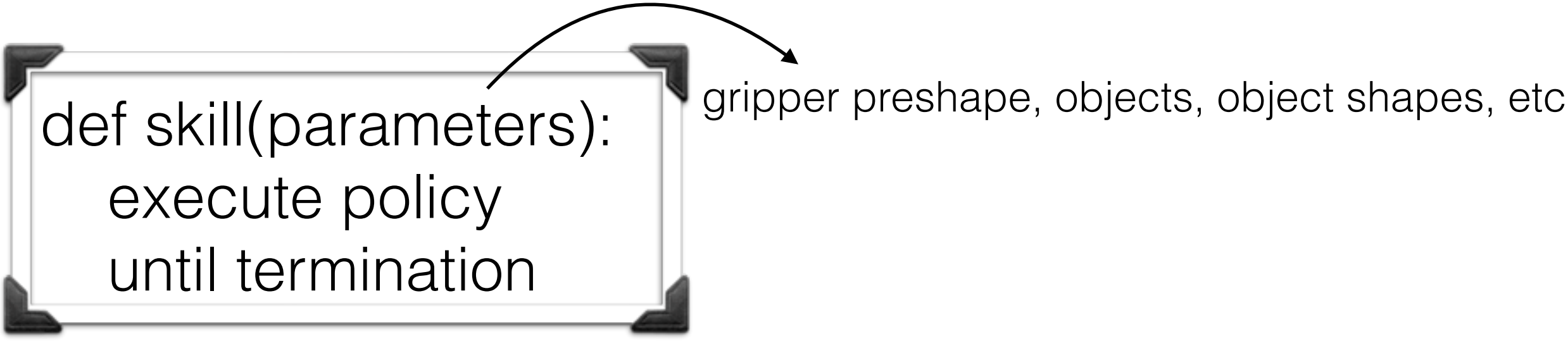
Challenges in TAMP

Zi Wang (MIT CSAIL)

Robot Learning

How to use them?

5x

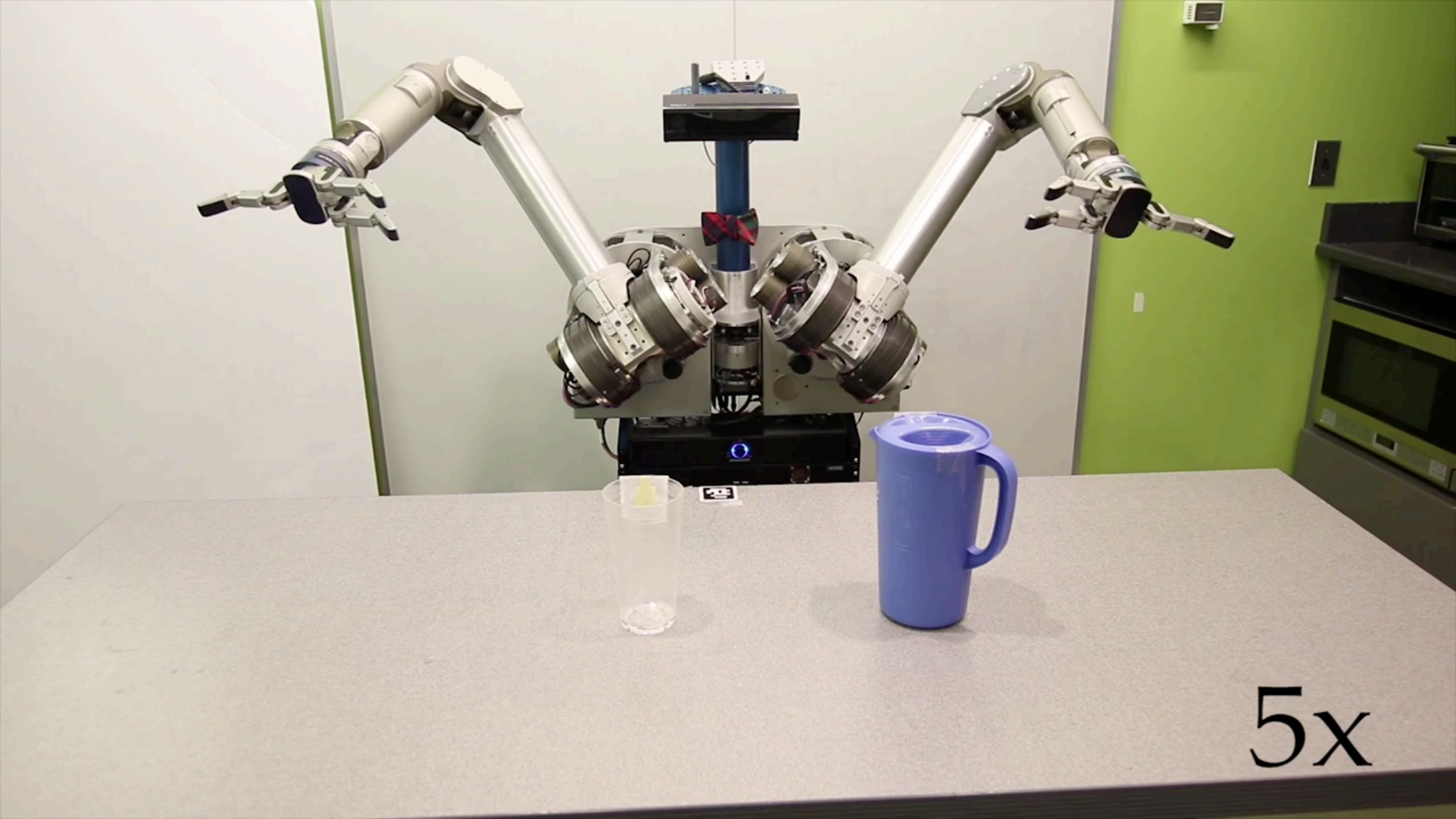

def skill(parameters):
execute policy
until termination
gripper preshape, objects, object shapes, etc

- how to acquire new low-level motor skills?

[Levin et al., ISER 2016] [Schenck et al., CoRL 2017] [OpenAI, 2018] [Ebert et al., CoRL 2017]……

most
robot
learning

r3d11
r3d24
r3d32


5x

Challenges in TAMP

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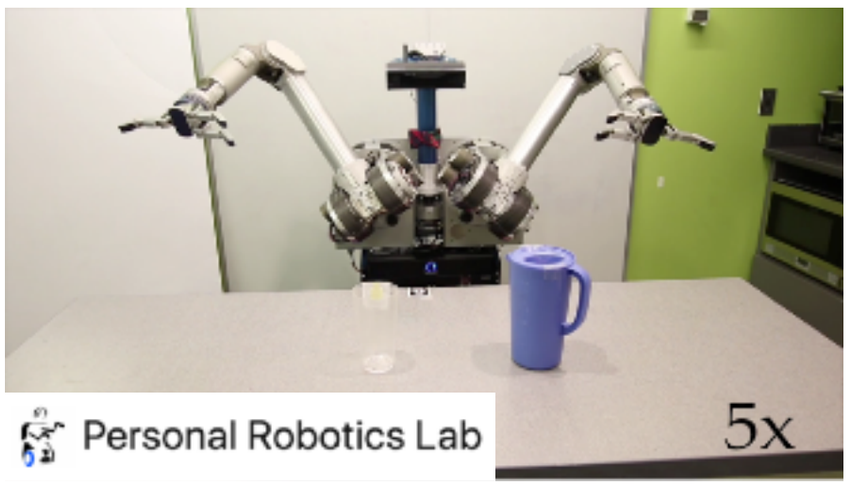
most robot learning




```
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```

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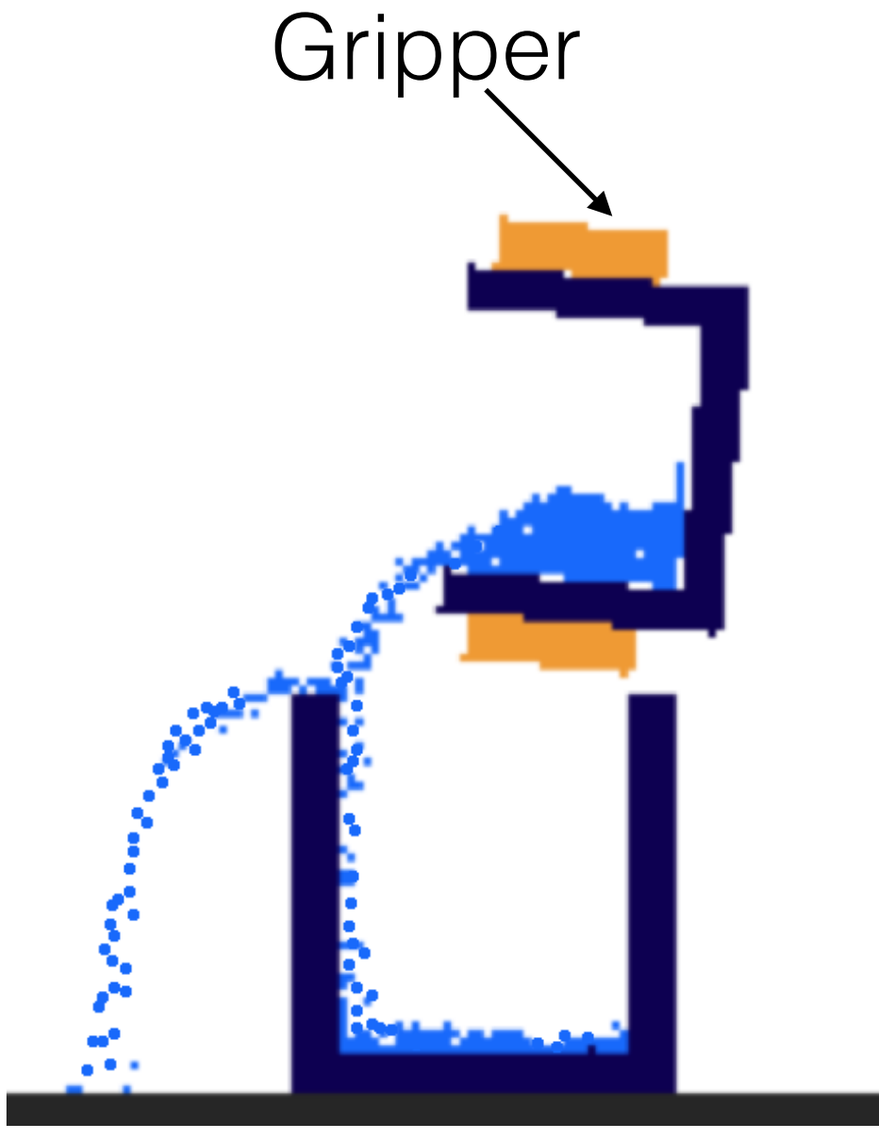
How to use them?

Describing model of a skill in TAMP