Xihao Zhu’s lab03 written part.

In this project I did it by myself. I think I finished p1-p4(puma 560 part) smoothly but had no time and effort to deal with FANUC part any more. Robot Simulation can give us visualization of how actually robot moves in reality and it can tell us is a specific location that robot’s ‘hand’ can reach or not, which is very useful to robotic problem in reality.