Machine Learning: Homework Assignment 1 E4525 Spring 2019, IEOR, Columbia University

Due: February 1st, 2019

- 1. ML Paper review Skim through the papers l [Tiwari et al., 2016] and [Esteva et al., 2017]. You don't need to read them carefully, or understand them in any detail. Answer the following questions:
 - (a) For [Tiwari et al., 2016]'s paper:
 - i. What are their inputs, what is their source of data?
 - ii. What is the medical problem they are trying to identify?
 - iii. Into how many classes do they classify their images?
 - iv. How many data samples do they use?
 - v. How do they evaluate the performance of their algorithm?
 - (b) For [Esteva et al., 2017]'s paper:
 - i. What are their inputs, what is their source of data?
 - ii. What is the medical problem they are trying to identify?
 - iii. How many disease classes do they train their classifier to recognize (only consider the finer level of their classification)?
 - iv. How many data samples do they use?
 - v. How do they evaluate the performance of their algorithm?
- 2. Scalar data types: Classify each one of this variables into one of
 - Categorical
 - Ordinal
 - Interval
 - Ratio
 - (a) Number of patients in a hospital
 - (b) Bronze, Silver, Gold medals as awarded in the Olympics
 - (c) Student Id number
 - (d) Film classification into: Comedy, Drama, etc.
 - (e) Distance in meters as measured from the surface of the earth.

- (f) A homework assignment grade in a 0 to 100 scale
- (g) A course grade in a E to A+ scale.
- (h) email address
- (i) An angle between 0 and 360 degrees.

3. Vector representation of Binary Variables

Let's assume two binary statements X and Y that can be either true of false.

We jointly observe N samples of X and Y and record the results on the following N dimensional vectors

- $Z^X = \{z_i^X\}$, where i = 1, ...N. $z_i^X = 1$ if statement X was true on sample i, zero otherwise.
- $Z^Y = \{z_i^Y\}$, where $i=1,\dots N.$ $z_i^Y = 1$ if statement Y was true on sample i, zero otherwise.

In what follows the operator A*B denotes **element wise** multiplication $(A*B)_i = A_iB_i$, the sum of a vector is $\text{sum}(Z) = \sum_{i=1}^N Z_i$, and the dot product of two vectors is $A^T \cdot B = \text{sum}(A*B) = \sum_{i=1}^N A_iB_i$

- Write a mathematical expression (in terms of z_i^X) for the total number of samples in which the statement X was true
- ullet Write a mathematical expression for the fraction of samples in which statement X was true
- What is the interpretation of the following vector expression?

$$Z^{XY} = Z^X * Z^Y \tag{1}$$

- What is the interpretation of the ordinary dot product of the vectors Z^X and Z^Y ?
- Write a vector expression for the proportion of samples in with X was true but Y was false.
- Write a vector form expression to compute the number of times that either X, Y or both were true.
- Write a vector form expression to compute the number of times than only one of X or Y was true, but not both.

4. Matrix and Index Notation:

Let's assume a D-dimensional regression model

$$y = x_1 \theta_1 + x_2 \theta_2 + \dots + x_D \theta_D + \epsilon = \sum_{d=1}^{D} x_d \theta_d + \epsilon$$
 (2)

where ϵ is some random noise term with zero mean.

Given

- a matrix of observations $X = \{x_{i,d}\}$ where i = 1, ..., N runs through N observations, and d = 1, ..., D runs through D variables.
- a vector of outcomes $Y = \{y_i\}$
- a vector of noise terms $\mathcal{E} = \{\epsilon_i\}$
- a vector of parameters $\Theta = \{\theta_d\}$.
- (a) Write in matrix notation (using X, Y, Θ and \mathcal{E}) an equation relating the outcome vector Y to the observations X and the noise \mathcal{E}
- (b) Write a matrix expression for the average square errors (the average of the square of ϵ_i) in terms of X,Y and Θ
- (c) Write an **explicit** expression for the average square error E in terms of the indexed variables $(x_{i,d}, \theta_d, y_i)$. Be explicit with the summation indexes.
- (d) To minimize the square error E relative to the parameters θ_d we must solve the first order conditions

$$\frac{\partial E}{\partial \theta_d} = 0 \tag{3}$$

Find explicit expressions for $\frac{\partial E}{\partial \theta_d}$ and write the equations 3 in terms of the indexed variables $x_{i,d}$, etc.

(e) Translate those equations into a matrix equation for Θ

5. Matrix and Index Notation II:

Let's assume a D-dimensional regression model for a K-dimensional outcome vector

$$y_1 = \sum_{d=1}^{D} x_d w_{1,d} + \epsilon_1$$

$$\vdots$$

$$y_k = \sum_{d=1}^{D} x_d w_{k,d} + \epsilon_k$$

$$(4)$$

$$: (5)$$

$$y_K = \sum_{d=1}^{D} x_d w_{K,d} + \epsilon_K \tag{6}$$

where ϵ_k , $k=1,\ldots,K$ is some random noise term with zero mean. ϵ_k is independent from $\epsilon_{k'}$ when $k \neq k'$.

Given

• a matrix of observations $X = \{x_{i,d}\}$ where i = 1, ..., N runs through N observations, and d = 1, ..., D runs through D variables.

- a matrix of outcomes $Y = \{y_{i,k}\}$ where k = 1, ..., K.
- a matrix of noise terms $\mathcal{E} = \{\epsilon_{i,k}\}$, were $\epsilon_{i,k} \sim \mathcal{N}(0,\sigma^2)$.
- a matrix of parameters $W = \{w_{k,d}\}.$
- (a) Write in matrix notation (using X, Y, W, and \mathcal{E}) an equation relating the outcome vector Y to the observations X and the noise \mathcal{E}
- (b) Write a matrix expression for the average square errors (the average over the observations i of the sum over k of $\epsilon_{i,k}$) in terms of X,Y and W.

[Hint] You may need to use the matrix trace function $tr(A) = \sum_{i} A_{i,i}$.

- (c) Write an **explicit** expression for the average square error E in terms of the indexed variables $(x_{i,d}, w_{k,d}, y_{i,k})$. Be explicit with the summation indexes.
- (d) To minimize the square error E relative to the parameters $w_{k,d}$ we must solve the first order conditions

$$\frac{\partial E}{\partial w_{k,d}} = 0 \tag{7}$$

Find explicit expressions for $\frac{\partial E}{\partial w_{k,d}}$ and write the equations 7 in terms of the indexed variables $x_{i,d}$, etc.

(e) Translate the equations derived in exercise 5d into a matrix equation for W

References

[Esteva et al., 2017] Esteva, A., Kuprel, B., Novoa, R. A., Ko, J., Swetter, S. M., Blau, H. M., and Thrun, S. (2017). Dermatologist-level classification of skin cancer with deep neural networks. *Nature*, 542:115–118. https://cs.stanford.edu/people/esteva/nature/#!

[Tiwari et al., 2016] Tiwari, P., Prasanna, P., Wolansky, L., Pinho, M., Cohen, M., Nayate, A., Gupta, A., Singh, G., Hattanpaa, K., Sloan, A., Rogers, L., and Madabhushi, A. (2016). Computer-extracted texture features to distinguish cerebral radionecrosis from recurrent brain tumors on multiparametric mri: A feasibility study. American Journal of Neuroradiology. https://doi.org/10.3174/ajnr.A4931.