```
from google.colab import drive
drive.mount('/content/drive')
Mounted at /content/drive
!python --version
Python 3.12.11
import os
os.getcwd()
'/content'
# os.chdir('/content/drive/MyDrive/XRA')
# os.getcwd()
!pip install -r requirements.txt
ERROR: Could not open requirements file: [Errno 2] No such file or direct
!pip install monai
!pip install torchmetrics
Collecting monai
  Downloading monai-1.5.1-py3-none-any.whl.metadata (13 kB)
Requirement already satisfied: numpy<3.0,>=1.24 in /usr/local/lib/pythor
Requirement already satisfied: torch>=2.4.1 in /usr/local/lib/python3.12
Requirement already satisfied: filelock in /usr/local/lib/python3.12/dis
Requirement already satisfied: typing-extensions>=4.10.0 in /usr/local/
Requirement already satisfied: setuptools in /usr/local/lib/python3.12/c
Requirement already satisfied: sympy>=1.13.3 in /usr/local/lib/python3.3
Requirement already satisfied: networkx in /usr/local/lib/python3.12/dis
Requirement already satisfied: jinja2 in /usr/local/lib/python3.12/dist-
Requirement already satisfied: fsspec in /usr/local/lib/python3.12/dist-
Requirement already satisfied: nvidia-cuda-nvrtc-cu12==12.6.77 in /usr/
Requirement already satisfied: nvidia-cuda-runtime-cu12==12.6.77 in /usi
Requirement already satisfied: nvidia-cuda-cupti-cu12==12.6.80 in /usr/
Requirement already satisfied: nvidia-cudnn-cu12==9.10.2.21 in /usr/location
Requirement already satisfied: nvidia-cublas-cu12==12.6.4.1 in /usr/loca
Requirement already satisfied: nvidia-cufft-cu12==11.3.0.4 in /usr/local
Requirement already satisfied: nvidia-curand-cu12==10.3.7.77 in /usr/loc
Requirement already satisfied: nvidia-cusolver-cu12==11.7.1.2 in /usr/lc
Requirement already satisfied: nvidia-cusparse-cu12==12.5.4.2 in /usr/lc
Requirement already satisfied idia-cusparselt-cu12==0.7.1 in /usr/loc Requirement already satisfied idia-nccl-cu12==2.27.3 in /usr/local/li
```

```
Requirement already satisfied: nvidia-nvtx-cu12==12.6.77 in /usr/local/
Requirement already satisfied: nvidia-nvjitlink-cu12==12.6.85 in /usr/lc
Requirement already satisfied: nvidia-cufile-cu12==1.11.1.6 in /usr/location
Requirement already satisfied: triton==3.4.0 in /usr/local/lib/python3.1
Requirement already satisfied: mpmath<1.4,>=1.1.0 in /usr/local/lib/pyth
Requirement already satisfied: MarkupSafe>=2.0 in /usr/local/lib/python:
Downloading monai-1.5.1-py3-none-any.whl (2.7 MB)
                                           - 2.7/2.7 MB 33.0 MB/s eta 0:0
Installing collected packages: monai
Successfully installed monai-1.5.1
Collecting torchmetrics
  Downloading torchmetrics-1.8.2-py3-none-any.whl.metadata (22 kB)
Requirement already satisfied: numpy>1.20.0 in /usr/local/lib/python3.13
Requirement already satisfied: packaging>17.1 in /usr/local/lib/python3.
Requirement already satisfied: torch>=2.0.0 in /usr/local/lib/python3.12
Collecting lightning-utilities>=0.8.0 (from torchmetrics)
  Downloading lightning_utilities-0.15.2-py3-none-any.whl.metadata (5.7
Requirement already satisfied: setuptools in /usr/local/lib/python3.12/
Requirement already satisfied: typing extensions in /usr/local/lib/pytho
Requirement already satisfied: filelock in /usr/local/lib/python3.12/dis
Requirement already satisfied: sympy>=1.13.3 in /usr/local/lib/python3.3
Requirement already satisfied: networkx in /usr/local/lib/python3.12/dis
Requirement already satisfied: jinja2 in /usr/local/lib/python3.12/dist-
Requirement already satisfied: fsspec in /usr/local/lib/python3.12/dist-
Requirement already satisfied: nvidia-cuda-nvrtc-cu12==12.6.77 in /usr/
Requirement already satisfied: nvidia-cuda-runtime-cu12==12.6.77 in /usi
Requirement already satisfied: nvidia-cuda-cupti-cu12==12.6.80 in /usr/
Requirement already satisfied: nvidia-cudnn-cu12==9.10.2.21 in /usr/loca
Requirement already satisfied: nvidia-cublas-cu12==12.6.4.1 in /usr/loca
Requirement already satisfied: nvidia-cufft-cu12==11.3.0.4 in /usr/local
Requirement already satisfied: nvidia-curand-cu12==10.3.7.77 in /usr/loc
Requirement already satisfied: nvidia-cusolver-cu12==11.7.1.2 in /usr/lc
Requirement already satisfied: nvidia-cusparse-cu12==12.5.4.2 in /usr/lc
Requirement already satisfied: nvidia-cusparselt-cu12==0.7.1 in /usr/loc
Requirement already satisfied: nvidia-nccl-cu12==2.27.3 in /usr/local/l:
Requirement already satisfied: nvidia-nvtx-cu12==12.6.77 in /usr/local/
```

!pip install opencv-python

Requirement already satisfied: opencv-python in /usr/local/lib/python3.12 Requirement already satisfied: numpy<2.3.0,>=2 in /usr/local/lib/python3.

import packages & dependencies

```
import os
import matplotlib.pyplot as plt
import numpy as np
from torch.utils.data import DataLoader, Dataset
from torchvision.io import read_image
from torchvision import transforms
from torch.utils.data import DataLoader
from torchvision.transforms import InterpolationMode
import torch
import torch.nn as nn
from transformers import ViTModel, AutoConfig, ViTImageProcessor, ViTConfig
from transformers import Trainer, TrainingArguments, AutoModelForSemanticSegmentatio
from transformers import EarlyStoppingCallback
from safetensors.torch import load_file
import monai.losses as ml
                                      # monai loss functions library
import monai.metrics as mm
                                      # monai metrics library
from monai.networks.utils import one_hot
from torchmetrics.segmentation import DiceScore, HausdorffDistance
from monai.losses import FocalLoss, TverskyLoss
from sklearn.metrics import accuracy_score, f1_score, recall_score, precision_score,
from skimage.filters import sato
import cv2
from transformers.models.vit.modeling_vit import ViTAttention, ViTSelfAttention
```

Image Data & Processing

```
# loading data
# ABS_PATH = '/Users/daofeng/Desktop/____/INM363/CODE/syntax' # ABS
ABS_PATH = '/content/drive/MyDrive/XRA/syntax'

# define custom data class
class Syntax():
    def __init__(self, root_path, dataset):
    self.root_path = root_path
    if dataset == 'train':
```

```
self.images = sorted([root_path + '/train/images/' + i for i in os.listd
                             key = lambda x: int(os.path.splitext(os.path.basena
        self.masks = sorted([root_path + '/train/masks/' + i for i in os.listdi
                             key = lambda x: int(os.path.splitext(os.path.basena
        self.labels = sorted(os.listdir(root_path + '/train/images/'), key = lam
        # self.annots = root_path + '/train/annotations/' + 'train.json'
    elif dataset == 'val':
        self.images = sorted([root_path + '/val/images/' + i for i in os.listdir
                             key = lambda x: int(os.path.splitext(os.path.basena
        self.masks = sorted([root_path + '/val/masks/' + i for i in os.listdir(
                             key = lambda x: int(os.path.splitext(os.path.basena
        self.labels = sorted(os.listdir(root_path + '/val/images/'), key = lambd
    elif dataset == 'test':
        self.images = sorted([root_path + '/test/images/' + i for i in os.listdi
                             key = lambda x: int(os.path.splitext(os.path.basena
        self.masks = sorted([root_path + '/test/masks/' + i for i in os.listdir
                             key = lambda x: int(os.path.splitext(os.path.basena
        self.labels = sorted(os.listdir(root_path + '/test/images/'), key = lamb
        raise ValueError("dataset parameter needs to be 'train', 'val', or 'test
        # pass
    self.transform = transforms.Compose([
        transforms.Resize((224,224)),
                                                                       # origina
        transforms.Grayscale(num_output_channels = 1),
                                                                       # convert
        transforms.ConvertImageDtype(torch.float32)
                                                                       # convert
    1)
    self.ch3_transform = transforms.Compose([
                                                                       # second
        transforms.Lambda(lambda x: x.repeat(3, 1, 1))
                                                                       # this co
    ])
    self.msk_transform = transforms.Compose([
        # transforms.Resize((224,224),
                            interpolation = InterpolationMode.NEAREST),
        transforms.ConvertImageDtype(torch.float32),
                                                                        # conver
        transforms.Lambda(lambda pixel: (pixel > 0).float())
                                                                        # binari
    ])
def __len__(self):
```

```
return len(self.labels)

def __getitem__(self, idx):

img = read_image(self.images[idx])  # loads images
img = self.transform(img)  # applies transforms
img = self.ch3_transform(img)  # converts to 3 channels

msk = read_image(self.masks[idx])  # loads masks
msk = self.transform(msk)  # applies transforms

lbl = self.labels[idx]
return img, msk, lbl
```

```
# initialize datasets
data_train = Syntax(root_path = ABS_PATH, dataset = 'train')
data_val = Syntax(root_path = ABS_PATH, dataset = 'val')
data_test = Syntax(root_path = ABS_PATH, dataset = 'test')
```

```
# define data loaders
BATCHN = [10, 20, 25, 50, 100]  # different batch sizes batch s

train_loader = DataLoader(dataset = data_train, shuffle = False, batch_size = BATCHN test_loader = DataLoader(dataset = data_test, shuffle = False, batch_size = BATCHN[3 val_loader = DataLoader(dataset = data_val, shuffle = False, batch_size = BATCHN[4])

train_imgs, train_msks, train_lbls = next(iter(train_loader))
val_imgs, val_msks, val_lbls = next(iter(val_loader))
```

```
# load full train/val/test data from dataloaders
data_train
data_val
data_test
def load_all(loader):
    imgs, msks, lbls = [], [], []
    for i, m, l in loader:
        imgs.append(i)
        msks.append(m)
        lbls.append(l)
    imgs = torch.cat(imgs, dim = 0)
                                                # concatenate batches
    msks = torch.cat(msks, dim = 0)
    return imgs, msks, lbls
train_imgs, train_msks, train_lbls = load_all(train_loader)
val_imgs, val_msks, val_lbls = load_all(val_loader)
test_imgs, test_msks, test_lbls = load_all(test_loader)
```

```
# define sato + sobel filter function
def apply_filters(img_ds):
    output = []
    for img in img_ds:
        grayscale_ch = img[0].numpy()
                                      # grayscale channel to np array
        # # clahe channel
       # clahe_ch = cv2.createCLAHE(clipLimit = 2, tileGridSize = (8, 8))
       # sato filter
        sato_ch = sato(grayscale_ch, sigmas=(1,2,3), black_ridges=True)
                                                                           # black_
        sato_ch = np.clip(sato_ch, 0.0, 1.0).astype(np.float32)
                                                                           # min-ma
        # sobel filter
        grad_x = cv2.Sobel(grayscale_ch, cv2.CV_32F, 1, 0, ksize = 3)
                                                                           # kernel
        grad_y = cv2.Sobel(grayscale_ch, cv2.CV_32F, 0, 1, ksize = 3)
                                                                           # CV_32F
        grad_m = cv2.magnitude(grad_x, grad_y)
                                                                           # gradie
        grad_m = grad_m / (grad_m.max() + 1e-6)
                                                                           # normal
        sobel_ch = grad_m.astype(np.float32)
        stacked_ch = np.stack([grayscale_ch, sato_ch, sobel_ch], axis = 0) # axis 0
        output.append(torch.from_numpy(stacked_ch))
                                                                           # append
    return torch.stack(output)
```

```
# apply fiters
train_imgs = apply_filters(train_imgs)
val_imgs = apply_filters(val_imgs)
test_imgs = apply_filters(test_imgs)
```

```
# compute normalizations
# use train img mean & std
                                        train_imgs[:, 0, :, :].std().item()
grayscale_mean = [train_imgs[:, 0, :, :].mean().item(),
                  train_imgs[:, 0, :, :].mean().item(),
                  train_imgs[:, 0, :, :].mean().item()]
grayscale_std = [train_imgs[:, 0, :, :].std().item(),
                 train_imgs[:, 0, :, :].std().item(),
                 train_imgs[:, 0, :, :].std().item()]
# channel wise mean
channel_mean = [train_imgs[:, 0, :, :].mean().item(),
                train_imgs[:, 1, :, :].mean().item(),
                train_imgs[:, 2, :, :].mean().item()]
channel_std = [train_imgs[:, 0, :, :].std().item(),
               train_imgs[:, 1, :, :].std().item(),
               train_imgs[:, 2, :, :].std().item()]
```

```
# use processor and collator to prepare the images
processor = ViTImageProcessor.from_pretrained('google/vit-base-patch16-224')
# model_input = processor(images = train_imgs, return_tensors = 'pt')
# processor settings
# processor.size = {'height': 512, 'width': 512}
processor.size = {'height': 224, 'width': 224}
processor.do_rescale = True
# processor.image_mean = grayscale_mean # defaults to [0.5, 0.5, 0.5]
# processor.image_std = grayscale_std
# processor.do_normalize = True
processor.image_mean = channel_mean # defaults to [0.5, 0.5, 0.5]
processor.image_std = channel_std
processor.do_normalize = True
/usr/local/lib/python3.12/dist-packages/huggingface hub/utils/ auth.py:94
The secret `HF TOKEN` does not exist in your Colab secrets.
To authenticate with the Hugging Face Hub, create a token in your setting
You will be able to reuse this secret in all of your notebooks.
Please note that authentication is recommended but still optional to acce
 warnings.warn(
Fetching 1 files: 100%
                                                       1/1 [00:00<00:00, 6.96it/s]
                                                    160/160 [00:00<00:00, 22.5kB/s]
preprocessor_config.json: 100%
```

```
# processing each dataset for trainer
train_x = processor(images = train_imgs, return_tensors = 'pt')
train_x = train_x['pixel_values']
train_y = train_msks

val_x = processor(images = val_imgs, return_tensors = 'pt')
val_x = val_x['pixel_values']
val_y = val_msks

test_x = processor(images = test_imgs, return_tensors = 'pt')
test_x = test_x['pixel_values']
test_y = test_msks
```

It looks like you are trying to rescale already rescaled images. If the i

```
# collate into one dataset dict of X, y
class SYN(Dataset):
    def __init__(self, pixel_values: torch.Tensor, masks: torch.Tensor):
        self.x = pixel_values
        self.y = masks

def __len__(self):
        return self.y.size(0)

def __getitem__(self, idx):
    dat = {
        'pixel_values': self.x[idx],
        'labels': self.y[idx]
    }
    return dat

ds_train = SYN(train_x, train_y)
ds_val = SYN(val_x, val_y)
ds_test = SYN(test_x, test_y)
```

Defining Model

```
model_id = 'google/vit-base-patch16-224'
# model_id = 'google/vit-base-patch32-224-in21k'
config = ViTConfig.from_pretrained(model_id)
VTmodel = ViTModel.from_pretrained(model_id)

config.json: 69.7k/? [00:00<00:00, 7.37MB/s]

model.safetensors: 100% 346M/346M [00:01<00:00, 316MB/s]
Some weights of ViTModel were not initialized from the model checkpoint a You should probably TRAIN this model on a down-stream task to be able to see the content of t
```

```
# config = ViTConfig(
      hidden_size = 768,
      num_hidden_layers = 12,
#
      num_attention_heads = 12,
      image_size = 512,
#
#
      patch_size = 32,
#
      hidden_dropout_prob = 0.0,
      attention_probs_dropout_prob = 0.0,
#
#
      qkv_bias = True
# )
config = ViTConfig(
    hidden_size = 768,
    num_hidden_layers = 12,
    num_attention_heads = 12,
    image size = 224,
    patch_size = 16,
    hidden_dropout_prob = 0.0,
    attention_probs_dropout_prob = 0.0,
    qkv_bias = True
```

```
class ViT(nn.Module):
    def __init__(self, model_id, img_size, patch_size, freeze):
        super().__init__()
        # loading the pre-trained model
        # self.config = ViTConfig.from_pretrained(model_id)
        self.config = ViTConfig(
            hidden_size = 768,
            num_hidden_layers = 12,
            num_attention_heads = 12,
            image_size = 224,
            patch_size = 16,
            hidden_dropout_prob = 0.0,
            attention_probs_dropout_prob = 0.0,
            qkv_bias = True
            )
        # self.vit = ViTModel(self.config)
        self.vit = ViTModel.from_pretrained(model_id, config = self.config)
        # self.embeddings = self.vit.embeddings
        # self.vit.get_position_embeddings
        # define params
        self.img_size = 224
                                                            # default ViT input size
```

```
self.patch_size = 16
                                                    # default 16 patches
self.num_patches = img_size // patch_size
                                                    # number of patches in i
self.grid_size = (img_size // patch_size) ** 2
                                                    # grid size of each patc
# backbone vit encoder param freeze
if freeze:
    for par in self.vit.parameters():
        par.requires_grad = False
                                                    # ViT params/weights fro
    print('encoder backbone frozen')
else:
    print('encoder backbone training enabled')
# define decoder
self.decoder = nn.Sequential(
    nn.LayerNorm(768),
                                                      # input dim [B, grid_s
    nn.Linear(768, 1024),
                                                      # fc layer to [B, 196,
    nn.GELU(),
                                                      # gelu activation
    nn.Dropout(0.1),
    nn.Linear(1024, 512),
                                                      # [B, 196, 512]
    nn.GELU(),
                                                      # gelu activation
    nn.Dropout(0.1),
                                                      # [B, 196, 64]
    nn.Linear(512, 64),
)
# define spatial upsampling
self.upsample = nn.Sequential(
    # nn.convTranspose2d(in_channels, out_channels, kernel_size, stride, pad
    # dimensions [B, C, H, W]
    nn.ConvTranspose2d(64, 128, kernel_size = 4, stride = 2, padding = 1),
    nn.BatchNorm2d(128),
    nn.ReLU(),
    nn.ConvTranspose2d(128, 64, kernel_size = 4, stride = 2, padding = 1),
    nn.BatchNorm2d(64),
    nn.ReLU(),
    nn.ConvTranspose2d(64, 32, kernel_size = 4, stride = 2, padding = 1),
    nn.BatchNorm2d(32),
    nn.ReLU(),
    nn.ConvTranspose2d(32, 16, kernel_size = 4, stride = 2, padding = 1),
    nn.BatchNorm2d(16),
    nn.ReLU(),
    nn.Conv2d(16, 1, kernel_size = 1),
# define loss functions
# bce + dice
# self.loss_bce = nn.BCEWithLogitsLoss(pos_weight = torch.tensor((1 - 0.0196
```

```
# # self.loss_dice = ml.dice.DiceLoss(sigmoid = True, squared_pred = True, r
    # self.loss_dice = ml.dice.DiceLoss(sigmoid = True, reduction = 'mean', smoo
    # self_a = 0.4
   # self.combined_loss = lambda y_pred, y_true: self.a * self.loss_bce(y_pred,
    # # combined weighted bce + dice loss
    # self.loss function = self.combined loss
    self.loss_focal = FocalLoss(gamma = 2, alpha = 0.90, weight = None,
                                reduction = 'mean')
    self.loss_tversky = TverskyLoss(alpha = 0.6, beta = 0.4, reduction = 'mean',
                                    sigmoid = True, smooth_nr = 1e-4, smooth_dr
    self_a = 0.6
    self.combined_loss = lambda y_pred, y_true: self.a * self.loss_focal(y_pred,
    # combined weighted focal + tversky loss
    self.loss_function = self.combined_loss
def forward(self, pixel_values, labels = None):
    encoder_outputs = self.vit(pixel_values, return_dict = True)
                                                                        # hidden
    patch_embeddings = encoder_outputs.last_hidden_state[:, 1:, :]
                                                                        # [batch
    patch_features = self.decoder(patch_embeddings)
                                                                        # passes
    batch_size = patch_features.shape[0]
                                                                         # return
    spatial_logits = patch_features.transpose(1, 2).reshape(
        batch_size, 64, self.num_patches, self.num_patches)
                                                                         # trans
    ups_logits = self.upsample(spatial_logits)
                                                                         # upsamp
    if labels is not None:
                                                                         # if gro
        labels = (labels > 0.5).float()
        loss = self.loss_function(ups_logits, labels)
        return {'loss': loss, "logits": ups_logits}
                                                                         # return
    else:
        return ups_logits
                                                                         # return
def predict(self, pixel_values, threshold):
    with torch.no_grad():
        logits = self.forward(pixel_values)
                                                                         # comput
```

```
probas = torch.sigmoid(logits)  # comput
  bin_msk = (probas > threshold).float()  # create
  return bin_msk  # bin_ms

def unfreeze(self):
  for par in self.vit.parameters():
    par.requires_grad = True  # unfre
  print('vit encoder unfrozen')
# comput
# comput
# comput
# comput
# unfre
```

Training

```
dice_mm = mm.DiceMetric(include_background=False, reduction = 'mean', get_not_nans=F
```

```
# define eval metrics
def eval metrics(evalpred):
   logits = evalpred.predictions
                                                            # returns model pred on
   y_true = evalpred.label_ids
                                                            # returns gt mask on val
    probas = 1 / (1 + np.exp(-logits))
                                                            # sigmoid function
   y_pred = (probas > 0.2).astype(np.float32)
                                                            # convert to binary
   y_pred_fl = y_pred.ravel().astype(int)
                                                           # flatten for sklearn
   y_true_fl = y_true.ravel().astype(int)
   y_pred_tensor = torch.from_numpy(y_pred.astype(np.float32))
   y_true_tensor = torch.from_numpy(y_true.astype(np.float32))
   y_pred_1hot = one_hot(y_pred_tensor, num_classes = 2)
   y_true_1hot = one_hot(y_true_tensor, num_classes = 2)
   # compute metrics
   acc = accuracy_score(y_pred_fl, y_true_fl)
    f1 = f1_score(y_pred_fl, y_true_fl, zero_division = 0)
    prec = precision_score(y_pred_fl, y_true_fl, zero_division = 0)
    rec = recall_score(y_pred_fl, y_true_fl, zero_division = 0)
   js = jaccard_score(y_pred_fl, y_true_fl, zero_division = 0)
   # dice and iou scores
   # dice_score = DiceScore(num_classes = 2, include_background = False)
   # dice = dice_score(y_pred_tensor, y_true_tensor)
   dice_score = dice_mm(y_pred_1hot, y_true_1hot)
   dice = dice_mm.aggregate().item()
   dice mm.reset()
                                                          # reset dice for next epoc
   # hausdorff = HausdorffDistance(num_classes = 2, include_background = False,
    #
                             distance_metric = 'euclidean', directed = False)
   # hd = hausdorff(y_pred_tensor, y_true_tensor)
    res_dict = {'acc': acc, 'dice': dice, 'f1': f1, 'rec': rec, 'prec': prec, 'jacc'
    return res_dict
```

```
vit = ViT(model_id, img_size = 224, patch_size = 16, freeze = True)
```

Some weights of ViTModel were not initialized from the model checkpoint a You should probably TRAIN this model on a down-stream task to be able to encoder backbone frozen

```
cpu
ViT(
  (vit): ViTModel(
    (embeddings): ViTEmbeddings(
      (patch_embeddings): ViTPatchEmbeddings(
        (projection): Conv2d(3, 768, kernel_size=(16, 16), stride=(16,
16))
      (dropout): Dropout(p=0.0, inplace=False)
    (encoder): ViTEncoder(
      (laver): ModuleList(
        (0-11): 12 x ViTLayer(
          (attention): ViTAttention(
            (attention): ViTSelfAttention(
              (query): Linear(in features=768, out features=768,
bias=True)
              (key): Linear(in_features=768, out_features=768,
bias=True)
              (value): Linear(in features=768, out features=768,
bias=True)
            (output): ViTSelfOutput(
              (dense): Linear(in_features=768, out_features=768,
bias=True)
              (dropout): Dropout(p=0.0, inplace=False)
          (intermediate): ViTIntermediate(
            (dense): Linear(in_features=768, out_features=3072,
bias=True)
            (intermediate_act_fn): GELUActivation()
          (output): ViTOutput(
            (dense): Linear(in_features=3072, out_features=768,
bias=True)
            (dropout): Dropout(p=0.0, inplace=False)
          (layernorm_before): LayerNorm((768,), eps=1e-12,
elementwise_affine=True)
          (layernorm_after): LayerNorm((768,), eps=1e-12,
```

```
targs1 = TrainingArguments(
    output_dir = 'training/vitbase/p1',
                                                            # separate training outp
   # logging_dir = 'training/vit-b16/logs',
    report_to = ['none'],
    num_train_epochs = 15,
                                                         # training decoder, use mor
    per_device_train_batch_size = 25,
    per_device_eval_batch_size = 25,
   learning rate = 1e-4,
                                                         # try 5e-4 for bigger steps
   weight_decay = 0.01,
   warmup_ratio = 0.10,
   lr_scheduler_type='cosine',
   # using fp32 -- full precision
   fp16 = False,
                                                        # disable half precision
    bf16 = False,
                                                        # disable bfloat precision
   logging_strategy = 'epoch',
    save_strategy = 'epoch',
    eval_strategy = 'epoch',
    load_best_model_at_end = True,
                                                        # trainer saves model
                                                        # ['eval_loss', 'eval_runtim
   metric_for_best_model = 'eval_loss',
   greater is better = False,
                                                         # false for BCE + dice loss
   save_total_limit = 3,
   save_safetensors = True,
```

```
# instantiate trainer
trainer1 = Trainer(
    model = vit,
    args = targs1,
    train_dataset = ds_train,
    eval_dataset = ds_val,
    compute_metrics = eval_metrics,
    callbacks = [EarlyStoppingCallback(early_stopping_patience = 5)]
)
```

```
from accelerate.state import AcceleratorState
from accelerate import Accelerator

AcceleratorState._reset_state()
accel = Accelerator()
```

		[600/600 01:40, Epoch 15/15]							
Epoch	Training Loss	Validation Loss	Acc	Dice	F1	Rec	Prec	J	
1	0.390300	0.389750	0.021255	0.041451	0.041625	0.021255	1.000000	0.	
2	0.385800	0.383294	0.029512	0.041784	0.041960	0.021430	0.999906	0.	
3	0.383300	0.382240	0.038389	0.042145	0.042324	0.021619	0.999719	0.	
4	0.382100	0.378811	0.127277	0.046154	0.046360	0.023731	0.998050	0.	
5	0.381200	0.379672	0.118990	0.045770	0.045971	0.023527	0.998659	0.	
6	0.380600	0.379299	0.129754	0.046295	0.046499	0.023804	0.998336	0.	
7	0.380000	0.377210	0.237855	0.052289	0.052546	0.026986	0.994346	0.	
8	0.379500	0.377718	0.193238	0.049663	0.049885	0.025583	0.996446	0.	
9	0.379000	0.375055	0.383596	0.062848	0.063210	0.032660	0.978415	0.	
10	0.378600	0.376921	0.228771	0.051763	0.051999	0.026697	0.995148	0.	
11	0.378100	0.374736	0.338667	0.059327	0.059637	0.030748	0.986638	0.	
12	0.377700	0.374625	0.315680	0.057614	0.057899	0.029822	0.989348	0.	
13	0.377400	0.374289	0.311381	0.057292	0.057573	0.029649	0.989611	0.	
14	0.377200	0.374526	0.296787	0.056263	0.056532	0.029095	0.991209	0.	
15	0.377100	0.374249	0.312125	0.057350	0.057632	0.029680	0.989615	0.	
TrainOu	tput(globa	al step=600,	training	g loss=0.	380529961	.58599856	, metrics	=	

```
# reinstantiate
vitp2 = ViT(model_id, img_size = 224, patch_size = 16, freeze = False)

# load params
checkpoint = trainer1.state.best_model_checkpoint
# checkpoint = 'training/vit16/phase_1/checkpoint-2760'

# load safetensors file
w_path = checkpoint + '/model.safetensors'

print(w_path)
# load weights into model
state = load_file(w_path, device = 'cpu')
vitp2.load_state_dict(state)
```

```
print(device)
vitp2.to(device)
```

```
Some weights of ViTModel were not initialized from the model checkpoint
You should probably TRAIN this model on a down-stream task to be able to
encoder backbone training enabled
training/vitbase/p1/checkpoint-600/model.safetensors
cpu
ViT(
  (vit): ViTModel(
    (embeddings): ViTEmbeddings(
      (patch_embeddings): ViTPatchEmbeddings(
        (projection): Conv2d(3, 768, kernel_size=(16, 16), stride=(16,
16))
      (dropout): Dropout(p=0.0, inplace=False)
    (encoder): ViTEncoder(
      (layer): ModuleList(
        (0-11): 12 x ViTLayer(
          (attention): ViTAttention(
            (attention): ViTSelfAttention(
              (query): Linear(in_features=768, out_features=768,
bias=True)
              (key): Linear(in_features=768, out_features=768,
bias=True)
              (value): Linear(in features=768, out features=768,
bias=True)
            (output): ViTSelfOutput(
              (dense): Linear(in_features=768, out_features=768,
bias=True)
              (dropout): Dropout(p=0.0, inplace=False)
          (intermediate): ViTIntermediate(
            (dense): Linear(in features=768, out features=3072,
bias=True)
            (intermediate_act_fn): GELUActivation()
          (output): ViTOutput(
            (dense): Linear(in_features=3072, out_features=768,
bias=True)
            (dropout): Dropout(p=0.0, inplace=False)
          (layernorm_before): LayerNorm((768,), eps=1e-12,
elementwise_affine=True)
          (layernorm_after): LayerNorm((768,), eps=1e-12,
elementwise_affine=True)
```

```
targs2 = TrainingArguments(
   output_dir = 'training/vitp2/p2',
                                                          # separate training output
   # logging_dir = 'training/vit-b16/logs',
    report to = ['none'],
   num_train_epochs = 100,
                                                          # training decoder, use mo
   per_device_train_batch_size = 25,
   per_device_eval_batch_size = 25,
   learning_rate = 1e-4,
                                                         # try 5e-4 for bigger steps
   weight_decay = 0.01,
   warmup_ratio = 0.10,
   lr_scheduler_type='cosine',
   # using fp32 -- full precision
   fp16 = False,
                                                        # disable half precision
   bf16 = False,
                                                        # disable bfloat precision
   logging_strategy = 'epoch',
   save_strategy = 'epoch',
   eval_strategy = 'epoch',
   load_best_model_at_end = True,
                                                        # trainer saves model
                                                       # ['eval_loss', 'eval_runtim
   metric_for_best_model = 'eval_loss',
   greater_is_better = False,
                                                         # false for BCE + dice loss
   save_total_limit = 3,
   save_safetensors = True,
```

```
trainer2 = Trainer(
    model = vitp2,
    args = targs2,
    train_dataset = ds_train,
    eval_dataset = ds_val,
    compute_metrics = eval_metrics,
    callbacks = [EarlyStoppingCallback(early_stopping_patience = 30)]
)
```

91/100]

Epoch	Training Loss	Validation Loss	Acc	Dice	F1	Rec	Prec
1	0.377500	0.374256	0.353429	0.060493	0.060801	0.031369	0.984655
2	0.376600	0.387739	0.099282	0.044814	0.045006	0.023022	0.998561
3	0.375200	0.372299	0.291278	0.055929	0.056139	0.028887	0.991617
4	0.372600	0.374585	0.085245	0.044195	0.044368	0.022688	0.999076
5	0.370000	0.369869	0.159885	0.047791	0.047928	0.024556	0.994890
6	0.366200	0.363797	0.065657	0.043364	0.043494	0.022231	0.999451
7	0.362300	0.353678	0.358062	0.061564	0.061686	0.031832	0.992766
8	0.358800	0.361820	0.072629	0.043931	0.043818	0.022400	0.999733
9	0.355100	0.350454	0.278476	0.058576	0.055436	0.028511	0.996160
10	0.351700	0.346976	0.407262	0.085932	0.066124	0.034208	0.987304
11	0.348400	0.322476	0.879974	0.268295	0.239593	0.138438	0.889646
12	0.346100	0.357123	0.230282	0.084222	0.051736	0.026564	0.987895
13	0.341900	0.354670	0.283212	0.087001	0.055376	0.028486	0.988490
14	0.338200	0.335760	0.479340	0.157711	0.073187	0.038032	0.967186
15	0.333400	0.310782	0.647568	0.229161	0.101956	0.053897	0.941255
16	0.330100	0.324500	0.517167	0.230967	0.075108	0.039148	0.922375
17	0.326200	0.333002	0.432570	0.197307	0.066465	0.034437	0.950360
18	0.322600	0.317715	0.640068	0.277604	0.095313	0.050346	0.892046
19	0.317900	0.335726	0.393300	0.183173	0.062570	0.032347	0.952615
20	0.313100	0.334751	0.404473	0.191256	0.063438	0.032816	0.948916
21	0.310100	0.318140	0.475516	0.226961	0.071033	0.036906	0.943421
22	0.306500	0.356484	0.184189	0.112424	0.048536	0.024885	0.978992
23	0.303100	0.303341	0.586903	0.269088	0.086856	0.045569	0.924330
24	0.298400	0.317133	0.474759	0.228177	0.070929	0.036850	0.943304
25	0.295100	0.297112	0.955981	0.471389	0.387503	0.275116	0.655130
26	0.295000	0.276304	0.749190	0.328234	0.133967	0.072289	0.912694

27	0.289100	0.309866	0.528282	0.263693	0.076618	0.039972	0.920767
28	0.284600	0.298156	0.621857	0.288601	0.093655	0.049341	0.919196
29	0.280300	0.270172	0.751135	0.357761	0.132684	0.071650	0.895614
30	0.276500	0.254082	0.851719	0.402855	0.201629	0.113843	0.880944
31	0.272400	0.279728	0.680295	0.308460	0.109374	0.058129	0.923603
32	0.268300	0.254315	0.821704	0.396370	0.173824	0.096407	0.882459
33	0.264400	0.250748	0.837612	0.402916	0.188502	0.105451	0.887353
34	0.260800	0.244500	0.861637	0.423271	0.211304	0.120217	0.872036
35	0.258000	0.255945	0.766177	0.383135	0.140548	0.076229	0.899505
36	0.253300	0.268246	0.700209	0.343494	0.115159	0.061433	0.917837
37	0.247800	0.245029	0.837034	0.426232	0.187188	0.104693	0.882881
38	0.243900	0.253232	0.827886	0.378814	0.184967	0.102834	0.918864
39	0.241400	0.252760	0.769104	0.425140	0.136627	0.074211	0.859547
40	0.239800	0.250118	0.821422	0.411548	0.176052	0.097597	0.897607
41	0.234800	0.248259	0.801783	0.434560	0.156438	0.085998	0.864732
42	0.229900	0.250701	0.785326	0.439230	0.143834	0.078578	0.848393
43	0.225100	0.247380	0.787474	0.425254	0.148530	0.081178	0.872111
44	0.225000	0.222112	0.898521	0.478603	0.261800	0.154841	0.846616
45	0.218200	0.221114	0.903428	0.473926	0.274173	0.163149	0.858145
46	0.217500	0.222998	0.893975	0.476806	0.253948	0.149304	0.848988
47	0.214200	0.237704	0.833276	0.430601	0.182729	0.101991	0.876912
48	0.214000	0.217665	0.930234	0.531431	0.330902	0.207813	0.811651
49	0.204600	0.244957	0.763868	0.447162	0.132276	0.071742	0.846780
50	0.200000	0.252589	0.693633	0.385618	0.109899	0.058566	0.889838
51	0.199200	0.218615	0.912365	0.504090	0.289667	0.174979	0.840681
52	0.196800	0.210949	0.897243	0.507225	0.256719	0.151679	0.834900
53	0.188700	0.220225	0.887005	0.510751	0.236843	0.138271	0.824937
54	0.183100	0.211204	0.940622	0.540036	0.362553	0.234867	0.794458
55	0.179900	0.214743	0.919099	0.516878	0.306158	0.187204	0.839757
				0 = 0000	0.00000		2 22222

56	0.175000	0.209422	0.941221	0.536884	0.368826	0.238949	0.808003
57	0.176600	0.206753	0.955504	0.526436	0.441062	0.300858	0.825978
58	0.175000	0.210731	0.940567	0.524615	0.369712	0.238649	0.820099
59	0.168600	0.210328	0.926751	0.544794	0.314477	0.196283	0.790464
60	0.165900	0.203980	0.954113	0.541333	0.427928	0.291100	0.807469
61	0.162900	0.203941	0.909611	0.519897	0.280190	0.168639	0.827685
62	0.159400	0.208268	0.909788	0.534115	0.274118	0.165336	0.801402
63	0.158700	0.207123	0.951253	0.550589	0.406239	0.274076	0.784571
64	0.155600	0.207994	0.923524	0.533849	0.309230	0.191351	0.805359
65	0.154900	0.206054	0.914300	0.532301	0.285101	0.173272	0.803990
66	0.151800	0.208521	0.912096	0.533159	0.280112	0.169573	0.804618
67	0.148500	0.213530	0.916100	0.541419	0.284852	0.173939	0.786137
68	0.146200	0.209285	0.916404	0.541368	0.287613	0.175616	0.793947
69	0.144700	0.209821	0.913337	0.538807	0.279959	0.170001	0.792658
70	0.142900	0.208772	0.915305	0.532750	0.286482	0.174484	0.799953
71	0.142300	0.204994	0.924371	0.537429	0.309829	0.192193	0.798678
72	0.140000	0.208107	0.921065	0.541948	0.299234	0.184415	0.792907
73	0.139700	0.207063	0.920501	0.545811	0.294600	0.181537	0.781040
74	0.138200	0.207582	0.932647	0.541924	0.331833	0.210249	0.786873
75	0.137700	0.205667	0.932687	0.541330	0.332997	0.210921	0.790544
76	0.136300	0.207650	0.930816	0.548427	0.322949	0.203882	0.776310
77	0.135600	0.206549	0.930668	0.547510	0.323110	0.203858	0.778537
78	0.133800	0.209163	0.922511	0.541837	0.300744	0.186058	0.783999
79	0.133300	0.206055	0.928278	0.543490	0.317459	0.198976	0.784744
80	0.132100	0.208427	0.926388	0.545129	0.310102	0.193620	0.778363
81	0.132400	0.210074	0.923590	0.544405	0.301913	0.187334	0.777388
82	0.132600	0.207022	0.928109	0.544536	0.315026	0.197512	0.777787
83	0.131500	0.207431	0.929847	0.543640	0.320848	0.201986	0.779643
84	0.131300	0.207678	0.924495	0.540209	0.306517	0.190434	0.785072
85	0.130100	0.207677	0.930132	0.547188	0.320047	0.201757	0.773623

86	0.130600	0.209666	0.923295	0.540501	0.302627	0.187557	0.783033
87	0.129500	0.207567	0.928399	0.545925	0.315408	0.197927	0.776029
88	0.129900	0.209017	0.928687	0.543926	0.316656	0.198822	0.777374
89	0.129300	0.206320	0.932492	0.543434	0.328765	0.208431	0.777824
90	0.129100	0.207300	0.930716	0.544373	0.322640	0.203635	0.776329
91	0.129300	0.210549	0.923350	0.540733	0.301790	0.187124	0.779376

```
# os.chdir('/content/drive/MyDrive/XRA')
os.getcwd()
```

```
torch.save(trainer2.model.state_dict(), 'vit_base.pt')
```

from monai.networks.utils import one_hot

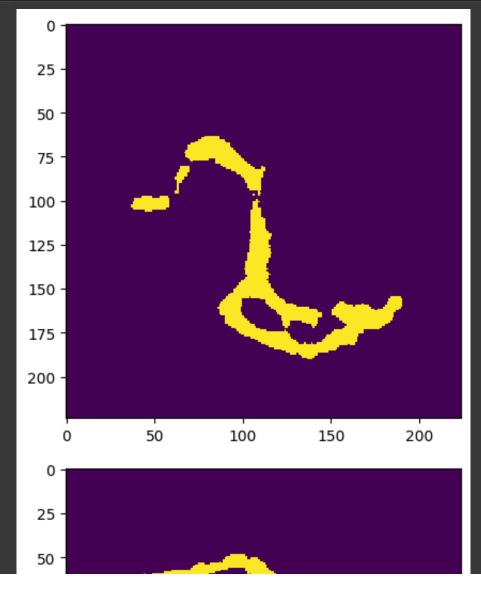
dice_mm = mm.DiceMetric(include_background=False, reduction = 'mean', get_not_nans=F

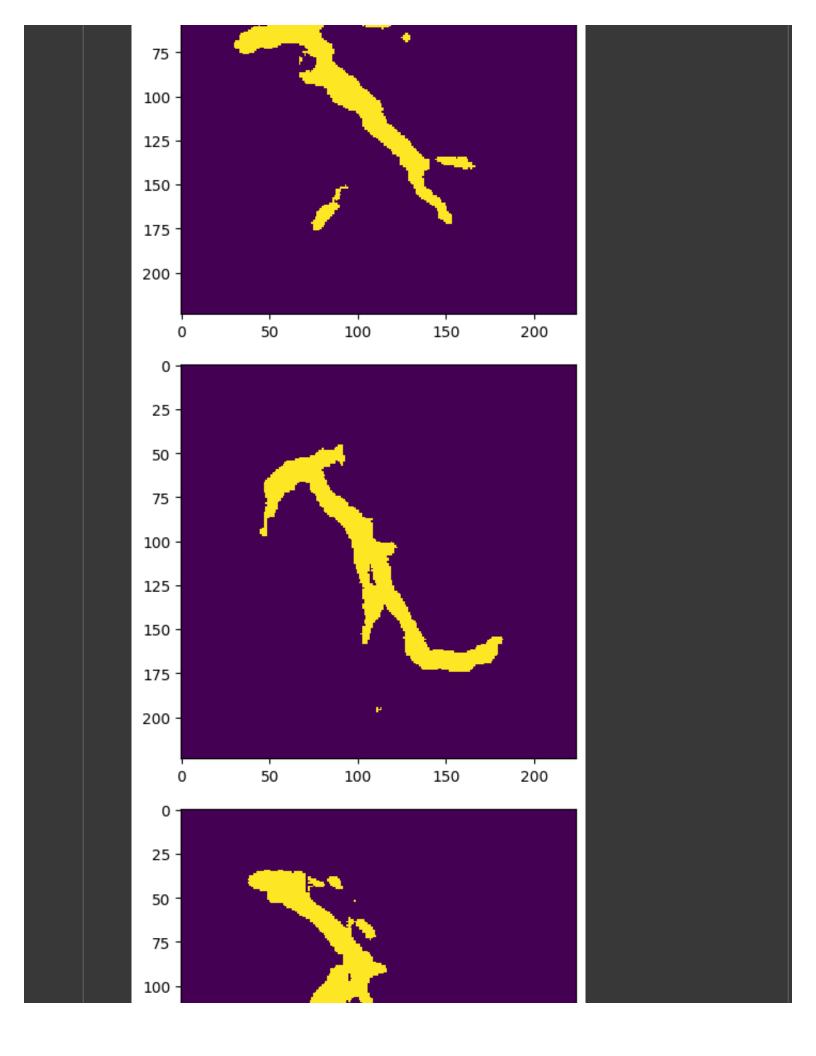
^{&#}x27;/content/drive/MyDrive/XRA'

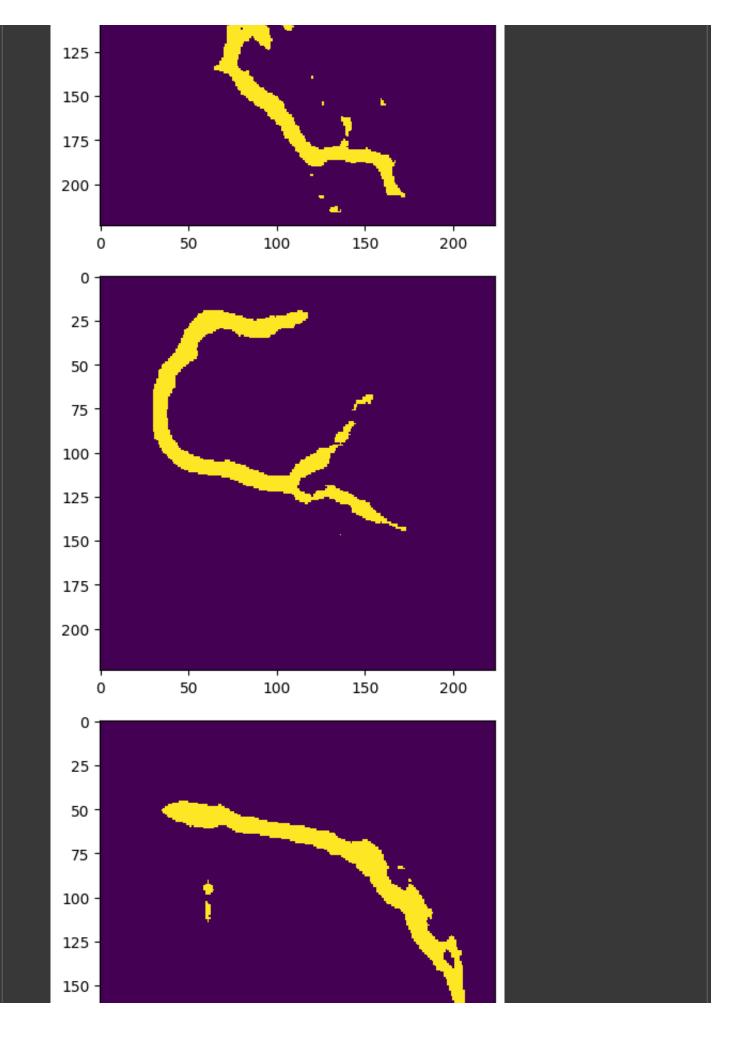
```
def get_metrics(y_pred, y_true):
    # for sklearn
    y_pred_np = y_pred.numpy().ravel().astype(int)
    y_true_np = y_true.numpy().ravel().astype(int)
    y_pred_tensor = y_pred
    y_true_tensor = y_true
    # compute metrics
    acc = accuracy_score(y_pred_np, y_true_np)
    f1 = f1_score(y_pred_np, y_true_np, zero_division = 0)
    prec = precision_score(y_pred_np, y_true_np, zero_division = 0)
    rec = recall_score(y_pred_np, y_true_np, zero_division = 0)
    js = jaccard_score(y_pred_np, y_true_np, zero_division = 0)
    # dice and hausdorff scores
    # pred_fg = y_pred
    \# pred_bg = 1 - y_pred
    # pred_dice = torch.cat([pred_bg, pred_fg], dim = 1)
    # dice_score = DiceScore(num_classes = 2, include_background = False)
    # dice = dice_score(y_pred_tensor, y_true_tensor)
    y_pred_1hot = one_hot(y_pred, num_classes = 2)
    y_true_1hot = one_hot(y_true, num_classes = 2)
    dice_score = dice_mm(y_pred_1hot, y_true_1hot)
    dice = dice_mm.aggregate().item()
    # hausdorff = HausdorffDistance(num_classes = 2, include_background = False,
                                    distance_metric = 'euclidean', directed = False)
    # hd = hausdorff(y_pred_tensor, y_true_tensor)
    res = {'acc': acc, 'dice': dice, 'f1': f1, 'rec': rec, 'prec': prec, 'jacc': js }
    return res
# visnr.to(device = 'cpu')
vitp2.to(device = 'cpu')
y_pred = vitp2.predict(test_x, threshold = 0.6)
```

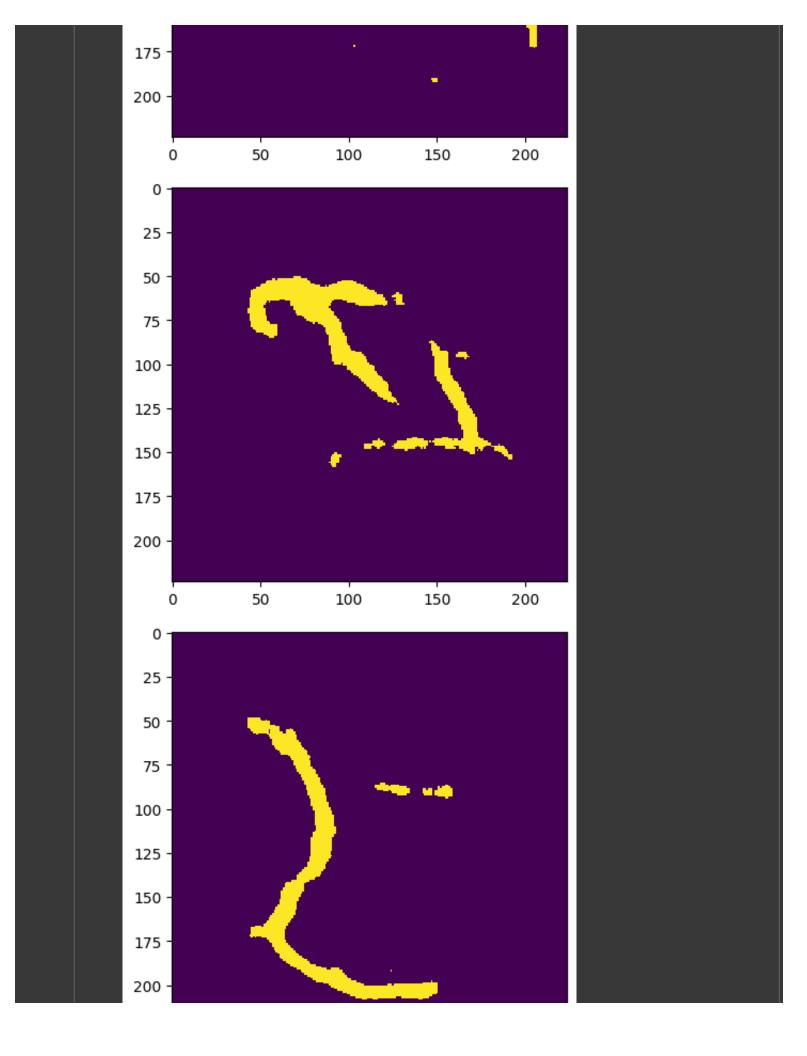
y = test y

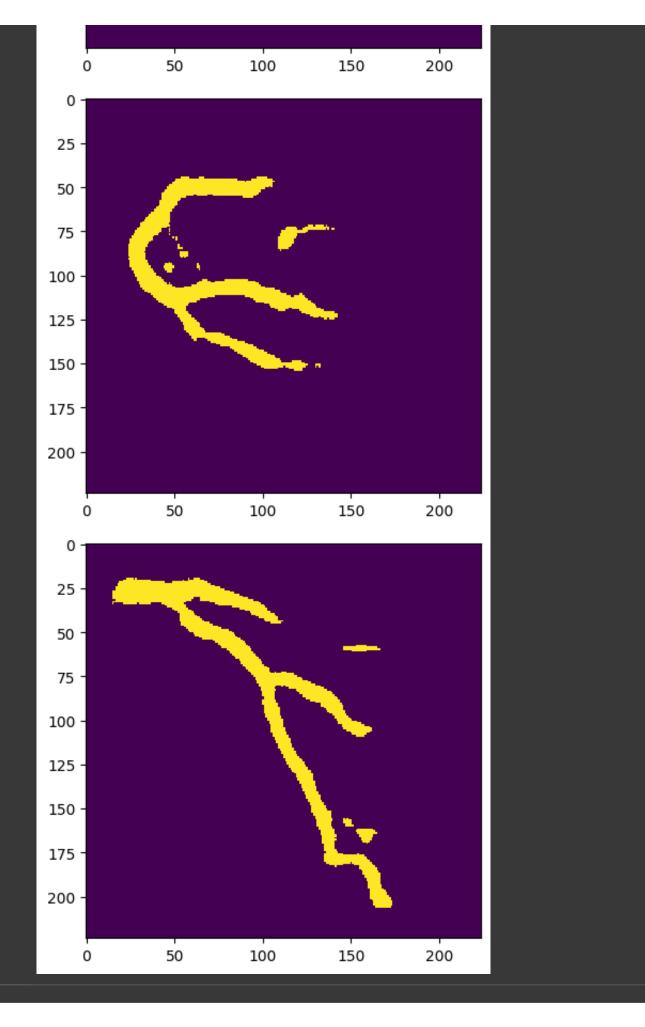
```
get_metrics(y_pred, y)
{'acc': 0.9617795360331632,
 'dice': 0.4230040907859802,
 'f1': 0.4290161899081285,
 'rec': 0.31365722768915083,
 'prec': 0.6785940786788484,
 'jacc': np.float64(0.2730875946347528)}
y_pred.shape
torch.Size([300, 1, 224, 224])
color_sequences = ['viridis', 'plasma', 'inferno', 'magma', 'cividis']
for i in range(10):
   pred_mask = y_pred[i].squeeze().numpy()
   plt.imshow(pred_mask, cmap = 'viridis',
              vmax = 0.75, vmin = 0.25, interpolation = 'nearest')
   plt.show()
```











```
# os.chdir('/content/drive/MyDrive/XRA')
os.getcwd()
'/content/drive/MyDrive/XRA'
```