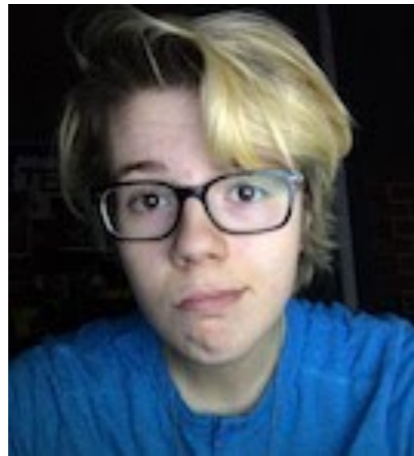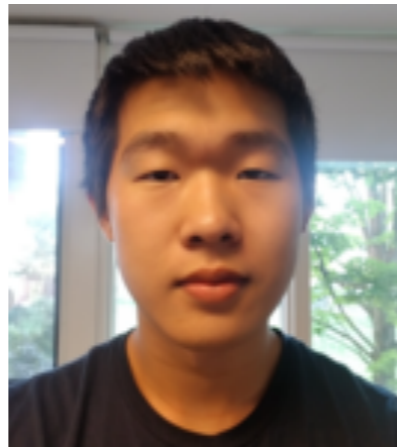# Acknowledgement

learning

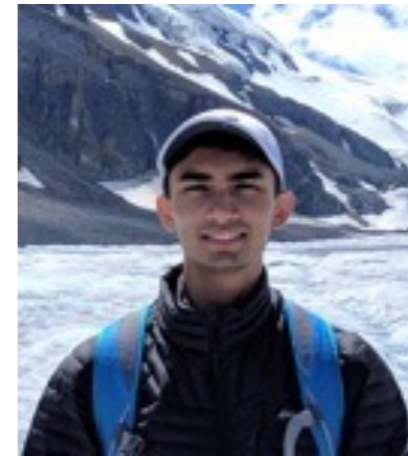Alex LaGrassa   Skye Thompson

control

Kevin Chen

perception

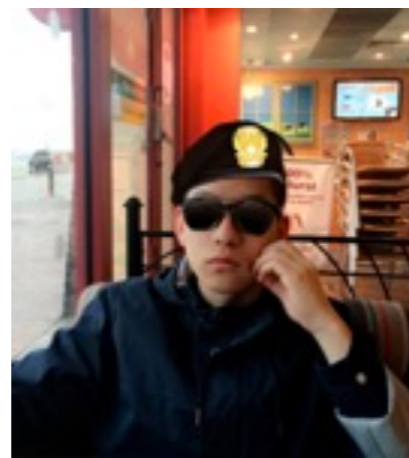Nishad Gothoskar   Ivan Jutamulia

planning

Caelan Garrett   Jingxi Xu
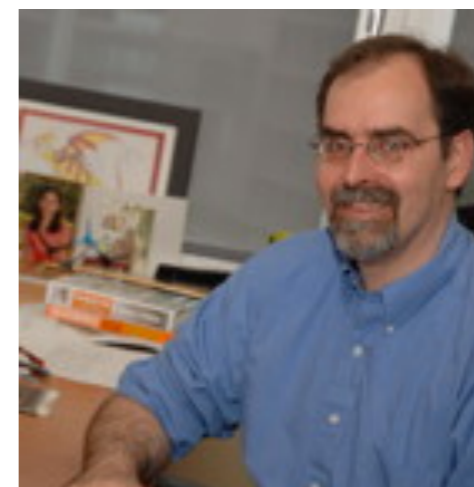
advisors

Leslie Kaelbling   Tomás Lozano-Pérez