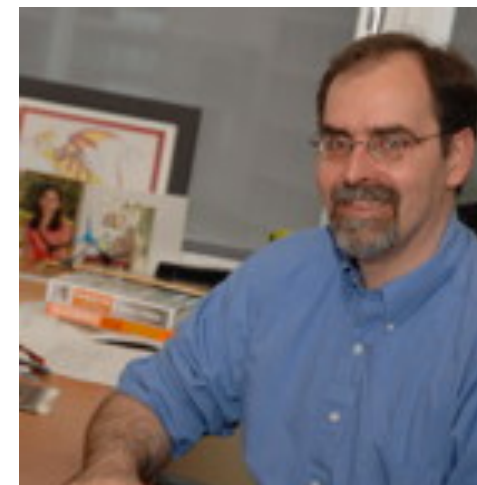




Active model learning and diverse action sampling for task and motion planning

Zi Wang

Sep 20 @ UW



joint work with Caelan Reed Garrett, Leslie Pack Kaelbling and Tomás Lozano-Pérez

Enable robots to solve high-level long-horizon problems

