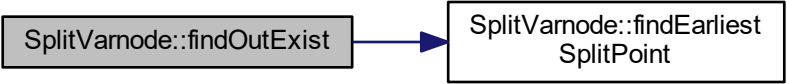


SplitVarnode::findOutExist



```
graph LR; A[SplitVarnode::findOutExist] --> B[SplitVarnode::findEarliestSplitPoint]
```

A diagram showing a call from the function SplitVarnode::findOutExist to the function SplitVarnode::findEarliestSplitPoint. The first box is shaded gray and the second is white. A blue arrow points from the first box to the second box.

SplitVarnode::findEarliest  
SplitPoint