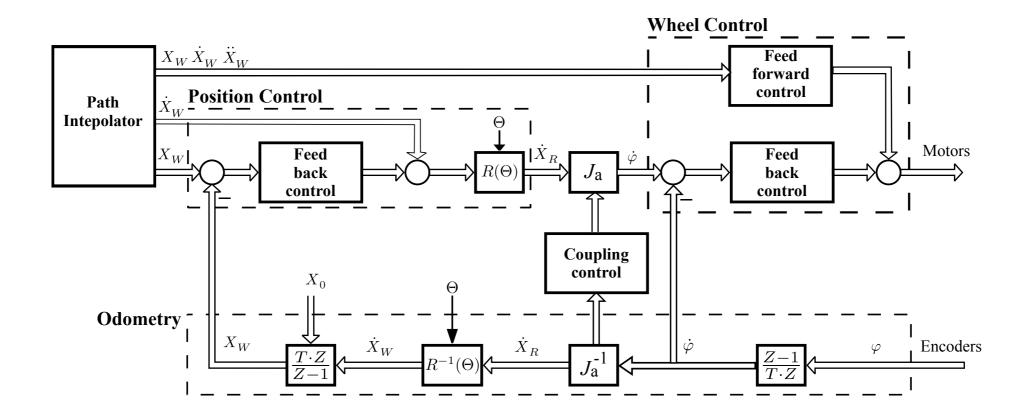
Bahnregelung omnidirektionaler mobiler Roboter



Prof. Dr. Christof Röhrig