) \frac{dg^{-1}(y)}{dy} = f_X(x) \frac{dx}{dy}|_{x=g^{-1}(y)}$$

Note: almost always first CDF then pdf



The random variable g(X) – general solution – continuous type r.v

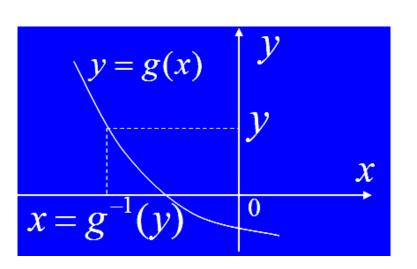
• Assume that g(x) is a derivable monotone function (可导的单调函数) whose inverse function is $g^{-1}(y)$, and it is monotonically increasing

Take the derivative of both sides

$$f_Y(y) = -f_X(g^{-1}(y)) \frac{dg^{-1}(y)}{dy}$$

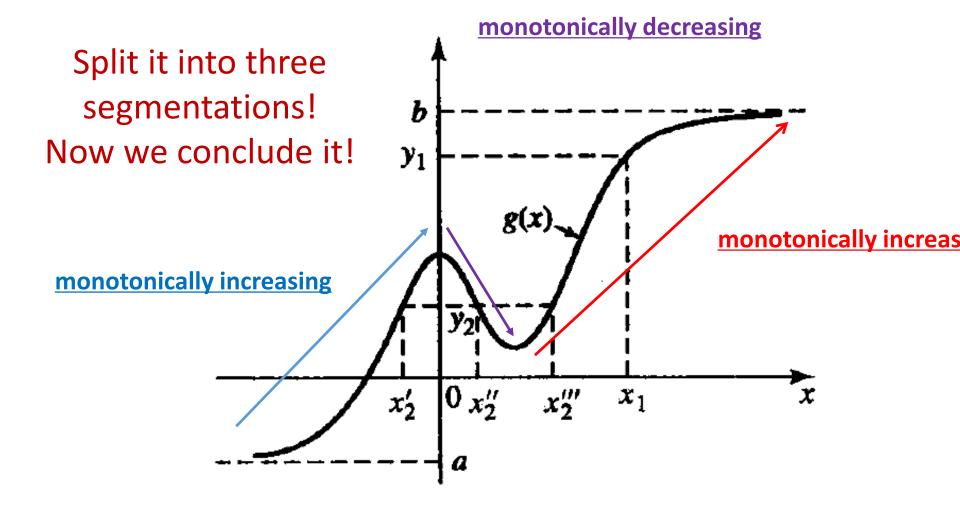
$$= -f_X(x) \frac{dx}{dy} |_{x=g^{-1}(y)}$$

$$= f_X(x) |\frac{dx}{dy}|_{x=g^{-1}(y)}$$



The random variable g(X) – general solution

- continuous type r.v
- How about a function like this?



The random variable g(X) – general solution – continuous type r.v

Define J = dx/dy and we have:

• If g(x) monotonically increasing \rightarrow

$$f_Y(y) = f_X(g^{-1}(y)) \frac{dg^{-1}(y)}{dy} = f_X(x) \frac{dx}{dy}|_{x=g^{-1}(y)}$$

• If g(x) monotonically decreasing \rightarrow

$$f_Y(y) = -f_X(g^{-1}(y)) \frac{dg^{-1}(y)}{dy} = -f_X(x) \frac{dx}{dy} \Big|_{x=g^{-1}(y)}$$

$$= f_X(x) \Big| \frac{dx}{dy} \Big|_{x=g^{-1}(y)}$$

• Which is, for both cases, generally speaking:

$$f_Y(y) = f_X(x)|J|_{X=g^{-1}(y)}$$

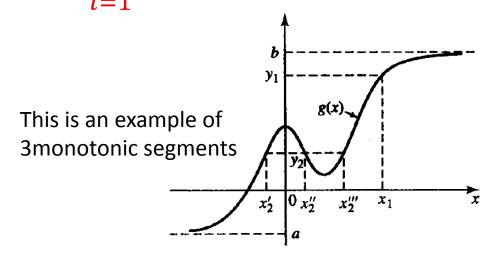
 In fact, the J is called the Jacobian, we will come back to this notation later when talking about two random variables The random variable g(X) – general solution – continuous type r.v

Define J = dx/dy and we have:

$$f_Y(y) = f_X(x)|J|_{X=g^{-1}(y)}$$

• If g(x) is not a monotonic function, then divided it into multiple monotonic segments: if there are n inverse functions for y=g(x) as $x_i=h_i(y), i=1,2,\ldots,n$, then

$$f_Y(y) = \sum_{i=1}^n f_X(x_i) |J_i|_{x_i = h_i(y)} \quad J_i = \frac{dx_i}{dy}$$



• Example 2.1: Assuming that the relationship between input and output is $Y = bX^2(b > 0)$, find the pdf of Y. $(f_Y(y) = ??? f_X(x)???)$

Note:
$$f_Y(y) = \sum_{i=1}^n f_X(x_i) |J_i|_{x_i = h_i(y)} \quad J_i = \frac{dx_i}{dy}$$

Solution:

- 1. For y < 0, $f_Y(y) = 0$.
- 2. For y > 0, we have $x_1 = \sqrt{y/b}$, $x_2 = -\sqrt{y/b}$

Taking the derivative of x_1 , x_2 for each respectively:

$$J_{1} = \frac{dx_{1}}{dy} = \frac{1}{2\sqrt{by}}$$

$$J_{2} = \frac{dx_{2}}{dy} = -\frac{1}{2\sqrt{by}}$$

$$f_{Y}(y) = \frac{1}{2\sqrt{by}}[f_{x}(\sqrt{\frac{y}{b}}) + f_{x}(-\sqrt{\frac{y}{b}})]$$
When $b = 1$, it is example 2

• Example 2.1: Assuming that the relationship between input and output is $Y = bX^2(b > 0)$, find the pdf of Y.

It is called 'power detector' (there are might be some other names)

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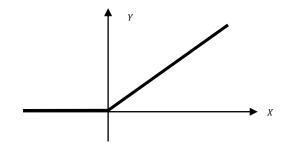
摘要 摘 要:射频信号是民航空管通信导航监视各类设备板件中不可或缺的信号,同时测量射频信号特征也是工程师排除 设备故障的必要方法,为使测量更加方便、排故更加准确,本文采用小信号平方率检波原理设计并制作了便携式调幅检波器.

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• Example 3: Half-wave rectifier(半波整流器), or the ReLU

$$Y = g(X),$$
 $g(x) = \begin{cases} x, & x > 0, \\ 0, & x \le 0. \end{cases}$



• Example 3: Half-wave rectifier(半波整流器), or the ReLU

$$Y = g(X),$$
 $g(x) = \begin{cases} x, & x > 0, \\ 0, & x \le 0. \end{cases}$

Solution: we have

$$P(Y = 0) = P(X(\xi) \le 0) = F_X(0).$$

and for y > 0 since Y = X,

$$F_Y(y) = P(Y(\xi) \le y) = P(X(\xi) \le y) = F_X(y)$$

Thus

$$f_Y(y) = \begin{cases} f_X(y), & y > 0, \\ F_X(0)\delta(y) & y = 0, \\ 0, & y < 0, \end{cases}$$

Mean or the Expected Value of a r.v X is defined as

$$\mu_X = \bar{X} = E(X) = \int_{-\infty}^{+\infty} x f_X(x) dx.$$

• If X is a discrete-type r.v:

$$\mu_X = \bar{X} = E(X) = \int x \sum_i p_i \delta(x - x_i) dx$$

$$= \sum_i x_i p_i \int \delta(x - x_i) dx = \sum_i x_i p_i = \sum_i x_i P(X = x_i).$$

• suppose Y = g(X) defines a new r.v with pdf $f_Y(y)$, then Y has a mean:

$$\mu_Y = E(Y) = \int_{-\infty}^{+\infty} y \, f_Y(y) dy.$$

- Mean of usually used distributions
 - Bernoulli distribution: $E(X) = p \cdot 1 + (1 p) \cdot 0 = p$
 - Binomial distribution: $E(X) = \sum_{x=0}^{\infty} x c_n^x p^x (1-p)^{n-x} = np$
 - Poisson distribution: $E(X) = \sum_{x=0}^{\infty} xe^{-\lambda} \frac{\lambda^x}{x!} = \lambda$
 - Uniform distributed: $E(X) = \int_a^b x/(b-a)dx = (b+a)/2$
 - Exponential distribution: $E(X) = \int_0^\infty x \lambda e^{-\lambda x} dx = 1/\lambda$
 - Normal distribution: $E(X) = \mu$

• For a r.v X with mean μ , $X-\mu$ represents the deviation of the r.v from its mean. Since this deviation can be either positive or negative, consider the quantity $(X-\mu)^2$ and its average value $E[(X-\mu)^2]$ represents the average mean square deviation of X around its mean:

$$\sigma_X^2 = E[(X - \mu)^2] > 0.$$

This is the **variance** of r.v X. Its square root $\sigma_X = \sqrt{E(X - \mu)^2}$ is known as the standard deviation of the r.v X. Note that the standard deviation represents the root mean square spread of the r.v X around its mean.

Note that

$$D(X) = Var(X) = \sigma_X^2 = \int_{-\infty}^{+\infty} (x^2 - 2x\mu + \mu^2) f_X(x) dx$$

$$= \int_{-\infty}^{+\infty} x^2 f_X(x) dx - 2\mu \int_{-\infty}^{+\infty} x f_X(x) dx + \mu^2$$

$$= E(X^2) - \mu^2 = E(X^2) - [E(X)]^2 = \overline{X^2} - \overline{X}^2.$$

- Variance of usually used distributions
 - Bernoulli distribution: $D(X) = p p^2$
 - Binomial distribution: D(X) = np(1-p)
 - Poisson distribution: $D(X) = \lambda = E(X)$

The mean and variance of a Poisson distribution are numerically equal

- Uniform distributed: $D(X) = (b-a)^2/12$
- Exponential distribution: $D(X) = 1/\lambda^2$
- Normal distribution: $D(X) = \sigma^2$

- Properties of Variance
 - Linear transformation:

$$D(aX + b) = a^2 D(X)$$

• If *X* and *Y* independent:

$$D(X \pm Y) = D(X) + D(Y)$$

• For any two random variables *X*, *Y* (not required to be independent):

$$D(X \pm Y) = D(X) + D(Y) \pm 2cov(X, Y)$$

• Moments:

$$m_n = \overline{X^n} = E(X^n), \qquad n \ge 1$$

are known as the moments of the r.v X, and

$$\mu_n = E[(X - \mu)^n]$$

are known as the central moments of X.

- Clearly
 - the mean $\mu=m_1$,
 - and the variance $\sigma^2 = \mu_2$

• In many experiments, the observations are expressible not as a single quantity, but as a family of quantities. For example, to record the height and weight of each person in a community or the number of people and the total income in a family, we need two numbers. Let *X* and *Y* denote two random variables (r.v). Then

$$P(x_1 < X(\xi) \le x_2) = F_X(x_2) - F_X(x_1) = \int_{x_1}^{x_2} f_X(x) dx,$$

and

$$P(y_1 < Y(\xi) \le y_2) = F_Y(y_2) - F_Y(y_1) = \int_{y_1}^{y_2} f_Y(y) dy$$
.

• What about the probability that the pair of r.vs (X,Y) belongs to an arbitrary region D? In other words, how to estimate, for example, $P[(x_1 < X(\xi) \le x_2) \cap (y_1 < X(\xi) \le x_2)]$

Properties

(i)
$$F_{XY}(-\infty, y) = F_{XY}(x, -\infty) = 0$$
, $F_{XY}(+\infty, +\infty) = 1$.

since
$$(X(\xi) \le -\infty, Y(\xi) \le y) \subset (X(\xi) \le -\infty)$$
, we get $F_{XY}(-\infty, y) \le P(X(\xi) \le -\infty) = 0$.

Similarly
$$F_{XY}(\infty, \infty) = P(S) = 1$$

(ii)
$$P(x_1 < X(\xi) \le x_2, Y(\xi) \le y) = F_{XY}(x_2, y) - F_{XY}(x_1, y)$$

 $P(X(\xi) \le x, y_1 < Y(\xi) \le y_2) = F_{XY}(x, y_2) - F_{XY}(x, y_1)$

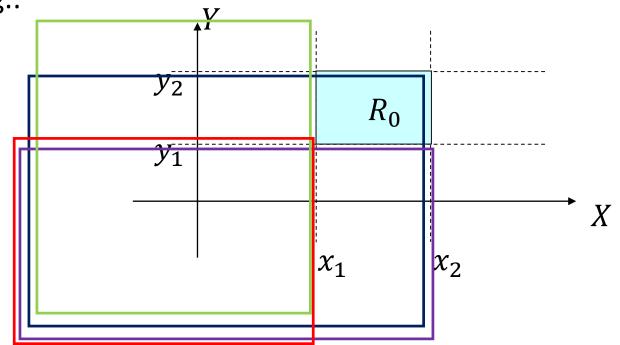
Properties

(iii)
$$P(x_1 < X(\xi) \le x_2, y_1 < Y(\xi) \le y_2)$$

$$= F_{XY}(x_2, y_2) - F_{XY}(x_2, y_1)$$

$$-F_{XY}(x_1, y_2) + F_{XY}(x_1, y_1).$$

<u>This</u> is the probability that (X,Y) belongs to the rectangle R_0 in the Fig.:



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Two Random Variables - Joint pdf

By definition, the joint pdf of X and Y is given by

$$f_{XY}(x,y) = \frac{\partial^2 F_{XY}(x,y)}{\partial x \, \partial y}.$$

and hence we obtain the useful forula

$$F_{XY}(x,y) = \int_{-\infty}^{x} \int_{-\infty}^{y} f_{XY}(u,v) \ dudv.$$

we also get
$$\int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} f_{XY}(x,y) \ dxdy = 1.$$

and

$$P((X,Y) \in D) = \int \int_{(x,y)\in D} f_{XY}(x,y) dx dy.$$

- In the context of several r.vs, the statistics of each individual ones are called marginal statistics.
- Thus $F_X(x)$ is the marginal CDF of X, and $f_X(x)$ is the marginal pdf of X. It is interesting to note that all marginals can be obtained from the joint pdf:

$$F_X(x) = F_{XY}(x, +\infty), \qquad F_Y(y) = F_{XY}(+\infty, y).$$

$$f_X(x) = \int_{-\infty}^{+\infty} f_{XY}(x, y) dy,$$

$$f_Y(y) = \int_{-\infty}^{+\infty} f_{XY}(x, y) dx$$

• If X and Y are discrete r.vs, then $p_{ij} = P(X = x_i, Y = y_j)$ represents their joint pdf, and their respective marginal pdfs are given by

$$P(X = x_i) = \sum_{j} P(X = x_i, Y = y_j) = \sum_{j} p_{ij}$$
And
$$P(Y = y_j) = \sum_{i} P(X = x_i, Y = y_j) = \sum_{i} p_{ij}$$

• Assuming that $P(X = x_i, Y = y_j)$ is written out in the form of a rectangular array, to obtain $P(X = x_i)$, one need to add up all entries in the *i*-th row.

$$\sum_{i} p_{ij}$$

$$p_{11} \quad p_{12} \quad \cdots \quad p_{1j} \quad \cdots \quad p_{1n}$$

$$p_{21} \quad p_{22} \quad \cdots \quad p_{2j} \quad \cdots \quad p_{2n}$$

$$\vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots$$

$$p_{i1} \quad p_{i2} \quad \cdots \quad p_{ij} \quad \cdots \quad p_{in}$$

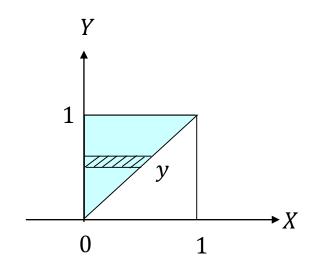
$$\vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots$$

$$p_{m1} \quad p_{m2} \quad \cdots \quad p_{mj} \quad \cdots \quad p_{mn}$$

$$33$$

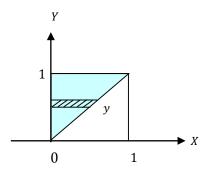
• Example 4: Calculate $f_X(x)$ and $f_Y(y)$ Given

$$f_{XY}(x,y) = \begin{cases} k, & 0 < x < y < 1, \\ 0, & \text{otherwise} \end{cases}$$



• Example 4: Calculate $f_X(x)$ and $f_Y(y)$ Given

$$f_{XY}(x,y) = \begin{cases} k, & 0 < x < y < 1, \\ 0, & \text{otherwise} \end{cases}$$



Solution: It is given that the joint pdf $f_{XY}(x, y)$ is a constant in the shaded region in the figure. Note that the integral of joint pdf is 1:

$$\int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} f_{XY}(x, y) dx dy = \int_{y=0}^{1} \left(\int_{x=0}^{y} k \cdot dx \right) dy =$$

$$\int_{y=0}^{1} ky dy = \frac{ky^2}{2} \Big|_{0}^{1} = \frac{k}{2} = 1$$

• Thus k = 2. Then

$$f_X(x) = \int_{-\infty}^{+\infty} f_{XY}(x, y) dy = \int_{y=x}^{1} 2dy = 2(1-x), \qquad 0 < x < 1,$$

$$f_Y(y) = \int_{-\infty}^{+\infty} f_{XY}(x, y) dx = \int_{x=0}^{y} 2dx = 2y, \qquad 0 < y < 1$$

Two Random Variables – Independence of r.vs

- Definition: The random variables X and Y are said to be statistically independent if the events $\{X(\xi) \in A\}$ and $\{Y(\xi) \in B\}$ are independent events for any two sets A and B in X and Y axes respectively.
- If the r.vs X and Y are independent, then $P((X(\xi) \le x) \cap (Y(\xi) \le y)) = P(X(\xi) \le x)P(Y(\xi) \le y)$ Which is $F_{XY}(x,y) = F_X(x)F_Y(y)$ or equivalently $f_{XY}(x,y) = f_X(x)f_Y(y)$.
- If X and Y are discrete-type r.vs then their independence implies

$$P(X = x_i, Y = y_i) = P(X = x_i)P(Y = y_i)$$
 for all *i*, *j*

Two Random Variables – Independence of r.vs

• Example 5: Given $f_{XY}(x,y) = \begin{cases} xy^2e^{-y}, & 0 < y < \infty, \ 0 < x < 1, \\ 0, & \text{otherwise.} \end{cases}$

Determine whether X and Y are independent.

Two Random Variables – Independence of r.vs

• Example 5: Given

$$f_{XY}(x,y) = \begin{cases} xy^2e^{-y}, & 0 < y < \infty, \ 0 < x < 1, \\ 0, & \text{otherwise.} \end{cases}$$

Determine whether *X* and *Y* are independent.

Solution:
$$f_X(x) = \int_0^{+\infty} f_{XY}(x, y) dy = x \int_0^{\infty} y^2 e^{-y} dy$$

= $x \left(-2ye^{-y} \Big|_0^{\infty} + 2 \int_0^{\infty} ye^{-y} dy \right) = 2x, 0 < x < 1$

Similarly
$$f_Y(y) = \int_0^1 f_{XY}(x, y) dx = \frac{y^2}{2} e^{-y}, \qquad 0 < y < \infty$$

In this case: $f_{XY}(x, y) = f_X(x)f_Y(y)$,

and hence X and Y are independent random variables.

• Assume that there are two r.vs (X_1, X_2) and (Y_1, Y_2) that

$$Y_1 = g_1(X_1, X_2)$$

 $Y_2 = g_2(X_1, X_2)$

• Then we have $f_{Y_1Y_2}(y_1, y_2) = f_{X_1X_2}(x_1, x_2)|J|$

$$J = \frac{\partial(x_1, x_2)}{\partial(y_1, y_2)} = \begin{vmatrix} \frac{\partial x_1}{\partial y_1} & \frac{\partial x_1}{\partial y_2} \\ \frac{\partial x_2}{\partial y_1} & \frac{\partial x_2}{\partial y_2} \end{vmatrix}$$

Jacobian determinant (雅可比行列式)

• Quick Example 6: Given two r.vs (X_1,X_2) , calculate the pdf of their summation Y_1 under $Y_1=X_1+X_2$ and $Y_2=X_1-X_2$

Note that we have: $x_1 = (y_1 + y_2)/2$ $x_2 = (y_1 - y_2)/2$

• Quick Example 6: Given two r.vs (X_1, X_2) , calculate the pdf of their summation Y_1 under $Y_1 = X_1 + X_2$ and $Y_2 = X_1 - X_2$

Note that we have: $x_1 = (y_1 + y_2)/2$ $x_2 = (y_1 - y_2)/2$

Solution: Cal. The
$$J$$

$$J = \frac{\partial(x_1, x_2)}{\partial(y_1, y_2)} = \begin{vmatrix} \frac{\partial x_1}{\partial y_1} & \frac{\partial x_1}{\partial y_2} \\ \frac{\partial x_2}{\partial y_1} & \frac{\partial x_2}{\partial y_2} \end{vmatrix} = \begin{vmatrix} 1/2 & 1/2 \\ 1/2 & -1/2 \end{vmatrix} = -\frac{1}{2}$$

$$f_{Y_1Y_2}(y_1, y_2) = f_{X_1X_2}(x_1, x_2)|J|$$

$$= \frac{1}{2} f_{X_1X_2}((y_1 + y_2)/2, (y_1 - y_2)/2)$$

$$f_{Y_1}(y_1) = \int_{-\infty}^{+\infty} f_{Y_1Y_2}(y_1, y_2) dy_2$$

$$= \frac{1}{2} \int_{-\infty}^{+\infty} f_{X_1X_2}(\frac{1}{2}(y_1 + y_2), \frac{1}{2}(y_1 - y_2)) dy_2$$

$$f_{Y_1Y_2}(y_1, y_2) = f_{X_1X_2}(x_1, x_2)|J|$$

$$= \frac{1}{2} f_{X_1X_2}((y_1 + y_2)/2, (y_1 - y_2)/2)$$

$$f_{Y_1}(y_1) = \int_{-\infty}^{+\infty} f_{Y_1Y_2}(y_1, y_2) dy_2$$

$$= \frac{1}{2} \int_{-\infty}^{+\infty} f_{X_1X_2}(\frac{1}{2}(y_1 + y_2), \frac{1}{2}(y_1 - y_2)) dy_2$$

Let
$$u = (y_1 + y_2)/2$$
 \longrightarrow $f_{Y_1}(y_1) = \int_{-\infty}^{+\infty} f_{X_1 X_2}(u, y_1 - u) du$

When (X_1, X_2) independent:

$$f_{Y_1}(y_1) = \int_{-\infty}^{+\infty} f_{X_1}(u) f_{X_2}(y_1 - u) du = f_{X_1}(y) \otimes f_{X_2}(y_1)$$

which is, the pdf of two independent r.vs' summation is the convolution of the pdfs of the two r.vs

• Given two r.vs X and Y and a function g(x,y), define the r.v

$$Z = g(X,Y)$$

we can define the mean of Z to be

$$\mu_Z = E(Z) = \int_{-\infty}^{+\infty} z \, f_Z(z) dz.$$

• It is possible to express the mean of Z = g(X, Y) in terms of $f_{XY}(x, y)$ without computing $f_Z(z)$.

$$E(Z) = E[g(X,Y)] = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} g(x,y) f_{XY}(x,y) dx dy.$$

If X and Y are discrete-type r.vs, then

$$E[g(X,Y)] = \sum_{i} \sum_{j} g(x_{i}, y_{j}) P(X = x_{i}, Y = y_{j}).$$

• If X and Y are independent r.vs, it is easy to see that Z = g(X) and W = h(Y) are always independent of each other. In that case, we get:

$$E[g(X)h(Y)] = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} g(x)h(y)f_X(x)f_Y(y)dxdy$$

$$= \int_{-\infty}^{+\infty} g(x) f_X(x) dx \int_{-\infty}^{+\infty} h(y) f_Y(y) dy = E[g(X)] E[h(Y)]$$
 (3-1)

- However it is in general not true (X and Y not always independent).
- In the case of one random variable, we defined the parameters mean and variance to represent its average behavior.
- How does one parametrically represent similar crossbehavior between two random variables? Towards this, we can generalize the variance definition to **Covariance**.

• Covariance: Given any two r.vs X and Y, define $Cov(X,Y) = E[(X - \mu_X)(Y - \mu_Y)]$.

Expanding and simplifying the right hand side of the above equation we get

$$Cov(X,Y) = E(XY) - \mu_X \mu_Y = E(XY) - E(X)E(Y) = \overline{XY} - \overline{XY}.$$
 (3-2)

Properties:

- cov(X, X) = E(XX) E(X)E(X) = D(X)
- cov(aX, bY) = abcov(X, Y)
- $|Cov(X,Y)| \le \sqrt{Var(X)Var(Y)}$.

•
$$co v(X, Y \pm Z) = E(XY \pm XZ) - E(X)E(Y \pm Z)$$

= $\{E(XY) - E(X)E(Y)\} \pm \{E(XZ) - E(X)E(Z)\}$
= $cov(X, Y) \pm cov(X, Z)$

- The range of **Covariance** is $(-\infty, +\infty)$, thus is hard to tell whether the value is large or small. Is a **Covariance** 10 highly correlated? Is a **Covariance** 0.1 weakly correlated? No one knows
- Therefore, we normalize it:

$$\rho_{XY} = \frac{Cov(X,Y)}{\sqrt{Var(X)Var(Y)}} = \frac{Cov(X,Y)}{\sigma_X \sigma_Y}, -1 \le \rho_{XY} \le 1$$

it represents the correlation coefficient between X and Y.

And we have: $Cov(X,Y) = \rho_{XY}\sigma_X\sigma_Y$

• Uncorrelated r.vs: If $\rho_{XY}=0$, then X and Y are said to be uncorrelated r.vs. note that in this case, $Cov(X,Y)=\rho_{XY}\sigma_X\sigma_Y=0$

Therefore, according to (3-2), if X and Y are uncorrelated, then E(XY) = E(X)E(Y).

• Orthogonality: X and Y are said to be orthogonal if E(XY) = 0.

Note that, if either X or Y has zero mean, then orthogonality implies uncorrelatedness also and vice-versa.

Expanding and simplifying the right hand side of the above equation we get

$$Cov(X,Y) = E(XY) - \mu_X \mu_Y = E(XY) - E(X)E(Y) = \overline{XY} - \overline{XY}. \quad (3-2)$$

• Suppose X and Y are independent r.vs. Then from (3-1) with g(X) = X, h(Y) = Y, we get

$$E[g(X)h(Y)] = E[g(X)]E[h(Y)]$$
 which is $E(XY) = E(X)E(Y)$

we conclude that if two r.vs **independence**, they are **uncorrelated**.

Note that, uncorrelated does not means independence.

• Uncorrelated r.vs: If $\rho_{XY} = 0$, then X and Y are said to be uncorrelated r.vs. note that in this case, $Cov(X,Y) = \rho_{XY}\sigma_X\sigma_Y = 0$

Therefore, according to (3-2), if X and Y are uncorrelated, then E(XY) = E(X)E(Y).

$$E[g(X)h(Y)] = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} g(x)h(y)f_X(x)f_Y(y)dxdy$$

=
$$\int_{-\infty}^{+\infty} g(x)f_X(x)dx \int_{-\infty}^{+\infty} h(y)f_Y(y)dy = E[g(X)]E[h(Y)]$$

uncorrelated

independence

- Example 7: Calculate the correlation coefficient between Y and X
 - 1. Y = aX + b

2.
$$Y = -aX + b$$

$$cov(X,Y) = E(XY) - E(X)E(Y)$$

3.
$$Y = X^2$$
, $X \in [-1,1]$ uniform distributed For $a > 0$

- Example 7: Calculate the correlation coefficient between Y and X
 - $1. \quad Y = aX + b$
 - 2. Y = -aX + b
 - 3. $Y = X^2$, $X \in [-1,1]$ uniform distributed

For a > 0

Solutions:

$$D(Y) = D(aX + b) = a^2 D(X)$$

- 1. $cov(X,Y) = E(X(aX+b)) E(X)E(aX+b) = aE(X^2) a(E(X))^2 = aD(X)$ $\rho(X,Y) = \frac{aD(X)}{\sqrt{D(Y)D(X)}} = 1$
- 2. Similarly as 1, get the result -1
- 3. $\operatorname{cov}(X,Y) = E(X^3) E(X)E(X^2) = E(X^3) = \int_{-1}^{1} x^3 \frac{1}{2} dx = 0$

The (linear) correlation coefficient is 0, i.e. no linear relationship between X and Y, they are uncorrelated, but clearly, X and Y are not independent to each other

cov(X,Y) = E(XY) - E(X)E(Y)

Multidimensional Random Variables – the covariance matrix

• For multidimensional random variables $X_1, X_2, ..., X_n$, the covariance matrix is usually used to describe the relationship between random variables:

$$K = \begin{bmatrix} K_{11} & \cdots & K_{1n} \\ \vdots & \ddots & \vdots \\ k_{n1} & \cdots & k_{nn} \end{bmatrix}$$
Where $k_{ij} = \text{cov}(X_i, X_j) = E\{[X_i - E(X_i)][X_j]\}$

See the review example 2 for pratice

 $-E(X_i)$

• Define two r.vs X_1 and X_2 , if their joint pdf is: $f_{X_1X_2}(x_1,x_2)$

$$=\frac{1}{2\pi\sigma_{X_1}\sigma_{X_2}\sqrt{1-\rho^2}}\exp\{-\frac{1}{2(1-\rho^2)}\left[\frac{(x_1-m_{X_1})^2}{\sigma_{X_1}^2}-\frac{2\rho(x_1-m_{X_1})(x_2-m_{X_2})}{\sigma_{X_1}\sigma_{X_2}}+\frac{(x_2-m_{X_2})^2}{\sigma_{X_2}^2}\}\right]$$

相关系数

They follows the joint Gaussian/Normal distribution, and their marginal pdf also follow Gaussian/Normal distribution

$$f_{X_1}(x_1) = \frac{1}{\sqrt{2\pi}\sigma_{X_1}} \exp\left[-\frac{(x_1 - m_{X_1})^2}{2\sigma_{X_1}^2}\right]; f_{X_2}(x_2) = \frac{1}{\sqrt{2\pi}\sigma_{X_2}} \exp\left[-\frac{(x_2 - m_{X_2})^2}{2\sigma_{X_2}^2}\right]$$

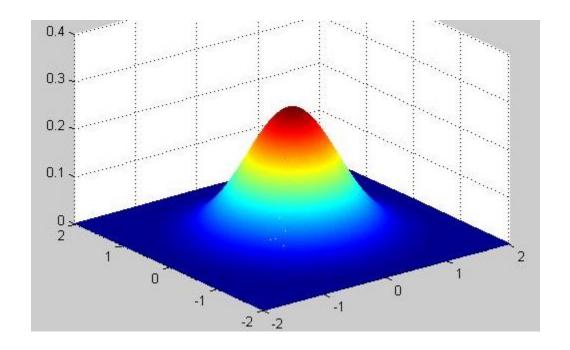
If $\rho = 0$ (uncorrelated), then $f_{X_1X_2}(x_1, x_2) = f_{X_1}(x_1)f_{X_2}(x_2)$, which is independent.

For two dimensional Gaussian r.vs, uncorrelated = independent

• Define two r.vs X_1 and X_2 , if their joint pdf is:

$$=\frac{1}{2\pi\sigma_{X_{1}}\sigma_{X_{2}}\sqrt{1-\rho^{2}}}\exp\{-\frac{1}{2(1-\rho^{2})}\left[\frac{f_{X_{1}X_{2}}(x_{1},x_{2})}{\sigma_{X_{1}}^{2}}-\frac{2\rho(x_{1}-m_{X_{1}})(x_{2}-m_{X_{2}})}{\sigma_{X_{1}}\sigma_{X_{2}}}+\frac{(x_{2}-m_{X_{2}})^{2}}{\sigma_{X_{2}}^{2}}\}$$

When $\rho = 0$



• Define two r.vs X_1 and X_2 , if their joint pdf is:

$$f_{X_1X_2}(x_1, x_2) = \frac{1}{2\pi\sigma_{X_1}\sigma_{X_2}\sqrt{1 - \rho^2}} \exp\{-\frac{1}{2(1 - \rho^2)} \left[\frac{(x_1 - m_{X_1})^2}{\sigma_{X_1}^2} - \frac{2\rho(x_1 - m_{X_1})(x_2 - m_{X_2})}{\sigma_{X_1}\sigma_{X_2}} + \frac{(x_2 - m_{X_2})^2}{\sigma_{X_2}^2}\right]$$

Write the joint pdf in matrix form:

$$f_{X}(x) = \frac{1}{2\pi |\mathbf{K}|^{1/2}} \exp\left[-\frac{1}{2}(x-\mathbf{m})^{\mathrm{T}}\mathbf{K}^{-1}(x-\mathbf{m})\right]$$

Where
$$\mathbf{x} = [\mathbf{x}_1, \mathbf{x}_2]^{\mathrm{T}} \, \mathbf{m} = [m_{x_1}, m_{x_2}]^T$$

$$\mathbf{K} = \begin{bmatrix} \mathbf{E}[(\mathbf{X}_1 - \mathbf{m}_{\mathbf{X}_1})^2] & \mathbf{E}[(\mathbf{X}_1 - \mathbf{m}_{\mathbf{X}_1})(\mathbf{X}_2 - \mathbf{m}_{\mathbf{X}_2})] \\ \mathbf{E}[(\mathbf{X}_2 - \mathbf{m}_{\mathbf{X}_2})(\mathbf{X}_1 - \mathbf{m}_{\mathbf{X}_1})] & \mathbf{E}[(\mathbf{X}_2 - \mathbf{m}_{\mathbf{X}_2})^2] \end{bmatrix}$$

$$= \begin{bmatrix} \sigma_{\mathbf{X}_1}^2 & r\sigma_{\mathbf{X}_1}\sigma_{\mathbf{X}_2} \\ r'\sigma_{\mathbf{X}_1}\sigma_{\mathbf{X}_2} & \sigma_{\mathbf{X}_2}^2 \end{bmatrix}$$

• Define two r.vs
$$X_1$$
 and X_2 , their joint pdf is:
$$f_{\mathbf{X}}(\mathbf{x}) = \frac{1}{2\pi |\mathbf{K}|^{1/2}} \exp\left[-\frac{1}{2}(\mathbf{x} - \mathbf{m})^{\mathrm{T}}\mathbf{K}^{-1}(\mathbf{x} - \mathbf{m})\right]$$

• Similarly, for multi-dimensional case (*): Inverse matrix
$$f_X(\mathbf{x}) = \frac{1}{(2\pi)^{\frac{n}{2}} |\mathbf{K}|^{\frac{1}{2}}} \exp\left[-\frac{1}{2}(\mathbf{x} - \mathbf{m})^T \mathbf{K}^{-1}(\mathbf{x} - \mathbf{m})\right]$$

Determinant

The covariance matrix

$$m{x} = egin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}, m{m} = egin{bmatrix} m_1 \\ m_2 \\ \vdots \\ m_n \end{bmatrix}, m{K} = egin{bmatrix} K_{11} & K_{12} & \cdots & K_{1n} \\ K_{21} & K_{22} & & K_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ K_{n1} & K_{n2} & \cdots & K_{nn} \end{bmatrix}$$

- As we have seen in the previous lecture conditional probability density functions are useful to update the information about an event based on the knowledge about some other related event (refer to example 7, lesson 2).
- In this section, we shall analyze the situation where the related event happens to be a random variable that is dependent on the one of interest.
- Recall that the distribution function of X given an event B is

$$F_X(x|B) = P(X(\xi) \le x|B) = \frac{P((X(\xi) \le x) \cap B)}{P(B)}$$

• Here we use a r.v
$$Y=y$$
 to represent the event B and get
$$F_{X|Y}(x|Y=y)=\frac{\int_{-\infty}^x f_{XY}(u,y)du}{f_Y(y)}.$$

The pdf is

$$f_{X|Y}(x|y) = \frac{f_{XY}(x,y)}{f_{Y}(y)}.$$

For discrete-type r.vs, the pmf is

For discrete-type r.vs, the pmf is
$$f_{X|Y}(x|y) = \frac{f_{XY}(x,y)}{f_{Y}(y)}.$$

$$P(X = x_i|Y = y_j) = \frac{P(X = x_i, Y = y_j)}{P(Y = y_j)}$$

Conditional CDF and pdf

$$F_{X|Y}(x|Y=y) = \frac{\int_{-\infty}^{x} f_{XY}(u,y)du}{f_{Y}(y)}; \quad f_{X|Y}(x|Y=y) = \frac{f_{XY}(x,y)}{f_{Y}(y)}$$
• Similarly
$$f_{Y|X}(y|x) = \frac{f_{XY}(x,y)}{f_{X}(x)} \tag{3-3}$$

• If the r.vs X and Y are independent, then $f_{XY}(x,y) = f_X(x)f_Y(y)$ and it becomes

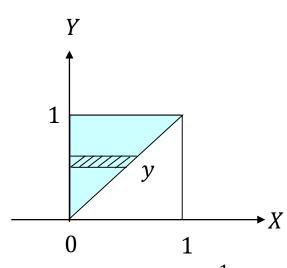
$$f_{X|Y}(x|y) = f_X(x),$$
 $f_{Y|X}(y|x) = f_Y(y),$

implying that the conditional pdfs coincide with their unconditional pdfs. This makes sense, since if X and Y are independent r.vs, information about Y shouldn't be of any help in updating our knowledge about X.

• Example 4.2 (see example 4 for review): Given

$$f_{XY}(x,y) = \begin{cases} k, & 0 < x < y < 1, \\ 0, & \text{otherwise} \end{cases}$$

determine $f_{X|Y}(x|y)$ and $f_{Y|X}(y|x)$.



Solution: Note that the integral of joint pdf is 1:

$$\int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} f_{XY}(x, y) dx dy = \int_{y=0}^{1} \left(\int_{x=0}^{y} k \cdot dx \right) dy = \int_{y=0}^{1} ky dy = \frac{ky^2}{2} \Big|_{0}^{1} = \frac{k}{2}$$
= 1.

Then

$$f_X(x) = \int_{-\infty}^{+\infty} f_{XY}(x, y) dy = \int_{y=x}^{1} 2dy = 2(1-x), \qquad 0 < x < 1,$$

$$f_Y(y) = \int_{-\infty}^{+\infty} f_{XY}(x, y) dx = \int_{x=0}^{y} 2dx = 2y, \qquad 0 < y < 1$$

Now calculate $f_{X|Y}(x|y)$ and $f_{Y|X}(y|x)$ yourself

Therefore
$$f_{X|Y}(x|y) = \frac{f_{XY}(x,y)}{f_{Y}(y)} = \frac{1}{y}$$
, $0 < x < y < 1$

$$f_{Y|X}(y|x) = \frac{f_{XY}(x,y)}{f_X(x)} = \frac{1}{1-x},$$
 $0 < x < y < 1$

Conditional CDF and pdf

$$F_{X|Y}(x|Y=y) = \frac{\int_{-\infty}^{x} f_{XY}(u,y)du}{f_{Y}(y)}; \quad f_{X|Y}(x|Y=y) = \frac{f_{XY}(x,y)}{f_{Y}(y)}$$
• Similarly
$$f_{Y|X}(y|x) = \frac{f_{XY}(x,y)}{f_{X}(x)}$$
 (3-3)

We can use (3-3) to derive an important result as:

$$f_{XY}(x,y) = f_{X|Y}(x|y)f_Y(y) = f_{Y|X}(y|x)f_X(x)$$

Or

$$f_{Y|X}(y|x) = \frac{f_{X|Y}(x|y)f_Y(y)}{f_X(x)}.$$

But

$$f_X(x) = \int_{-\infty}^{+\infty} f_{XY}(x, y) dy = \int_{-\infty}^{+\infty} f_{X|Y}(x|y) f_Y(y) dy$$

Therefore we get

$$f_{Y|X}(y|x) = \frac{f_{X|Y}(x|y)f_{Y}(y)}{\int_{-\infty}^{+\infty} f_{X|Y}(x|y)f_{Y}(y)dy}$$
(3-4)

This equation represents the pdf version of Bayes' theorem. Here we use an example to illustrate the significance of it.

• Example 8: An unknown random phase θ is uniformly distributed in the interval $(0,2\pi)$, and $r = \theta + n$ where $n \sim N(0, \sigma^2)$. Determine $f(\theta|r)$.

$$f_{Y|X}(y|x) = \frac{f_{X|Y}(x|y)f_Y(y)}{\int_{-\infty}^{+\infty} f_{X|Y}(x|y)f_Y(y)dy}$$
(3-4)

• Example 8: An unknown random phase θ is uniformly distributed in the interval $(0,2\pi)$, and $r=\theta+n$ where $n{\sim}N(0,\sigma^2)$. Determine $f(\theta|r)$.

Solution:

Initially almost nothing about the r.v θ is known, so that we assume its a-priori pdf to be uniform in the interval $(0,2\pi)$.

In the equation $r = \theta + n$, we can think of n as the noise contribution and r as the observation. It is reasonable to assume that θ and n are independent. In that case

$$f(r|\boldsymbol{\theta}=\theta) \sim N(\theta,\sigma^2)$$

since it is given that $\theta = \theta$ is a constant, $r = \theta + n$ behaves like n. Using (3-4) can gives the apposteriori pdf of θ given r

$$f_{Y|X}(y|x) = \frac{f_{X|Y}(x|y)f_{Y}(y)}{\int_{-\infty}^{+\infty} f_{X|Y}(x|y)f_{Y}(y)dy}$$

• Using (3-4) can gives the a-posteriori pdf of θ given r, note that $f_{\theta}(\theta)=1/2\pi$ and $f(r|\theta)=\frac{1}{\sqrt{2\pi}\sigma}e^{-\frac{(r-\theta)^2}{2\sigma^2}}$:

$$f(\theta|r) = \frac{f(r|\theta)f_{\theta}(\theta)}{\int_{0}^{2\pi} f(r|\theta)f_{\theta}(\theta)d\theta}$$

$$= \frac{\frac{1}{\sqrt{2\pi}\sigma}e^{-(r-\theta)^{2}/2\sigma^{2}}\frac{1}{2\pi}}{\int_{0}^{2\pi} \frac{1}{\sqrt{2\pi}\sigma}e^{-(r-\theta)^{2}/2\sigma^{2}}\frac{1}{2\pi}d\theta}$$

$$= \frac{e^{-(r-\theta)^{2}/2\sigma^{2}}\frac{1}{\sqrt{2\pi}\sigma}e^{-(r-\theta)^{2}/2\sigma^{2}}\frac{1}{2\pi}d\theta}{\int_{0}^{2\pi} e^{-(r-\theta)^{2}/2\sigma^{2}}d\theta} = \phi(r)e^{-(\theta-r)^{2}/2\sigma^{2}}, 0 < \theta < 2\pi,$$
Where $\phi(r) = \frac{1}{\int_{0}^{2\pi} e^{-(r-\theta)^{2}/2\sigma^{2}}d\theta}$

$$f(\theta|r) = \phi(r)e^{-(\theta-r)^2/2\sigma^2}, 0 < \theta < 2\pi,$$
 Where $\phi(r) = \frac{1}{\int_0^{2\pi} e^{-(r-\theta)^2/2\sigma^2}d\theta}$

• Notice that the knowledge about the observation r is reflected in the a-posteriori pdf of θ in Fig. 3.1 (b). It is no longer flat as the a-priori pdf in Fig. 3.1 (a), and it shows higher probabilities in the neighborhood of $\theta = r$.

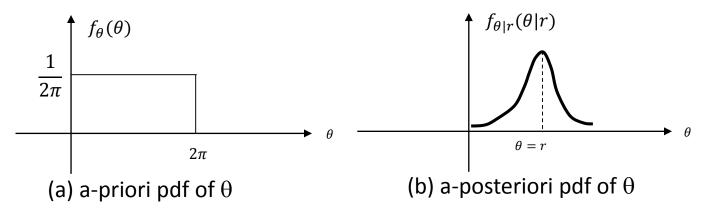
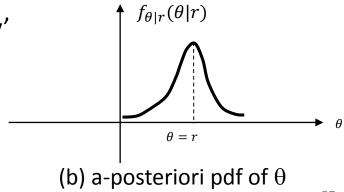


Fig. 3.1

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- A very straight forward application:
 - Suppose a r.v θ is uniformly distributed in the interval (50,80), and $r = \theta + n$, where n is noise. Note that r is also a r.v
 - We observe the r.v r 10 times, and get the result: {40,68,72,95,38,85,67,99,63,51}
 - What is a good estimation of θ ?
- Based on the a-posteriori pdf of θ , we can see that
 - The observed pdf should be Gaussian
 - Gaussian Distribution has a mean $\theta = r$
 - Therefore, the mean of $\{40,68,72,95,38,85,67,99,63,51\}$ is a good estimation of θ !
 - This is the basic of 'estimation theory'



Conditional mean

 We can use the conditional pdfs to define the conditional mean:

$$\mu_{X|Y} = E(X|Y = y) = \int_{-\infty}^{+\infty} x f_{X|Y}(x|y) dx$$

to be the conditional mean of X given Y = y. Notice that E(X|Y = y) will be a function of y. Also

$$\mu_{Y|X} = E(Y|X = x) = \int_{-\infty}^{+\infty} y f_{Y|X}(y|x) dy.$$

• similarly, the conditional variance of X given Y = y is given by

$$Var(X|Y) = \sigma_{X|Y}^2 = E(X^2|Y = y) - (E(X|Y = y))^2$$
$$= E((X - \mu_{X|Y})^2|Y = y).$$

Lesson 3 – reading

- This week: Text book, Chapters 3-4
- Next week: Text book, pages 207-228 of Chapters 5

Lesson 3 – review examples for next week

1. Assume that X is a r.v follows exponential distribution with parameter $\lambda > 1$, find the expectation of $Y = e^X$

Note that for exponential distribution:

- Mean: $E(X) = \int_0^\infty x \lambda e^{-\lambda x} dx = 1/\lambda$
- Variance:D(X) = $1/\lambda^2$
- pdf: $f(x) = \begin{cases} \lambda e^{-\lambda x}, & x \ge 0 \\ 0, & x < 0 \end{cases}$
- 2. Given Y = 0.5X + 1, Z = -0.5X + 1 and D(X) = 1, calculate the covariance matrix of the vector (X, Y, Z)

Note:
$$cov(X, Y) = E[(X - \overline{X})(Y - \overline{Y})] = E(XY) - E(X)E(Y)$$