



Societal Importance of Spatial Fairness

A glimpse of spatial fairness:

	Spatially Fair			Spatially Biased		
Overall Accuracy:	80%			80%		
Accuracy by location:	80%	80%	80%	100%	100%	100%
	80%	80%	80%	100%	40%	100%
	80%	80%	80%	100%	40%	40%

- If left unattended, spatial bias may cause unfair distribution of resources, social division, spatial disparity in sustainability.

Energy Budget: Temperature estimation

- Risk of unfair temperature estimation...
- Risk of unfair heat energy projections...

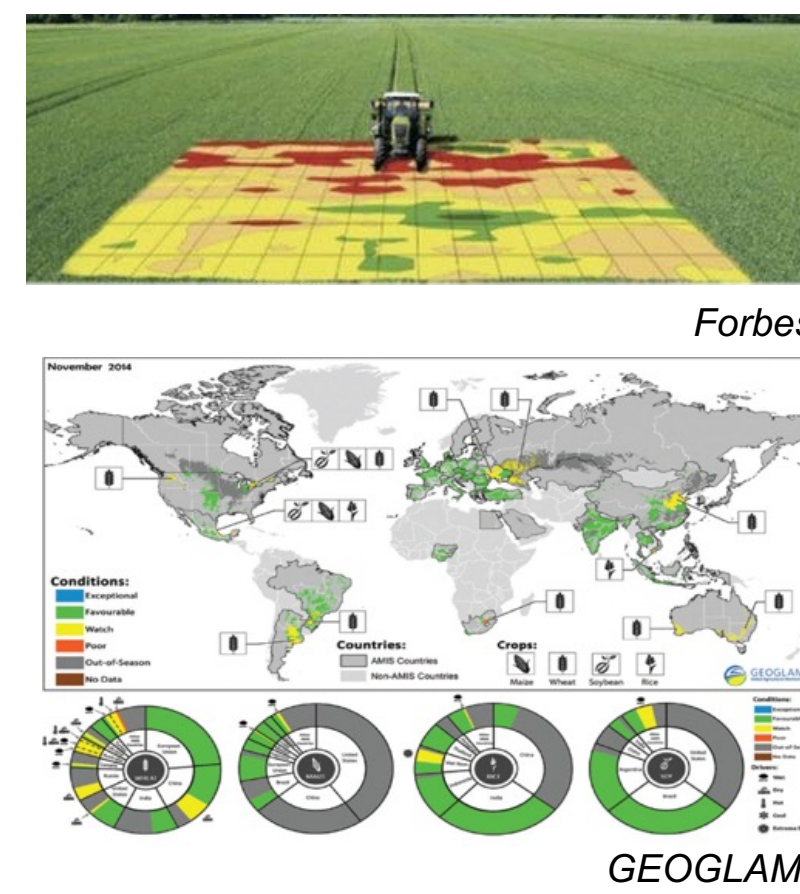
Agriculture: Crop monitoring

- Machine learning based crop mapping
 - G20's GEOGLAM, NASA Harvest, ...
- Risk of unfair distribution of subsidies...

Natural disasters: Flood mapping

- Risk of unfair distribution of resources...
- Risk of unfair estimation of insurance rates...

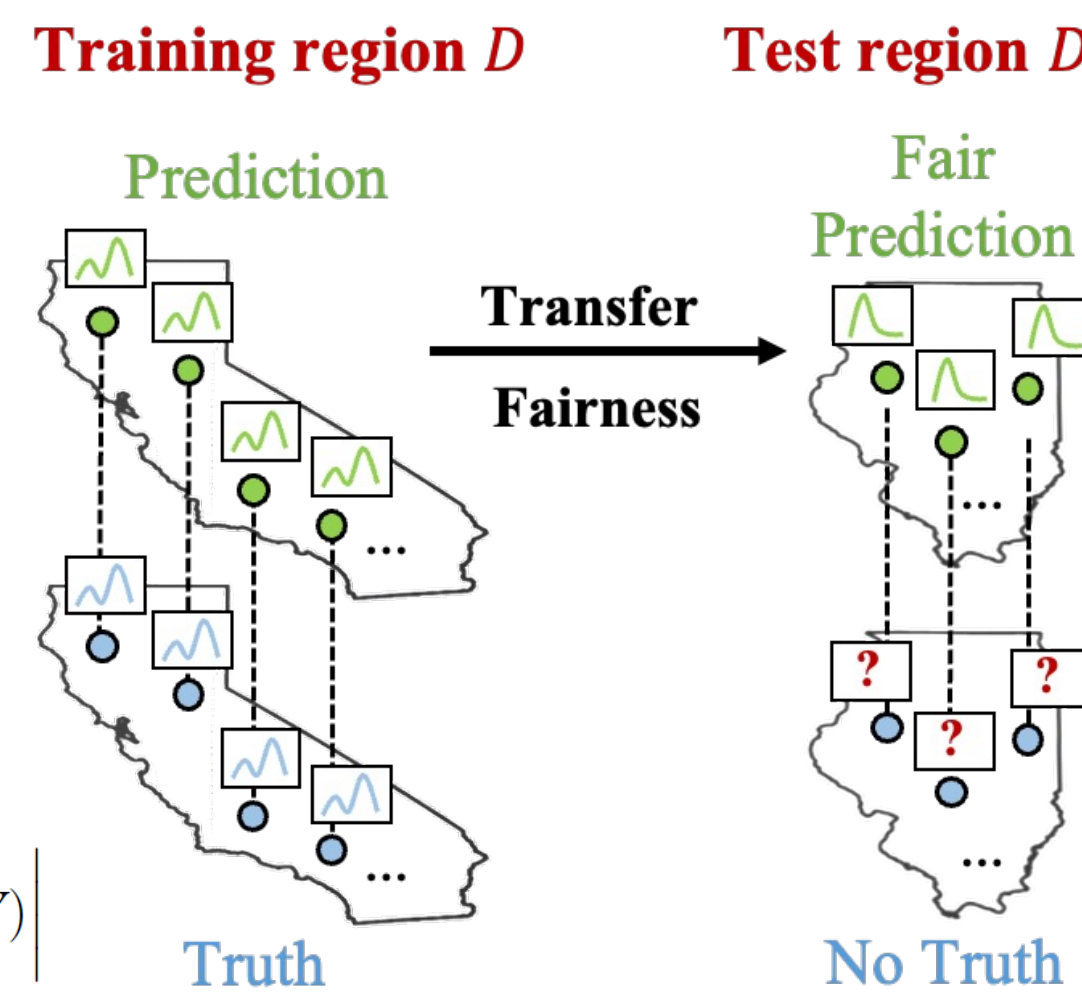
...



Problem Definition

- Inputs**
 - \mathbf{X} : Input features.
- Outputs**
 - \mathbf{Y}_{pred} : fairer predictions.
- Objectives**
 - Prediction performance
 - RMSE, ...
 - Transfer Fairness to test

$$\mathcal{L}_f = \frac{1}{|S|} \sum_{s_i \in S} |\mathcal{L}_p(\mathcal{F}(x_i), y_i) - \overline{\mathcal{L}_p(\mathcal{F}(X), Y)}|$$

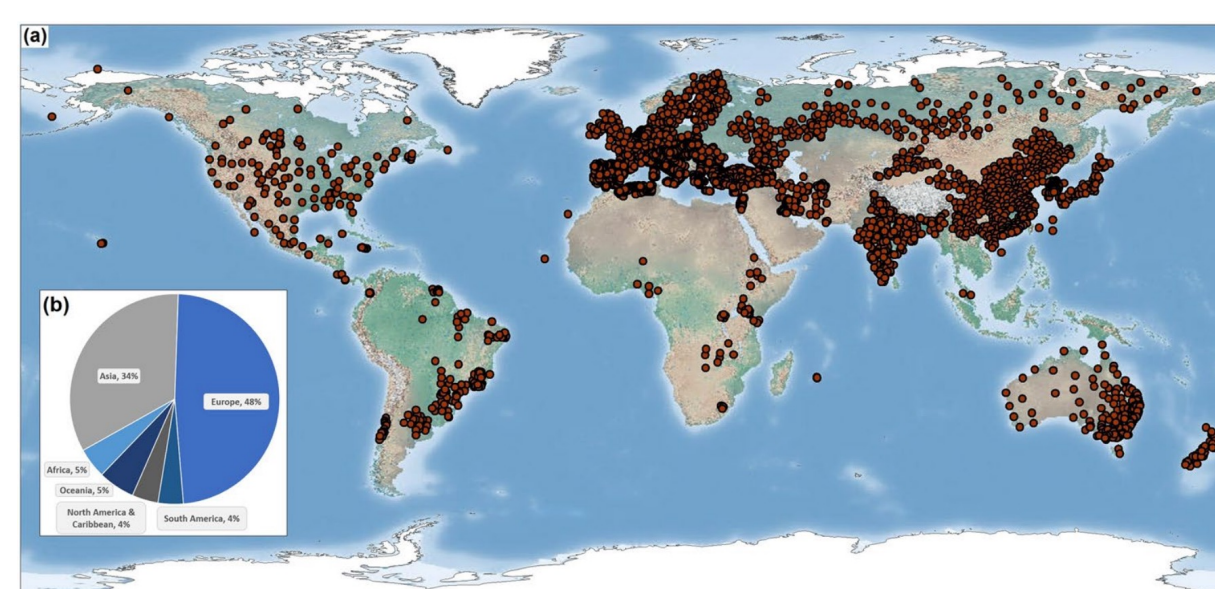


Challenges

- Test groups are **not prefixed** and can be **highly dynamic**.
 - Difficult to transfer learning objectives from train to test.
- No truth** available in test regions.



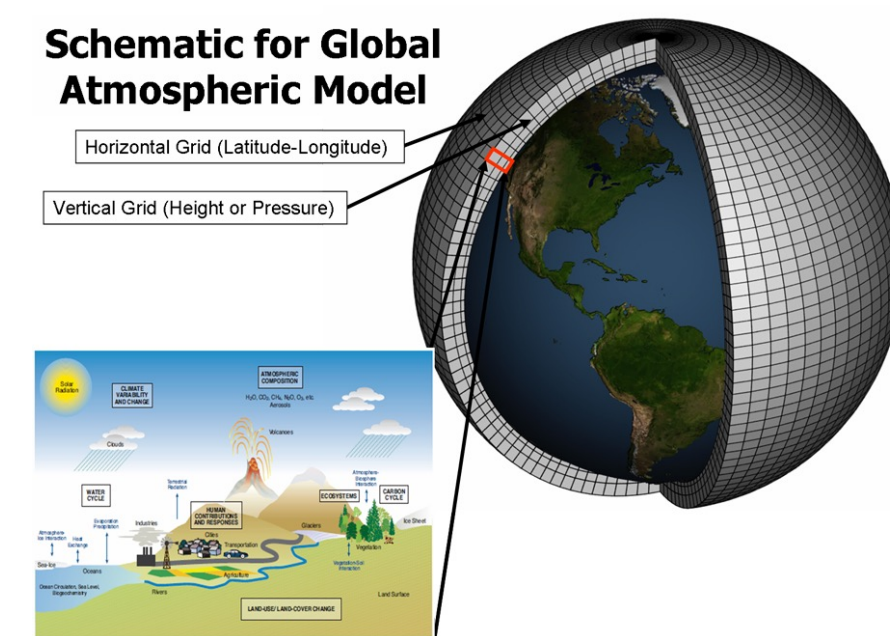
Distribution of U.S. Climate Reference Network



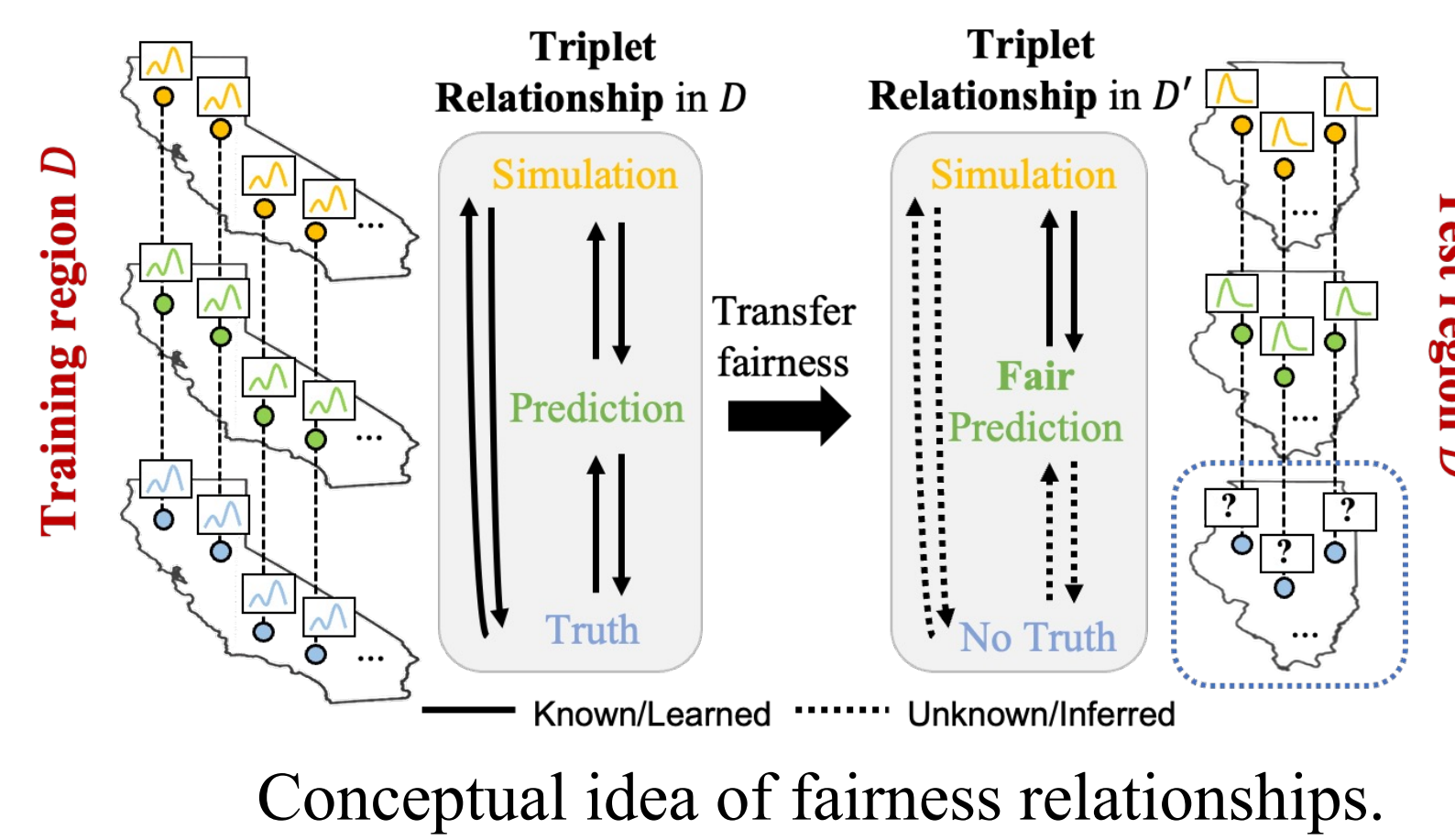
Global distribution of rainfall stations
Scientific Report, 2017

Contributions

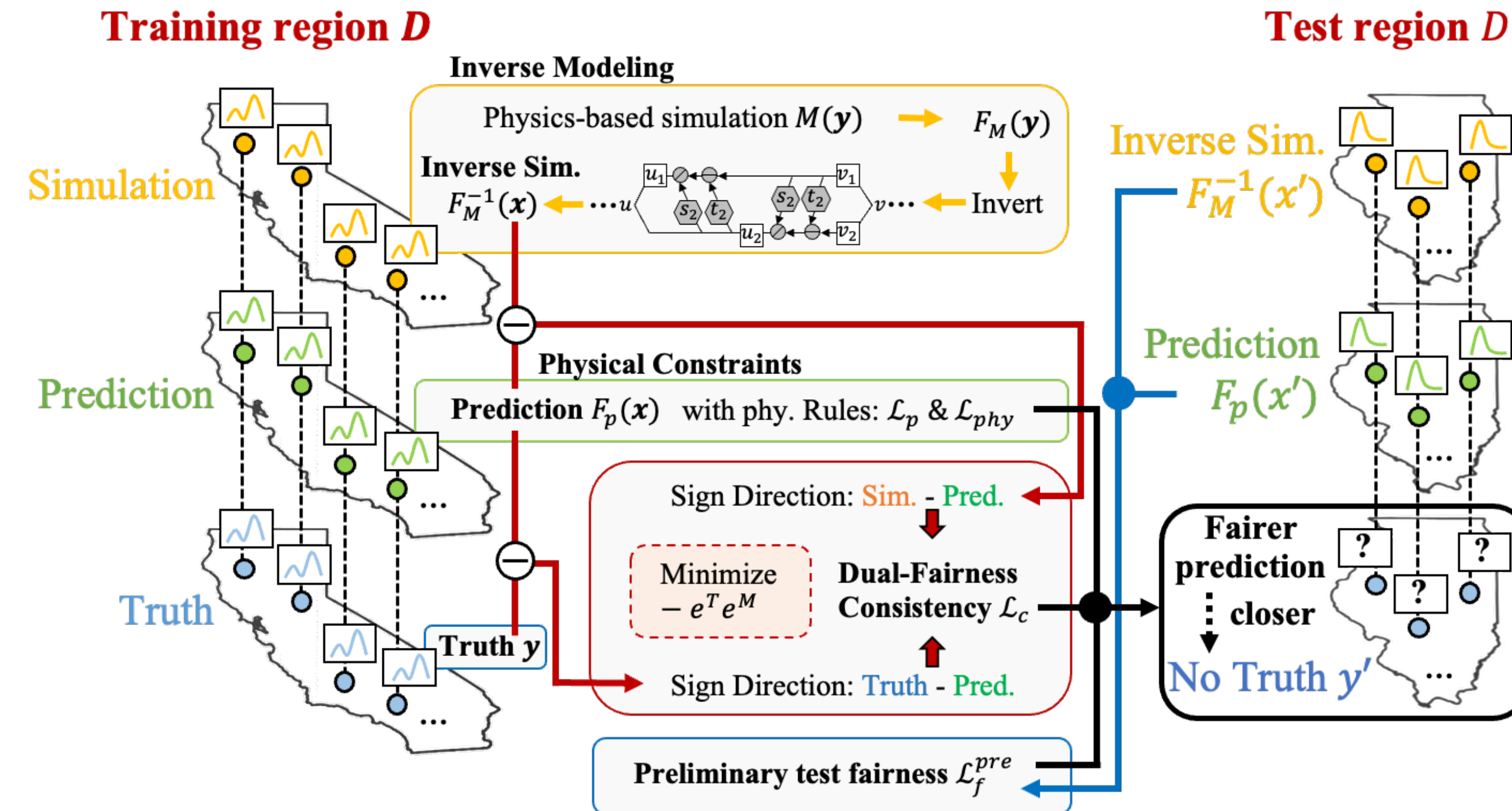
- A **Dual-fairness consistency** to improve fairness to new locations by reducing the gap between simulations and predictions.
- An **inverse-modeling** design to align the physics-based simulation with the learning objectives for embedding physical laws.
- Physical-rule-based constraints** to improve prediction performance.



Simulation models: (1) unlimited theoretical labels, (2) flexible spatio-temporal sets of location.



SimFair Framework

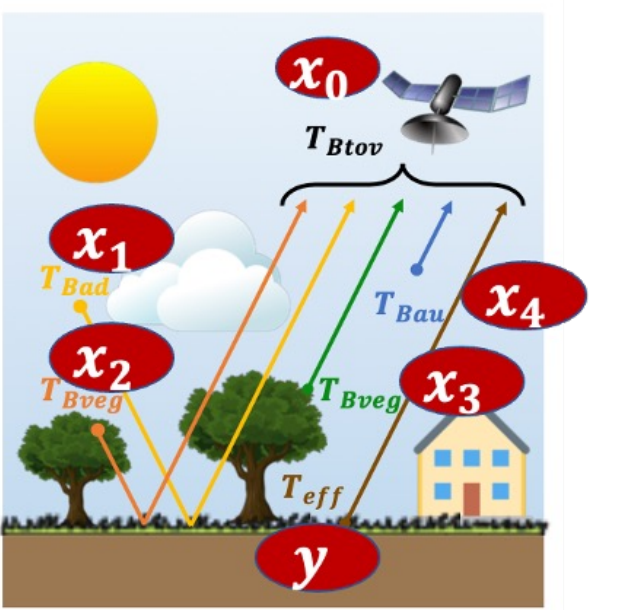
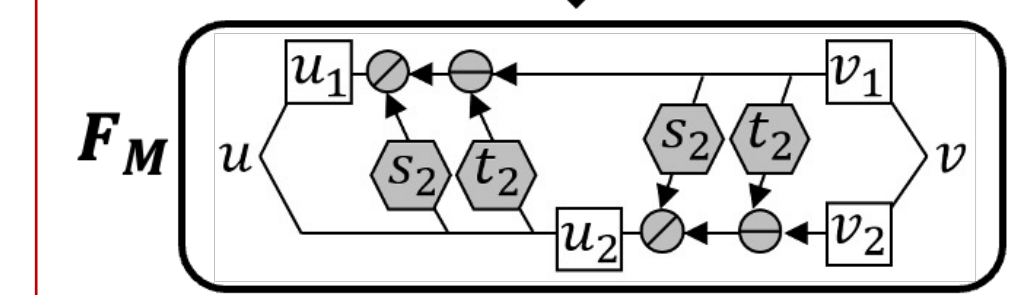


Inverse Modeling

A bijector-based invertible network F_M .

- Forward path: learn **prior physical knowledge** in M .

$$x_0 = F_M(y, x_1, x_2, x_3, x_4)$$

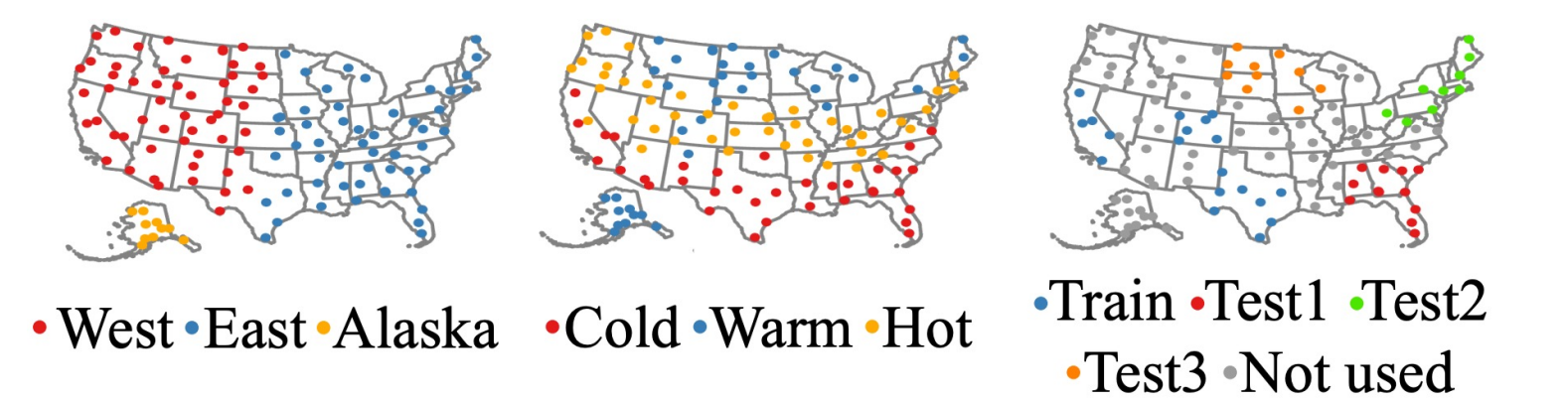


A physical model M .
 $x_0 = M(y, x_1, x_2, x_3, x_4)$

- Inverse path: output target y .
 $y, x_1, x_2, x_3, x_4 = F_M^{-1}(x_0)$

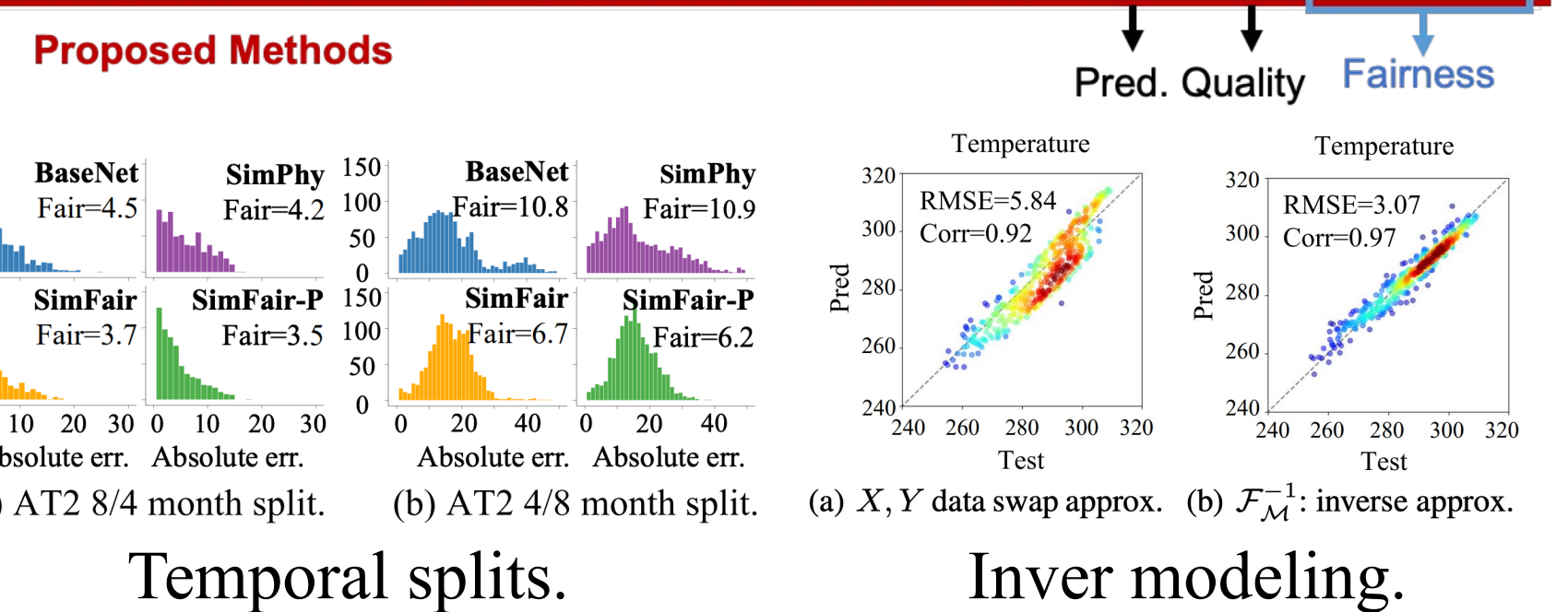
Experiment Results

Spatial distributions of temperature data:



Results:

	Model	Train-Test: West-East			Train-Test: East-West			Train-Test: East-Alaska		
		RMSE	Corr.	Fairness	RMSE	Corr.	Fairness	RMSE	Corr.	Fairness
FNN	BaseNet	6.75	0.83	4.49 (± 0.81)	27.56	0.34	13.65 (± 2.48)	52.03	0.19	44.42 (± 3.37)
	Sim	6.45	0.86	4.69 (± 0.82)	20.33	0.44	11.93 (± 2.19)	43.74	0.29	38.84 (± 5.69)
	SimPhy	7.19	0.84	5.56 (± 0.4)	17.78	0.48	10.79 (± 1.98)	45.52	0.29	38.84 (± 3.4)
	RegFair	7.22	0.8	4.97 (± 0.69)	25.35	0.37	12.36 (± 2.42)	38.5	0.06	29.73 (± 6.78)
	Self-Reg	6.35	0.84	4.27 (± 0.7)	31.97	0.31	16.48 (± 2.42)	38.01	0.06	28.95 (± 4.15)
	SimFair	3.07	0.97	2.04 (± 0.19)	3.11	0.96	1.94 (± 0.08)	6.23	0.84	4.25 (± 0.78)
LSTM	SimFair-P	2.88	0.97	1.89 (± 0.06)	3.13	0.96	1.96 (± 0.05)	6.29	0.81	4.45 (± 0.51)
	BaseNet	4.22	0.93	2.66 (± 0.14)	4.02	0.97	2.45 (± 0.16)	11.93	0.8	5.14 (± 0.31)
	Sim	3.89	0.95	2.43 (± 0.15)	3.3	0.97	2.21 (± 0.40)	13.32	0.85	5.25 (± 0.49)
	SimPhy	4.46	0.95	2.69 (± 0.17)	3.23	0.97	2.04 (± 0.17)	12.27	0.88	4.82 (± 0.28)
	RegFair	4.17	0.94	2.66 (± 0.22)	4.03	0.96	2.59 (± 0.58)	12.16	0.81	5.03 (± 0.4)
	Self-Reg	4.10	0.94	2.57 (± 0.26)	3.85	0.96	2.41 (± 0.16)	11.24	0.84	4.68 (± 0.41)
	SimFair	3.46	0.96	2.21 (± 0.11)	3.22	0.98	1.91 (± 0.11)	11.05	0.86	4.55 (± 0.27)
	SimFair-P	3.35	0.96	2.12 (± 0.11)	3.24	0.97	1.99 (± 0.17)	10.52	0.89	4.15 (± 0.23)



Conclusions

SimFair: a simulation-guided fairness-aware learning

- transfer fairness to the regions without truth;
- inversely model simulations to align learning objectives;
- softly regularize predictions using physical constraints.

Future: expand to more knowledge- or rule-based models with various domain tasks for fairness-aware learning.

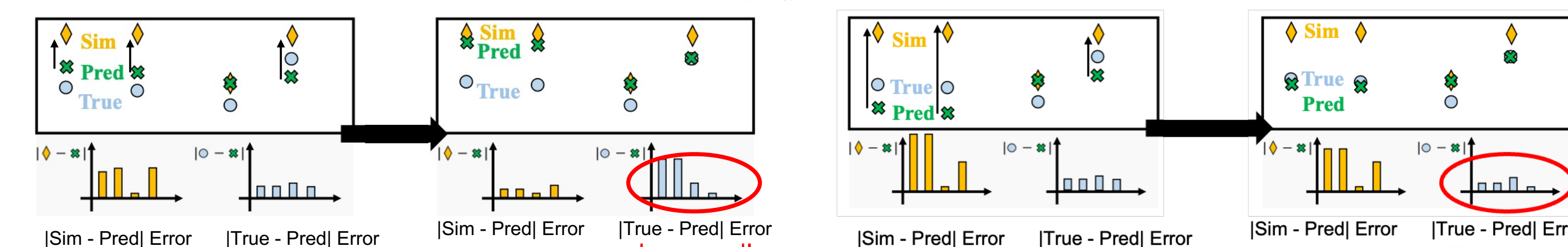
Acknowledgements



Dual-Fairness Consistency

- Goal: to make **predictions** closer to **truth** given **simulations**.
- How: learn **triplet relationships** to have better initial conditions for predictions.

$$\mathcal{L}_c = -\mathbf{e}^T \mathbf{e}_M = - \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - \mathcal{F}_p(x_i)) \cdot (\mathcal{F}_M^{-1}(x_i) - \mathcal{F}_p(x_i))$$



Normal training process.

Dual-fairness-guided training process.