

# Double Machine Learning for DiD Models

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# Basic two-period model

- Treatment  $D_i \in \{0, 1\}$  is received between  $t = 1$  and  $t = 2$
- Potential outcomes framework:

$$Y_{i,t} = D_i Y_{i,t}(1) + (1 - D_i) Y_{i,t}(0) = \begin{cases} Y_{i,t}(1) & \text{if } D_i = 1 \\ Y_{i,t}(0) & \text{if } D_i = 0 \end{cases}$$

- Causal parameter of interest is the ATT in period 2:

$$\theta_0 = \mathbb{E}[Y_{i,2}(1) - Y_{i,2}(0) \mid D_i = 1]$$

## Basic two-period model (cont.)

- Identifying assumptions:

- Parallel trends:  $\mathbb{E}[Y_{i,2}(0) - Y_{i,1}(0) | D_i = 1] = \mathbb{E}[Y_{i,2}(0) - Y_{i,1}(0) | D_i = 0]$

- No anticipation:  $\mathbb{E}[Y_{i,1}(0) | D_i = 1] = \mathbb{E}[Y_{i,1}(1) | D_i = 1]$

$$\implies \theta_0 = \mathbb{E}[Y_{i,2} - Y_{i,1} | D_i = 1] - \mathbb{E}[Y_{i,2} - Y_{i,1} | D_i = 0]$$

- DiD estimator:

$$\hat{\theta}_{0,\text{DiD}} = \frac{1}{N_1} \sum_{i:D_i=1} (Y_{i,2} - Y_{i,1}) - \frac{1}{N_0} \sum_{i:D_i=0} (Y_{i,2} - Y_{i,1})$$

# Incorporating covariates

- Conditional version of identifying assumptions:

- Parallel trends:

$$\mathbb{E}[Y_{i,2}(0) - Y_{i,1}(0) | D_i = 1, X_i] = \mathbb{E}[Y_{i,2}(0) - Y_{i,1}(0) | D_i = 0, X_i]$$

- No anticipation:  $\mathbb{E}[Y_{i,1}(0) | D_i = 1, X_i] = \mathbb{E}[Y_{i,1}(1) | D_i = 1, X_i]$

- Uniform overlap:  $\mathbb{P}(D_i = 1 | X_i) \in (\varepsilon, 1 - \varepsilon)$  for some  $\varepsilon > 0$

- Cond. ATT can be written as cond. DiD expression, so that ATT is identified via the LIE

# Classical estimation approaches

- Regression adjustment:

- Moment equation:  $\theta_0 = \mathbb{E}[Y_{i,2} - Y_{i,1} | D_i = 1] - \mathbb{E}[g_0(X_i) | D_i = 1]$ ,  
with regression function  $g_0(X_i) = \mathbb{E}[Y_{i,2} - Y_{i,1} | D_i = 0, X_i]$

$$\implies \hat{\theta}_{0,\text{reg}} = \frac{1}{N_1} \sum_{i:D_i=1} (Y_{i,2} - Y_{i,1} - \hat{g}_0(X_i))$$

- Inverse probability weighting:

- Moment equation:  $\theta_0 = \frac{1}{p_0} \cdot \mathbb{E}\left[\frac{D_i - m_0(X_i)}{1 - m_0(X_i)} (Y_{i,2} - Y_{i,1})\right]$ ,  
with propensity score  $m_0(X_i) = \mathbb{P}(D_i = 1 | X_i)$  and prior prob.  $p_0 = \mathbb{P}(D_i = 1)$

$$\implies \hat{\theta}_{0,\text{ipw}} = \frac{1}{\bar{D}} \cdot \frac{1}{N} \sum_{i=1}^N \left( \frac{D_i - \hat{m}_0(X_i)}{1 - \hat{m}_0(X_i)} (Y_{i,2} - Y_{i,1}) \right)$$

- Plug in non-parametric estimator  $\hat{g}_0$  or  $\hat{m}_0$  of nuisance function  $g_0$  or  $m_0$   
 $\implies$  Estimator of  $\theta_0$  won't attain parametric convergence rate  $N^{-1/2}$

# Double machine learning (DML)

- Proposed by Chernozhukov et al. [2018] and extended to DiD framework by Chang [2020]
- Main ingredients of DML:
  - Moment equation that defines an *infeasible* method-of-moments estimator, as some nuisance parameters need to be estimated beforehand
  - Employ ML methods to learn the nuisance functions
  - Use Neyman orthogonality to “remove” non-parametric convergence rates
  - Use cross-fitting to avoid overfitting bias

# Neyman orthogonal moment equation

- Scalar nuisance parameter  $p$  with true value  $p_0 = \mathbb{P}(D = 1)$
- Infinite-dimensional nuisance parameter  $\eta = (g, m)$  with true value  $\eta_0 = (g_0, m_0)$
- Consider the score function:

$$\psi(W; \theta, p, \eta) = \frac{D - m(X)}{p(1 - m(X))} (Y_2 - Y_1 - g(X)) - \theta$$

## Proposition (Identification and Neyman orthogonality)

*The ATT parameter  $\theta_0$  is identified by the moment equation  $\mathbb{E}[\psi(W; \theta_0, p_0, \eta_0)] = 0$ . This moment equation is “insensitive” to small errors in the nuisance parameter  $\eta$ , in the sense that  $\partial_\eta \mathbb{E}[\psi(W; \theta_0, p_0, \eta)]|_{\eta=\eta_0} = 0$ .*

# DML algorithm

1. Form a  $K$ -fold partition of  $\{1, \dots, N\}$  into  $\{I_k\}_{k=1}^K$  each of the size  $n := N/K$ , and define  $I_k^c := \{1, \dots, N\} \setminus I_k$ .
2. For each  $k$ , use  $\{W_i\}_{i \in I_k^c}$  to compute estimators of  $\eta_0$  and  $p_0$ :

$$\hat{\eta}_0(I_k^c) := (\hat{g}_0(\cdot; I_k^c), \hat{m}_0(\cdot; I_k^c)), \quad \bar{D}(I_k^c) := \frac{1}{N-n} \sum_{i \in I_k^c} D_i$$

3. For each  $k$ , define  $\check{\theta}_{0,k}$  as the root  $\theta$  of:

$$\frac{1}{n} \sum_{i \in I_k} \psi(W_i; \theta, \bar{D}(I_k^c), \hat{\eta}_0(I_k^c)) = 0$$

4. Obtain the final estimator of  $\theta_0$  by averaging:

$$\hat{\theta}_0 := \frac{1}{K} \sum_{k=1}^K \check{\theta}_{0,k}$$



# Asymptotics of DML estimator

Existence of moments + High-level assumptions on the ML estimators:

- Conv. rates:  $\|\hat{g}_0(X; I_k^c) - g_0(X)\|_{L^2} + \|\hat{m}_0(X; I_k^c) - m_0(X)\|_{L^2} = o_P(N^{-1/4})$
- $\hat{m}_0(X; I_k^c) \in (\varepsilon, 1 - \varepsilon)$  with probability approaching 1

## Theorem (Asymptotic normality)

$$\sqrt{N}(\hat{\theta}_0 - \theta_0) \xrightarrow{d} \mathcal{N}(0, \sigma^2)$$

- Asymptotic variance  $\sigma^2 = \mathbb{E}[(\psi(W; \theta_0, p_0, \eta_0) - \theta_0(D - p_0)/p_0)^2]$  can be consistently estimated
- Approximate  $(1 - \alpha) \cdot 100\%$  CI:  $[\hat{\theta}_0 \pm z_{1-\alpha/2} \cdot \hat{\sigma}/\sqrt{N}]$

## References

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