

## **Shadow**

Teacher: A. Prof Chengying Gao(高成英)

E-mail: mcsgcy@mail.sysu.edu.cn

**School of Data and Computer Science** 

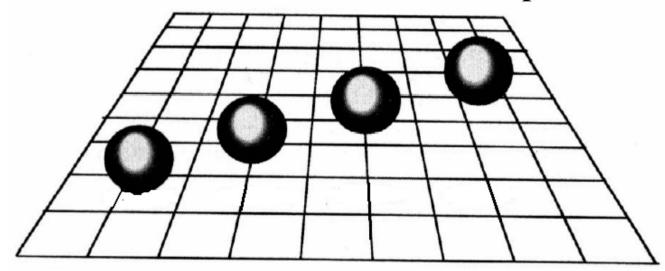


Most of slides are from Graphics & Geometry Computing Group of Tsinghua University

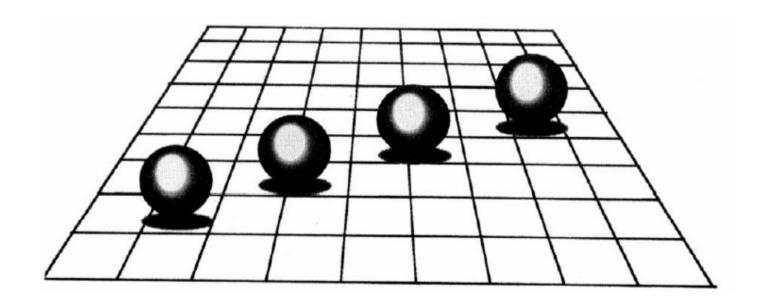
• Shadow generation is a fundamental problem in Computer Graphics.

- Why shadow is so important?
  - Lets see an example.

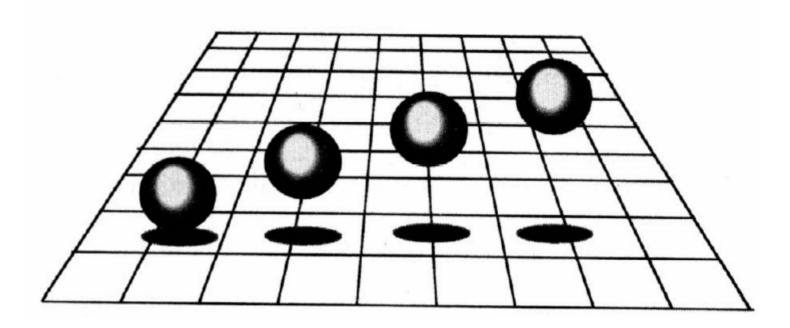
- Do you know where are the balls located?(Without shadows)
- It is hard to determine the actual position



We know where the balls located are (With shadows)



Different shadows implies different balls location



## More Examples

without shadow



► Status

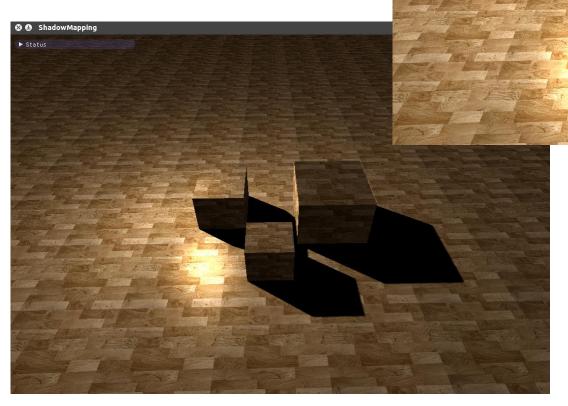


Scene B



## More Examples

withshadow



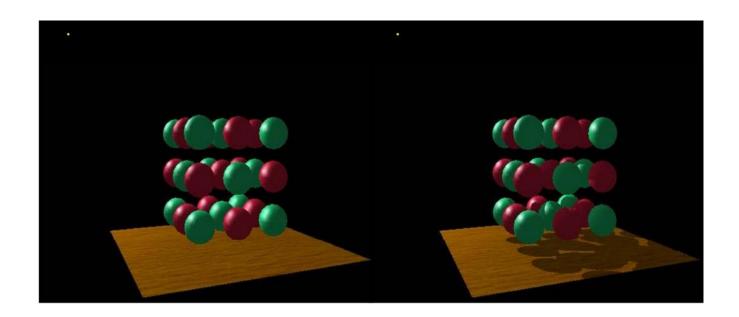
► Status



Scene B



- From these examples, we could conclude that:
  - Shadows give an important visual cue of object position.
  - Same images with different shadows implies different object positions.
- So, shadow is important.

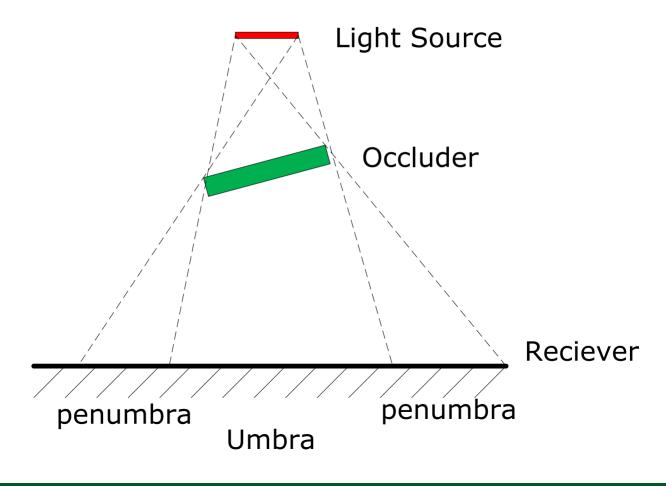


#### What is shadow?

#### Definition and Terminations

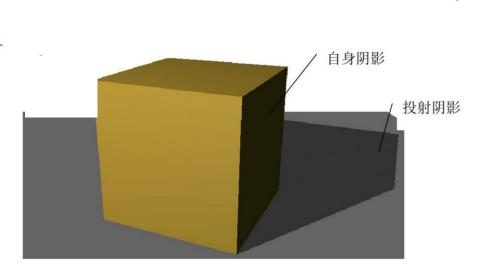
- Consider a light source L illuminating a scene:
- Receivers are objects of the scene that are potentially illuminated by L.
- A point P of the scene is considered to be in the umbra(本影) if it can not see any part of light source L.
- If P can see a part of the light source , it is in the penumbra(半影).
- Shadow is the union of the umbra and penumbra, is the region of space for which at least one point of the light source is occluded.
- Objects that hide a point from the light source are called occluders(遮挡物).

### What is shadow?



## Types of Shadows

- Cast shadows: occurring when a shadow falls on an object whose normal is facing toward the light source (投射阴影).
- Attached shadows: occurring when the normal of the receiver is facing away from the light source (自身阴影或附着阴影);
- Self-shadows: are a specific case of cast shadows that occur when the shadow of an object is projected onto itself, i.e. the occlude and the receiver are the same (自阴影).



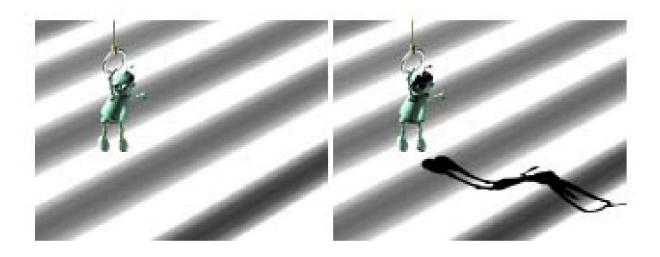
自阴影



### Importance of Shadow

- Shadows help to understand relative object position and size in a scene.
- Shadows can also help us understanding the geometry of a complex receiver.
- Shadows provide useful visual cues that help in understanding the geometry of a complex occluder.

# Importance of Shadow



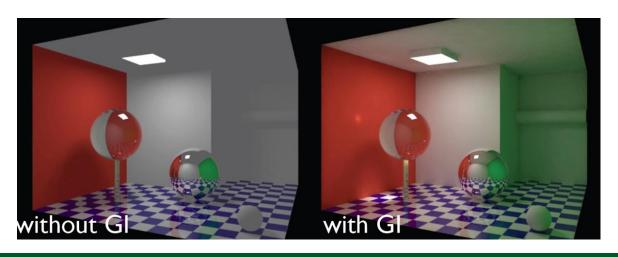
Shadow helps to determine the geometry of receiver

## • Importance of Shadow

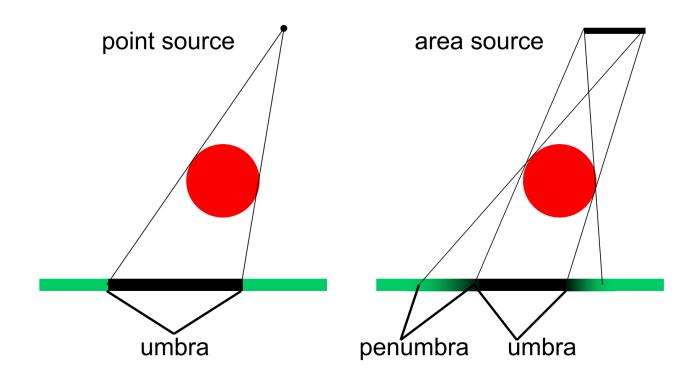


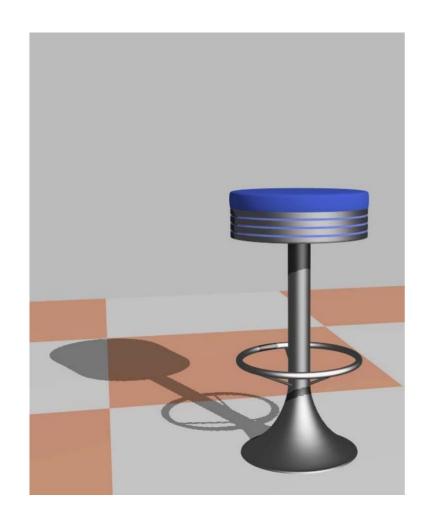
Shadow helps to determine the geometry of occluder

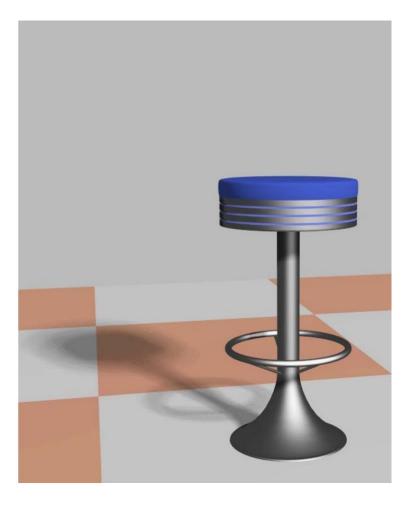
- The common-sense notion of shadow is a binary status, i.e. a point is either "in shadow" or not. This corresponds to hard shadows, as produced by point light sources.
- However, point light sources do not exist in practice and hard shadows give a rather unrealistic feeling to images. Note that even the sun, the most common light source in our daily life, has a significant angular extent and does not create hard shadows.



- Point light sources are easy to model in computer graphics and we shall see that several algorithms let us compute hard shadows in real time.
- For a light source with finite extent (actually an area source), the determination of the umbra and penumbra is a difficult task in general, as it amounts to solving visibility relationships in 3D, a notoriously hard problem.

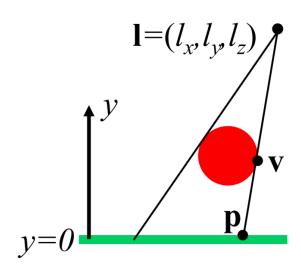






- What is planar shadow?
  - A simple case of shadow when objects cast shadows on planar surface.

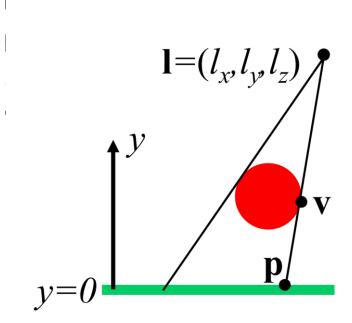
- Projection Shadow
  - In this case, the three-dimensional objects is rendered second times. A matrix could be derived that projects the vertices of an object onto a plane. Consider the situation in the figure, where the light source is located at l, the vertex to be projected is at v, and the projected vertex is at p.
  - Further suppose the receiver plane is y=0 (this could also be generalized to work with any planes)



- Projection Shadow
  - By deriving the projection of x-coordinated. From similar triangles, the following equation could be obtained

$$\frac{p_x - l_x}{v_x - l_x} = \frac{l_y}{l_y - v_y}$$

$$= > p_x = \frac{l_y v_x - l_x v_y}{l_y - v_y}$$



- Projection Shadow
  - The z-coordinate could be obtained in the same way.

$$p_z = \frac{l_y v_z - l_z v_y}{l_y - v_y}$$

 These equations can be converted into a projection matrix M.

- Projection Shadow
  - Projection Matrix

$$\mathbf{M} = \begin{pmatrix} l_y & -l_x & 0 & 0\\ 0 & 0 & 0 & 0\\ 0 & -l_z & l_y & 0\\ 0 & -1 & 0 & l_y \end{pmatrix}$$

It is easy to verity that: Mv = P.

- Projection Shadow
  - In the general case, the plane onto which the shadows should be cast is not the plane y = 0. But instead a plane n\*x + d = 0.
  - Similar to the y = 0 plane case, the projected point p could be described as:

$$p = l - \frac{d + n \cdot l}{n \cdot (v - l)} (v - l)$$

- Projection Shadow
  - The equation can also be converted into a projection matrix, which satisfy Mv = p.

$$\mathbf{M} = \begin{pmatrix} \mathbf{n} \cdot \mathbf{l} + d - l_X n_X & -l_X n_y & -l_X n_z & -l_X d \\ -l_y n_X & \mathbf{n} \cdot \mathbf{l} + d - l_y n_y & -l_y n_z & -l_y d \\ -l_z n_X & -l_z n_y & \mathbf{n} \cdot \mathbf{l} + d - l_z n_z & -l_z d \\ -n_X & -n_y & -n_z & \mathbf{n} \cdot \mathbf{l} \end{pmatrix}$$

• As expected, this matrix turns into the matrix in previous page if the plane is y = 0 (n = (0,1,0) and d = 0)

- Projection Shadow
  - To render the shadow, simply apply this matrix to the objects that should cast shadows on the plane. And render this projected object with a dark color and no illumination (只绘制环境光,不绘制漫反射和镜面反射).
  - Limitation of the projection shadow method:
    - The receiver must be planar
    - The shadow has to be rendered for each frame, even though the shadow may not change.

#### Failure cases

false shadow
 If the light source is below the topmost point on the object, the algorithm will produce false shadow (right figure)



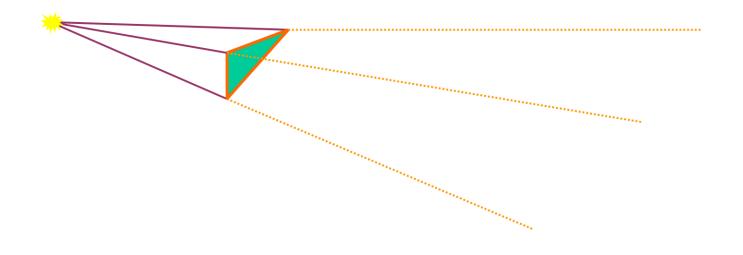
### **Shadow Generation Methods**

- Shadow Volume
- Shadow Mapping

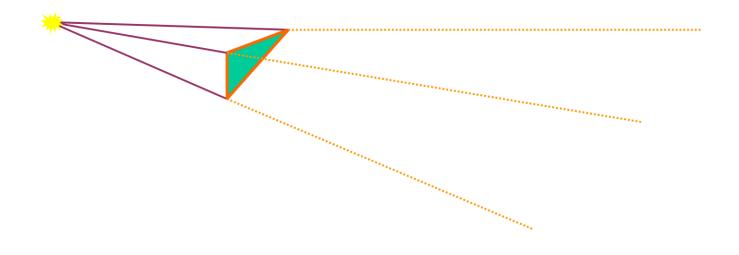
- A method proposed by Crow, which can cast shadows onto arbitrary objects.
- This technique is also sometimes called volumetric shadows.



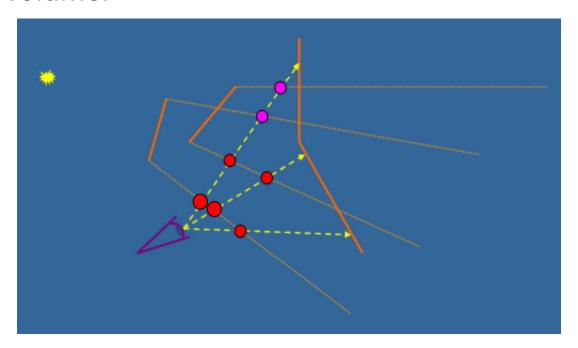
To begin, imagine a point and a triangle.
 Extending the lines from the point through the vertices of the triangle to infinity yields an infinite pyramid.



 Now, imagine the point is actually a point light source. Then any part of an object which is inside the volume of the truncated pyramid(under the triangle) is in shadow. This volume is called shadow volume.



- Suppose we cast a ray through a pixel until the ray hits an object in the scene. Now we need to determine whether or not the pixel is in shadow.
- What we need to do is to determine whether the point is in a shadow volume.



- While the ray is on its way to the object, we increment a counter each time when it crosses a face of the adow volume that is front-facing, thus the counter is incremented each time the ray goes into shadow.
- In the same manner, we decrement the same counter each time the ray crosses a back-facing face.
- Thus, finally, if the counter is greater than zero, then that pixel is in shadow; otherwise it is not.

- Using Stencil Buffer
  - Certainly, doing this geometrically is tedious and time-consuming. But there is a much smarter solution: using hardware's stencil buffer do the counting
  - A stencil buffer is a buffer which stores integer numbers in each pixel while Z-buffer stores depth value in real number.

- Using Stencil Buffer
  - First, clear the stencil buffer
  - Second, the whole scene is drawn into the frame buffer with only ambient component, in order to get these lighting components in the color buffer and the depth information into z-buffer.
  - **Third,** z-buffer updates and writing to the color buffer are turned off, and then the front faces of shadow volumes are drawn.
    - In this process, a stencil operation is set to increase the values in the stencil buffer whereever a poly gon is drawn(+1 each time).
  - **Fourth,** another pass is done by drawing the back-facing polygons. For this pass, the stencil operation is set to decrements(-1 each time)
  - **Finally,** the whole scene is rendered again, with diffuse and specular components, where the value in the stencil buffer is 0.

#### Advantages

- First, it can be used on general-purpose graphics hardware. The only requirement is a stencil buffer.
- Second, since it is not image based method(unlike the shadow map method described later), it does not have sampling problems, and thus produces correct sharp shadows everywhere.

#### Disadvantages

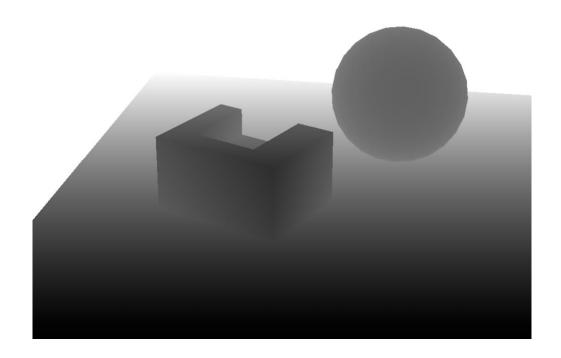
- The performance problem.
- This algorithm burns frame rate, as the number of shadow volume polygons is often large, and shadow volume polygons often cover many pixels, and so the rasterizer becomes a bottleneck

## **Shadow Volume**



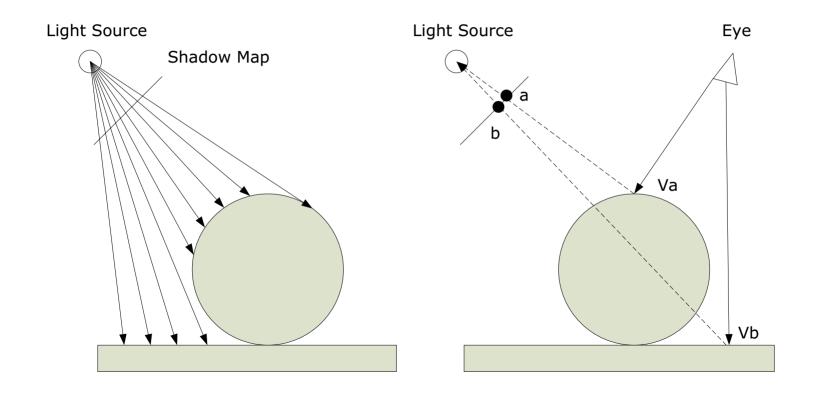
- In 1978, Williams proposed a common z-buffer based algorithm to generate shadows quickly on arbitrary objects.
- The idea is to render the scene, using the Z-buffer algorithm, from the position of the light source.

- By using **z-buffer**, the captured image from light's view records the distance to the object closest to the light.
- We call this entire content of the depth image "shadow map".

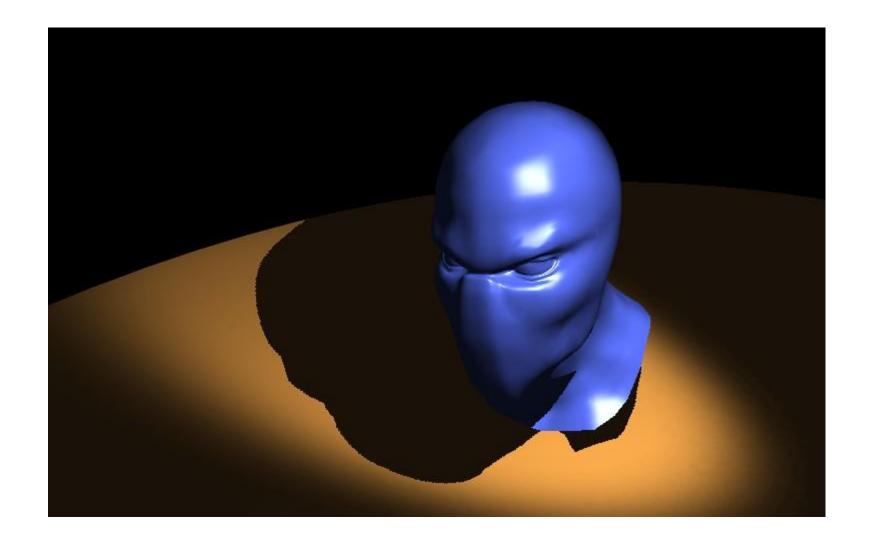


- To use the shadow map, the scene is rendered a second time, but this time from the viewer's view.
- Now, when each primitive is being rendered, its location is compared to the shadow map:
  - If a rendered point from the light source is farther away than the value in the shadow map, then that point is in shadow;
  - Otherwise it is not.

### Illustration



- For the Picture, a shadow map is formed by storing the depths to the surface; on the right, the eye is shown looking at two locations.
  - The sphere is hit at point Va, and this point is found to be located at texture position a on the shadow map. The depth stored in a is not less than point Va is from light, so the point is not in shadow;
  - For point *Vb* distance from point light is farther than stored in shadow map, so the point is in shadow.



#### Advantages

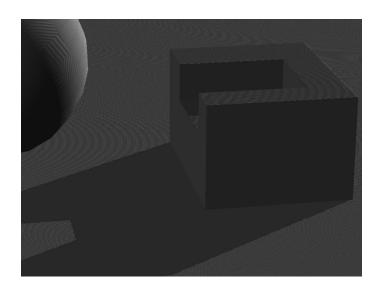
- Most hardwares directly support shadow map, and it can be used to render arbitrary geometry.
- It is fast. The cost of building the shadow map is linear to the number of rendered primitives and access time is constant.

#### Disadvantages

 Because shadow map is image-based, so the quality depends on the resolution of the shadow map, and the numerical precision of the Zbuffer.

#### Shadow map Problems

- If the epsilon value for comparison is low, it produces a pattern on object's surfaces ( see Fig a ) .
- If the epsilon value is set too high, we will see shadow "creeps" from under the block object(see Fig b).



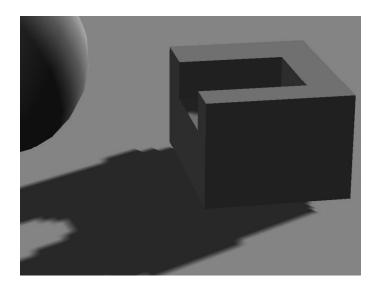
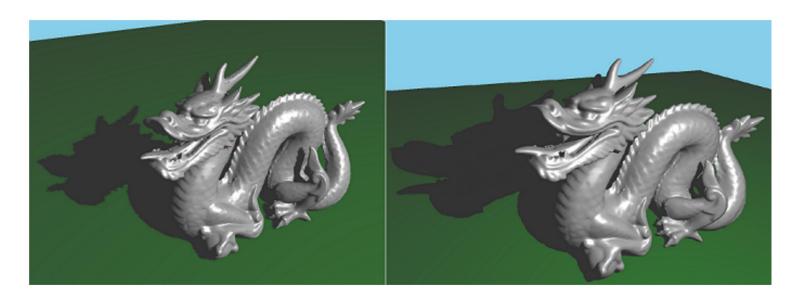


Fig a Fig b

# Shadow map & Shadow Volume



Shadow map

**Shadow Volume** 

#### Some conclusion

- Shadow map and shadow volume are the most widely used shadow genereation methods(especially, shadow map is used more).
- There are various extensions for these 2 techniques.
- For more information:
  - nVidia/ATI websites
  - http://www.realtimerendering.com
  - SIGGRAPH, SIGGRAPH Asia and Eurographics websites

#### Reference

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