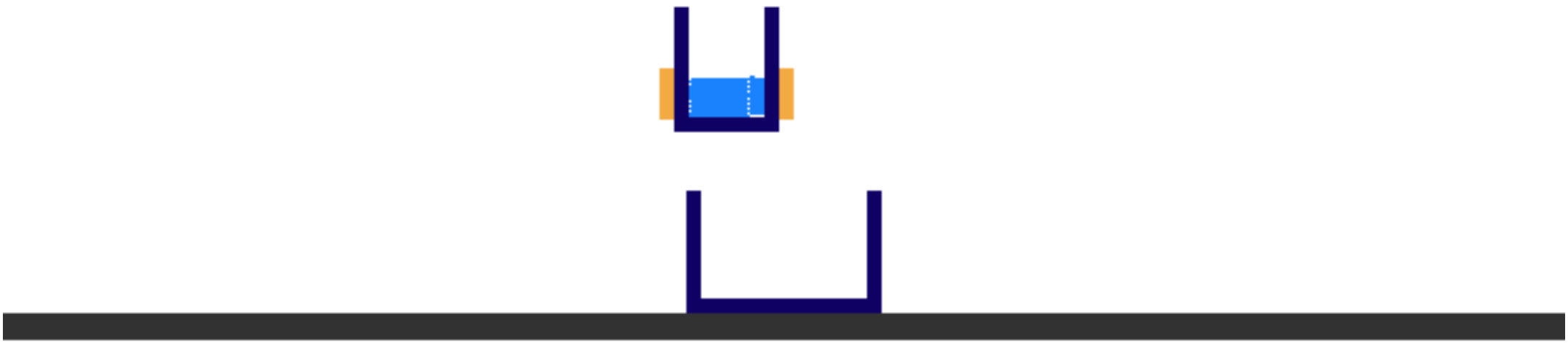

Zi Wang (MIT CSAIL)

Robot Learning

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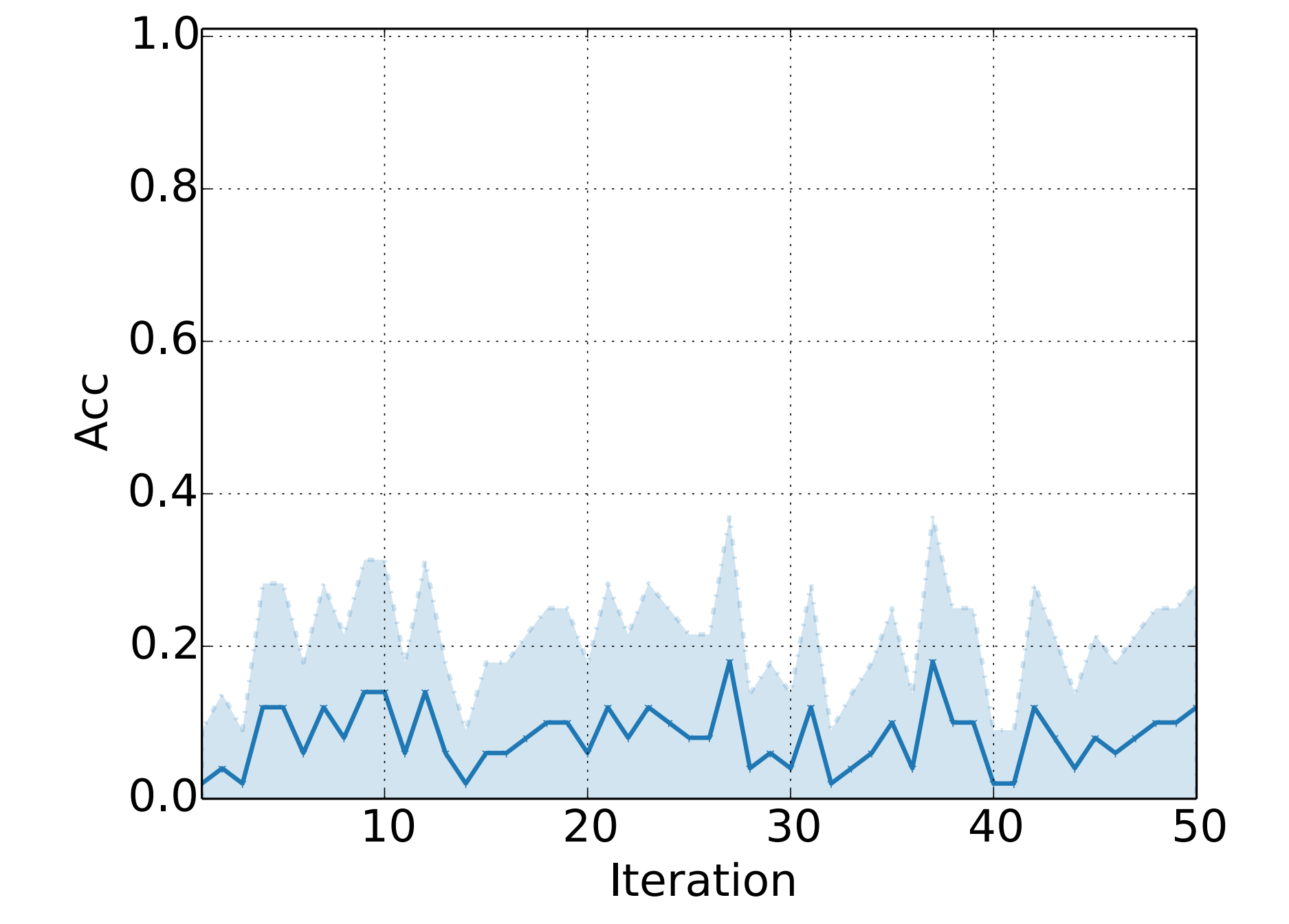
Active selection is data efficient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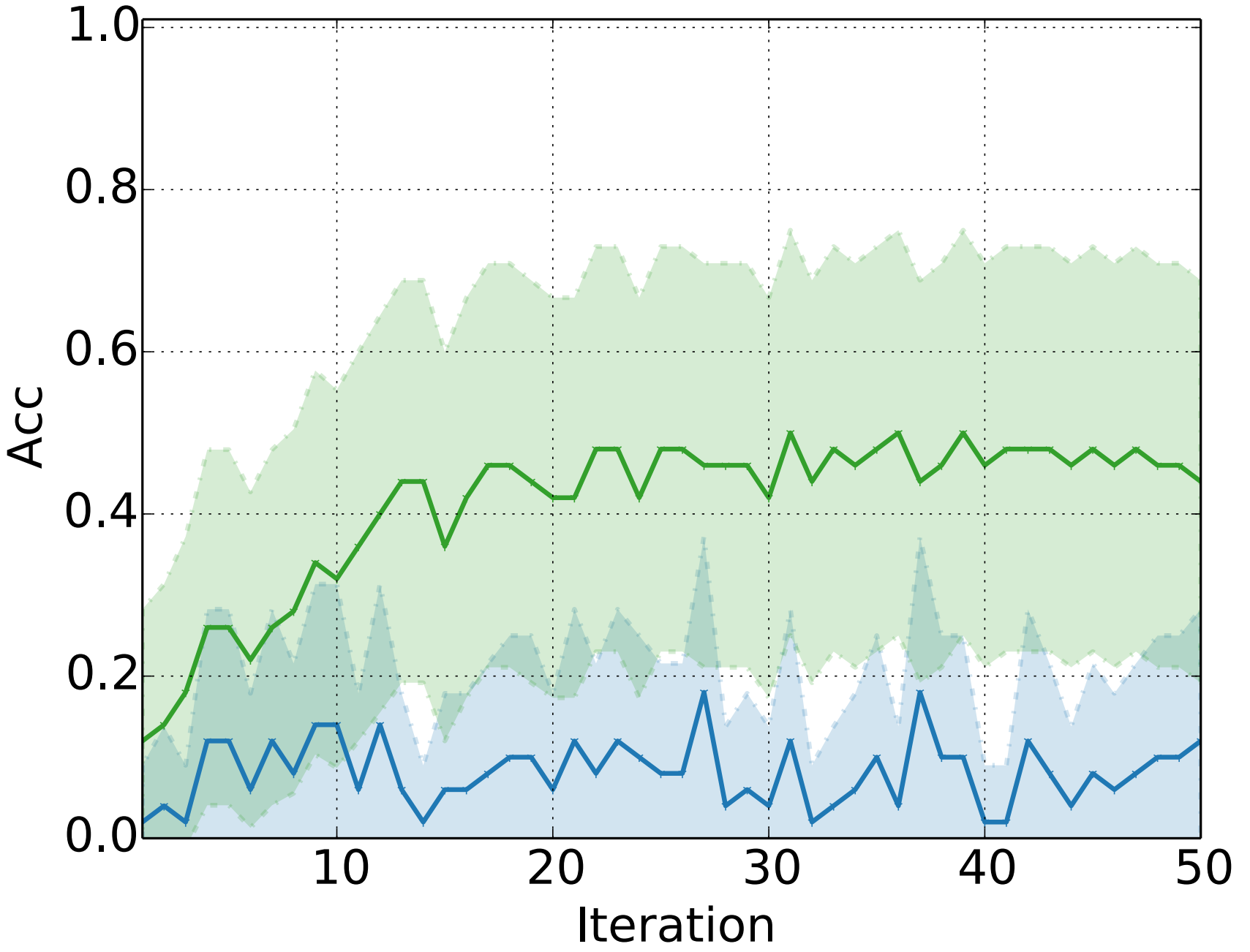
0.8
0.6
0.4
0.2
0.0
Acc
10
20
30
40
50
Iteration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0.8
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Acc
10
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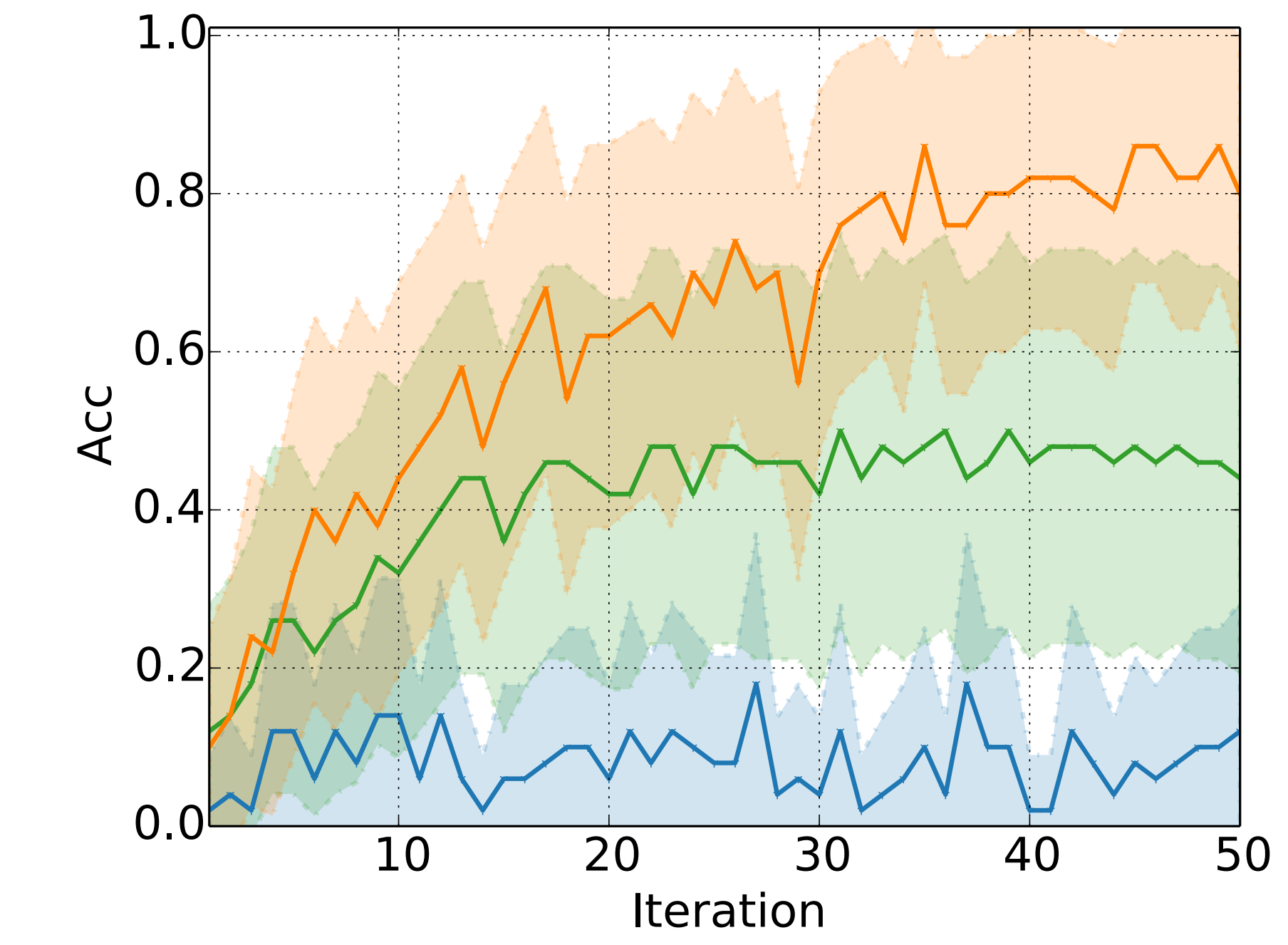
Iteration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0.8
0.6
0.4
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Acc
10
20
30
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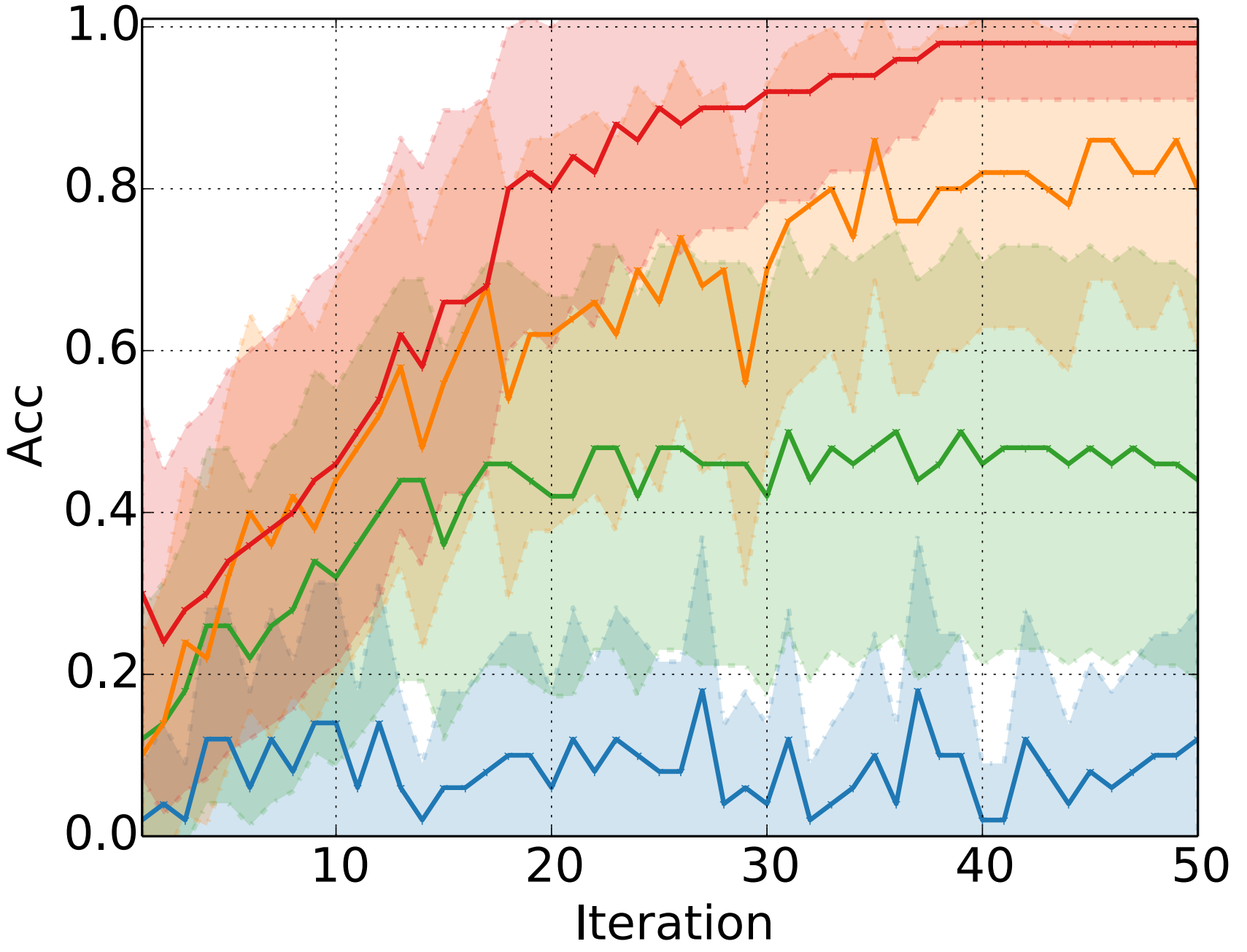
50
Iteration


1.0
0.8
0.6
0.4
0.2
0.0
Acc
10
20
30
40
50
Iteration

randomly chosen

neural network classifier*

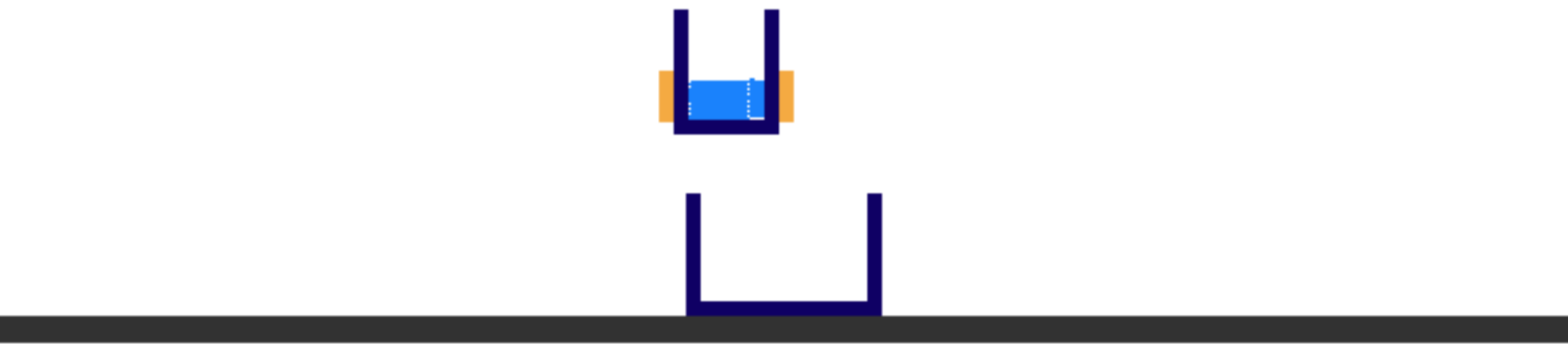
neural network regression*

GP active learning

#Training examples

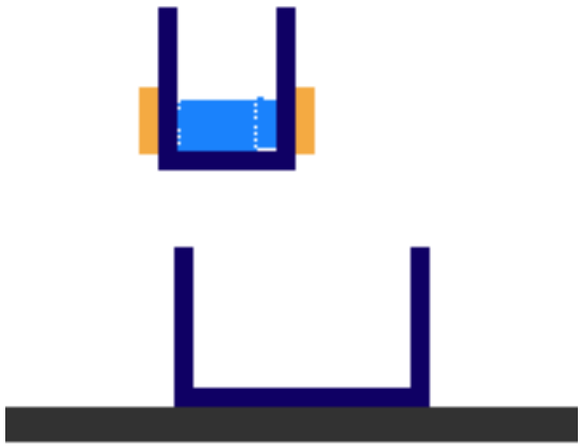
Success rate of recommended ‘pour’

[Kaelbling&Lozano-Perez, ICRA 2017]

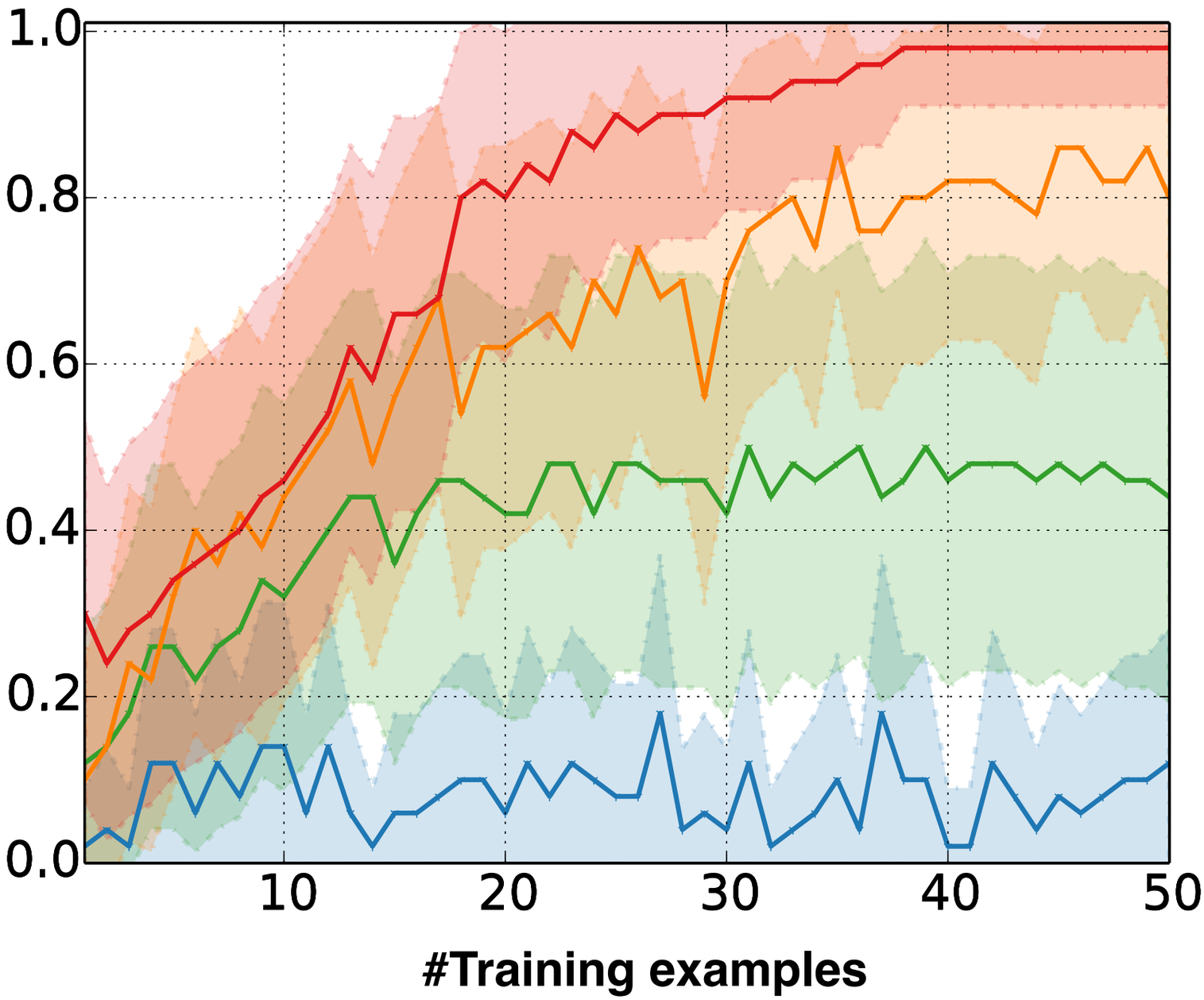


Active selection is data efficient

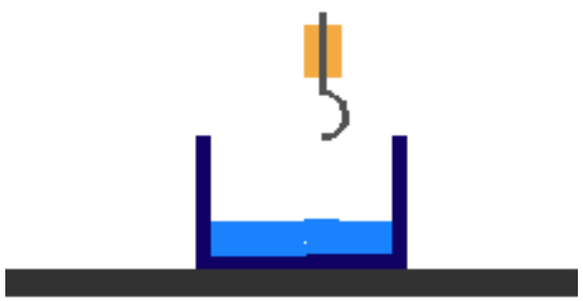
Success rate of recommended ‘pour’



- randomly chosen
- neural network classifier*
- neural network regression*
- GP active learning



[Kaelbling&Lozano-Perez, ICRA 2017]

Active selection is data efficient

Success rate of recommended ‘scoop’