

# Math 449: Numerical Applied Mathematics

## Lecture 23

10/27/2017 Wenzhen

Today's topic: Interpolation

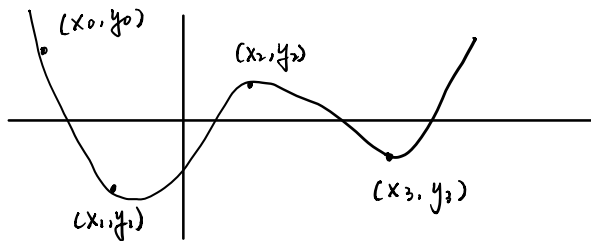
Let  $P_n$  be the set of all polynomials  $p_n: \mathbb{R} \rightarrow \mathbb{R}$  of degree  $\leq n$

$$p_n(x) = a_0 + a_1x + a_2x^2 + \dots + a_nx^n$$

where  $a_0, \dots, a_n \in \mathbb{R}$  are arbitrary coefficients.

Problem: Suppose  $x_0, \dots, x_n$  are distinct real and  $y_0, \dots, y_n$  be real #s.

Find  $p_n \in P_n$  s.t.  $p_n(x_i) = y_i$  for  $i = 0, 1, \dots, n$



Why do we care?

1. missing data

unknown function  $f$

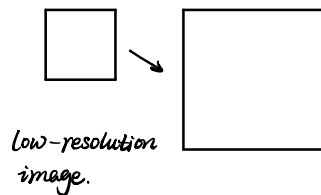
take finite # of measurements.  $y_i = f(x_i)$

But I don't know  $f$  for other values of  $x$

Polynomial interp "fills in" missing values.

$y = p_n(x)$  consistent w/ measurement. estimate of  $f$ .

Ex. Image upscaling

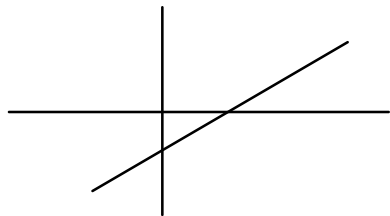


Suppose we want to differentiate or integrate a function

Hard for arbitrary functions. Trivial for polynomials. Instead of integrating  $f$ ,

approximate  $f$  by a polynomial and integrate that instead

Not interpolation: best fit line.



interpolating polynomials go through all pts  $(x_i, y_i)$

For our purposes, no difference between interpolation and "extrapolation".

Can we find such a  $p_n$ ?

$$p_n(x) = a_0 + a_1x + \dots + a_nx^n$$

To interpolate, must satisfy

$$\left. \begin{array}{l} p_n(x_0) = y_0 \\ p_n(x_1) = y_1 \\ \vdots \\ p_n(x_n) = y_n \end{array} \right\} \quad n+1 \text{ linear equations}$$

$$a_0 + a_1x + \dots + a_nx^n = y_i$$

Instead of doing this, we represent  $p_n$  in a different way.

Monomials  $\{1, x, x^2, \dots, x^n\}$  are a basis for  $P_n$ .

$$p_n(x) = a_0 + a_1x + \dots + a_nx^n \quad a_0, a_1, \dots, a_n \text{ are coeff. in the monomial basis.}$$

## Lagrange Interpolation.

Given distinct  $x_0, x_1, \dots, x_n$

Claim: For each  $k=0, \dots, n$  we can find a polynomial  $L_k \in P_n$  (Lagrange basis poly)

$$\text{s.t. } \begin{cases} L_k(x_k) = 1 \\ L_k(x_i) = 0 \quad i \neq k \end{cases}$$

Want to find  $L_1 \in P_2$

Quadratic Vanishing @  $x_0, x_2$

$$q(x) = (x-x_0)(x-x_2)$$

$$q(x_1) = (x_1-x_0)(x_1-x_2) \neq 0 \quad \text{Assuming } x_0, x_1, x_2 \text{ are distinct.}$$

$$L_1(x) = \frac{(x-x_0)(x-x_2)}{(x_1-x_0)(x_1-x_2)} = \begin{cases} 0 & \text{at } x_0, x_2 \\ 1 & \text{at } x_1 \end{cases}$$

Def.

Given distinct  $x_0, x_1, \dots, x_n$

$$L_k(x) = \prod_{\substack{i=0 \\ i \neq k}}^n \frac{(x-x_i)}{(x_k-x_i)} \quad k=0, 1, \dots, n$$

$\{L_0, L_1, \dots, L_n\}$  are the Lagrange basis polynomials. for the pts  $x_0, \dots, x_n$ .

Solution to interpolation prob.

$$\text{let } p_n(x) = \sum_{k=0}^n L_k(x) y_k$$

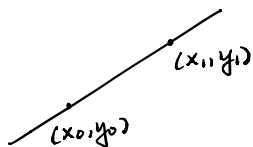
$$\text{then } p_n(x_i) = \sum_{k=0}^n L_k(x_i) y_k = 0 + \dots + 0 + L_i(x_i) y_i + 0 + \dots + 0 = y_i$$

for  $i=0, 1, \dots, n$

instead of using monomial basis & solving for coefficients  $a_0, \dots, a_n$ .

We use a different basis where the coefficients are just  $y_0, \dots, y_n$ .

Ex. Linear Interpolation



$$L_0(x) = \frac{x - x_1}{x_0 - x_1}$$

$$L_1(x) = \frac{x - x_0}{x_1 - x_0}$$

$$p_1(x) = \frac{x - x_1}{x_0 - x_1} y_0 + \frac{x - x_0}{x_1 - x_0} y_1$$

$y = p_1(x)$  rearranges "point-slope" for a line.

$$y - y_0 = m(x - x_0)$$

$$= \frac{y_1 - y_0}{x_1 - x_0} (x - x_0)$$

*Thm*  $\{L_0, \dots, L_n\}$  are a basis of  $P_n$

Proof Suffices to show linearly independent.

Suppose

$$p_n = \sum_{k=0}^n L_k y_k = 0$$

want to show that  $y_0 = \dots = y_n = 0$

if this is true, then  $p_n(x_i) = 0$  for  $i = 0, 1, \dots, n$ .

$$= y_i$$

So all the  $y_i = 0$ .

corollary.