



Challenges in TAM

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Robot Learning

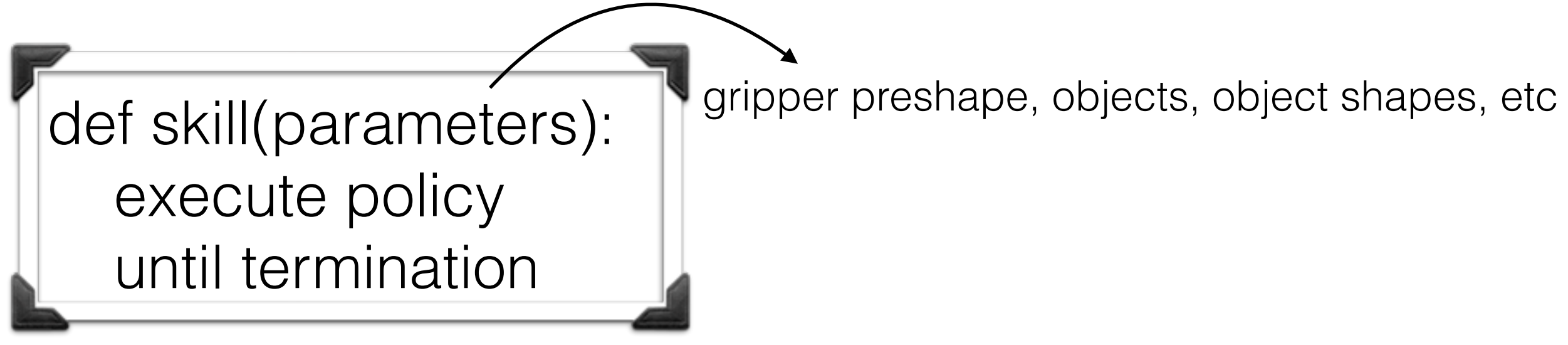


How to use them?









```
def skill(parameters):  
    execute policy  
    until termination
```

The diagram features a white rectangular box with a thin black border and four black corner tabs. Inside the box is a Python function definition. An arrow originates from the 'parameters' argument in the function signature and points to the text 'gripper preshape, objects, object shapes, etc' located to the right of the box.

gripper preshape, objects, object shapes, etc

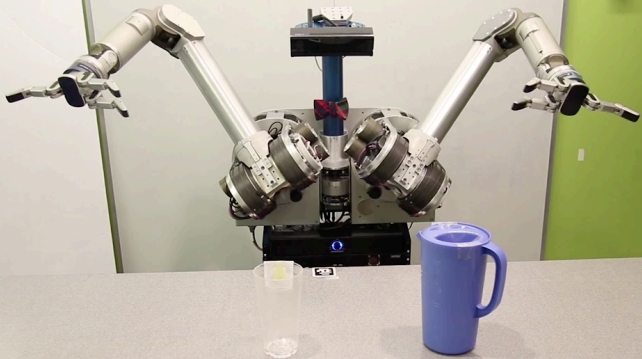
- how to acquire new low-level motor skills?

[Levin et al., ISER 2016] [Schenck et al., CoRL 2017] [OpenAI, 2018] [Ebert et al., CoRL 2017].....

most
robot
learning







5x

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Describing model of a skill in TAMP

