# **Lecture #7: Naïve Bayes**

#### **Probabilistic Classifier Learning Approaches**

 To learn a probabilistic classifier, there are two types of approaches

#### • Generative:

- ightharpoonup Learn P(y) and  $P(\mathbf{x}|y)$
- ightharpoonup Compute  $P(y|\mathbf{x})$  using Bayes rule

$$P(y|\mathbf{x}) = \frac{P(\mathbf{x}|y)P(y)}{P(\mathbf{x})} = \frac{P(\mathbf{x}|y)P(y)}{\sum_{y} P(\mathbf{x}, y)}$$

#### Discriminative:

- ightharpoonup Learn  $P(y|\mathbf{x})$  directly
- Logistic regression is one of such techniques

## **Bayes Classifier**

• Generative model learns p(y) and p(x|y)

Prediction is made by

$$p(y|\mathbf{x}) = \frac{p(\mathbf{x}|y)p(y)}{p(\mathbf{x})} = \frac{p(\mathbf{x}|y)p(y)}{\sum_{y} p(\mathbf{x}, y)}$$

 Often referred to as the Bayes Classifier due to using the Bayes rule

## **Joint Density Estimation**

• More generally, learning  $p(\mathbf{x}|y)$  is a density estimation problem, which is a challenging task

• Now we will consider the case where  $\mathbf{x}$  is a d-dimensional binary vector

• How to learn  $P(\mathbf{x}|y)$  in this case?

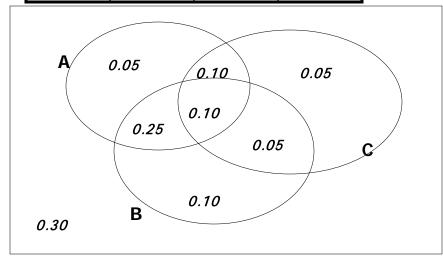
# The Joint Distribution

Example: Boolean variables A, B, C

Recipe for making a joint distribution of M variables:

- Make a truth table listing all combinations of values of your variables (M Boolean variables ⇒ 2<sup>M</sup> rows).
- 2. For each combination of values, say how probable it is.
- If you subscribe to the axioms of probability, those numbers must sum to 1.

A	В	С	Prob
0	0	0	0.30
0	0	1	0.05
0	1	0	0.10
0	1	1	0.05
1	0	0	0.05
1	0	1	0.10
1	1	0	0.25
1	1	1	0.10



# Learning a joint distribution

Build a JD table in which the probabilities are unspecified

A	В	С	Prob
0	0	0	?
0	0	1	?
0	1	0	?
0	1	1	?
1	0	0	?
1	0	1	?
1	1	0	?
1	1	1	?

Fraction of all records in which A and B are True but C is False

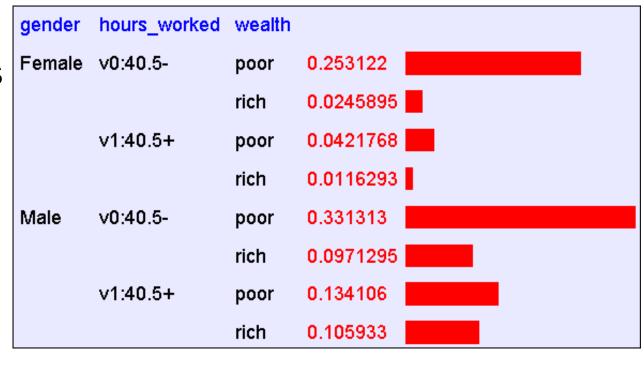
Then fill in each row with

$$\hat{P}(\text{row}) = \frac{\text{records matching row}}{\text{total number of records}}$$

Α	В	С	Prob
0	0	0	0.30
0	0	1	0.05
0	1	0	0.10
0	1	1	0.05
1	0	0	0.05
1	0	1	0.10
1	1	0	0.25
1	1	1	0.10

# Example of Learning a Joint

 This Joint was obtained by learning from three attributes in the UCI "Adult" Census Database [Kohavi 1995]



UCI machine learning repository: http://www.ics.uci.edu/~mlearn/MLRepository.html

## **Learning Joint Distribution and Overfitting**

• Let  $\mathbf{x}$  be a d-dimensional binary vector, and  $y \in \{1,2,\ldots,k\}$ 

- Learning the joint distribution  $P(\mathbf{x}|y=i)$  for i=1,...,k involves estimating  $k \times (2^d-1)$  parameters
  - ightharpoonup For large d, this number is prohibitively large
  - Not enough data to estimate the joint distribution accurately
  - ^ Common to encounter the situation where no training examples have the exact  $\mathbf{x} = [u_1, ..., u_d]^T$  value combination
  - ↑ Then  $P(\mathbf{x} = [u_1, ..., u_d]^T | y = i) = 0$  for all values of i
  - This will lead to severe overfitting

#### **Naïve Bayes Assumption**

- Assumption: each feature is independent from one another given the class label
- **Definition:** x is **conditionally independent** of y given z, if the probability distribution governing x is independent of the value of y, given the value of z  $\forall i, j, k \ P(x = i|y = j, z = k) = P(x = i|z = k)$  Often denoted as p(x|y,z) = p(x|z)

#### • Example:

```
p(thunder|raining, lightening)
= p(thunder|lightening)
```

#### Conditional Independence vs. Independence

#### Conditional Independence:

$$p(x,y|z) = p(x|z)p(y|z)$$

or equivalently: p(x|y,z) = p(x|z)

• Independence:

$$p(x,y) = p(x)(y)$$

or equivalently: p(x|y) = p(x)

Conditional independence ≠ independence

#### **Naïve Bayes Classifier**

Under Naïve Bayes assumption, we have:

$$p(\mathbf{x}|y) = \prod_{i=1}^{d} p(x_i|y)$$

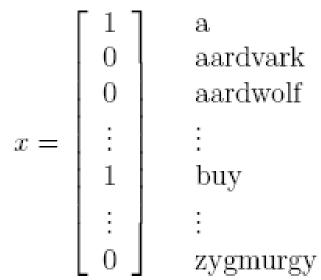
No need to estimate the joint distribution

• We only need to estimate  $p(x_i|y)$  for each feature i

- Example: with d binary features and k classes, we reduce the number of parameters from  $k(2^d-1)$  to kd
  - Significantly reduces overfitting

#### **Example: Spam Filtering**

- Bag-of-words representation to describe emails
- Represent an email by a vector whose dimension = the number of words in our "dictionary"
- Example: Bernoulli feature
  - $x_i = 1$  if the *i*-th word is present
  - $x_i = 0$  if the *i*-th word is not present



- The ordering/position of the words does not matter
- "Dictionary" can be formed by looking through the training set and identifying all the words & tokens that have appeared at least once (with stop-words like "the", "and" removed)

#### MLE for Naïve Bayes with Bernoulli Model

Suppose our training set contains N emails,
 maximum likelihood estimate of the parameters are:

$$P(y=1) = \frac{N_1}{N}$$
, where  $N_1$  is the number of spam emails

$$P(x_i = 1 \mid y = 1) = \frac{N_{i|1}}{N_1},$$

i.e., the fraction of spam emails where  $x_i$  appeared

$$P(x_i = 1 | y = 0) = \frac{N_{i|0}}{N_0}$$

i.e., the fraction of nonspam emails where  $x_i$  appeared

## **Naïve Bayes Prediction**

• To make a prediction for a new example with feature  $\mathbf{x} = [u_1, ..., u_d]^T$ 

$$P(y = 1 | \mathbf{x})$$

$$= \frac{P(y = 1) \prod_{i=1}^{d} P(x_i = u_i | y = 1)}{\sum_{y' \in \{0,1\}} P(y = y') \prod_{i=1}^{d} P(x_i = u_i | y = y')}$$

$$\propto P(y = 1) \prod_{i=1}^{d} P(x_i = u_i | y = 1)$$

#### **Discrete and Continuous Features**

- Naïve Bayes can be easily extended to handle features that are not binary-valued
- Discrete:  $x_i \in \{1, 2, ..., k_i\}$ 
  - ^  $P(x_i = j | y)$  for  $j ∈ \{1,2,...,k_i\}$  categorical distribution in place of Bernoulli
- Continuous:  $x_i \in R$ 
  - Discretize the feature, then build categorical distribution for each feature
  - When the feature does not follow Gaussian, this can result in a better classifier

#### **Problem with MLE**

- $^{ullet}$  Suppose you picked up a new word "Mahalanobis" in your class and started using it in your email x
- Because "Mahalanobis" (say it's the n+1 th word in the vocabulary) has never appeared in any of the training emails, the probability estimate for this word will be  $P(x_{n+1} = 1 | y = 1) = P(x_{n+1} = 1 | y = 0) = 0$
- Now  $P(\mathbf{x}|y) = \prod_i P(x_i|y) = 0$  for both y = 0 and y = 1
- Given limited training data, MLE can often result in probabilities of 0 or 1. Such extreme probabilities are "too strong" and cause problems

#### **Laplace Smoothing**

• Suppose we estimate a probability P(z) and we have  $n_0$  examples where z=0 and  $n_1$  examples where z=1 MLE estimate is

$$P(z = 1) = \frac{n_1}{n_0 + n_1}$$

 Laplace Smoothing: Add 1 to the numerator and 2 to the denominator

$$P(z=1) = \frac{n_1 + 1}{n_0 + n_1 + 2}$$

If we don't observe any examples, we expect P(z=1) = 0.5, but our belief is weak (equivalent to seeing one example of each outcome).

## MAP for Naïve Bayes Spam Filter

- When estimating  $p(x_i|y=1)$  and  $p(x_i|y=0)$ 
  - ▲ Bernoulli case:

$$P(x_i = 1 \mid y = 0) = \frac{N_{i|0}}{N_0} \Rightarrow P(x_i = 1 \mid y = 0) = \frac{N_{i|0} + 1}{N_0 + 2}$$
MLE

- When encounter a new word that has not appeared in training set, now the probabilities do not go to zero
- This is called Laplace Smoothing

## **MLE for Naïve Bayes with Multinomial Model**

• The likelihood of observing one email *E*:

$$p(y) \prod_{i}^{length of E} p(x_i|y)$$

• MLE estimate for the *i*-th word in the dictionary:  $p(x_i|y) = \frac{\text{total } \# \text{ of words } i \text{ in class } y \text{ emails}}{\text{total } \# \text{ of words in class } y \text{ emails}}$ 

• Total number of parameters?

$$^{\blacktriangle}$$
 *k*(|*D*| − 1)

## **Laplace Smoothing for Multinomial Case**

#### MLE:

$$p(w_i|y=0) = \frac{\text{total } \# \text{ of words } i \text{ in n-s emails}}{\text{total } \# \text{ of words in n-s emails}}$$

#### MAP:

$$p(w_i|y=0) = \frac{\text{total } \# \text{ of words } i \text{ in n-s emails+1}}{\text{total } \# \text{ of words in n-s emails+|D|}}$$

where |D| is the size of the dictionary

## **Naïve Bayes Summary**

- Generative classifier
  - ightharpoonup learn P( $\mathbf{x}|\mathbf{y}$ ) and P( $\mathbf{y}$ )
  - ightharpoonup Use Bayes rule to compute P( $y \mid x$ ) for classification

- Assumes conditional independence between features given class labels
  - Greatly reduces the numbers of parameters to learn

- MAP estimation (or Laplace smoothing) is necessary to avoid overfitting and extreme probability values
- In practice, a fast and solid baseline for text classification