

Math 449: Numerical Applied Mathematics

Lecture 21

10/27/2017 Wenzhen

Today's topic: Iterative Methods in Numerical Linear Algebra

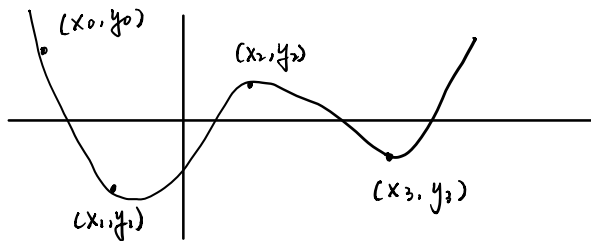
Let P_n be the set of all polynomials $p_n: \mathbb{R} \rightarrow \mathbb{R}$ of degree $\leq n$

$$p_n(x) = a_0 + a_1x + a_2x^2 + \dots + a_nx^n$$

where $a_0, \dots, a_n \in \mathbb{R}$ are arbitrary coefficients.

Problem: Suppose x_0, \dots, x_n are distinct real and y_0, \dots, y_n be real #s.

Find $p_n \in P_n$ s.t. $p_n(x_i) = y_i$ for $i = 0, 1, \dots, n$



Why do we care?

1. missing data

unknown function f

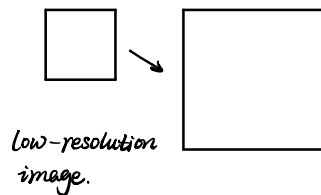
take finite # of measurements. $y_i = f(x_i)$

But I don't know f for other values of x

Polynomial interp "fills in" missing values.

$y = p_n(x)$ consistent w/ measurement. estimate of f .

Ex. Image upscaling

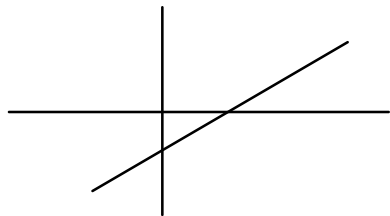


Suppose we want to differentiate or integrate a function

Hard for arbitrary functions. Trivial for polynomials. Instead of integrating f ,

approximate f by a polynomial and integrate that instead

Not interpolation: best fit line.



interpolating polynomials go through all pts (x_i, y_i)

For our purposes, no difference between interpolation and "extrapolation".

Can we find such a p_n ?

$$p_n(x) = a_0 + a_1x + \dots + a_nx^n$$

To interpolate, must satisfy

$$\left. \begin{array}{l} p_n(x_0) = y_0 \\ p_n(x_1) = y_1 \\ \vdots \\ p_n(x_n) = y_n \end{array} \right\} \quad n+1 \text{ linear equations}$$

$$a_0 + a_1x + \dots + a_nx^n = y_i$$

Instead of doing this, we represent p_n in a different way.

Monomials $\{1, x, x^2, \dots, x^n\}$ are a basis for P_n .

$$p_n(x) = a_0 + a_1x + \dots + a_nx^n \quad a_0, a_1, \dots, a_n \text{ are coeff. in the monomial basis.}$$

Lagrange Interpolation.

Given distinct x_0, x_1, \dots, x_n

Claim: For each $k=0, \dots, n$ we can find a polynomial $L_k \in P_n$ (Lagrange basis poly)

$$\text{s.t. } \begin{cases} L_k(x_k) = 1 \\ L_k(x_i) = 0 \quad i \neq k \end{cases}$$

Want to find $L_1 \in P_2$

Quadratic Vanishing @ x_0, x_2

$$q(x) = (x-x_0)(x-x_2)$$

$$q(x_1) = (x_1-x_0)(x_1-x_2) \neq 0 \quad \text{Assuming } x_0, x_1, x_2 \text{ are distinct.}$$

$$L_1(x) = \frac{(x-x_0)(x-x_2)}{(x_1-x_0)(x_1-x_2)} = \begin{cases} 0 & \text{at } x_0, x_2 \\ 1 & \text{at } x_1 \end{cases}$$

Def.

Given distinct x_0, x_1, \dots, x_n

$$L_k(x) = \prod_{\substack{i=0 \\ i \neq k}}^n \frac{(x-x_i)}{(x_k-x_i)} \quad k=0, 1, \dots, n$$

$\{L_0, L_1, \dots, L_n\}$ are the Lagrange basis polynomials. for the pts x_0, \dots, x_n .

Solution to interpolation prob.

$$\text{let } p_n(x) = \sum_{k=0}^n L_k(x) y_k$$

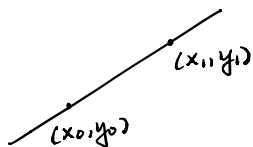
$$\text{then } p_n(x_i) = \sum_{k=0}^n L_k(x_i) y_k = 0 + \dots + 0 + L_i(x_i) y_i + 0 + \dots + 0 = y_i$$

for $i=0, 1, \dots, n$

instead of using monomial basis & solving for coefficients a_0, \dots, a_n .

We use a different basis where the coefficients are just y_0, \dots, y_n .

Ex. Linear Interpolation



$$L_0(x) = \frac{x - x_1}{x_0 - x_1}$$

$$L_1(x) = \frac{x - x_0}{x_1 - x_0}$$

$$p_1(x) = \frac{x - x_1}{x_0 - x_1} y_0 + \frac{x - x_0}{x_1 - x_0} y_1$$

$y = p_1(x)$ rearranges "point-slope" for a line.

$$y - y_0 = m(x - x_0)$$

$$= \frac{y_1 - y_0}{x_1 - x_0} (x - x_0)$$

Thm $\{L_0, \dots, L_n\}$ are a basis of P_n

Proof Suffices to show linearly independent.

Suppose

$$p_n = \sum_{k=0}^n L_k y_k = 0$$

want to show that $y_0 = \dots = y_n = 0$

if this is true, then $p_n(x_i) = 0$ for $i = 0, 1, \dots, n$.

$$= y_i$$

So all the $y_i = 0$.

corollary.