Zi Wang

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2014 – 2020

Education

Ph.D. in Computer Science, Massachusetts Institute of Technology Cambridge, MA

- Thesis: Robot Learning With Strong Priors. GPA: 5.0/5.0.
- Advisors: Prof. Leslie Pack Kaelbling and Prof. Tomás Lozano-Pérez.

2014 – 2016

S.M. in EECS, Massachusetts Institute of Technology

Cambridge, MA

- Thesis: Optimization as Estimation with Gaussian Process Bandits. GPA: 5.0/5.0.
- o Advisors: Prof. Stefanie Jegelka and Prof. Leslie Pack Kaelbling.

2010 – 2014

B.Eng. in Computer Science and Technology, *Tsinghua University* Beijing, China

- Thesis: Fast Dropout Training for Deep Neural Networks. GPA: 92/100; class rank: 2/129.
- Advisors: Prof. Fei Sha and Prof. Jun Zhu.

2021 2020 2019 2019 2018 2014-2015 Jul. 2014 Nov. 2013 Sep. 2013

Honors and Awards

NeurlPS 2021 Outstanding Reviewer Award (top 8%).

Virtual

Top 33% Reviewer of ICML 2020.

Virtual

Robotics: Science and Systems (RSS) Pioneers 2019.

Freiburg, Germany

MIT Graduate Women of Excellence 2019.

Cambridge, MA
Cambridge, MA

Rising Stars in Electrical Engineering & Computer Science 2018. Greater China Computer Science Fellowship, *MIT.*

Cambridge, MA

Outstanding Graduates Award, Tsinghua.

Beijing, China

Science and Innovation Scholarship, Tsinghua.

Beijing, China

Anita Borg Scholarship, Google China.

Beijing, China

Beijing, China

ESS Scholarship, awarded to 2% students, Tsinghua.

Tung OOCL Scholarship, awarded to 3% students, Tsinghua.

Beijing, China

Rising Stars of Shanghai's Science and Technology, top 0.02%.

Shanghai, China

Mathematical Contest in Modeling (MCM), Honorable Mention.

Bedford, MA



Oct. 2012

May 2010

Feb. 2009

Professional Experience

Research Scientist, Google Research.

Cambridge, MA

- Prior learning for Bayesian optimization and active learning.
- Large pre-trained models for uncertainty predictions.

2022 Spring

Lecturer, School of Engineering & Applied Sciences, Harvard University. Cambridge, MA

- Co-lectured Harvard CS 282r Topics in Machine Learning: Advancements in Probabilistic Machine Learning, ML Applications in Science, and Causality.
- Advised students on Gaussian processes, Bayesian optimization and data distillation.

2014 – 2020

Research Assistant, Learning & Intelligent Systems Group, CSAIL, MIT. Cambridge, MA

- Integrated learning and planning for long-horizon robot manipulation problems.
- Global optimization in high dimensions with large scale observations.

2019 Summer Research Intern, Microsoft Research New England. Cambridge, MA Interactive machine learning for Bayesian optimization. Jul. - Aug. 2017 Software Engineering Intern, Motion Planning Team @ Uber ATG. Pittsburgh, PA Developed a decision making module that enables safe, reliable and intelligent motion planning. Jun. - Jul. 2017 **Software Engineering Intern**, *Prediction Team @ Uber ATG.* Pittsburgh, PA Contributed to the trajectory prediction code base for the self-driving fleet of Uber. 2013 - 2014 Research Assistant, Prof. Fei Sha's Group, USC. Los Angeles, CA Fast training algorithms with regularizer for neural nets via noise marginalization. Discriminative non-negative matrix factorization algorithm for speech separation. 2013 - 2014 Research Assistant, Prof. Jun Zhu's Group, Tsinghua. Beijing, China • Visualizations and scalable inference algorithms for variants of topic models. 2012 - 2013 **Research Assistant**, Future Internet Technology Group, Tsinghua. Beijing, China Researched matrix factorization and random forest for movie recommendation for Baidu Inc.

Leadership and Service

Area Chair of AlStats 2023.

Co-organizer of 2022-2023 Virtual Seminar Series on Gaussian Processes, Spatiotemporal Modeling, and Decision-making Systems.

Co-organizer of 2022 NeurlPS Workshop on Gaussian Processes, Spatiotemporal Modeling, and Decision-making Systems.

Organizer of 2021-2022 Google BayesOpt Speaker Series and 2021 Google/Alphabet BayesOpt Workshop.

Co-organizer of Machine Learning Across MIT 2018-2019.

Organizer of MIT Graduate Women Book Club in 2019.

Reviewer of JMLR, IEEE T-RO, PAMI, JAIR, NeurlPS, ICML, AlStats, ICLR, AAAI, UAI, IROS, CoRL.

Research supervisor of undergraduate, MEng and visiting students at MIT:

- Michael Amoako (2016-2017; now at Microsoft);
- Kevin Chen (2018);
- Skye Thompson (2018-2019);
- o Ivan Jutamulia (2018 Summer);
- Victoria Xia (2017-2018; now at Confluent);
- Alex LaGrassa (2018-2019; now PhD student at CMU);
- Nishad Gothoskar (2018 Summer; now PhD student at MIT);
- Jingxi Xu (2018 Summer; now PhD student at Columbia University);

Co-president of Graduate Women in Course 6 (GW6) in 2016.

Teaching Assistant of 6.883 Advanced Machine Learning, MIT, 2015.

Invited Talks

Using pre-trained models and Gaussian processes to make uncertainty-aware decisions.

 Sustainable Urban Mobility: Simulation and Optimization Workshop, Mountain View, CA, Jun 2023.

Experimental Design and Domain Expertise: The Essential Ingredients for Robot Learning.

Experimental Design and Active Learning in the Real World Reading Group, Mar 2023.

Pre-trained Gaussian processes for Bayesian optimization.

- BayesOpt Session of INFORMS 2022, Indianapolis, IN, Oct 2022.
- HEC Montreal Optimization Days, May 2022.
- AutoML Seminars, May 2022.
- o Dagstuhl Seminar on Probabilistic Numerical Methods, Oct 2021.

Tutorials on Bayesian optimization.

- Vilnius Machine Learning Workshop, July 2021.
- Machine Learning and Friends Lunch, University of Massachusetts Amherst, Oct 2019.
- Computer Science Colloquium, University of Southern California, Nov 2017.

Human intelligence assisted robot learning.

- Al Colloquium, University Stuttgart, Germany, Jun 2019.
- o Shift Technology, Paris, France, Jun 2019.
- Robotics: Science and Systems (RSS) Pioneers Workshop, Freiburg, Germany, Jun 2019.

Active model learning and diverse action sampling for task and motion planning.

- University of Washington, Seattle, WA, Sep 2018.
- o International Conference on Intelligent Robots and Systems, Madrid, Spain, Oct 2018.

Regret bounds of Bayesian optimization with unknown GP prior.

Microsoft Research Al Breakthroughs Workshop, Redmond, WA, Sep 2018.

Bayesian optimization guided by max-values.

International Symposium on Mathematical Programming, Bordeaux, France, Jul 2018.

Scaling up Bayesian optimization with ensembles and additive models.

o DeepMind, Jun 2017.

Focused model-learning and planning for non-Gaussian continuous state-action systems.

- The Manipulation Lab at Carnegie Mellon University Robotics Institute, Jun 2017.
- Uber ATG, Pittsburgh, PA, Jun 2017.

Selected Publications

- **Z.** Wang*, A. Ku*, J. Baldridge, T. L. Griffiths, B. Kim. **Gaussian Process Probes (GPP)** for Uncertainty-Aware Probing. *arXiv preprint arXiv:2305.18213, 2023.*
- Z. Fan, X. Han, **Z. Wang**. **A Model Pre-training Framework for Bayesian Optimization on Heterogeneous Search Spaces**. *In preparation. 2023.*
- B. Wang, Z. Wang, X. Wang, Y. Cao, R.A. Saurous, Y. Kim. Grammar Prompting for Domain-Specific Language Generation with Large Language Models. arXiv preprint arXiv:2305.19234, 2023.
- **Z. Wang**, G. E. Dahl, K. Swersky, C. Lee, Z. Nado, J. Gilmer, J. Snoek, Z. Ghahramani. **Pre-trained Gaussian processes for Bayesian optimization**. *arXiv* preprint arXiv:2109.08215, 2023.
- Y. Chen, X. Song, C. Lee, **Z. Wang**, Q. Zhang, D. Dohan, K. Kawakami, G. Kochanski, A. Doucet, M. Ranzato, S. Perel, N. de Freitas. **Towards Learning Universal Hyperparameter Optimizers with Transformers**. *Advances in Neural Information Processing Systems (NeurIPS)*, 2022.
- Z. Fan, X. Han, **Z. Wang**. **HyperBO+: Pre-training a universal hierarchical Gaussian process prior for Bayesian optimization**. *NeurlPS Workshop on Gaussian Processes, Spatiotemporal Modeling, and Decision-making Systems, 2022.*
- **Z. Wang**, G. E. Dahl, K. Swersky, C. Lee, Z. Mariet, Z. Nado, J. Gilmer, J. Snoek, Z. Ghahramani. **Pre-training helps Bayesian optimization too**. *ICML Workshop on Adaptive Experimental Design and Active Learning in the Real World, 2022.*

- **Z.** Wang*, C. R. Garrett*, L. P. Kaelbling, T. Lozano-Pérez. Learning compositional models of robot skills for task and motion planning. *International Journal of Robotics Research (IJRR)*, 2021.
- **Z. Wang**. **Robot Learning with Strong Priors**. *MIT Ph.D. Thesis*, 2020.
- B. Kim, **Z. Wang**, L. P. Kaelbling, T. Lozano-Pérez. **Learning to guide task and motion planning using score-space representation**. *International Journal of Robotics Research (IJRR), 2019.*
- V. Xia*, **Z. Wang***, K. Allen, T. Silver, L. P. Kaelbling. **Learning sparse relational transition models**. *International Conference on Learning Representations (ICLR), 2019.*
- **Z.** Wang*, B. Kim*, L. P. Kaelbling. Regret bounds for meta Bayesian optimization with an unknown Gaussian process prior. Advances in Neural Information Processing Systems (NeurIPS), 2018. Spotlight talk (3.5% acceptance rate).
- **Z.** Wang, C. R. Garrett, L. P. Kaelbling, T. Lozano-Pérez. **Active model learning and diverse action sampling for task and motion planning**. *International Conference on Intelligent Robots and Systems (IROS), 2018.*
- **Z.** Wang, C. Gehring, P. Kohli, S. Jegelka. **Batched large-scale Bayesian optimization in high-dimensional spaces**. *International Conference on Artificial Intelligence and Statistics (AIStats), 2018.*
- **Z.** Wang, S. Jegelka. Max-value entropy search for efficient Bayesian optimization. *International Conference on Machine Learning (ICML), 2017.*
- **Z.** Wang*, C. Li*, S. Jegelka, P. Kohli. Batched high-dimensional Bayesian optimization via structural kernel learning. International Conference on Machine Learning (ICML), 2017.
- **Z.** Wang, S. Jegelka, L. P. Kaelbling, T. Lozano-Pérez. **Focused model-learning and planning for non-Gaussian continuous state-action systems**. *IEEE Conference on Robotics and Automation (ICRA), 2017.*
- **Z.** Wang, B. Zhou, S. Jegelka. **Optimization as estimation with Gaussian processes in bandit settings**. *International Conference on Artificial Intelligence and Statistics (AlStats), 2016. Oral presentation (6% acceptance rate).*
- Z. Lu*, **Z. Wang***, F. Sha. **Fast Learning with Noise in Deep Neural Nets**. *NIPS Workshop: Perturbations, Optimization, and Statistics, 2014.* Spotlight talk.
- **Z. Wang**, F. Sha. **Discriminative non-negative matrix factorization for single-channel speech separation**. *IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP), 2014.*
- J. Chen, J. Zhu, **Z. Wang**, X. Zheng, B. Zhang. **Scalable inference for logistic-normal topic models**. *Neural Information Processing Systems (NIPS), 2013.*

Skills and Others

Most experienced (>5 years) with Python, Matlab and $\mbox{\sc ETe}X$. Some experience (>2 years) with ROS, Java, C/C++, JavaScript, HTML.

Languages: Chinese (native), English (fluent), Japanese (beginner).