# Main Algorithms

# Helper function

```
PNGtoGray[filename_]:=Reverse[Map[Map[First,#]&,Import[filename,"Data"]]];
GIFtoGray[filename_]:=255-Reverse[Map[Map[First,#]&,Import[filename,"Data"]]];
showGrayImage[img_]:=Graphics[Raster[img/Max[img]],Frame→False];
showBinaryImage[img_]:=Graphics[Raster[img],Frame→False];
showBinaryOverlay[img_,mask_]:=Graphics[Raster[MapThread[MapThread[If[#2=1,{1,0,0},{#1,#1 {img,mask}]],Frame→False];
showGrayOverlay[img_,mask_]:=Graphics[{Raster[img/Max[img]],Raster[Map[Map[{#,0,0,If[#==1,
```

# $S_{op}$

We remove noise while preserving most of the capillaries using geodesic reconstruction of the opened images into the original image  $S_0$ 

Each structuring element  $L_i$  (every 15°) is a 15-pixel long 1-pixel wide. Its size is approximately the range of the diameter of the biggest vessels for 512 × 512 × 8 images of retinal angiography.

In the image  $S_{op}$ , every isolated round and bright zone whose diameter is less than 15 pixels has been removed. Being a supremum of openings by reconstruction this operation is an opening, called linear opening by reconstruction of size 15.

$$S_{op} = \gamma_{S_0}^{rec} (Max_{i=1...} _{12} {\{\gamma_{L_i}(S_0)\}})$$

#### My question:

Is this equation means

- 1. apply erosion with structure elements  $L_1 \dots L_{12}$  to  $S_0$
- 2. Find the maximum for every pixel
- 3. apply geodesic opening with marker image being original image

```
\gamma_{S_0}^{\text{rec}} = \text{geodesic opening}

\gamma_{S_0}^{\text{rec}}(S) = \sup_{d \in \mathbb{N}} (\Delta_{S_0}^d(S)) // S_0 = \text{marker image}
```

### Step 1: Construct L<sub>i</sub>

```
ln[4]:= angles = Table [\{Cos[t], Sin[t]\}, \{t, 0, 11\pi/12, \pi/12\}]
Out[4]= \left\{ \{1,0\}, \left\{ \frac{1+\sqrt{3}}{2\sqrt{2}}, \frac{-1+\sqrt{3}}{2\sqrt{2}} \right\}, \left\{ \frac{\sqrt{3}}{2}, \frac{1}{2} \right\}, \left\{ \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}} \right\}, \right\}
         \left\{\frac{1}{2}, \frac{\sqrt{3}}{2}\right\}, \left\{\frac{-1+\sqrt{3}}{2\sqrt{2}}, \frac{1+\sqrt{3}}{2\sqrt{2}}\right\}, \left\{0, 1\right\}, \left\{-\frac{-1+\sqrt{3}}{2\sqrt{2}}, \frac{1+\sqrt{3}}{2\sqrt{2}}\right\},\right
          \left\{-\frac{1}{2}, \frac{\sqrt{3}}{2}\right\}, \left\{-\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right\}, \left\{-\frac{\sqrt{3}}{2}, \frac{1}{2}\right\}, \left\{-\frac{1+\sqrt{3}}{2\sqrt{2}}, \frac{-1+\sqrt{3}}{2\sqrt{2}}\right\}\right\}
In[69]:= Graphics[{ Point[angles]}]
Out[69]=
In[10]:= linearStrut =
            Table[Round[{Cos[t], Sin[t]} * #] & /@ (Range[15] - 8), {t, 0, 11\pi/12, \pi/12}];
In[49]:= kernelFromStructure[structure_] := Block[
               {size = 2 Max @ Abs @ MinMax @ structure + 1},
               Transpose@ReplacePart[Table[0, size, size],
               Thread[Append[structure, \{0, 0\}] + \frac{\text{size} + 1}{2} \rightarrow 1]
In[78]:= GraphicsRow[showBinaryImage[kernelFromStructure[#]] & /@ linearStrut]
Out[78]=
In[21]:= kernels = kernelFromStructure[#] & /@linearStrut;
    Step 2: Applying Opening with L_i
In[22]:= AbsoluteTiming[erosionByLinearStrucImageList = Erosion[img, #] & /@ kernels]
In[28]:= AbsoluteTiming[erosionByLinearStrucImageDataList =
            ImageData[#] & /@erosionByLinearStrucImageList]
```

In[80]:= maxErosion = MapThread[Max, erosionByLinearStrucImageDataList, 2];

In[81]:= maskImage = Image[maxErosion]

But the built-in GeodesicOpening doesn't have imageMarker.

Therefore, I implemented GeodesicOpening myself.

$$\gamma^{\mathrm{rec}}_{S_0}$$
 = geodesic opening 
$$\gamma^{\mathrm{rec}}_{S_0}(S) = \sup_{d \in \mathbb{N}} \left( \Delta^d_{S_0}(S) \right) \ /\!/ \ S_0 = \mathrm{marker\,image}$$

Pick the maximum until the Dilation doesn't change

geodesicOpening[marker\_, mask\_]:= FixedPointList[GeodesicDilation[#, mask]&, marker]

geodesicOpening[marker\_, mask\_]:= In[89]:=

MapThread[Max, ImageData/@ FixedPointList[GeodesicDilation[#, mask]&, marker], 2]

In[82]:= markerImage = img;

<code>mgsj:= geodesicDilationList = geodesicOpening[markerImage, maskImage]</code>



|n[84]:= geodesicDilationImageDataList = ImageData/@geodesicDilationList

```
{{-1---}, {--1---}}
Out[84]=
        large output
                    show less
                                show more
                                             show all
                                                       set size limit...
```

In[05]:= AbsoluteTiming[SopData = geodesicOpening[markerImage, maskImage]]

```
\{0.271236, \{ \cdots 1 \cdots \} \}
Out[95]=
           large output
                             show less
                                              show more
                                                                show all
                                                                                set size limit...
```

In[96]:= Sop = Image[SopData]

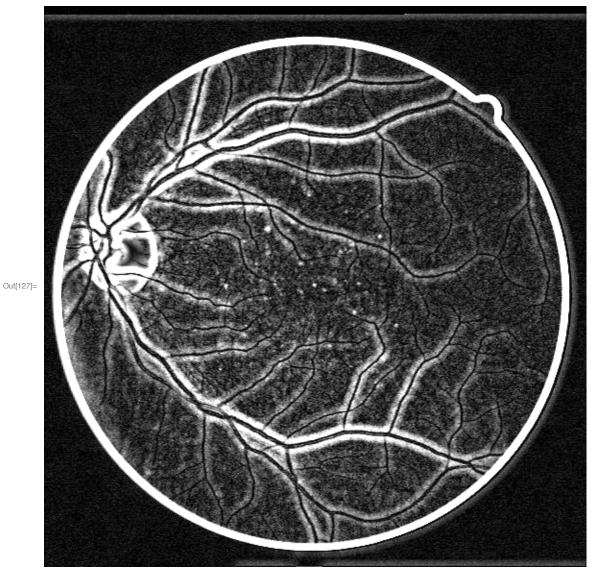
In[99]:= Dimensions /@ {erosionByLinearStrucImageDataList}

Out[99]=  $\{\{12, 584, 565\}\}$ 

In[119]:= AbsoluteTiming[topHatList = (SopData - #) & /@erosionByLinearStrucImageDataList]

In[126]:= AbsoluteTiming[SsumData = Total[topHatList]]

In[127]:= Ssum = Image[SsumData]



This transformation (a sum of top hats) reduces small bright noise and improves the contrast of all linear parts. Vessels could be manually segmented with a simple threshold on  $S_{\text{sum}}$ 

## **Alternating Filter**

#### In[123]:= ?GaussianFilter

 ${\it GaussianFilter}[{\it image}, r] {\it filters} {\it image} {\it by convolving with a Gaussian kernel of pixel radius} {\it r.}$ 

 $\text{GaussianFilter}[\textit{image}, \textit{r}, \{\textit{n}_1, \textit{n}_2\}] \text{ convolves } \textit{image} \text{ with a kernel formed from the } \textit{n}_i^{\text{th}} \text{ derivatives of the discrete Gaussian.}$ 

GaussianFilter[image,  $\{r, \sigma\}$ , ...] uses a Gaussian kernel with radius r and standard deviation  $\sigma$ .

GaussianFilter[image, { $\{r_1, r_2\}$ , ...}] uses radii  $r_i$  etc. in vertical and horizontal directions.

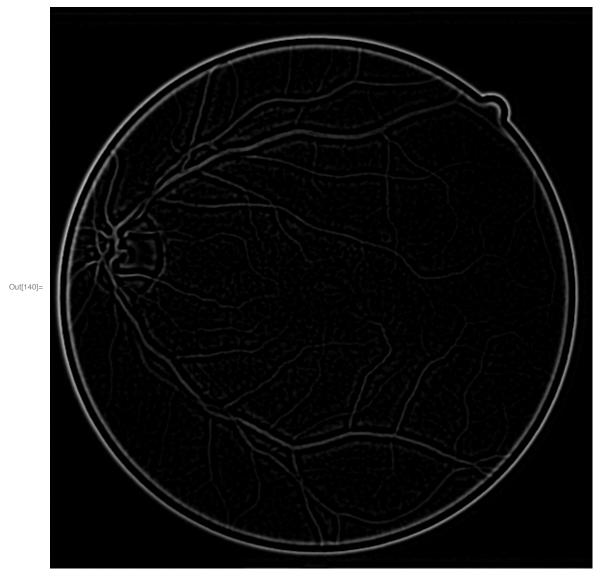
GaussianFilter[data, ...] applies Gaussian filtering to an array of data.  $\gg$ 

#### In[128]:= GaussianFilter[Ssum, {7, 7/4}]



Out[128]=

ln[140]:= Slap = LaplacianFilter[GaussianFilter[Ssum,  $\{7, 7/4\}], 1]$ 



## Final Result

## SI

- 1. Apply Erosion with Linear Structure Element
- In[142]:= SlapErosionByLinearStrucImageList = Erosion[Slap, #] & /@ kernels;
  - 2. Pick the Maximum pixel-wise

In[143]:= AbsoluteTiming[SlapErosionByLinearStrucImageDataList = ImageData[#] & /@ SlapErosionByLinearStrucImageList]



In[154]:= slapMaxData = MapThread[Max, SlapErosionByLinearStrucImageDataList, 2];

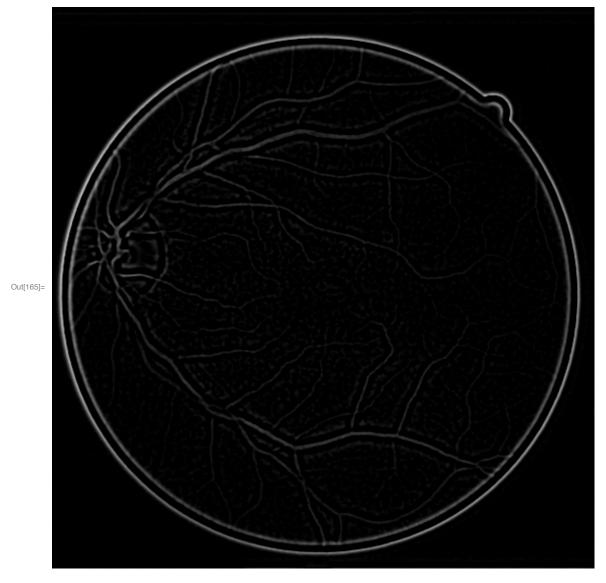
3. Apply GeodesicOpening

In[163]:= slapMax = Image[slapMaxData]

In[164]:= S1Data = geodesicOpening[Slap, slapMax]



In[165]:= S1 = Image[S1Data]

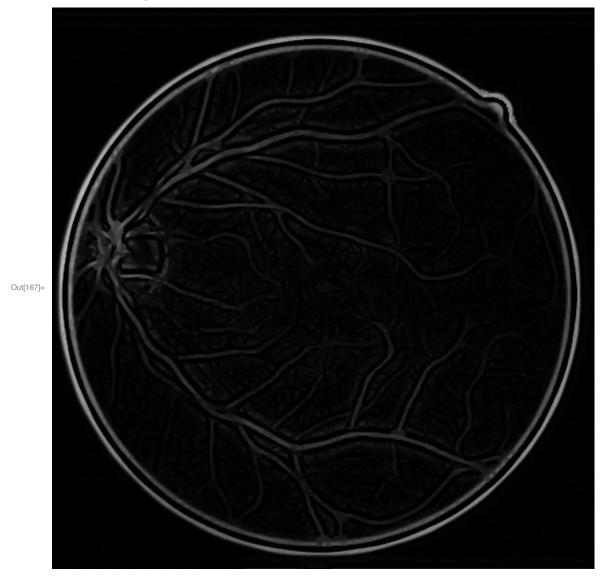


## **S2**

- 1. Apply Dilation with Linear Structure Element
- In[159]:= SlapDilationByLinearStrucImageList = Dilation[S1, #] & /@ kernels;
  - 2. Pick the Maximum pixel-wise
- In[160]:= AbsoluteTiming[SlapDilationByLinearStrucImageDataList = ImageData[#] & /@ SlapDilationByLinearStrucImageList]



In[166]:= slapMinData = MapThread[Min, SlapDilationByLinearStrucImageDataList, 2]; In[167]:= slapMin = Image[slapMinData]

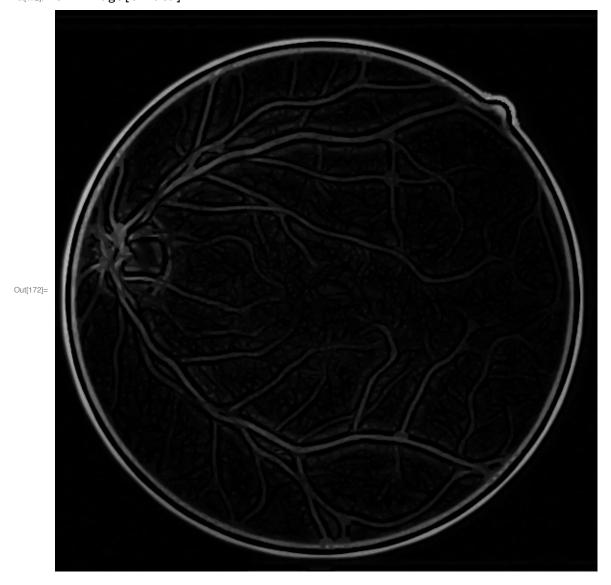


3. Apply GeodesicOpening with marker image = S1

In[169]:= S2Data = geodesicOpening[S1, slapMin]



In[172]:= S2 = Image[S2Data]



 $S_{\text{res}}$ 

## new linear struct e = 2

In[222]:= linearStrut30 = Table[Round[{Cos[t], Sin[t]} \* #] &/@ (Range[30] - 16), {t, 0,  $11\pi/12$ ,  $\pi/12$ }];

In[223]:= GraphicsRow[showBinaryImage[kernelFromStructure[#]] & /@linearStrut30]

Out[223]=

In[224]:= kernels30 = kernelFromStructure[#] & /@linearStrut30;

## I. Erosion with $L_i$ e = 2

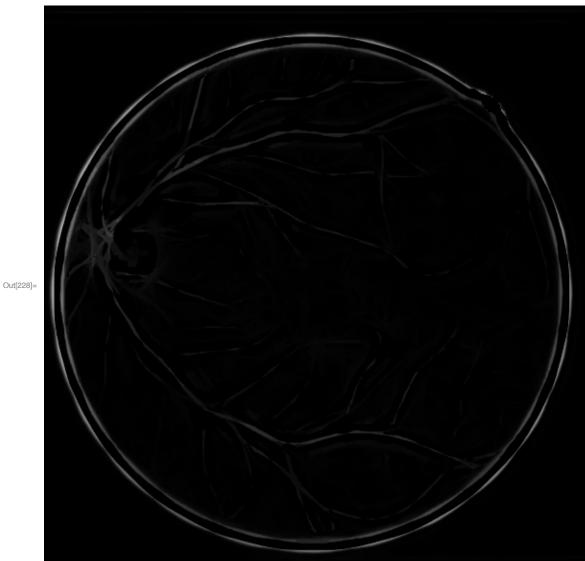
In[225]:= erosionOnSres = Erosion[S2, #] & /@kernels30

n[226]≔ erosionOnSresData = ImageData /@erosionOnSres;

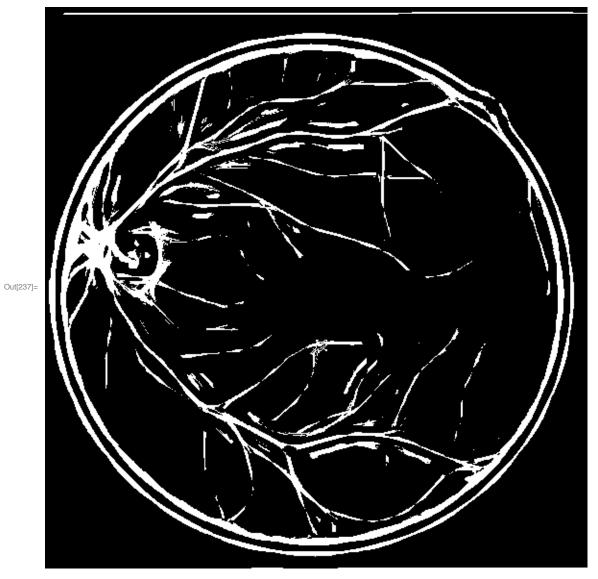
## 2. Pick maximum

In[227]:= erosionOnSresMaxData = MapThread[Max, erosionOnSresData, 2];

In[228]:= Sres = Image[erosionOnSresMaxData]



In[237]:= bin = Binarize[Sres, 0.025]



In[238]:= binData = ImageData[bin];

In[239]:= showGrayOverlay[imgData, binData]

