

Advanced Union-Find

Algorithms: Design and Analysis, Part II

Lazy Unions

The Union-Find Data Structure

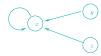
Raison d'être: Maintain a partition of a set X.



FIND: Given $x \in X$, return name of x's group. UNION: Given x & y, merge groups containing them.

Previous solution (for Kruskal's MST algorithm)

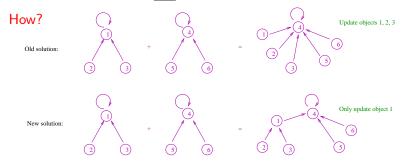
- Each $x \in X$ points directly to the "leader" of its group.



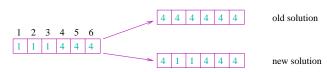
- O(1) FIND [just return x's leader]
- O(n log n) total work for n UNIONS [when 2 groups merge, smaller group inherits leader of larger one]

Lazy Unions

New idea: Update only one pointer each merge!



In array representation: (Where $A[i] \leftrightarrow$ name of i's parent)



How to Merge?

In general: When two groups merge in a UNION, make one group's leader (i.e., root of the tree) a child of the other one.

Pro: UNION reduces to 2 FINDS $[r_1 = FIND(x), r_2 = FIND(y)]$ and O(1) extra work [link r_1, r_2 together]

Con: To recover leader of an object, need to follow a <u>path</u> of parent pointers [not just one!]

 \Rightarrow Not clear if FIND still takes O(1) time.



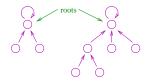
Advanced Union-Find

Algorithms: Design and Analysis, Part II

Union by Rank

The Lazy Union Implementation

New implementation: Each object $x \in X$ has a parent field.



Invariant: Parent pointers induce a collection of directed trees on X. (x is a root \iff parent[x]=x)

Initially: For all x, parent[x]=x



FIND(x): Traverse parent pointers from x until you hit the root.

UNION(x, y): $s_1 = FIND(x)$; $s_2 = FIND(y)$; Reset parent of one of s_1, s_2 to be the other.

Quiz on Lazy Unions

Question: Suppose, in the UNION operation, we choose the new root arbitrarily from the two old ones. What is the worst-case running time of the FIND and UNION operations, respectively?

- A) $\Theta(1), \Theta(1)$
- B) $\Theta(\log n), \Theta(1)$
- C) $\Theta(\log n), \Theta(\log n)$
- D) $\Theta(n), \Theta(n)$

Issue: Scraggly trees:

Union by Rank

Ranks: For each $x \in X$, maintain field rank[x].

[In general rank[x]=1+(max rank of x's children)]





Invariant (for now): For all $x \in X$, rank[x]=maximum number of hops from some leaf to x.

[Initially, rank[
$$x$$
]=0 for all $x \in X$]

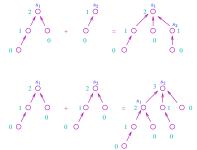
To avoid scraggly trees ("Union by Rank"): Given x & y:

- s_1 =FIND(x), s_2 =FIND(y)
- If $rank[s_1] > rank[s_2]$ then set $parent[s_2]$ to s_1 else set $parent[s_1]$ to s_2 .

To-do: Update ranks to restore Invariant.

Quiz on Rank Updates

Question: Recall s_1 =FIND(x), s_2 =FIND(y). How do the ranks of $s_1 \& s_2$ change after UNION(x, y)?



- A) Unchanged
- B) The one with larger rank goes up by 1
- C) The one with smaller rank goes up by 1
- D) No change unless ranks of s_1 , s_2 were equal, in which case s_2 's rank goes up by 1



Advanced Union-Find

Algorithms: Design and Analysis, Part II

Union by Rank -Analysis

Properties of Ranks

Recall: Lazy Unions.

Invariant (for now): $\operatorname{rank}[x] = \max \# \text{ of hops from a leaf to } x$. [Note $\max_x \operatorname{rank}[x] \approx \text{worst-case running time of FIND.}]$

Union by Rank: Make old root with smaller rank child of the root with the larger rank.

[Choose new root arbitrarily in case of a tie, and add 1 to its rank.]



Immediate from Invariant/Rank Maintenance:

- (1) For all objects x, rank[x] only goes up over time
- (2) Only ranks of roots can go up [once x a non-root, rank[x] frozen for evermore]
- (3) Ranks strictly increase along a path to the root

Rank Lemma

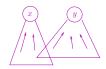
Rank Lemma: Consider an arbitrary sequence of UNION (+FIND) operations. For every $r \in \{0, 1, 2, ...\}$, there are at most $n/2^r$ objects with rank r.

Corollary: Max rank always $\leq \log_2 n$

Corollary: Worst-case running time of FIND, UNION is $O(\log n)$. [With Union by Rank.]

Proof of Rank Lemma

Claim 1: If x, y have the same rank r, then their subtrees (objects from which can reach x, y) are disjoint.



Claim 2: The subtree of a rank-r object has size $\geq 2^r$. [Note Claim 1 + Claim 2 imply the Rank Lemma.]

Proof of Claim 1: Will show contrapositive. Suppose subtrees of x, y have object z in common $\Rightarrow \exists$ path $z \rightarrow x, z \rightarrow y$ \Rightarrow One of x, y is an ancestor of the other \Rightarrow The ancestor has strictly larger rank. [By property (3)] QED (Claim 1)

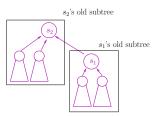
Proof of Claim 2

Rank $r \Rightarrow$ Subtree size $\geq 2^r$

Base case: Initially all ranks = 0, all subtree sizes = 1

Inductive step: Nothing to prove unless the rank of some object changes (subtree sizes only go up).

Interesting case: UNION(x, y), with s_1 =FIND(x), s_2 =FIND(y), and rank[s_1]=rank[s_2]= $r \Rightarrow s_2$'s new rank = r+1 $\Rightarrow s_2$'s new subtree size = s_2 's old subtree size + s_1 's old subtree size (each at least 2^r by the inductive hypothesis) $\geq 2^{r+1}$. QED!





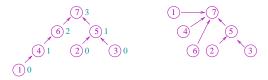
Advanced Union-Find

Algorithms: Design and Analysis, Part II

Path Compression

Path Compression

Idea: Why bother traversing a leaf-root path multiple times? Path compression: After FIND(x), install shortcuts (i.e., revise parent pointers) to x's root all along the $x \to root$ path.



In array representation:

Con: Constant-factor overhead to FIND (from "multitasking").

Pro: Speeds up subsequent FINDs. [But by how much?]

On Ranks

Important: Maintain all rank fields EXACTLY as without path compression.

- Ranks initially all 0
- In UNION, new root = old root with bigger rank
- When merging two nodes of common rank r, reset new root's rank to r+1

Bad news: Now rank[x] is only an upper bound on the maximum number of hops on a path from a leaf to x (which could be much less)

Good news: Rank Lemma still holds $(\le n/2^r)$ objects with rank r) Also: Still always have rank[parent[x]]>rank[x] for all non-roots x

Hopcroft-Ullman Theorem

Theorem: [Hopcroft-Ullman 73] With Union by Rank and path compression, m Union+Find operations take $O(m \log^* n)$ time, where $\log^* n =$ the number of times you need to apply \log to n before the result is < 1.

Quiz on log*

Question: What is $\log^*(2^{65536})$?

- A) 2
- B) 5
- C) 16
- D) 65536

```
In general: \log^*(2^{2\cdots t \text{ times } ...^2}) = t
```

Measuring Progress



Advanced Union-Find

Algorithms: Design and Analysis, Part II

Path Compression: The Hopcroft-Ullman Analysis

Hopcroft-Ullman Theorem

Theorem: [Hopcroft-Ullman 73] With Union by Rank and path compression, m UNION+FIND operations take $O(m \log^* n)$ time, where $\log^* n =$ the number of times you need to apply \log to n before the result is < 1.

[Will focus on interesting case where $m = \Omega(n)$]

Measuring Progress

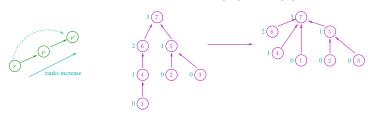
Intuition: Installing shortcuts should significantly speed up subsequent FINDs+UNIONs.

Question: How to track this progress and quantify the benefit?

Idea: Consider a non-root object $x \longrightarrow \text{Recall: } \text{rank}[x] \text{ frozen}$

Progress measure: rank[parent[x]] - rank[x]

Path compression increases this progress measure: If x has old parent p, new parent $p' \neq p$, then rank[p'] > rank[p].



Proof Setup

Note: There are $O(\log^* n)$ different rank blocks.

Semantics: Traversal $x \to \operatorname{parent}(x)$ is "fast progress" \iff rank[parent[x]] in larger block than rank[x]

Definition: At a given point in time, call object x good if

- (1) x or x's parent is a root OR
- (2) rank[parent[x]] in larger block than rank[x]

x is bad otherwise.

Proof of Hopcroft-Ullman

Point: Every FIND visits only $O(\log^* n)$ good nodes $[2 + \# \text{ of rank blocks} = O(\log^* n)]$

Upshot: Total work done during m operations = $O(m \log^* n)$ (visits to good objects) + total # of visits to bad nodes (need to bound globally by separate argument)

Consider: A rank block $\{k+1, k+2, \dots, 2^k\}$.

Note: When a bad node is visited



its parent is changed to one with strictly larger rank \Rightarrow Can only happen 2^k times before x becomes good (forevermore).

Proof of Hopcroft-Ullman II

Total work: $O(m \log^* n) + O(\# \text{ visits to bad nodes })$.

 $\leq n$ for each of $O(\log^* n)$ rank blocks \checkmark

Consider: A rank block $\{k+1, k+2, \dots, 2^k\}$.

Last slide: For each object x with final rank in this block, # visits

to x while x is bad is $\leq 2^k$.

Rank Lemma: Total number of objects x with final rank in this rank block is $\sum_{i=k+1}^{2^k} n/2^i \le n/2^k$.

 $\leq n$ visits to bad objects in this rank block.

Recall: Only $O(\log^* n)$ rank blocks.

Total work: $O((m+n)\log^* n)$.



Advanced Union-Find

Algorithms: Design and Analysis, Part II

Path Compression: The Hopcroft-Ullman Analysis

Hopcroft-Ullman Theorem

Theorem: [Hopcroft-Ullman 73] With Union by Rank and path compression, m UNION+FIND operations take $O(m \log^* n)$ time, where $\log^* n =$ the number of times you need to apply \log to n before the result is < 1.

[Will focus on interesting case where $m = \Omega(n)$]

Measuring Progress

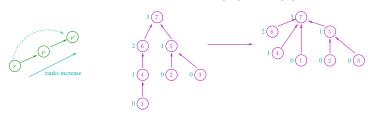
Intuition: Installing shortcuts should significantly speed up subsequent FINDs+UNIONs.

Question: How to track this progress and quantify the benefit?

Idea: Consider a non-root object $x \longrightarrow \text{Recall: } \text{rank}[x] \text{ frozen}$

Progress measure: rank[parent[x]] - rank[x]

Path compression increases this progress measure: If x has old parent p, new parent $p' \neq p$, then rank[p'] > rank[p].



Proof Setup

Note: There are $O(\log^* n)$ different rank blocks.

Semantics: Traversal $x \to \operatorname{parent}(x)$ is "fast progress" \iff rank[parent[x]] in larger block than rank[x]

Definition: At a given point in time, call object x good if

- (1) x or x's parent is a root OR
- (2) rank[parent[x]] in larger block than rank[x]

x is bad otherwise.

Proof of Hopcroft-Ullman

Point: Every FIND visits only $O(\log^* n)$ good nodes $[2 + \# \text{ of rank blocks} = O(\log^* n)]$

Upshot: Total work done during m operations = $O(m \log^* n)$ (visits to good objects) + total # of visits to bad nodes (need to bound globally by separate argument)

Consider: A rank block $\{k+1, k+2, \dots, 2^k\}$.

Note: When a bad node is visited



its parent is changed to one with strictly larger rank \Rightarrow Can only happen 2^k times before x becomes good (forevermore).

Proof of Hopcroft-Ullman II

Total work: $O(m \log^* n) + O(\# \text{ visits to bad nodes })$.

 $\leq n$ for each of $O(\log^* n)$ rank blocks \checkmark

Consider: A rank block $\{k+1, k+2, \dots, 2^k\}$.

Last slide: For each object x with final rank in this block, # visits

to x while x is bad is $\leq 2^k$.

Rank Lemma: Total number of objects x with final rank in this rank block is $\sum_{i=k+1}^{2^k} n/2^i \le n/2^k$.

 $\leq n$ visits to bad objects in this rank block.

Recall: Only $O(\log^* n)$ rank blocks.

Total work: $O((m+n)\log^* n)$.



Advanced Union-Find

Algorithms: Design and Analysis, Part II

The Ackermann Function

Tarjan's Bound

Theorem: [Tarjan 75] With Union by Rank and path compression, m UNION+FIND operations take $O(m\alpha(n))$ time, where $\alpha(n)$ is the inverse Ackerman function (will define in this video)

Proof in next video.

The Ackermann Function

Aside: Many different definitions, all more or less equivalent.

Will define $A_k(r)$ for all integers k and $r \ge 1$. (recursively)

Base case:
$$A_0(r) = r + 1$$
 for all $r \ge 1$.

In general: For $k, r \ge 1$:

$$A_k(r) = \text{Apply } A_{k-1} \ r \text{ times to } r$$

$$= (A_{k-1} \circ A_{k-1} \circ \dots \circ A_{k-1})(r)$$

r-fold composition

Quiz: A_1

Quiz: $A_1(r)$ corresponds to what function of r?

- A) Successor $(r \mapsto r + 1)$
- B) Doubling $(r \mapsto 2r)$
- C) Exponentation $(r \mapsto 2^r)$ D) Tower function $(r \mapsto 2^{2\cdots r \text{ times } \dots^2})$

$$A_1(r) = (A_0 \circ A_0 \circ \ldots \circ A_0)(r) = 2r$$

(r-fold composition, add 1 each time)

Quiz: A₂

Quiz: What function does $A_2(r)$ correspond to?

A)
$$r \mapsto 4r$$

B)
$$r \mapsto 2^r$$

B)
$$r \mapsto r2^r$$

D)
$$r \mapsto 2^{2\cdots r \text{ times } \dots^2}$$

$$A_2(r) = (A_1 \circ A_1 \circ \ldots \circ A_1)(r) = r2^r$$

(r-fold composition, doubles each time)

Quiz: A_3

Quiz: What is $A_3(2)$? Recall $A_2(r) = r2^r$

- A) 8
- B) 1024
- B) 2048 «
- D) Bigger than 2048

$$A_3(2) = A_2(A_2(2)) = A_2(8) = 82^8 = 2^{11} = 2048$$

In general: $A_3(r) = (A_2 \circ A_2 \circ \dots (r \text{ times}) \dots \circ A_2)(r) \ge a$ tower of r 2's = $2^{2 \dots r \text{ times} \dots^2}$

A_4

$$A_4(2) = A_3(A_3(2)) = A_3(2048) \geq 2^{2 \cdot \cdot \cdot \cdot \text{ height 2048 } \cdot \cdot \cdot \cdot^2}$$

In general: $A_4(r) = (A_3 \circ \dots r \text{ times } \dots \circ A_3)(r) \approx \text{iterated tower function (aka "wowzer" function)}$

The Inverse Ackermann Function

Definition: For every $n \ge 4$, $\alpha(n) = \min \max$ value of k such that $A_k(2) \ge n$.

$$\alpha(n) = 1, \ n = 4 \ (A_1(2) = 4)$$
 $\log^* n = 1, \ n = 2$ $\alpha(n) = 2, \ n = 5, \dots, 8 \ (A_2(2) = 8)$ $\log^* n = 2, \ n = 3, 4$ $\alpha(n) = 3, \ n = 9, 10, \dots, 2048$ $\log^* n = 3, \ n = 5, \dots, \underline{16}$ $\alpha(n) = 4, \ n \text{ up to roughly a tower}$ $\log^* n = 4, \ n = 17, \underline{65536}$ of 2's of height 2048 $\log^* n = 5, \ n = 65537, \underline{2^{65536}}$ $\alpha(n) = 5 \text{ for } n \text{ up to } ???$ $\log^* n = 2048 \text{ for such } n$



Advanced Union-Find

Algorithms: Design and Analysis, Part II

Tarjan's Analysis

Tarjan's Bound

Theorem: [Tarjan 75] With Union by Rank and path compression, m UNION+FIND operations take $O(m\alpha(n))$ time, where $\alpha(n)$ is the inverse Ackerman function

Acknowledgement: Kozen, "Design and Analysis of Algorithms"

Building Blocks of Hopcroft-Ullman Analysis

Block #1: Rank Lemma (at most $n/2^r$ objects of rank r)

Block #2: Path compression \Rightarrow If x's parent pointer updated from p to p', then rank(p') \geq rank(p)+1

New idea: Stronger version of building block #2. In most cases, rank of new parent $\underline{\text{much}}$ bigger than rank of old parent (not just by 1).

Quantifying Rank Gaps

```
Definition: Consider a non-root object x (so rank[x] fixed
forevermore)
Define \delta(x) = \max \text{ value of } k \text{ such that }
rank[parent[x] \ge A_k(rank[x])
(Note \delta(x) only goes up over time)
Examples: Always have \delta(x) \geq 0
\delta(x) \ge 1 \iff \operatorname{rank}[\operatorname{parent}[x]] \ge 2 \operatorname{rank}[x]
\delta(x) \ge 2 \iff \operatorname{rank}[\operatorname{parent}[x]] \ge \operatorname{rank}[x] 2^{\operatorname{rank}[x]}
Note: For all objects x with rank[x] \ge 2, then \delta(x) \le \alpha(n)
[Since A_{\alpha(n)}(2) \geq n]
```

Good and Bad Objects

Definition: An object x is bad if all of the following hold:

- (1) x is not a root
- (2) parent(x) is not a root
- (3) $\operatorname{rank}(x) \ge 2$
- (4) x has an ancestor y with $\delta(y) = \delta(x)$

x is good otherwise.

Quiz

Question: What is the maximum number of good objects on an object-root path?

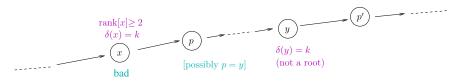
- A) $\Theta(1)$
- B) $\Theta(\alpha(n))$
- C) $\Theta(\log^* n)$
- $D) \Theta(\log n)$

```
\leq 1 \text{ root} + 1 \text{ child of root}
+ 1 object with rank 0
+ 1 object with rank 1
+ 1 object with \delta(x) = k
for each k = 0, 1, 2, ..., \alpha(n)
```

Proof of Tarjan's Bound

Upshot: Total work of m operations = $O(m\alpha(n))$ (visits to good objects)+ total # of visits to bad objects (will show is $O(n\alpha(n))$)

Main argument: Suppose a FIND operation visits a bad object x:



Path compression: x's new parent will be p' or even higher. $\Rightarrow \operatorname{rank}[x]$'s new parent] $\geq \operatorname{rank}[p'] \geq A_k(\operatorname{rank}[y]) \geq A_k(\operatorname{rank}[p])$ ranks only go up since $\delta(y) = k$ ranks only go up

Proof of Tarjan's Bound II

Point: Path compression (at least) applies the A_k function to rank[x's parent]

Consequence: If $r=\operatorname{rank}[x]\ (\geq 2)$, then after r such pointer updates we have

$$\operatorname{rank}[x's \ \operatorname{parent}] \geq (A_k \circ \dots \ r \ \operatorname{times} \ \dots \circ A_k)(r) = A_{k+1}(r)$$

Definition of Ackermann function

Thus: While x is bad, every r visits increases $\delta(x)$ $\Rightarrow \leq r\alpha(n)$ visits to x while it's bad

Proof of Tarjan's Bound III

Recall: Total work of m operations is $O(m\alpha(n))$ (visits to good objects) + total # of visits to bad objects.

$$\leq \sum_{\text{objects } x} rank[x]\alpha(n)$$

$$= \alpha(n) \sum_{r \geq 0} r \quad (\text{# of objects with rank } r)$$

$$\leq n/2^r \text{ for each } r \text{ by the Rank Lemma}$$

$$= n\alpha(n) \sum_{r \geq 0} r/2^r \longrightarrow = O(1)$$

$$= O(n\alpha(n)). \qquad \text{QED!}$$

Epilogue

"This is probably the first and maybe the only existing example of a simple algorithm with a very complicated running time. ... I conjecture that there is <u>no</u> linear-time method, and that the algorithm considered here is optimal to within a constant factor."

-Tarjan, "Efficiency of a Good But Non Linear Set Union Algorithm", Journal of the ACM, 1975.

Conjecture proved by [Fredman/Saks 89]!



Advanced Union-Find

Algorithms: Design and Analysis, Part II

Tarjan's Analysis

Tarjan's Bound

Theorem: [Tarjan 75] With Union by Rank and path compression, m UNION+FIND operations take $O(m\alpha(n))$ time, where $\alpha(n)$ is the inverse Ackerman function

Acknowledgement: Kozen, "Design and Analysis of Algorithms"

Building Blocks of Hopcroft-Ullman Analysis

Block #1: Rank Lemma (at most $n/2^r$ objects of rank r)

Block #2: Path compression \Rightarrow If x's parent pointer updated from p to p', then rank(p') \geq rank(p)+1

New idea: Stronger version of building block #2. In most cases, rank of new parent $\underline{\text{much}}$ bigger than rank of old parent (not just by 1).

Quantifying Rank Gaps

```
Definition: Consider a non-root object x (so rank[x] fixed
forevermore)
Define \delta(x) = \max \text{ value of } k \text{ such that }
rank[parent[x] \ge A_k(rank[x])
(Note \delta(x) only goes up over time)
Examples: Always have \delta(x) \geq 0
\delta(x) \ge 1 \iff \operatorname{rank}[\operatorname{parent}[x]] \ge 2 \operatorname{rank}[x]
\delta(x) \ge 2 \iff \operatorname{rank}[\operatorname{parent}[x]] \ge \operatorname{rank}[x] 2^{\operatorname{rank}[x]}
Note: For all objects x with rank[x] \ge 2, then \delta(x) \le \alpha(n)
[Since A_{\alpha(n)}(2) \geq n]
```

Good and Bad Objects

Definition: An object x is bad if all of the following hold:

- (1) x is not a root
- (2) parent(x) is not a root
- (3) $\operatorname{rank}(x) \ge 2$
- (4) x has an ancestor y with $\delta(y) = \delta(x)$

x is good otherwise.

Quiz

Question: What is the maximum number of good objects on an object-root path?

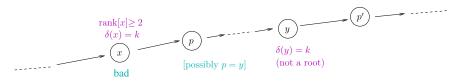
- A) $\Theta(1)$
- B) $\Theta(\alpha(n))$
- C) $\Theta(\log^* n)$
- D) $\Theta(\log n)$

```
\leq 1 \text{ root} + 1 \text{ child of root}
+ 1 object with rank 0
+ 1 object with rank 1
+ 1 object with \delta(x) = k
for each k = 0, 1, 2, ..., \alpha(n)
```

Proof of Tarjan's Bound

Upshot: Total work of m operations = $O(m\alpha(n))$ (visits to good objects)+ total # of visits to bad objects (will show is $O(n\alpha(n))$)

Main argument: Suppose a FIND operation visits a bad object x:



Path compression: x's new parent will be p' or even higher. $\Rightarrow \operatorname{rank}[x'] \operatorname{sew} \operatorname{parent}] \geq \operatorname{rank}[p'] \geq A_k(\operatorname{rank}[p]) \geq A_k(\operatorname{rank}[p])$ ranks only go up since $\delta(y) = k$ ranks only go up

Proof of Tarjan's Bound II

Point: Path compression (at least) applies the A_k function to rank[x's parent]

Consequence: If $r=\operatorname{rank}[x]\ (\geq 2)$, then after r such pointer updates we have

$$rank[x's parent] \ge (A_k \circ \dots r times \dots \circ A_k)(r) = A_{k+1}(r)$$

Definition of Ackermann function

Thus: While x is bad, every r visits increases $\delta(x)$ $\Rightarrow \leq r\alpha(n)$ visits to x while it's bad

Proof of Tarjan's Bound III

Recall: Total work of m operations is $O(m\alpha(n))$ (visits to good objects) + total # of visits to bad objects.

$$\leq \sum_{\text{objects } x} rank[x]\alpha(n)$$

$$= \alpha(n) \sum_{r \geq 0} r \quad (\text{# of objects with rank } r)$$

$$\leq n/2^r \text{ for each } r \text{ by the Rank Lemma}$$

$$= n\alpha(n) \sum_{r \geq 0} r/2^r \longrightarrow = O(1)$$

$$= O(n\alpha(n)). \qquad \text{QED!}$$

Epilogue

"This is probably the first and maybe the only existing example of a simple algorithm with a very complicated running time. ... I conjecture that there is <u>no</u> linear-time method, and that the algorithm considered here is optimal to within a constant factor."

-Tarjan, "Efficiency of a Good But Non Linear Set Union Algorithm", Journal of the ACM, 1975.

Conjecture proved by [Fredman/Saks 89]!