

Introduction COMP / ELEC / STAT 502

<http://www.ece.rice.edu/~erzsebet/ANNcourse.html>



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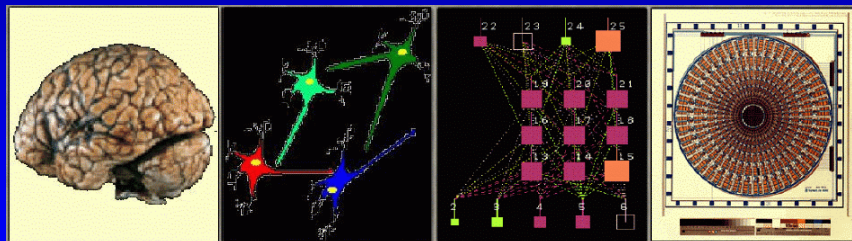
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What is an ANN?

For the neurobiologist:
mathematical model of
the nervous system

For the computational scientist:
biologically inspired
computing architecture



To mimic the smarts of brain-like
information processing



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An ANN is ...

- **Massively parallel**

A *very large number* of (usually) identical, densely interconnected processing units work parallel in time on one task.

- **Very finely distributed**

The units perform *very low level (usually identical) function*. ANN's can be viewed as "ultimate RISC machines"; ultimate level in Parallel Distributed Processing, finest granularity.

Current computer clusters:

- *High level function of CPUs*
- *Low connectivity*

ANNs:

- *Low level function of units*
- *Dense connectivity*

- **Learning machine**

Distribution of a task among the processing units is achieved by adaptation (learning), not by scheduling (programming).

Learning from data (examples, experience); acquire knowledge, store, & apply to solve new problems.



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The subject of ANN research

How does coordination / collaboration evolve
"on its own" among locally, individually acting
units, to solve tasks?

How can we control what kind of coordination /
collaboration evolves?

What inspiration can be found
from biology about PDP?

What can the computational
side tell about biology?



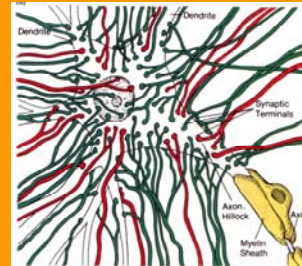
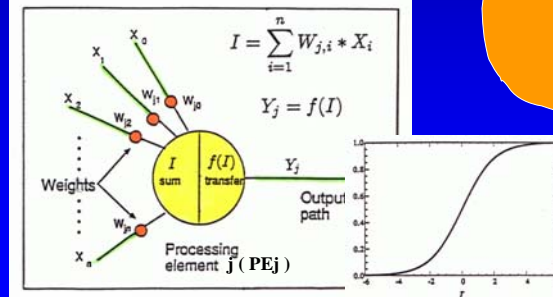
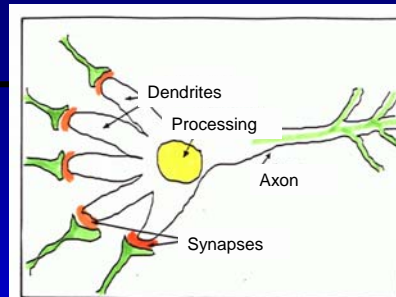
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The building block of ANNs

Artificial neuron model



(From Wessels & Hopson: Biology)

More at "Neuroscience for Kids", under "Additional Links of Interest" at the course web site.



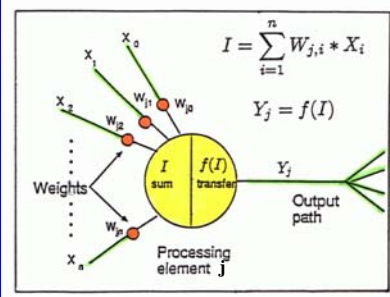
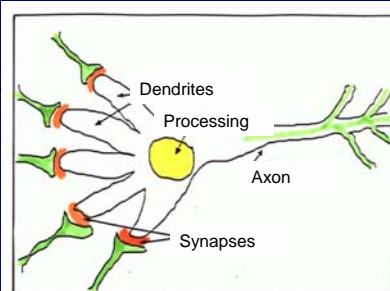
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The building block of ANNs

Artificial neuron model



Processing cycle in nervous systems

(= receiving data through dendrites & reacting by adapting the synaptic strength and firing, then recovering)

~ 20 – 50 msec

SLOW

Connectivity in real nervous systems

$10^3 - 10^4$ synapses per neuron;

~ 10^9 neurons in the human brain;

With 10^2 cycles / sec,

~ $10^{15} - 10^{16}$ ops/sec

a LOT

Real intelligence is thought to be related to this kind of computational bandwidth. Computers are not yet there.

Consider: PE with $f(I) = I$ is a correlator: max response is for $w = x$ (the stored weight = memory, recognizes x). Each PE can recognize a different pattern \Rightarrow combined effect is powerful

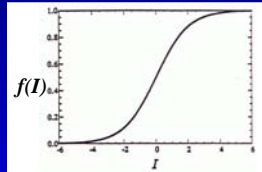


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Transfer functions in Processing Elements



Desirable properties:

- Monoton non-decreasing
- Non-linear
- Bounded (asymptotically)
- Largest change is at intermediate range.
Least change is at extremes.
- Derivative is easy to compute

Examples from MATLAB NN Toolbox

dhardlim

Hard limit function

Dhardlms

Symmetric hard limit (Heaviside)

Dlogsig

Log sigmoid (logistic, in figure)

Dposlin

Positive linear

dpurelin

Linear

dradbas

Radial basis

dtansig

Hyperbolic tangent sigmoid

HW: Study and know transfer functions

$$f(x) = \frac{1}{1 + e^{-ax}}$$

$$f(x) = a \frac{e^{bx} - e^{-bx}}{e^{bx} + e^{-bx}}$$



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Schematics of an ANN

(a typical supervised example)

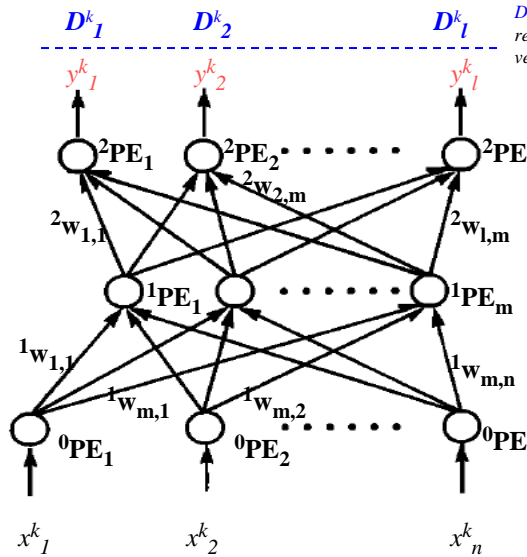
2-layer
ANN

Output
buffer
layer 2

Hidden
layer
layer 1

Input
buffer
layer 0

Many iterations ...



Desired outputs: Target
responses for k^{th} input
vector, from teacher

Output vector:
actual values
computed by ANN

Learning:
Adaptation of
weights at every
time step (k),
based on $(y-D)$
according to a
learning rule,
such that the
output gets closer
to the target. The
learned ANN can
predict for
unseen patterns.
The knowledge is
stored in the
weights.

k^{th} input vector
(training pattern)



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Schematics of an ANN, cont'd

Learning:

- *Adaptation of the weights* at every time step (k), in response to a training pattern \mathbf{x}^k , *according to a learning rule*, such that the output y^k gets closer to the target \mathbf{D}^k . Training is finished when all training patterns are recognized satisfactorily. The knowledge is stored in the weights.
- The goal is to learn to *generalize*, i.e., for the ANN to be able to predict / recognize unseen patterns (patterns that were not part of the training set). Generalization performance is measured on *test patterns*.

Major types of machine learning:

Supervised

Unsupervised

Reinforcement

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The learning rule of an ANN

$$F: \mathbf{W}^{old} \longrightarrow \mathbf{W}^{new} \quad \mathbf{W}^{old} = \mathbf{W}(t), \quad \mathbf{W}^{new} = \mathbf{W}(t+1), \quad t: \text{time step}$$

$$F(\mathbf{W}^{old}, \mathbf{x}, \mathbf{y}, \mathbf{D}, \{\text{learning parameters}\}) = \mathbf{W}^{new}$$



Learning is data driven, the final 'brain' is determined by the training data

\mathbf{W} : weight matrix
 \mathbf{x} : input vector at t
 \mathbf{y} : output vector at t
 \mathbf{D} : target vector

At every time step t , a different training pattern $\mathbf{x} = \mathbf{x}^k$ is chosen randomly, for input. $k=1, \dots, P$, P is the number of training patterns.

The learning rule of a given ANN paradigm may not have all of the above arguments. (For example, \mathbf{D} is not used for unsupervised learning.)

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ANN paradigms are defined by

- connection topology and data flow direction
 - fully or partially connected
 - feed forward or feed back (e.g., recurrent nets)
 - numerous combinations
- transfer function
 - non-linear transfer function makes ANNs powerful
- learning rule

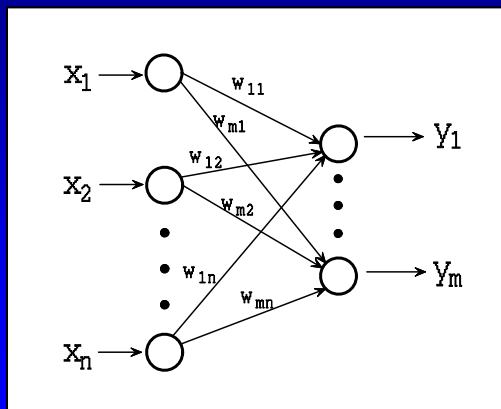


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Example: Simple Perceptron or ?



Topology:

- Fully connected, 1-layer
- Feed forward

This could be a

- Simple perceptron
- Associative memory
- Principal Components network

Depending on the choice of

Transfer function:

- {Sigmoid | hyperbolic tangent | linear | linear}

Learning rule:

- {Delta | Hebb/supervised | Hebb/unsupervised}

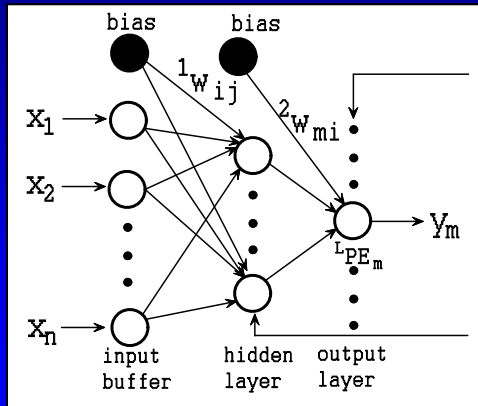


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Example of Multilayer Perceptron (Back Propagation Network)



Topology:

- Fully connected
- Feed forward, 2-layer (2 layers of weights !!)

Transfer function:

- Sigmoid, or hyperbolic tangent

Learning rule:

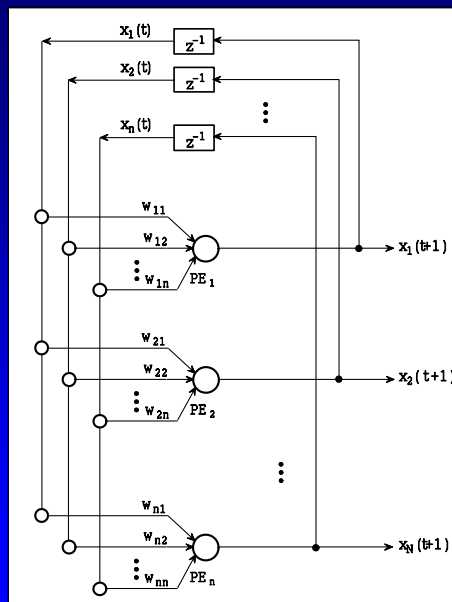
- Error Back Propagation



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Example: Recurrent Network (Hopfield Net)

Topology:

- Feed back, no layers

Transfer function:

- Identity

Learning rule:

- Hopfield



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Some standard ANN paradigms (often found in packages)

- Adaline and Madaline (old, historical)
- Adaptive Resonance Theory (ARTxx)
- Associative Memory
- Back-Propagation (BP)
- Bi-Directional Associative Memory (BAM)
- Boltzmann Machine
- Cascade Correlation Network
- Hopfield Network
- Learning Vector Quantization (LVQxx)
- Neocognitron
- Perceptron (simple)
- Probabilistic Neural Network (PNN)
- Radial Basis Function Network (RBF net)
- Recirculation Network
- Self-Organizing Map (SOM)



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Types of tasks ANN's are good for

ANNs perform well on types of tasks on which humans traditionally perform well and serial computers do not.

These are tasks which are easier to solve by learning from examples than by defining rules, because

- the *rules are not (well) known*
- the *rules are too complicated* or impractical to formulate

Wide range of applications: pattern recognition, classification, clustering (structure discovery), data compression, feature extraction, optimization, image restoration, speech analysis, forecasting, time series analysis, real time process control, system identification, ...

Many different ANN paradigms (both supervised and unsupervised) have been devised for different types of tasks.



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ANN computation has sound mathematical foundations

some

Theoretically proven fact:
A 3-layer ANN with non-linear transfer function is capable of learning any functional mapping.

Hecht-Nielsen, R. (1989) "Theory of the Backpropagation Neural Networks", IJCN on Neural Networks, Vol. 1, Washington, DC, pp 593-605

Hornik, K., (1991) "Approximation Capabilities of Multilayer Feedforward Networks", Neural Networks, Vol. 4, pp. 251-257

Kreinovich, V. Ya. (1991) "Arbitrary Nonlinearity Is Sufficient to Represent All Functions by Neural Networks: A Theorem", Neural Networks, Vol. 4, pp. 381-383



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Approximation capabilities of ANNs

STRUCTURE	TYPES OF DECISION REGIONS	EXCLUSIVE OR PROBLEM	CLASSES WITH MESHED REGIONS	MOST GENERAL REGION SHAPES
SINGLE-LAYER 	HALF PLANE BOUNDED BY HYPERPLANE			
TWO-LAYER 	CONVEX OPEN OR CLOSED REGIONS			
THREE-LAYER 	ARBITRARY (Complexity Limited By Number of Nodes)			

Source: R. P. Lippman, "An Introduction to Computing with Neural Nets"
IEEE ASSP Magazine, April 1987, p. 4



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Major journals / publications

Neural Networks

Journal of the Int'l Neural Network Society; European NN Society; and Japanese NN Society

IEEE Transactions on Neural Networks

Journal of the IEEE Computational Intelligence Society (formerly NN Society)

Neurocomputing (Elsevier)

Neural Processing Letters

Biological Cybernetics

Springer series "Lecture Notes in Computer Science" and "Lecture Notes in Artificial Intelligence"

Many ANN-related articles are submitted to Computational Intelligence (CI) AI, and Soft Computing type journals and conferences.



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Some tools

MATLAB NN Toolbox

NeuralWorks Professional Plus, by NeuralWare, expensive, proprietary (in my research environment)

Free software

- Stuttgart Neural Network Simulator (SNNS) -- at your own risk.
- LVQ PAK, SOM PAK
- SOM Toolbox for MATLAB
- FastICA Package for MATLAB
- more

Download these from "Free Software" link, under "Additional links of interest" at the course web site. Scroll down to Freeware and Shareware.

For this course, you will have to code most NNs that we use.



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