

Applications of algebraic effect theories

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Reasoning about programs

$$f_1 = \text{fun } x \mapsto x + x$$

$$f_2 = \text{fun } x \mapsto 2 * x$$

We know mathematical properties of operations $+$ and $*$ so we can argue that the functions are equal (whatever that means).

Harder with effectful operations, such as *print*.

$$\text{print_twice} = \text{fun } s \mapsto \text{print } s; \text{print } s$$

$$\text{print_double} = \text{fun } s \mapsto \text{print } s \wedge s$$

“Implementing print”

We give meaning to operations with handlers. An example:

```
collect_prints = handler {  
  | print(s; k)  $\mapsto$   
    do (v, s')  $\leftarrow$  k () in (v, s ^ s')  
  | ret x  $\mapsto$  (x, "")  
}
```

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and proceeds with the evaluation

`do (v, s') ← k () in
 (v, "test" ^ s')`

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We want reasoning tools that can separate handlers from the rest of our code!

The theory of algebraic effects consists of operations and **equations** between them.

We can use equations such as

$$\textit{print } s_1; \textit{ print } s_2 \sim \textit{print } s_1 \wedge s_2$$

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Can we achieve that without restricting ourselves to a global effect theory?

Idea

Include the desired equations in types.

$$\underline{C} = A! \Sigma / \mathcal{E}$$

Operations of type \underline{C} either return a value of type A or call an operation from Σ in the effect theory \mathcal{E} .

Equations in \mathcal{E} tell us what computations we deem equal.

Term Syntax

values v	$::=$	x	variable
		$()$	unit constant
		$\text{true} \mid \text{false}$	boolean constants
		$\text{fun } x \mapsto c$	function
		$\text{handler } (\text{ret } x \mapsto c_r; h)$	handler

computations c	$::=$	$\text{if } v \text{ then } c_1 \text{ else } c_2$	conditional
		$v_1 \ v_2$	application
		$\text{ret } v$	returned value
		$\text{op}(v; y.c)$	operation call
		$\text{do } x \leftarrow c_1 \text{ in } c_2$	sequencing
		$\text{with } v \text{ handle } c$	handling

operation clauses $h \quad ::= \quad \emptyset \mid h \cup \{\text{op}(x; k) \mapsto c_{op}\}$

Type Syntax

(value) type A, B	$::=$	<code>unit</code>	unit type
	$ $	<code>bool</code>	boolean type
	$ $	$A \rightarrow \underline{C}$	function type
	$ $	$\underline{C} \Rightarrow \underline{D}$	handler type

computation type $\underline{C}, \underline{D} ::= A! \Sigma / \mathcal{E}$

signature $\Sigma ::= \emptyset \mid \Sigma \cup \{op : A \rightarrow B\}$

Type Syntax (additions)

value context $\Gamma ::= \varepsilon \mid \Gamma, x:A$

template context $Z ::= \varepsilon \mid Z, z:A \rightarrow *$

template $T ::=$
 $z \ v$
 $\mid \text{ if } v \text{ then } T_1 \text{ else } T_2$
 $\mid \text{ op}(v; y.T)$

(effect) theory $\mathcal{E} ::= \emptyset \mid \mathcal{E} \cup \{\Gamma; Z \vdash T_1 \sim T_2\}$

The *any type* $*$ used in template types can be instantiated to any computation type so that we can reuse templates.

Full equation

$$\Gamma; Z = (x:\text{string}, y:\text{string}); (z:\text{unit} \rightarrow *)$$

$$\Gamma; Z \vdash \text{print}(x; _.\text{print}(y; _.\text{z} ())) \sim \text{print}(x^{\wedge}y; _.\text{z} ())$$

We can use different kinds of logics

We can use any logic that implements some kind of **respects** relation (though there are requirements for denotational semantics to make sense).

The simplest logic we can use is the free logic, in which

$$\frac{\Gamma \vdash h:\Sigma \Rightarrow \underline{D}}{\Gamma \vdash h:\Sigma \Rightarrow \underline{D} \text{ respects } \emptyset}$$

and corresponds to the conventional approach where we ignore equations.