Остановились на формуле Лиувилля для однородной системы.

$$\dot{\vec{X}} = \dot{A}(t)\vec{X} \implies W(t) = \det \Phi(T) : \dot{W}(t) = (\operatorname{Tr} A(t))W \ W(t) = W(t_0)e^{\int_{t_0}^t \operatorname{Tr} A(\tau)d\tau} 
L_n[y] = y^{(n)} + a_{n-1}(t)y^{(n-1)} + \dots + a_0(t)y = 0 
x_1(t) = y(t) 
x_2(t) = y'(t) 
x_n(t) = y^{(n-1)}(t) 
A(t) = \begin{pmatrix} 0 & 1 \\ & \ddots \\ & & 0 & 1 \\ -a_0 & \dots & -a_{n-1} \end{pmatrix} \implies \operatorname{Tr} A(t) = -a_{n-1}(t) 
\implies W(t) = W(t_0)e^{\int_{t_0}^t a_{n-1}(\tau)d\tau}$$

$$y''+a_1(t)y'+a_0(t)y(t)=0$$
. Знаем  $\phi_1(t)$  - нетривиальное решение. Не знаем  $\phi_2$   $W(t)=\begin{vmatrix}\phi_1(t)&\phi_2(t)\\\dot{\phi}_1(t)&\dot{\phi}_2(t)\end{vmatrix}=\phi_1(t)\dot{\phi}_2(t)-\dot{\phi}_1(t)\phi_2(t)=\underbrace{A}_{\neq 0}e^{-\int a_1(\tau)d\tau}$   $\phi_2'-\frac{\phi_1'(t)}{\phi_1(t)}\phi_2=e^{-\int a_1(\tau)d\tau}$ 

## ЛНСДУ

$$\begin{array}{l} \dot{\vec{x}} = A(t)\vec{x} + \vec{b}(t) \quad \vec{x_{\text{ч}}} = ? \\ \text{Матрица Коши:} \\ K(t,\tau) = \Phi(t)\Phi^{-1}(t) \\ \left\{ \dot{\Phi} = A(t)\Phi \\ \Phi(\tau) = I(\text{единичная}) \right\} \Longrightarrow \\ \Longrightarrow \vec{x_{\text{ч}}}(t) = \int_{t_0}^t K(t,\tau)\vec{b}(\tau)d\tau = \int_{t_0}^t \Phi(t)\Phi^{-1}(\tau)\vec{b}(\tau)d\tau \\ \dot{\underline{\vec{x}}} = \Phi(t)\Phi^{-1}(t)\vec{b}(t) + \int_{t_0}^t \dot{\Phi}(t)\Phi^{-1}(\tau)\vec{b}(\tau)d\tau = \vec{b}(t) + \int_{t_0}^t A(t)\Phi(t)\Phi^{-1}(\tau)\vec{b}(\tau)d\tau = \vec{b}(t) + A(t)\vec{x} \end{array}$$

$$\begin{split} A(t) &\equiv A \implies K(t,\tau) = e^{A(t-\tau)} \\ \Phi(t) &= e^{At} \quad x_{\mathbf{q}}(t) = \int_{t_0}^t e^{A(t-\tau)} \vec{b}(\tau) d\tau \\ \begin{cases} \dot{\vec{x}} &= A(t) \vec{x} + b(\tau) \\ \vec{x}(t_0) &= \vec{C}_0 \end{cases} \\ \tilde{\Phi}(t) &= \Phi(t) \Phi^{-1}(t_0) = K(t,t_0) = K(t,t_0) \vec{C}_0 + \int_{t_0}^t \vec{b}(\tau) d\tau \end{split}$$

$$\widetilde{\Phi}(t_0) = I$$

Otbet: 
$$x(t) = \widetilde{\Phi}(t) \vec{C_0} + \int_{t_0}^t K(t,\tau) \vec{b}(\tau) d\tau$$

## Периодическая задача

Коэффициенты - периодические функции

$$P=P(t)\in\mathbb{C}^{n imes n}\quad w$$
 - период,  $P(t+w)=P(t)$ 

$$\dot{\vec{x}} = P(t)x$$

**Theorem**. o  $\Phi(t)$  sistemy s period koeff.

$$\Phi(t) = G(t)e^{tR} \quad R \in \mathbb{R}^{n \times n}$$

$$G(t) - w$$
-Периодическая,  $\det G(t) \neq 0$ 

Proof. 
$$\dot{\Phi} = P(t)\Phi \implies \Psi(t) = \Phi(t+w)$$
 - тоже фундаментальная матрица

$$\dot{\Psi} = \dot{\Phi}(t+w) = P(t+w)\Phi(t+w) = P(t)\Psi(t)$$

$$\Psi(t) = \Phi(t+w) = \Phi(t)B, \det B \neq 0, B$$
 - какая-то матрица, которая называется матрицой МонодромиИ.

$$B = \Phi^{-1}(t)\Phi(t+w)$$

$$B = \Phi^{-1}(0)\Phi(w)$$

Положим 
$$R = \frac{1}{w} \ln B$$
,  $B = e^{wR}$   
Если  $\det B \neq 0 \implies \exists \ln B$ 

Если 
$$\det B \neq 0 \implies \exists \ln B$$

$$\ln z = \ln|z| + i\arg z + 2\pi kz$$

$$\ln z = \ln |z| + i \arg z + 2\pi k i$$
  
$$\ln J_r = \ln \lambda I_r + \sum_{k=1}^{\infty} \frac{(-1)^{k-1}}{k} (\frac{1}{\lambda} z_r)^k$$

$$\Phi_1(t+w) = \Phi_1(t)B_1$$

$$\begin{aligned}
\Phi_{1}(t+w) &= \Phi_{1}(t)B_{1} \\
\Pi_{1}(t+w) &= \Phi_{1}(t)B_{1} = \Phi_{1}(t)BS \\
\Phi_{1}(t)B_{1} &= \Phi(t+w)S = \Phi_{1}(t)BS
\end{aligned}$$

$$S^{-1}|SB_1 = BS$$

$$B_1 = S^{-1}BS$$

$$B_1 \sim B$$

$$\widetilde{\Phi}(0) = I$$

$$\widetilde{\Phi}(w) = \widetilde{\Phi}(0)B$$

$$B = \widetilde{\Phi}(w)$$

 $\mu_1, \dots, \mu_n$  - собственные числа B, мультипликаторы

 $\lambda_1,\ldots,\lambda_n$  собственные числа R (характеристические показатели)

$$\lambda_j = \frac{1}{w} \ln \mu_j$$

$$\det B = \det \widetilde{\Phi}(w) \stackrel{\text{миувиль}}{=} e^{\int_0^w \text{Tr} P(\tau) d\tau} = \mu_1 \dots \mu_n$$

$$y'' + P(t)y = 0$$

$$y = x_1, y' = x_2$$

$$\Rightarrow \begin{cases} \dot{x_1} = x_2 \\ \dot{x_2} = -P(t)x_1 \end{cases}, P(t) = \begin{pmatrix} 0 & 1 \\ -P(t) & 0 \end{pmatrix}$$

$$\operatorname{Tr} P(t) = 0 \stackrel{\text{liuville}}{\Longrightarrow} \mu_1 \mu_2 = 1$$

 $\mu_2 - 2a\mu + 1 = 0$  - характеристический полином

$$\Phi(w) = \begin{pmatrix} \phi_1(w) & \phi_2(w) \\ \dot{\phi}_1(w) & \dot{\phi}_2(w) \end{pmatrix}$$

$$\begin{cases} \dot{\phi}_1(t) = 1 \\ \dot{\phi}_1(0) = 0 \end{cases} \begin{cases} \dot{\phi}_2(0) = 0 \\ \dot{\phi}_2(0) = 1 \end{cases}$$
$$a = \frac{1}{2}(\phi_1(w) + \dot{\phi}_2(w))$$

**Theorem**.  $\mu$  - мультипликатор  $\iff$ 

$$\exists \vec{\phi}$$
 решение  $\dot{\vec{\phi}} = \Phi(t) \vec{\phi} : \forall t \quad \phi(t+w) = \mu \phi(t)$ 

Proof.  $\mu$  - мультипликатор  $\exists \vec{x_{\mu}}$  собственный вектор,  $\widetilde{\Phi}(w)\vec{x_{\mu}} = \mu\vec{x_{\mu}}$ 

$$\begin{cases} \dot{\vec{\pi}} = P(t)\vec{\phi} \\ \bar{\phi}(0) = \vec{x_{\mu}} \end{cases} \stackrel{\overline{\phi}(t) = \widetilde{\Phi}(t)\vec{x_{\mu}}}{\rightleftharpoons \widetilde{\phi}(t + w) = \widetilde{\Phi}(t + w)x_{\mu} = \widetilde{\Phi}(t)} = \mu\widetilde{\Phi}(t)\vec{x_{\mu}} = \mu\widetilde{\Phi}($$

Замена переменных в x' = P(t)x

$$\Phi(t) = G(t)e^{tR} = \underbrace{G(t)S}_{=G_1(t) \Longrightarrow \Phi_1(t)e^{tJ}} e^{tJ}S^{-1} \mid \cdot S$$

$$R = Se^{tJ}S^{-1}$$

$$G_1(t) = \{\vec{g_1}(t) \dots \vec{g_n}(t)\}$$

$$\vec{g_j}(t+w) = \vec{g}(t)$$
 лин. незав.

$$\Phi_1(t) = {\vec{\phi_1}(t) \dots \vec{\phi_n}(t)}, e^{tJ} = \text{diag}{e^{tJ_0} \dots e^{tJ_a}}$$

$$J_k = \lambda_{p+k} I + Z_{rk} \quad \lambda_{p+k} = \frac{1}{w} \ln \mu_{p+k}$$

$$\vec{\phi_j}(t) = \vec{g_j}(t)e^{t\lambda_j} \quad j = 1, \dots,$$

$$\vec{\phi}_{p+r_1+\ldots+r_{p-1}}(t) = g_{-||-}(t)e^{t\lambda_{p+k}}$$

$$\vec{\phi}_{p+r_1+\ldots+r_k}(t) = \left(\frac{t^{r_n-1}}{(r_k-1)!}\vec{g}_{p+r_1+\ldots+r_{k-1}+1}(t) + \ldots + \vec{g}_{p+r_1+\ldots+r_k-1}(t)\right)e^{t\lambda_{p+k}}$$

Приводимость

$$\begin{split} &\Phi(t) = G(t)e^{tK} \mid \cdot e^{-tK} \quad G(t) = \Phi e^{-tK} \mid \cdot \frac{d}{dt} \\ &\Longrightarrow \dot{G}(t) = P(t)\Phi(t)e^{-tR} - \Phi(t)e^{-tR}R = P(t)G(t) - G(t)R \\ &\dot{\vec{x}} = P(t)x \quad x(t) = G(t)\vec{y}(t) \mid \cdot \frac{d}{dt} \end{split}$$

$$\begin{split} \dot{G}(t)\vec{y}(t) + G(t)\dot{\vec{y}}(t) &= P(t)G(t)y(t) - G(t)Ry(t) + G(t)\dot{y}(t) = P(t)G(t)y(t) \\ \Longrightarrow & G(t)\dot{\vec{y}}(t) = G(t)R\vec{y}(t) \end{split}$$

 $\implies \dot{\vec{y}} = R \vec{y}$  существует линейная периодическая замена