Data-Driven Discovery of Partial Differential Equations

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Partial Differential Equations - Governing a System

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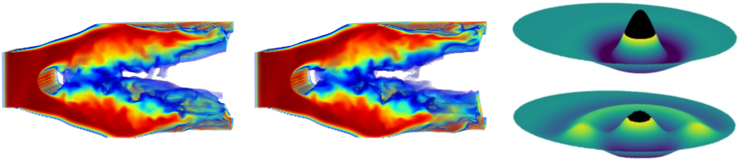

Figure: Left: the 3D Navier-Stokes Equation. Right: the 2D wave equation

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Obtaining the PDE - Mathematical Deduction vs Data-Driven Discovery

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Data-driven PDE discovery

- Suppose we have a dataset for a system regarding a certain quantity u, but the governing equation for u is unknown. Assume its governing equation is of the generic form

$$u_t = F(u, u_x, u_{xx}, \dots, x, \mu), \tag{4}$$

where $F(\cdot)$ **is an unknown, usually nonlinear function of** $u(x, t)$ **and its derivatives, parameterized by** μ. Goal: to discover F from the data.

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  where $F(\cdot)$ **is an unknown, usually nonlinear function of** $u(x,t)$ **and its derivatives, parameterized by** μ. Goal: to discover F from the data.
- **Input data** $\mathbf{U} \in \mathbb{C}^{mn}$ is **a matrix of values of** u collected at m time points with time interval Δt and n spatial locations with space interval Δx given by

$$\mathbf{U} = \begin{bmatrix} u(0,0) & \ldots & u(n\Delta x, 0) \\ \vdots & & \vdots \\ u(0, m\Delta t) & \ldots & u(n\Delta x, m\Delta t) \end{bmatrix}. \tag{5}$$

  $\mathbf{U}$ is flattened as a vector $[u(0,0)\ldots u(n\Delta x,0)\ldots u(0,m\Delta t)\ldots u(n\Delta x, m\Delta t)]$ of length mn to serve as the input to our the machine learning algorithm.

Discretizing Target PDE and Learning Coefficients

Applying numerical methods (finite difference methods, or polynomial interpolation) to input data $\mathbf{U}$ yields **a discrete dataset $\mathbf{U}_t$ of time derivative** u_t. The discrete form of the target PDE $u_t = F(u, u_x, u_{xx}, \ldots, x, \mu)$ can thus be written as

$$\mathbf{U}_t = [u_t(0,0) \ldots u_t(n\Delta x, m\Delta t)]^T = \mathbf{\Theta}(\mathbf{U}, \mathbf{Q})\xi. \tag{6}$$

Here $\mathbf{Q} \in \mathbb{C}^{mn}$ denotes **additional input**, and $\mathbf{\Theta}(\mathbf{U}, \mathbf{Q}) \in \mathbb{C}^{mn \times D}$ is **a library of D candidate terms** and takes the form

$$\mathbf{\Theta}(\mathbf{U}, \mathbf{Q}) = [\mathbf{1} \quad \mathbf{U} \quad \mathbf{U^2} \ldots \quad \mathbf{Q} \quad \ldots \quad \mathbf{U}_x \quad \mathbf{U}\mathbf{U}_x \quad \ldots]. \tag{7}$$

$\xi \in \mathbb{C}^D$ **is the coefficient vector** containing coefficients of each of the candidate terms. We apply machine learning methods to obtain the correct coefficient vector ξ.

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Example (Diffusion Equation)

Suppose the data $\mathbf{U}$ is governed by the 1D heat equation $u_t = du_{xx}$, then we may build a library of $D = 6$ candidate terms

$$\mathbf{\Theta}(\mathbf{U}, \mathbf{Q}) = [\mathbf{1} \quad \mathbf{U} \quad \mathbf{U^2} \quad \mathbf{U}_x \quad \mathbf{U}_{xx} \quad \mathbf{U}\mathbf{U}_x],$$

and if our method is successful, we will get a coefficient vector $\xi \in \mathbb{C}^{D=6}$ that takes the value

$$\xi = [0\ 0\ 0\ 0\ 1\ 0]^T.$$

Sparse Regression: Ridge, LASSO, and Elastic Net

Our goal is to find the optimal coefficient vector $\xi \in \mathbb{C}^D$ satisfying

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- ξ is sparse, so that only the most relevant terms are included.

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Three Types of Sparse Regression

- **Ridge Regression**: aims to find $\hat{\xi}$ that minimizes the loss function

$$\hat{\xi} = \text{argmin}_\xi L(\xi), \text{where } L(\xi) = \|\mathbf{\Theta}\xi - \mathbf{U}_t\|_2^2 + \lambda\|\xi\|_2, \tag{8}$$

  where $\|\xi\|_2 = \sqrt{\xi_1^2 + \cdots + \xi_D^2}$ is the L_2 norm and λ a constant coefficient

- **LASSO Regression**: similar structure, but uses L_1 norm instead of the L_2 norm

$$L(\xi) = \|\mathbf{\Theta}\xi - \mathbf{U}_t\|_2^2 + \alpha\|\xi\|_1, \tag{9}$$

  where $\|\xi\|_1 = |\xi_1|_+ \cdots + |\xi_D|$ is the L_1 norm.

- **Elastic Net Regression** simply combines the two regularization terms above:

$$L(\xi) = \|\mathbf{\Theta}\xi - \mathbf{U}_t\|_2^2 + \lambda\|\xi\|_2 + \alpha\|\xi\|_1. \tag{10}$$

Minimizing $\|\mathbf{\Theta}\xi - \mathbf{U}_t\|_2^2$ fits ξ to the data $\mathbf{U_t}$, and minimizing $\|\xi\|_1$ and/or $\|\xi\|_2$ helps ensuring that coefficients of irrelevant candidate terms are small.

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Sequential Threshold Ridge Regression

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$$\hat{\xi} = \mathrm{argmin}_{\xi} L(\xi), \text{where } L(\xi) = \|\boldsymbol{\Theta}(\mathbf{U}, \mathbf{Q})\xi - \mathbf{U}_t\|_2^2 + \epsilon\kappa(\boldsymbol{\Theta}(\mathbf{U}, \mathbf{Q}))\|\xi\|_0. \tag{11}$$

$\|\cdot\|_0$ is the L_0 **norm that counts the number of nonzero elements** in ξ, $\kappa(\boldsymbol{\Theta}(\mathbf{U}, \mathbf{Q}))$ is the **condition number** of the matrix $\boldsymbol{\Theta}$.

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Algorithm 4: Sequential Threshold Ridge Regression:STRidge($\boldsymbol{\Theta}, \mathbf{U}_t, \lambda, tol$, iters, num_big)

$\hat{\xi} \leftarrow \text{argmin}_{\xi}(\|\boldsymbol{\Theta}\xi - \mathbf{U}_t\|_2^2 + \lambda\|\xi\|_2)$ `#standard ridge regression`

bigInds $\leftarrow \{j : |\hat{\xi}_j| \geq tol\}$ `#select indices of large coefficients`

`#Check if number of big coefficients changed from last time`

if *num_big != len(biginds)* **then**

- num_big $\leftarrow$ len(biginds) `#Updates number of big coefficients`
- $\hat{\xi}[\sim$ biginds$] \leftarrow 0$ `#set small coefficients to 0`
- $\hat{\xi}$[biginds] $\leftarrow$ STRidge($\boldsymbol{\Theta}$[:, biginds], $\mathbf{U}_t, \lambda, tol$, iters $-$ 1, num_big) `#recursive call with fewer coefficients`

else

- **return** $\hat{\xi}$

end

Generating Simulation Data with Finite Difference Method

It remains to obtain the input data $\mathbf{U} = (u(j\Delta x, k\Delta t))_{j=1,k=1}^{n,m} = (U_j^k)_{j=1,k=1}^{n,m}$, which can be generated using **finite difference methods (FDM)**.

Finite Difference Methods: FTCS and Crank-Nicholson

- **Forward difference in time, central difference for space (FTCS):**

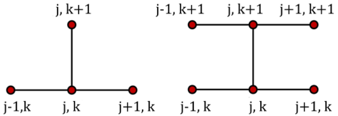
$$U_t \approx \frac{U_j^{k+1} - U_j^k}{\Delta t}, \; U_x = \frac{U_{j+1}^k - U_{j-1}^k}{2\Delta x}, \; U_{xx} = \frac{U_{j+1}^k - 2U_j^k + U_{j+1}^k}{2(\Delta x)^2} \tag{12}$$

- **Crank-Nicholson method,** which uses the same formulation of U_t and U_x but

$$UU_x = \frac{1}{2}\left(U_j^k \frac{U_{j+1}^{k+1} - U_{j-1}^k}{2\Delta x} + U_j^{k+1} \frac{U_{j+1}^k - u_{j-1}^k}{2\Delta x} \right) \tag{13}$$

$$U_{xx} \approx \frac{1}{2}\left(\frac{U_{j+1}^{k+1} - 2U_j^{k+1} + U_{j-1}^{K+1}}{2\Delta x} + U_j^{k+1} \frac{U_{j+1}^k - U_{j-1}^k}{2\Delta x} \right) \tag{14}$$

Schematics for the two methods are shown on the right. Since initial conditions $(U_j^0)_{j=1}^n$ and boundary conditions $(U_0^k)_{k=1}^m, (U_n^k)_{k=1}^m$ are given, the rest can be calculated.



Testing results: Linear Advection Equation

We now generate data set with FDM and test the accuracy of the regression algorithm.

The advection equation

The **advection equation** is a hyperbolic equation that represents how a scalar quantity u (such as temperature, concentration, etc.) is transported by a fluid moving with a constant velocity c in a single spatial dimension. For our example we set $c = 1$ and use **Gaussian initial condition** and **periodic boundary condition**.

$$u_t(x,t) = -cu_x(x,t), \quad x \in [-L/2, L/2], t \in [0, T] \tag{15}$$

$$u(x,0) = \exp(-x^2) \quad , \tag{16}$$

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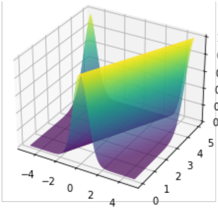
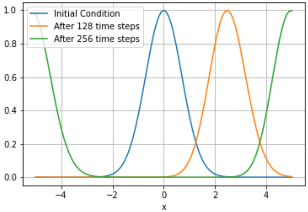
The simulation results of $u_t = -u_x$ from Crank-Nicholson is given by the figure below.





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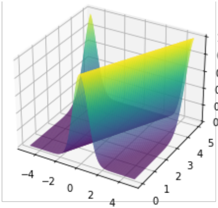

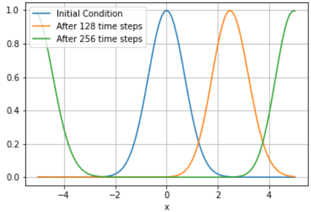

The PDE discovered by STRidge from this dataset is $u_t = 0999448u_x$.

Testing results: Diffusion Equation

The Diffusion Equation

The **diffusion equation**, also known as **the 1D heat equation**, describes how heat u (or similar diffusive scalar quantity) is distributed over time in a one dimensional system. The heat equation deals with the spreading or dissipation of heat due to diffusion.

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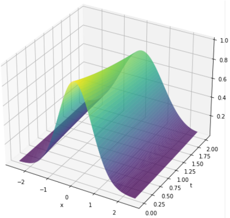
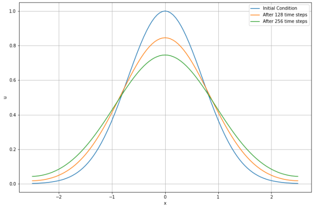
The simulation results of $u_t = 0.1u_{xx}$ from Crank-Nicholson is given by below.





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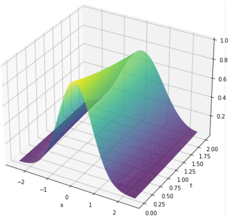

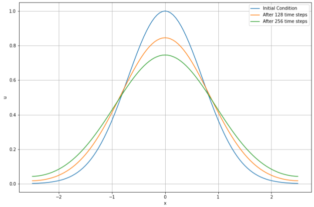

The PDE discovered by STRidge from this dataset is $u_t = 0.100003u_{xx}$.

Testing Results: Burger's Equation

Burger's Equation

Burgers' equation is a fundamental PDE from the field of fluid mechanics and can be used for studying shock waves. The equation is given by

$$u_t = -uu_x + \nu u_{xx}, \quad x \in [-L/2, L/2], t \in [0, T], \tag{19}$$

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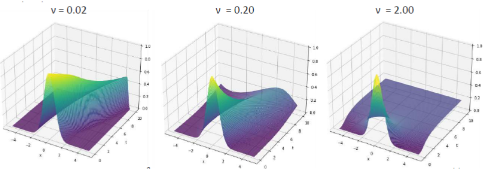
The analytical solution to viscous equation is complicated, and Crank-Nicholson simulation is preferred. Wani and Thakar (2013) provides the formulation

$$\frac{U_j^{k+1} - U_j^k}{\Delta t} + \frac{1}{4\Delta x}[U_j^k(U_{j+1}^{k+1} - U_j^{k+1}) + U_j^{k+1}(U_j^{k+1}(U_{j+1}^k - U_j^k)]$$
$$= \frac{\nu}{2(\Delta x)^2}(U_{j+1}^{k+1} - 2U_j^{k+1} + U_{j-1}^{k+1} + U_{j+1}^k - 2U_j^k + U_{j-1}^K) \tag{20}$$

ν	Discovered PDE
0.02	$u_t = -1.06uu_x + 0.29u^2u_x - 0.26u^3u_x + 0.02u_{xx}$
0.20	$u_t = -uu_x + 0.20u_xx$
2.00	$u_t = 0.04u - 0.30u^2 - 0.46u^3 + \ldots$



Effect of Smoothness

Previous results show that sparse regression appears to only work for a certain range of viscosity ν. We tested the method on $\nu = 0.01, 0.02, \ldots, 2.00$ to investigate the cut-off points.

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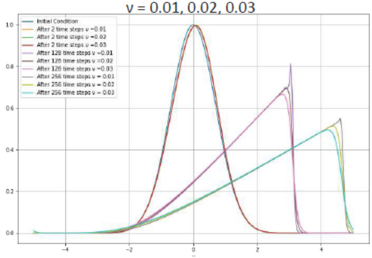
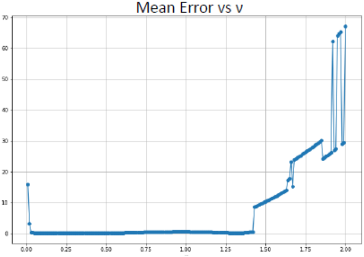
v	PDE	Mean parameter error	Std. of parameter error
0.01	u_t = (0.050140 +0.000000i)u + (-0.163713 +0.000000i)u^2 + (0.100025 +0.000000i)u^3 + ...	16.009310%	14.174193%
0.02	u_t = (-1.057625 +0.000000i)uu_{x} + (0.283156 +0.000000i)u^2u_{x} + ...	3.319493%	2.442960%
0.03	u_t = (-0.995775 +0.000000i)uu_{x} + (0.029581 +0.000000i)u_{xx}	0.420690%	0.001847%
0.04	u_t = (-0.997450 +0.000000i)uu_{x} + (0.039687 +0.000000i)u_{xx}	0.283914%	0.028941%
	...		
1.41	u_t = (-0.995066 +0.000000i)uu_{x} + (1.409464 +0.000000i)u_{xx}	0.514596%	0.021155%
1.42	u_t = (-0.994757 +0.000000i)uu_{x} + (1.419375 +0.000000i)u_{xx}	0.574683%	0.050394%
1.43	u_t = (-0.998046 +0.000000i)uu_{x} + (1.447058 +0.000000i)u_{xx} + (-0.312211 +0.000000i)uu_{xx} + ...	8.626920%	8.431511%
1.44	u_t = (-0.997805 +0.000000i)uu_{x} + (1.457516 +0.000000i)u_{xx} + (-0.320027 +0.000000i)uu_{xx} + ...	8.867872%	8.648358%
	...		
1.99	u_t = (-0.034076 +0.000000i)u + (0.260786 +0.000000i)u^2 + (-0.391764 +0.000000i)u^3 + ...	29.460429%	16.816766%
2.00	u_t = (0.000286 +0.000000i) + (-0.039955 +0.000000i)u + (0.296344 +0.000000i)u^2 +...	67.171925%	20.811909%





- $\nu < 0.02$: a shock is formed, does not identify the correct terms.
- $0.02 \le \nu \le 1.42$: retrieves the original PDE.
- $\nu \ge 1.43$: smoothing too strong, picks up unrelated terms.

Effect of Regression Type

The original paper does not test the model with LASSO and Elastic Net. To fill the blank, I modified the STRidge code to develop the algorithms STLasso and STElasticNet for further exploration.

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ν	Regression Type	Discovered PDE	Runtime (s)	Mean Error (%)	Std Error(%)
2.00	Ridge	$u_t = 2.221u^2u_{xx} - 1.751u^3u_{xx} - 0.009u_{xxx} + 0.060uu_{xxx} \dots$	1.90	67.2	20.8
2.00	LASSO	$u_t = 2.047u_{xx} - 0.750uu_{xx} + 2.284u^2u_{xx} - 1.792u^3u_{xx} \dots$	37.88	29.9	17.1
2.00	Elastic Net	$u_t = 2.047u_{xx} - 0.750uu_{xx} + 2.284u^2u_{xx} - 1.792u^3u_{xx} \dots$	8.61	29.9	17.1
0.20	Ridge	$u_t = -1.00uu_x + 0.200u_{xx}$	**1.2**	0.1	0.1
0.20	LASSO	$u_t = -1.00uu_x + 0.200u_{xx}$	**7.0**	0.1	0.1
0.20	Elastic Net	$u_t = -1.00uu_x + 0.200u_{xx}$	**8.9**	0.1	0.1
0.02	Ridge	$u_t = -0.040u + 0.296u^2 - 0.457u^3 + 0.057u_x - 1.880uu_x + \dots$	3.0	742.9	2429.8
0.02	LASSO	$u_t = -0.035u + 0.266u^2 - 0.402u^3 - 1.128uu_x + 1.411u^2u_x \dots$	18.8	701.4	2437.6
0.02	Elastic Net	$u_t = -0.035u + 0.266u^2 - 0.402u^3 - 1.128uu_x + 1.411u^2u_x \dots$	18.7	701.4	2437.6

Conclusion

- For Burger's equation, the data-driven method works well until a shock is formed.
- Ridge regression is the most efficient compared to the other two sparse regressions, and accuracy does not seem to differ.
- (Not included in this presentation) Accuracy suffers when a certain level of noise is introduced.

Conclusion

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Related Works

- More on machine learning for PDE-discovery:
  - Brunton et al., *"Discovering governing equations from data by sparse identification of nonlinear dynamical systems"* (2016)
  - Baddoo et al., *"Physics-informed dynamic mode decomposition"* (2023)
- Physics-Informed Neural Networks (PINN) for PDE-discovery:
  - Raissi et al., *"Physics-informed neural networks: A deep learning framework for solving forward and inverse problems involving nonlinear partial differential equations"* (2019)
  - Chen et al., *"Physics-informed learning of governing equations from scarce data"* (2021)
- PDE-discovery for climate science and geophysics:
  - Lai et al., *"Machine learning for climate physics and simulations"* (2024)
  - Cheng and Alkhalifah, *"Robust data driven discovery of a seismic wave equation"* (2024)
  - Zanna and Bolton, *"Data-driven equation discovery of ocean mesoscale closures"*, (2020)

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Lai, Ching-Yao et al. (2024). "Machine learning for climate physics and simulations". In: *Annual Review of Condensed Matter Physics* 16.

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