



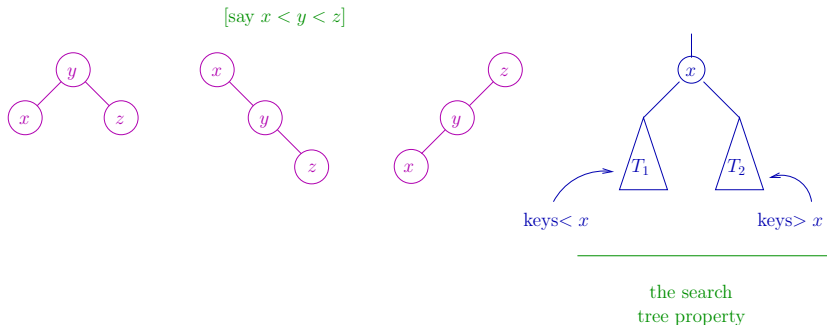
Dynamic Programming

Algorithms: Design
and Analysis, Part II

Optimal Binary Search
Trees: Problem Definition

A Multiplicity of Search Trees

Recall: For a given set of keys, there are lots of valid search trees.



Question: What is the “best” search tree for a given set of keys?

A good answer: A balanced search tree, like a red-black tree.

(Recall Part I)

\Rightarrow Worst-case search time = $\Theta(\text{height}) = \Theta(\log n)$

Exploiting Non-Uniformity

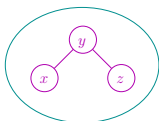
Question: Suppose we have keys $x < y < z$ and we know that:

80% of searches are for x

10% of searches are for y

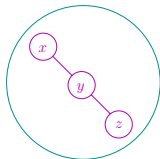
10% of searches are for z

What is the average search time (i.e., number of nodes looked at) in the trees:



$$0.8 \cdot 2 + 0.1 \cdot 1 + 0.1 \cdot 2 = 1.9$$

and



respectively?

$$0.8 \cdot 1 + 0.1 \cdot 2 + 0.1 \cdot 3 = 1.3$$

A) 2 and 3

B) 2 and 1

C) 1.9 and 1.2

D) 1.9 and 1.3

Problem Definition

Input: Frequencies p_1, p_2, \dots, p_n for items $1, 2, \dots, n$.

[Assume items in sorted order, $1 < 2 < \dots < n$]

Goal: Compute a valid search tree that minimizes the weighted (average) search time.

$$C(T) = \sum_{\text{items } i} p_i \text{ [search time for } i \text{ in } T]$$

Depth of i in $T + 1$



Example: If T is a red-black tree, then $C(T) = O(\log n)$.
(Assuming $\sum_i p_i = 1$.)

Comparison with Huffman Codes

Similarities:

- Output = a binary tree
- Goal is (essentially) to minimize average depth with respect to given probabilities

Differences:

- With Huffman codes, constraint was prefix-freeness [i.e., symbols only at leaves]
- Here, constraint = search tree property [seems harder to deal with]



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Optimal BSTs: Optimal
Substructure

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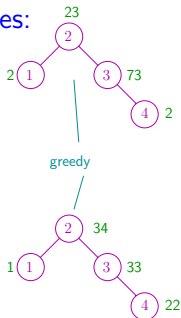
Greedy Doesn't Work

Intuition: Want the most (respectively, least) frequently accessed items closest (respectively, furthest) from the root.

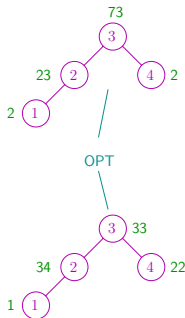
Ideas for greedy algorithms:

- Bottom-up [populate lowest level with least frequently accessed keys]
- Top-down [put most frequently accessed item at root, recurse]

Counter examples:



instead of



instead of

Choosing the Root

Issue: With the top-down approach, the choice of root has hard-to-predict repercussions further down the tree.

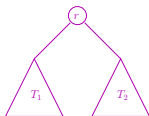
[stymies both greedy and naive divide + conquer approaches]

Idea: What if we knew the root?

(i.e., maybe can try all possibilities within a dynamic programming algorithm!)

Optimal Substructure

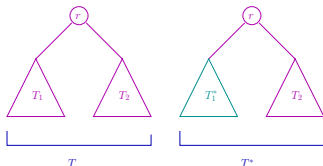
Question: Suppose an optimal BST for keys $\{1, 2, \dots, n\}$ has root r , left subtree T_1 , right subtree T_2 . Pick the strongest statement that you suspect is true.



- A) Neither T_1 nor T_2 need be optimal for the items it contains.
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- D) T_1 is optimal for the keys $\{1, 2, \dots, r - 1\}$ and T_2 for the keys $\{r + 1, r + 2, \dots, n\}$

Proof of Optimal Substructure

Let T be an optimal BST for keys $\{1, 2, \dots, n\}$ with frequencies p_1, \dots, p_n . Suppose T has root r . Suppose for contradiction that T_1 is not optimal for $\{1, 2, \dots, r-1\}$ [other case is similar] with $C(T_1^*) < C(T_1)$. Obtain T^* from T by “cutting+pasting” T_1^* in for T_1 .



Note: To complete contradiction + proof, only need to show that $C(T^*) < C(T)$.

Proof of Optimal Substructure (con'd)

A Calculation:

$$\begin{aligned} &= 1 + \text{search time for } i \text{ in } T_1 \quad = 1 + \text{search time for } i \text{ in } T_2 \\ C(T) &= \sum_{i=1}^n p_i [\text{search time for } i \text{ in } T] \\ &= p_r \cdot 1 + \sum_{i=1}^{r-1} p_i [\text{search time for } i \text{ in } T] \\ &\quad + \sum_{i=r+1}^n p_i [\text{search time for } i \text{ in } T] \\ &= \sum_{i=1}^n p_i + \sum_{i=1}^{r-1} p_i [\text{search time for } i \text{ in } T_1] \\ &\quad + \sum_{i=r+1}^n p_i [\text{search time for } i \text{ in } T_2] \\ &\text{a constant (independent of } T) \quad = C(T_1) \quad = C(T_2) \end{aligned}$$

Similarly: $C(T^*) = \sum_{i=1}^n p_i + C(T_1^*) + C(T_2)$

Upshot: $C(T_1^*) < C(T_1)$ implies $C(T^*) < C(T)$, contradicting optimality of T . **QED!**



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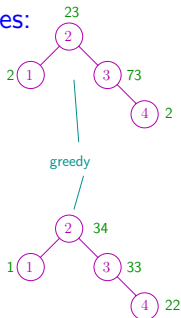
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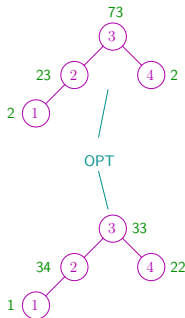
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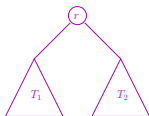
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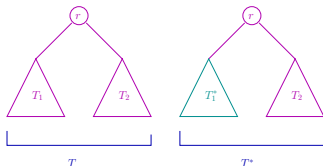
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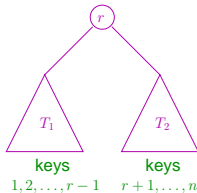
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Note: Items in a subproblem are either a prefix or a suffix of the original problem.

Relevant Subproblems

Question: Let $\{1, 2, \dots, n\}$ = original items. For which subsets $S \subseteq \{1, 2, \dots, n\}$ might we need to compute the optimal BST for S ?

- A) Prefixes ($S = \{1, 2, \dots, i\}$ for every i)
- B) Prefixes and suffixes ($S = \{1, \dots, i\}$ and $\{i, \dots, n\}$ for every i)
- C) Contiguous intervals ($S = \{i, i + 1, \dots, j - 1, j\}$ for every $i \leq j$)
- D) All subsets S

The Recurrence

Notation: For $1 \leq i \leq j \leq n$, let C_{ij} = weighted search cost of an optimal BST for the items $\{i, i+1, \dots, j-1, j\}$ [with probabilities p_i, p_{i+1}, \dots, p_j]

Recurrence: For every $1 \leq i \leq j \leq n$:

$$C_{ij} = \min_{r=i, \dots, j} \left\{ \sum_{k=i}^j p_k + C_{i, r-1} + C_{r+1, j} \right\}$$

(Recall formula $C(T) = \sum_k p_k + C(T_1) + C(T_2)$ from last video)

Interpret $C_{xy} = 0$ if $x > y$

Correctness: Optimal substructure narrows candidates down to $(j - i + 1)$ possibilities, recurrence picks the best by brute force.

The Algorithm

Important: Solve smallest subproblems (with fewest number $(j - i + 1)$ of items) first.

Let A = 2-D array. $[A[i, j]]$ represents opt BST value of items $\{1, \dots, j\}$

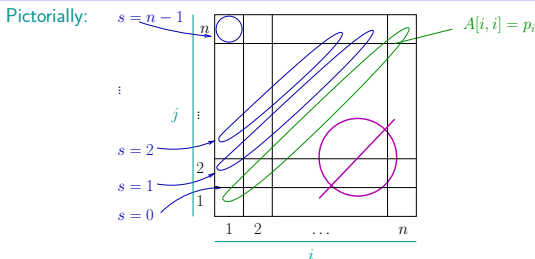
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For $i = 1$ to n [so $i + s$ plays role of j]

$$A[i, i + s] = \min_{r=1, \dots, i+s} \{ \sum_{k=1}^{i+s} p_k + A[i, r - 1] + A[r + 1, i + s] \}$$

Return $A[1, n]$

Interpret as 0 if 1st index $>$ 2nd index. Available for $O(1)$ -time lookup



Running Time

- $\Theta(n^2)$ subproblems
 - $\Theta(j - i)$ time to compute $A[i, j]$
- $\Rightarrow \Theta(n^3)$ time overall

Fun fact: [Knuth '71, Yoo '80] Optimized version of this DP algorithm correctly fills up entire table in only $\Theta(n^2)$ time [$\Theta(1)$ on average per subproblem]

[Idea: piggyback on work done in previous subproblems to avoid trying all possible roots]



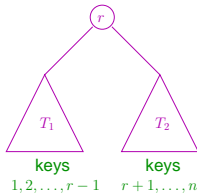
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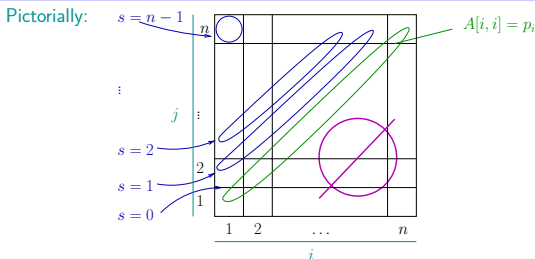
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