

Zi Wang (MIT CSAIL)

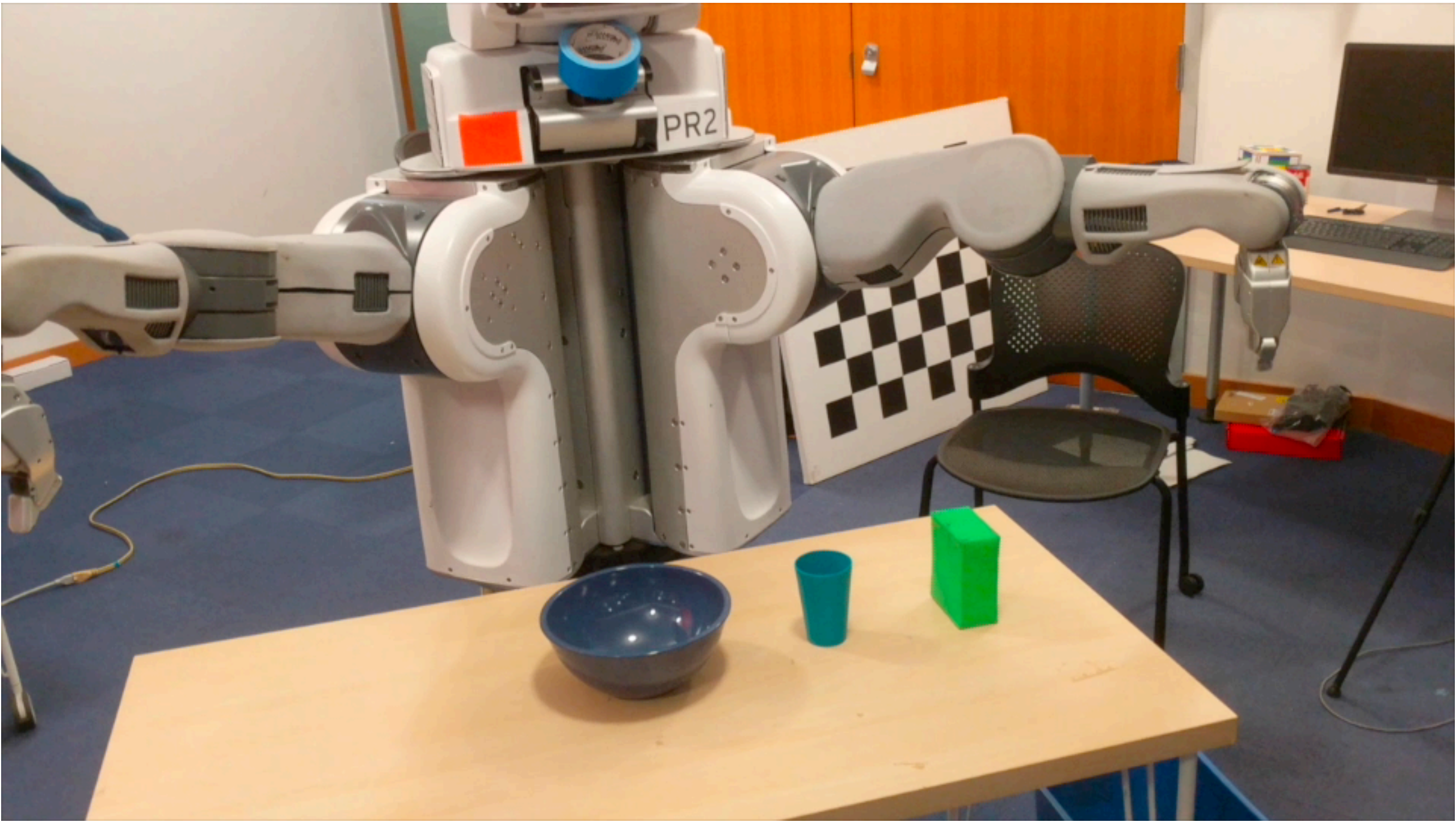
Robot Learning

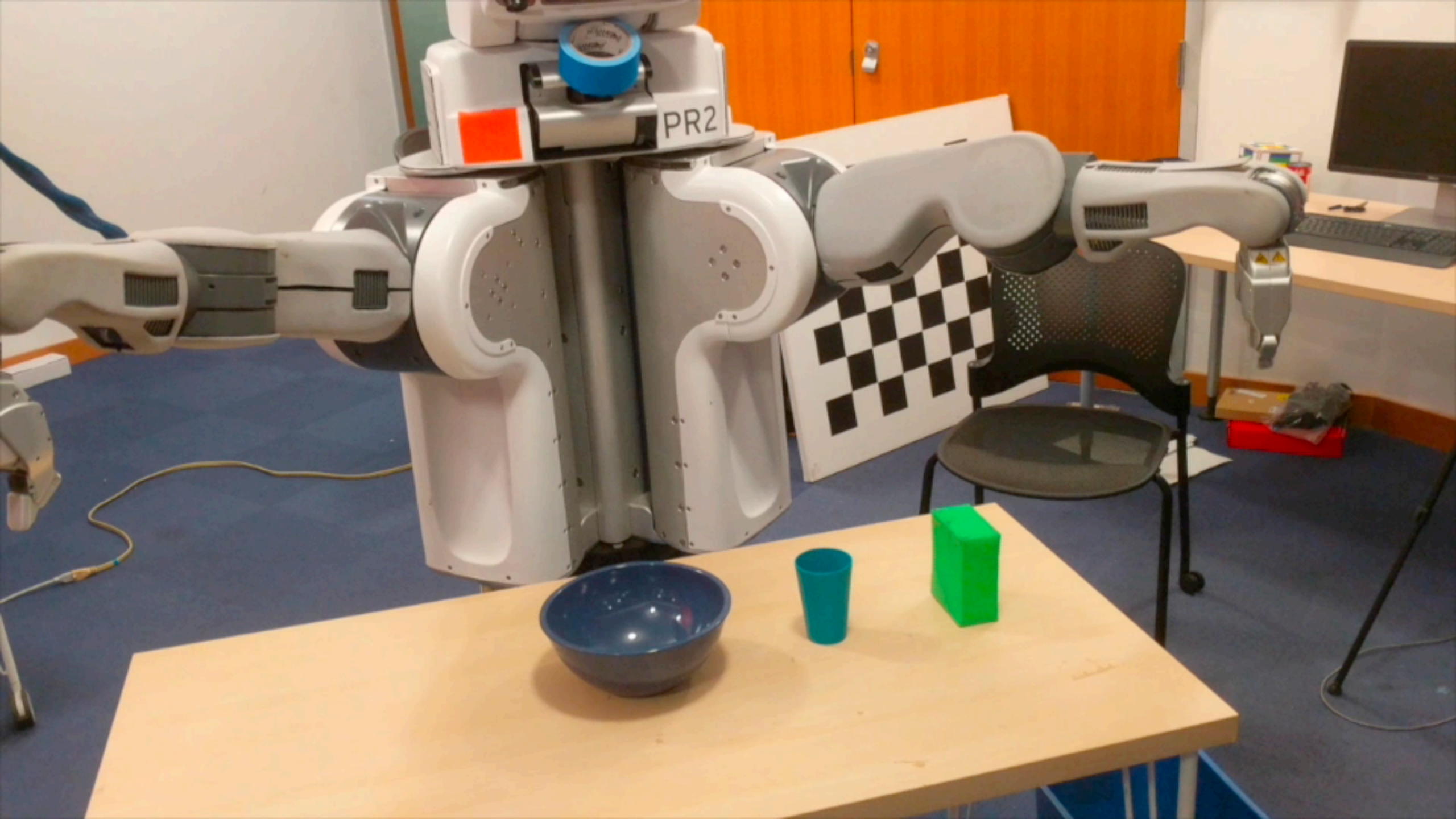
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6

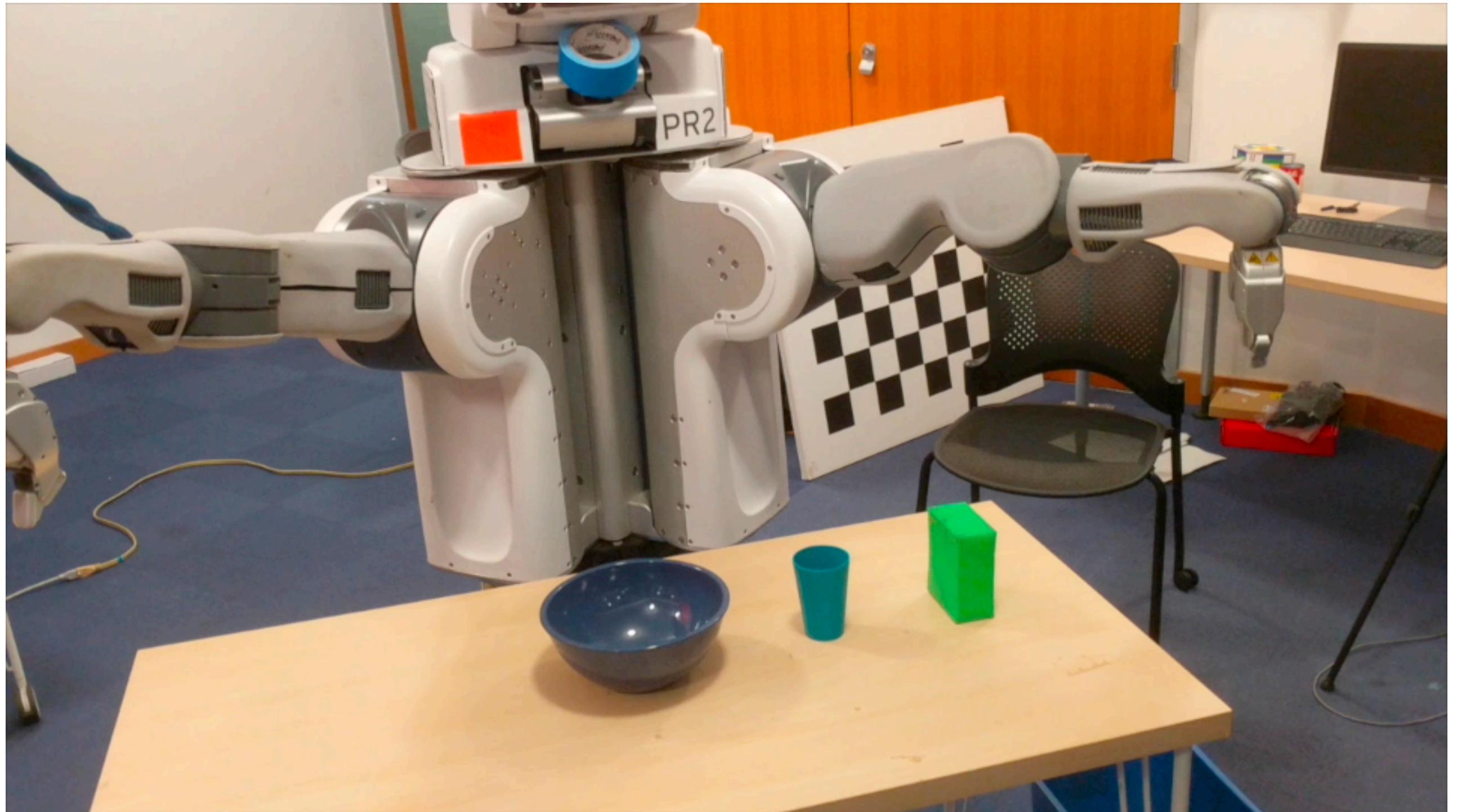


Preliminary results



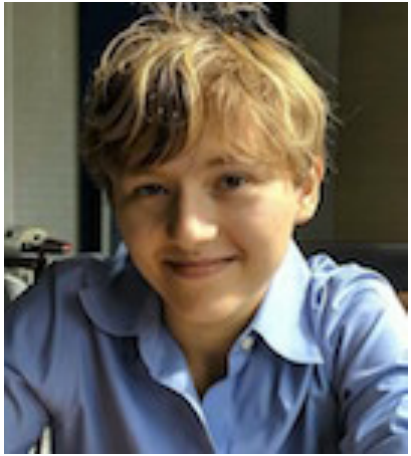


Preliminary results

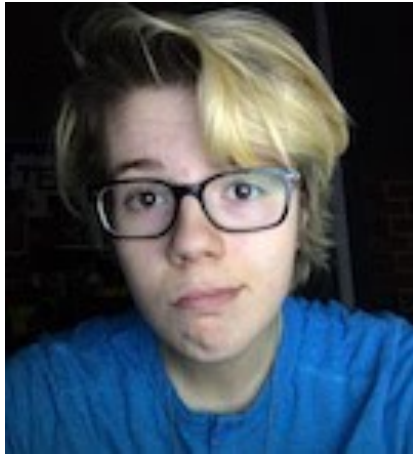


Acknowledgement

learning



Alex LaGrassa



Skye Thompson

control



Kevin Chen

perception



Nishad Gothoskar



Ivan Jutamulia

planning



Caelan Garrett

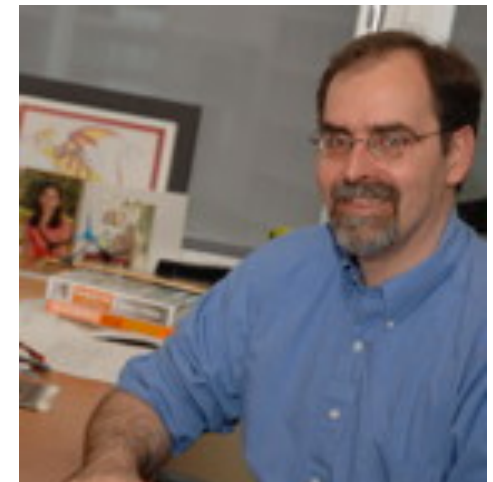


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