Zi Wang

32-331, MIT Cambridge, MA 02139 ⊠ ziw@mit.edu 🗓 ziw.mit.edu



2014 - 2019

Education

Ph.D. Candidate in EECS, Massachusetts Institute of Technology

Cambridge, MA

- Thesis: Robot Learning With Strong Priors
- o Advisors: Prof. Leslie Pack Kaelbling and Prof. Tomás Lozano-Pérez

2014 - 2016

S.M. in EECS, Massachusetts Institute of Technology

Cambridge, MA

- Thesis: Optimization as Estimation with Gaussian Process Bandits o Advisors: Prof. Stefanie Jegelka and Prof. Leslie Pack Kaelbling

2010 - 2014

B.Eng. in Computer Science and Technology, Tsinghua University • Thesis: Fast Dropout Training for Deep Neural Networks (in Chinese)

Beijing, China

Advisors: Prof. Fei Sha and Prof. Jun Zhu

2019 2019 2018 2014-2015 Jul. 2014 Nov. 2013

Sep. 2013

Honors & Awards

Robotics: Science and Systems (RSS) Pioneers 2019.	Freiburg, Germany
MIT Graduate Women of Excellence 2019.	Cambridge, MA
Rising Stars in Electrical Engineering & Computer Science 2018.	Cambridge, MA
Greater China Computer Science Fellowship, MIT.	Cambridge, MA
Outstanding Graduates Award, Tsinghua.	Beijing, China
Science and Innovation Scholarship, Tsinghua.	Beijing, China
Anita Borg Scholarship, Google China.	Beijing, China



2013 - 2014 2012 - 2013

Professional Experience

Research Intern, Microsoft Research New England.	Cambridge, MA
Research Assistant, Learning and Intelligent Systems Group, CSAIL, MIT.	Cambridge, MA
Software Engineering Intern, Uber Advanced Technologies Group.	Pittsburgh, PA
Teaching Assistant, 6.883 Advanced Machine Learning, MIT.	Cambridge, MA
Research Assistant, Theoretical and Empirical Data Sciences Group, USC.	Los Angeles, CA
Research Assistant, State Key Lab of Intelligent Tech. & Systems, Tsinghua.	Beijing, China
Research Assistant, Future Internet Technology Sub-interest Group, Tsinghua.	Beijing, China



- Z. Wang, C. R. Garrett, J. Mao, K. Chen, S. Thompson, A. LaGrassa, N. Gothoskar, I. Jutamulia, J. Xu, L. P. Kaelbling, T. Lozano-Pérez. Learning for task and motion planning. In preparation.
- B. Kim, Z. Wang, L. P. Kaelbling, T. Lozano-Pérez. Learning to guide task and motion planning using score-space representation. International Journal of Robotics Research (IJRR), 2019.
- V. Xia*, Z. Wang*, K. Allen, T. Silver, L. P. Kaelbling. Learning sparse relational transition models. International Conference on Learning Representations (ICLR), 2019.
- Z. Wang*, B. Kim*, L. P. Kaelbling. Regret bounds for meta Bayesian optimization with an unknown Gaussian process prior. Advances in Neural Information Processing Systems (NeurIPS), 2018. Spotlight talk (3.5% acceptance rate).

- **Z.** Wang, C. R. Garrett, L. P. Kaelbling, T. Lozano-Pérez. Active model learning and diverse action sampling for task and motion planning. *International Conference on Intelligent Robots and Systems (IROS)*, 2018.
- **Z. Wang**, C. Gehring, P. Kohli, S. Jegelka. **Batched large-scale Bayesian optimization in high-dimensional spaces**. *International Conference on Artificial Intelligence and Statistics (AlStats)*, 2018.
- **Z.** Wang, S. Jegelka. Max-value entropy search for efficient Bayesian optimization. *International Conference on Machine Learning (ICML), 2017.*
- **Z.** Wang*, C. Li*, S. Jegelka, P. Kohli. **Batched high-dimensional Bayesian optimization via structural kernel learning**. *International Conference on Machine Learning (ICML)*, 2017.
- **Z.** Wang, S. Jegelka, L. P. Kaelbling, T. Lozano-Pérez. **Focused model-learning and planning for non-Gaussian continuous state-action systems**. *IEEE Conference on Robotics and Automation (ICRA)*, 2017.
- **Z.** Wang, B. Zhou, S. Jegelka. **Optimization as estimation with Gaussian processes in bandit settings**. *International Conference on Artificial Intelligence and Statistics (AlStats), 2016. Oral presentation (6% acceptance rate).*
- **Z. Wang**, F. Sha. **Discriminative non-negative matrix factorization for single-channel speech separation**. *IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP), 2014.*
- J. Chen, J. Zhu, **Z. Wang**, X. Zheng, B. Zhang. **Scalable inference for logistic-normal topic models**. *Neural Information Processing Systems (NIPS), 2013.*

Invited Talks

Human intelligence assisted robot learning.

- o Al Colloquium, University Stuttgart, Stuttgart, Germany, Jun 2019.
- Shift Technology, Paris, France, Jun 2019.

Active model learning and diverse action sampling for task and motion planning.

University of Washington, Seattle, WA, Sep 2018.

Regret bound of Bayesian optimization with unknown GP prior.

Microsoft Research Al Breakthroughs Workshop, Redmond, WA, Sep 2018.

Bayesian optimization guided by max-values.

International Symposium on Mathematical Programming (ISMP), Bordeaux, France, Jul 2018.

Bayesian optimization and how to scale it up.

o Computer Science Colloquium, University of Southern California, Los Angeles, CA, Nov 2017.

Scaling up Bayesian optimization with ensembles.

o DeepMind, London, UK (remote talk), Jun 2017.

Focused model-learning and planning for non-Gaussian continuous state-action systems.

- The Manipulation Lab at Carnegie Mellon University Robotics Institute, Pittsburgh, PA, Jun 2017.
- O Uber ATG, Pittsburgh, PA, Jun 2017.

Academic Service

Co-president of Graduate Women in Course 6 (GW6) in 2016.

Co-organizer of Machine Learning Across MIT 2018-2019.

Reviewer of JMLR, IEEE T-RO, NeurIPS, ICML, AIStats, ICLR, AAAI, UAI, IROS.

Research supervisor of undergraduate, MEng and visiting students at MIT: Michael Amoako (2016-2017; now at Microsoft), Kevin Chen (2018), Skye Thompson (2018-2019), Ivan Jutamulia (2018 Summer), Victoria Xia (2017-2018; now at Confluent), Alex LaGrassa (2018-2019; now PhD student at CMU), Nishad Gothoskar (2018 Summer; now at Vicarious), Jingxi Xu (2018 Summer), Jiayuan Mao (2018-2019; now PhD student at MIT).

Skills and Others

Most experienced (>5 years) with Python, Matlab and LATEX.

Some experience (>2 years) with ROS, Java, C/C++, JavaScript, HTML.

Languages: Chinese (native), English (fluent), Japanese (beginner).