ON LOOPS IN THE HYPERBOLIC LOCUS OF THE COMPLEX HÉNON MAP AND THEIR MONODROMIES

ZIN ARAI

ABSTRACT. We prove John Hubbard's conjecture on the topological complexity of the hyperbolic horseshoe locus of the complex Hénon map. In fact, we show that there exist several non-trivial loops in the locus which generate infinitely many mutually different monodromies. Furthermore, we prove that the dynamics of the *real* Hénon map is completely determined by the monodromy of the *complex* Hénon map, providing the parameter is contained in the hyperbolic horseshoe locus of the complex Hénon map.

1. Introduction

One of the motivations of this work is to give an answer to the conjecture of John Hubbard on the topology of hyperbolic horseshoe locus of the complex Hénon map

$$H_{a,c}: \mathbb{C}^2 \to \mathbb{C}^2: \begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} x^2+c-ay \\ x \end{pmatrix}.$$

Here a and c are complex parameters.

Below we describe the conjecture following a formulation given by Bedford and Smillie [5].

Let us define

$$K_{a,c}^{\mathbb{C}}:=\{p\in\mathbb{C}^2:\{H_{a,c}^n(p)\}_{n\in\mathbb{Z}}\text{ is bounded}\},\quad K_{a,c}^{\mathbb{R}}:=K_{a,c}^{\mathbb{C}}\cap\mathbb{R}^2.$$

The set $K_{a,c}^{\mathbb{C}}$ is compact and invariant with respect to $H_{a,c}$. When the parameters a and c are both real, the real plane $\mathbb{R}^2 \subset \mathbb{C}^2$ is invariant and hence so is $K_{a,c}^{\mathbb{R}}$. In this case, we call $H_{a,c}|_{\mathbb{R}^2}: \mathbb{R}^2 \to \mathbb{R}^2$ the real Hénon map.

Our primary interest is on the structure of the parameter space, especially on the topology of the set of parameter values on which complex and/or real Hénon maps become a uniformly hyperbolic horseshoe. More precisely, we study the following sets:

$$\mathcal{H}^{\mathbb{C}} := \{(a,c) \in \mathbb{C}^2 : H_{a,c} | K_{a,c}^{\mathbb{C}} \text{ is a hyperbolic full horseshoe}\},$$

 $\mathcal{H}^{\mathbb{R}} := \{(a,c) \in \mathbb{R}^2 : H_{a,c} | K_{a,c}^{\mathbb{R}} \text{ is a hyperbolic full horseshoe}\}.$

 $^{2000\} Mathematics\ Subject\ Classification.$ Primary 37F45; Secondary 37B10, 37D20 and 58K10.

Key words and phrases. Hénon map, monodromy, symbolic dynamics and the pruning front

Research supported in part by Grant-in-Aid for Scientific Research (No. 17740054), Japan Society for Promotion of Science.

Here we mean by a hyperbolic full horseshoe an uniformly hyperbolic invariant set which is topologically conjugate to the full shift map σ defined on $\Sigma_2 = \{0,1\}^{\mathbb{Z}}$, the space of bi-infinite sequences of two symbols.

A classical result of Devaney and Nitecki [12] claims that if (a, c) is in

$$\mathsf{DN} := \{ (a,c) \in \mathbb{R}^2 : c < -(5+2\sqrt{5}) \, (|a|+1)^2/4, \, a \neq 0 \}$$

then $K_{a,c}^{\mathbb{R}}$ is a hyperbolic full horseshoe. Thus $\mathsf{DN} \subset \mathcal{H}^{\mathbb{R}}$ holds. They also showed that the set

$$\mathsf{EMP} := \{(a,c) \in \mathbb{R}^2 : c > (a+1)^2/4\}$$

consists of parameter values such that $K_{a,c}^{\mathbb{R}} = \emptyset$. Later, Hubbard and Oberste-Vorth investigated the Hénon map form the complex dynamical point of view, and improved the hyperbolicity criterion by showing that

$$\mathsf{HOV} := \{(a,c) \in \mathbb{C}^2 : |c| > 2(|a|+1)^2, \, a \neq 0\}$$

is contained in $\mathcal{H}^{\mathbb{C}}$. Remark that EMP \cap HOV is non-empty; in this parameter region, although $K_{a.c}^{\mathbb{C}}$ is a full horseshoe, it does not intersect with \mathbb{R}^2 .

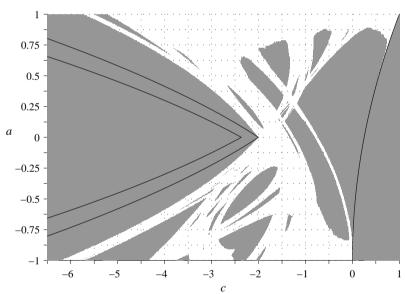


FIGURE 1. The shaded regions consist of hyperbolic (not necessarily full horseshoe) parameters of the *real* Hénon map.

Figure 1 illustrates a subset of parameter values on which the chain recurrent set of the *real* Hénon map is uniformly hyperbolic (not necessarily a full horseshoe) [1]. Three solid lines are parts of the boundaries of DN, HOV and EMP, from left to right. On the biggest island to the left, the chain recurrent set coincides with $K_{a,c}^{\mathbb{R}}$ and is conjugate to the full shift. Hence the island is contained in $\mathcal{H}^{\mathbb{R}}$.

We then consider the relation between $\mathcal{H}^{\mathbb{R}}$ and $\mathcal{H}^{\mathbb{C}}$. By the result of Bedford, Lyubich and Smillie [3, Theorem 10.1], we know $\mathcal{H}^{\mathbb{R}} \subset \mathcal{H}^{\mathbb{C}} \cap \mathbb{R}^2$. It is then natural to ask what happens in $(\mathcal{H}^{\mathbb{C}} \cap \mathbb{R}^2) \setminus \mathcal{H}^{\mathbb{R}}$. To be specific, we divide $\mathcal{H}^{\mathbb{C}} \cap \mathbb{R}^2$ into three mutually disjoint sets.

Definition 1 (Bedford and Smillie [5]). We call $(a, c) \in \mathcal{H}^{\mathbb{C}} \cap \mathbb{R}^2$ is of type-1 if $(a, c) \in \mathcal{H}^{\mathbb{R}}$, and of type-2 if $K_{a,c}^{\mathbb{R}} = \emptyset$. Otherwise, it is of type-3.

Since $\mathsf{DN} \subset \mathcal{H}^\mathbb{R}$, the set of type-1 parameter values is non-empty. The set of type-2 parameter values is also non-empty since it contains $\mathsf{EMP} \cap \mathsf{HOV}$. However, the existence of a type-3 parameter value was open.

Conjecture 1 (Hubbard). There exists a parameter value of type-3.

As we will see later, this conjecture turned to be true.

Besides the existence, Hubbard also conjectured that there are infinitely many classes of type-3 parameter values corresponding to mutually different real dynamics. This stronger conjecture is, to be precise, given in terms of the monodromy representation of the fundamental group of the hyperbolic horseshoe locus as below.

Denote by $\mathcal{H}_0^{\mathbb{C}}$ the component of $\mathcal{H}^{\mathbb{C}}$ that contains HOV. Let us fix a basepoint $(a_0, c_0) \in \mathsf{DN}$ and a topological conjugacy $h_0 : K_{a_0, c_0}^{\mathbb{C}} \to \Sigma_2$.

Given a loop $\gamma:[0,1]\to\mathcal{H}_0^{\mathbb{C}}$ based at (a_0,c_0) , we construct a continuous family of conjugacies $h_t^{\gamma}:K_{\gamma(t)}^{\mathbb{C}}\to\Sigma_2$ along γ such that $h_0^{\gamma}=h_0$ (see §4 for the details). This is possible because $K_{a,c}^{\mathbb{C}}$ is uniformly hyperbolic along γ . When no confusion may result, we suppress γ and write h_t^{γ} as h_t . Then we define

$$\rho(\gamma) := h_1 \circ (h_0)^{-1} : \Sigma_2 \to \Sigma_2.$$

It is easy to see that ρ defines a group homomorphism

$$\rho: \pi_1(\mathcal{H}_0^{\mathbb{C}}, (a_0, c_0)) \to \operatorname{Aut}(\Sigma_2)$$

where $\operatorname{Aut}(\Sigma_2)$ is the group of the automorphisms of Σ_2 . Recall that an automorphism of Σ_2 is a homeomorphism of Σ_2 which commutes with the shift map σ [18]. We call ρ the monodromy homomorphism and denote its image by Γ .

For example, let γ_{\emptyset} be a loop in $\mathcal{H}_{0}^{\mathbb{C}}$ based at (a_{0}, c_{0}) which is homotopic to the generator of $\pi_{1}(\mathsf{HOV})$. It is then shown [5] that $\rho(\gamma_{\emptyset})$ is an involution which interchanges the symbols 0 and 1. Namely, $(\rho(\gamma_{\emptyset})(s))_{i} = 1 - s_{i}$ for all $s = (s_{i}) \in \{0, 1\}^{\mathbb{Z}}$.

The monodromy homomorphism was originally defined for polynomial maps of one complex variable. In this case, since the map does not have the inverse, the target space of the monodromy homomorphism is the automorphism group of *one-sided* shift space of d-symbols, where d is the degree of the polynomial. When d=2, this group is isomorphic to \mathbb{Z}_2 and the monodromy homomorphism is shown to be surjective since it maps the generator of $\pi_1(\mathbb{C} \setminus \{\text{the Mandelbrot set}\})$ to $1 \in \mathbb{Z}_2$. The monodromy homomorphism is also surjective even when d > 2, although the proof is much harder than the case d=2 because the automorphism group becomes much more complicated [6].

Hubbard conjectured that the surjectivity also holds in the case of the complex Hénon map, with the only exception being σ .

Conjecture 2 (Hubbard). The image Γ of the monodromy homomorphism and the shift map σ generate $\operatorname{Aut}(\Sigma_2)$.

The structure of $\operatorname{Aut}(\Sigma_2)$ is quite complicated [7]: it contains every finite group; furthermore, it contains the direct sum of any countable collection of finite groups; and it also contains the direct sum of countably many copies of \mathbb{Z} . Therefore, the conjecture implies, provided it is true, that the topological structure of $\mathcal{H}^{\mathbb{C}}$ is very rich, in contrast to the one-dimensional case where the fundamental group of $\mathbb{C} \setminus \{\text{the Mandelbrot set}\}$ is simply \mathbb{Z} .

Let us state the main results of the paper now.

First, we claim that Conjecture 1 is true.

Theorem 1. There exist parameter values of type-3. In fact, if (a, c) is in one of the following sets:

$$I_p := \{1\} \times [-5.46875, -5.3125], \qquad I_q := \{0.25\} \times [-2.296875, -2.21875],$$
 $I_r := \{-1\} \times [-5.671875, -4.4375], \quad I_s := \{-0.375\} \times [-2.15625, -1.8125]$ then (a, c) is of type 3.

Toward Conjecture 2, we obtain the following result.

Theorem 2. The order of the group Γ is infinite. In particular, it contains an element of infinite order.

Apart form the theoretical interest, the monodromy theory of complex Hénon map can contribute to the understanding of the real Hénon map.

Let $(a,c) \in \mathcal{H}^{\mathbb{C}} \cap \mathbb{R}^2$. If (a,c) is of type-1 or 2, then by definition $K_{a,c}^{\mathbb{R}}$ is a full horseshoe, or empty. Suppose (a,c) is of type-3. We then ask what is $K_{a,c}^{\mathbb{R}}$ in this case. By definition, $K_{a,c}^{\mathbb{R}}$ is a proper subset of $K_{a,c}^{\mathbb{C}} \cong \Sigma_2$. The uniform hyperbolicity implies the existence of a Markov partition for $K_{a,c}^{\mathbb{R}}$, and therefore, $K_{a,c}^{\mathbb{R}}$ must be topologically conjugate to some subshift of finite type. The following theorem reveals that $K_{a,c}^{\mathbb{R}}$ is actually a subshift of Σ_2 which is realized as the fixed point set of the monodromy of a loop passing through (a,c).

Theorem 3. For any $(a,c) \in \mathcal{H}_0^{\mathbb{C}} \cap \mathbb{R}^2$, there exists a loop $\gamma : [0,1] \to \mathcal{H}_0^{\mathbb{C}}$ with $\gamma(1/2) = (a,c)$ such that $H_{a,c} : K_{a,c}^{\mathbb{R}} \to K_{a,c}^{\mathbb{R}}$ is topologically conjugate to

$$\sigma|_{\operatorname{Fix}(\rho(\gamma))} : \operatorname{Fix}(\rho(\gamma)) \to \operatorname{Fix}(\rho(\gamma)).$$

In fact, it suffices to set $\gamma := \bar{\alpha}^{-1} \cdot \alpha$, where α is an arbitrary path in $\mathcal{H}_0^{\mathbb{C}}$ connecting a point in DN to (a,c). Here $\bar{\alpha}$ denotes the complex conjugate of α . The conjugacy is given by the restriction of $h_{1/2}$ to $K_{a,c}^{\mathbb{R}}$. Namely, the following diagram commutes;

$$K_{a,c}^{\mathbb{R}} \xrightarrow{H_{a,c}} K_{a,c}^{\mathbb{R}}$$

$$\downarrow^{h_{1/2}|_{K_{a,c}^{\mathbb{R}}}} \cong \bigoplus^{h_{1/2}|_{K_{a,c}^{\mathbb{R}}}} \operatorname{Fix}(\rho(\gamma)) \xrightarrow{\sigma} \operatorname{Fix}(\rho(\gamma)).$$

As an application of Theorem 3, we obtain the following.

Theorem 4. Let $(a,c) \in I_p$. The real Hénon map $H_{a,c} : K_{a,c}^{\mathbb{R}} \to K_{a,c}^{\mathbb{R}}$ is topologically conjugate to the subshift of Σ_2 with two forbidden blocks 0010100 and 0011100. Similarly, $K_{a,c}^{\mathbb{R}}$ is conjugate to the subshift of Σ_2 defined by the following forbidden blocks: 10100 and 11100 for $(a,c) \in I_q$; 10010 and 10110 for $(a,c) \in I_r$; 0010 and 0110 for $(a,c) \in I_s$.

Notice that I_p contains (a, c) = (1, -5.4), the parameter studied by Davis, MacKay and Sannami [10]. The subshift for $(a, c) \in I_p$ given in Theorem 4 is equivalent to that observed by them. Thus, we can say that their observation is now rigorously verified. We also remark that this theorem is closely related to the so-called "pruning front" theory [9, 10]. Theorem 3 implies that "primary pruned regions", or, "missing blocks" of $K_{a,c}^{\mathbb{R}}$ is nothing else but the region where the generating partition are interchanged along γ .

The structure of the paper is as follows. We prove the theorems in Section 2, leaving computational algorithms to Section 3 and 4. In Section 3, we summarize the algorithm for proving uniform hyperbolicity developed by the author [1]. Section 4 is devoted to an algorithm for computing the monodromy homomorphism. In the appendix, we discuss a method for rigorously counting the number of periodic points, which gives rise to an alternative proof of Theorem 1. Programs for computer assisted proofs are available at the author's web page (http://www.math.kyoto-u.ac.jp/~arai/).

The author is grateful, first of all, to John Hubbard, the originator of the problem. He also would like to thank E. Bedford, P. Cvitanović, S. Hruska, H. Kokubu, A. Sannami, J. Smillie, and S. Ushiki for many valuable suggestions.

2. Proofs

We first prove Theorem 3. We note that this is similar to Theorem 5.2 of [5], but we give it in order to have the precise formulation that we need.

The key is the symmetry of the Hénon map with respect to the complex conjugation [5], by which we mean the equation

$$\phi \circ H_{a.c} = H_{\bar{a}.\bar{c}} \circ \phi$$

where ϕ is the complex conjugation that maps z=(x,y) to $\bar{z}=(\bar{x},\bar{y})$.

Proof of Theorem 3. Let $\gamma = \bar{\alpha}^{-1} \cdot \alpha$ be a loop in $\mathcal{H}_0^{\mathbb{C}}$ where α is a path connecting a point in DN to (a,c), and let $\bar{\gamma} := \phi \circ \gamma$ be the complex conjugate of it. Note that by construction, we have $\bar{\gamma} = \gamma^{-1}$.

Take an arbitrary point $z \in K_{a,c}^{\mathbb{C}}$ and define

$$s_z := h_{1/2}(z) \in \Sigma_2.$$

To prove the theorem, it suffices to show that $\rho(\gamma)(s_z) = s_z$ if and only if $z \in \mathbb{R}^2$.

Remark that the continuation of z along γ coincides with

$$z(\gamma, t) := (h_t)^{-1}(s_z) \in \mathbb{C}^2$$

where $z(\gamma, 1/2) = z$. By the continuity of hyperbolic invariant sets,

$$z(\gamma, \cdot): [0, 1] \to \mathbb{C}^2: t \mapsto z(\gamma, t)$$

defines a continuous curve, which is a closed loop if $z(\gamma,0)=z(\gamma,1)$.

From the symmetry of the Hénon map with respect to the complex conjugation it follows that

$$\overline{z(\gamma,t)} = \bar{z}(\bar{\gamma},t).$$

Here $\bar{z}(\bar{\gamma},t)$ is the continuation of \bar{z} along $\bar{\gamma}$. Since $\bar{\gamma}=\gamma^{-1}$, we have $\bar{z}(\bar{\gamma},t)=\bar{z}(\gamma,1-t)$. Therefore,

$$\rho(\gamma)(s_z) = h_1((h_0)^{-1}(s_z)) = h_1(z(\gamma, 0)) = h_1(\overline{z(\gamma, 0)})$$

= $h_1(\bar{z}(\bar{\gamma}, 0)) = h_1(\bar{z}(\gamma, 1)) = h_1((h_1)^{-1}(s_{\bar{z}})) = s_{\bar{z}}.$

The third equality holds because $K_{\gamma(0)}^{\mathbb{C}} \subset \mathbb{R}^2$ and hence $z(\gamma,0) = \overline{z(\gamma,0)}$.

Thus, we know that $\rho(\gamma)(s_z) = s_z$ if and only if $s_z = s_{\bar{z}}$. Since the map $h_{1/2}$ is a bijection between $K_{a,c}^{\mathbb{C}}$ and Σ_2 , it follows that $s_z = s_{\bar{z}}$ if and only if $z = \bar{z}$. This proves the theorem.

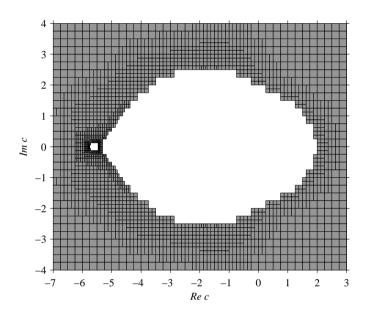


FIGURE 2. The shaded region is contained in $\mathcal{H}^{\mathbb{C}} \cap \{a = 1\}$.

Now we discuss Theorem 1. We begin by defining I_p , I_q , I_r and I_s . Let

 $L_p := \{1\} \times \{\mathbb{C} \setminus \text{ white regions in Figure 2}\},$

 $L_q := \{0.25\} \times \{\mathbb{C} \setminus \text{white regions in Figure 3}\},$

 $L_r := \{-1\} \times \{\mathbb{C} \setminus \text{ white regions in Figure 4}\},$

 $L_s := \{-0.375\} \times \{\mathbb{C} \setminus \text{white regions in Figure 5}\}$

and $L := L_p \cup L_q \cup L_r \cup L_s \subset \mathbb{C}^2$. To be precise, these regions are defined by a finite number of closed rectangles. The complete list of these rectangles is available at the author's web page.

Lemma 5. If $(a,c) \in L$ then $H_{a,c}$ is uniformly hyperbolic on its chain recurrent set $\mathcal{R}(H_{a,c})$.

The proof of this lemma is computer assisted. We leave it to §3.

Recall that the hyperbolicity of the chain recurrent set implies the \mathcal{R} -structural stability [22, Corollary 8.24]. Therefore, it follows from Lemma 5 that no bifurcation occurs in $\mathcal{R}(H_{a,c})$ as long as $(a,c) \in L$. Since L and DN have non-empty intersection and $K_{a,c}^{\mathbb{C}} = K_{a,c}^{\mathbb{R}} = \mathcal{R}(H_{a,c})$ is a hyperbolic full

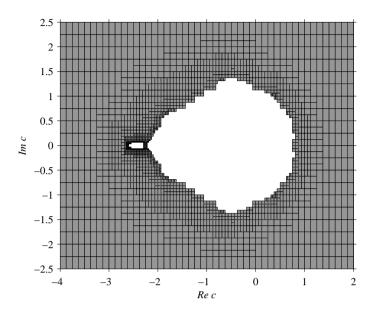


FIGURE 3. The shaded region is contained in $\mathcal{H}^{\mathbb{C}} \cap \{a = 0.25\}$.

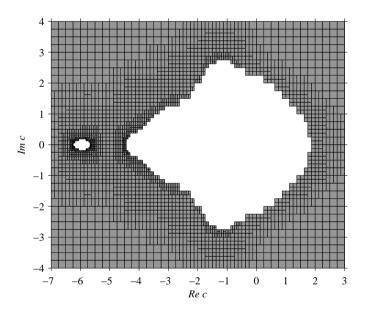


FIGURE 4. The shaded region is contained in $\mathcal{H}^{\mathbb{C}} \cap \{a = -1\}$.

horseshoe on DN, we know that $\mathcal{R}(H_{a,c})$ is also a hyperbolic full horseshoe for all $(a,c) \in L$. However, this observation is not sufficient for our purpose because $\mathcal{R}(H_{a,c})$ and $K_{a,c}^{\mathbb{C}}$ do not necessarily coincide. To conclude the hyperbolicity of $K_{a,c}^{\mathbb{C}}$, we need to show that these sets are equal in the horseshoe locus, as follows.

Corollary 6. If $(a, c) \in L$ then $H_{a,c}|K_{a,c}^{\mathbb{C}}$ is a hyperbolic full horseshoe, that is, $L \subset \mathcal{H}^{\mathbb{C}}$.

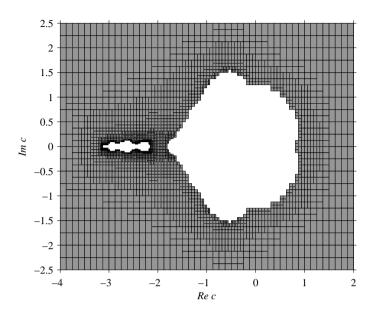


FIGURE 5. The shaded region is contained in $\mathcal{H}^{\mathbb{C}} \cap \{a = -0.375\}$.

Proof of Corollary 6. Let

$$\begin{split} K_{a,c}^+ := & \{ p \in \mathbb{C}^2 : \{ H_{a,c}^n(p) \}_{n \geq 0} \text{ is bounded} \}, \\ K_{a,c}^- := & \{ p \in \mathbb{C}^2 : \{ H_{a,c}^n(p) \}_{n \leq 0} \text{ is bounded} \} \end{split}$$

and $J_{a,c}^{\pm} := \partial K_{a,c}^{\pm}$. Define $J_{a,c} = J_{a,c}^{+} \cap J_{a,c}^{-}$. Then $K_{a,c}^{\mathbb{C}} = K_{a,c}^{+} \cap K_{a,c}^{-}$ and we have $J_{a,c} \subset \mathcal{R}(H_{a,c}) \subset K_{a,c}^{\mathbb{C}}$ [20, Proposition 9.2.6, Theorem 9.2.7]. Suppose $(a,c) \in L$. Since $\mathcal{R}(H_{a,c})$ is a full horseshoe, all periodic points of $H_{a,c}$ is contained in $\mathcal{R}(H_{a,c})$ and therefore they are of saddle type. Thus there exists no attracting periodic orbit. Furthermore, $J_{a,c}$ is uniformly hyperbolic because it is a closed sub-invariant set of $\mathcal{R}(H_{a,c})$. It follows that int $K^+ = \emptyset$ [4, Theorem 5.9]. Since $|a| \leq 1$, we also have int $K^- = \emptyset$ [4, Lemma 5.5]. As a consequence, $J_{a,c}^+ = K_{a,c}^+$ and $J_{a,c}^- = K_{a,c}^-$, and hence $J_{a,c} = \mathcal{R}(H_{a,c}) = K_{a,c}^{\mathbb{C}}$. Therefore, Lemma 5 implies this corollary.

The set $L_p \cap \mathbb{R}^2$ have three components: two unbounded intervals, and one bounded interval connecting two white regions in Figure 2. We define I_p to be this bounded one. Similarly, I_q , I_r and I_s are defined to be the bounded intervals contained in $L_q \cap \mathbb{R}^2$, $L_q \cap \mathbb{R}^2$ and $L_s \cap \mathbb{R}^2$, respectively. From Corollary 6 it follows that I_p , I_q , I_s and I_r are contained in $\mathcal{H}_0^{\mathbb{C}} \cap \mathbb{R}^2$. To complete the proof of Theorem 1, we need to show that these intervals are of type-3.

A simple and direct way for proving this is to show that the number of periodic points contained in $K_{a,c}^{\mathbb{R}}$ is non-zero and different from that of a full horseshoe. Rigorous interval arithmetic and the Conley index theory can be applied for this purpose. We discuss this method in the appendix.

Another way is to make use of Theorem 3. Since we have already shown that $L \subset \mathcal{H}_0^{\mathbb{C}}$, we can consider the monodromy of loops in L, from which we derive the information of $K_{a.c.}^{\mathbb{R}}$.

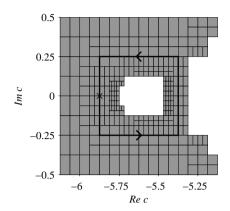


FIGURE 6. The loop $\beta_p:[0,1]\to L_p$ based at (a,c)=(1,-5.875).

Let $\beta_p:[0,1]\to L_p$ be a loop that turns around the smaller white island of Figure 2 as illustrated in Figure 6. We require that $\beta_p(1/2)\in I_p$, and that β_p be symmetric, that is, $\bar{\beta}_p=\beta_p^{-1}$. Then we define a loop $\gamma_p:[0,1]\to L_p\cup\mathsf{HOV}$ based at $(1,-10)\in\mathsf{DN}$ by setting

$$\gamma_p := \bar{\alpha}^{-1} \cdot \beta_p \cdot \alpha$$

where $\alpha:[0,1]\to \mathsf{HOV}\cup L_p$ is a path from (1,-10) to the basepoint of β_p . Choose the parametrization of γ_p so that $\gamma_p(1/2)\in I_p$ and $\bar{\gamma}_p=\gamma_p^{-1}$ hold. Similarly we define loops γ_q , γ_r and γ_s based at (1,-10) turning around the smaller islands in L_q , L_r and L_s , respectively.

Proposition 7. The automorphism $\rho(\gamma_p)$ interchanges the words 0010100 and 0011100 contained in $s = (s_i)_{i \in \mathbb{Z}} \in \Sigma_2$. Namely,

$$(\rho(\gamma_p)(s))_i = \begin{cases} 0 & \text{if } s_{i-3} \cdots s_i \cdots s_{i+3} = 0011100 \\ 1 & \text{if } s_{i-3} \cdots s_i \cdots s_{i+3} = 0010100 \\ s_i & \text{otherwise.} \end{cases}$$

Similarly, $\rho(\gamma_q)$ interchanges 10100 and 11100, $\rho(\gamma_r)$ interchanges 10010 and 10110, and $\rho(\gamma_s)$ interchanges 0010 and 0110.

The proof of Proposition 7 is also computer assisted. An algorithm for this will be discussed in §4.

Now we are prepared to prove Theorem 1.

Proof of Theorem 1. Since $\operatorname{Fix}(\rho(\gamma_p))$ is a non-empty proper subset of Σ_2 , Theorem 3 implies that $\gamma_p(1/2) \in I_p$ is of type-3. By considering loops homotopic to γ_p , we can show that all $(a,c) \in I_p$ are also of type-3. Proofs for other intervals are the same.

Theorem 2 immediately follows from the following proposition.

Proposition 8. The order of $\psi = \rho(\gamma_{\emptyset}) \cdot \rho(\gamma_s)$ is infinite.

The proof below is due to G. A. Hedlund [14, Theorem 20.1].

Proof. For non-negative integer p, we define elements of Σ_2 named $x^{(2p)}$ and $x^{(2p+1)}$ by

```
x^{(2p)} = \cdots 010101010110110(10)^p.111111\cdots,
x^{(2p+1)} = \cdots 010101010110110(10)^p1.00000\cdots.
```

We then look at the orbit of $x=x^{(0)}$ under the map ψ . A simple calculation shows that

```
x = \cdots 010101010110110.11111 \cdots = x^{(0)},

\psi(x) = \cdots 101010101101101.00000 \cdots = x^{(1)},

\psi^{2}(x) = \cdots 010101011011010.11111 \cdots = x^{(2)},

\psi^{3}(x) = \cdots 1010101101101101.00000 \cdots = x^{(3)}.
```

By induction, it follows that $\psi^n(x^{(0)}) = x^{(n)}$. Since $x^{(n)} \neq x^{(m)}$ if $n \neq m$, this implies that the order of ψ is infinite.

Theorem 4 is a direct consequence of Theorem 3 and Proposition 7.

3. Hyperbolicity

We recall an algorithm for proving the uniform hyperbolicity of chain recurrent sets developed by the author [1]. We also refer the reader to the work of Suzanne Lynch Hruska [15, 16] for another algorithm.

Let f be a diffeomorphism on a manifold M and Λ a compact invariant set of f. We denote by $T\Lambda$ the restriction of the tangent bundle TM to Λ .

Definition 2. We say that f is uniformly hyperbolic on Λ if $T\Lambda$ splits into a direct sum $T\Lambda = E^s \oplus E^u$ of two Tf-invariant subbundles and there exist constants c > 0 and $0 < \lambda < 1$ such that $||Tf^n|_{E^s}|| < c\lambda^n$ and $||Tf^{-n}|_{E^u}|| < c\lambda^n$ hold for all $n \ge 0$. Here $||\cdot||$ denotes a metric on M.

Proving the uniform hyperbolicity of f according to this usual definition is quite difficult, in general. Because we must control two parameters c and λ at the same time, and further, we also need to constant a metric on M adapted to the hyperbolic splitting.

To avoid this difficulty, we introduce a weaker notion of hyperbolicity called "quasi-hyperbolicity". We consider $Tf:T\Lambda\to T\Lambda$, the restriction of Tf to $T\Lambda$, as a dynamical system. An orbit of Tf is said to be trivial if it is contained in the image of the zero section.

Definition 3. We say that f is *quasi-hyperbolic* on Λ if $Tf: T\Lambda \to T\Lambda$ has no non-trivial bounded orbit.

It is easy to see that hyperbolicity implies quasi-hyperbolicity. The converse is not true in general. However, when $f|_{\Lambda}$ is chain recurrent, these two notions of hyperbolicity are equivalent.

Theorem 9 ([8, 21]). Assume that $f|_{\Lambda}$ is chain recurrent, that is, $\mathcal{R}(f|_{\Lambda}) = \Lambda$. Then f is uniformly hyperbolic on Λ if and only if f is quasi-hyperbolic on it.

The definition of quasi-hyperbolicity can be rephrased in terms of isolating neighborhoods as follows. Recall that a compact set N is an isolating neighborhood with respect to f if the maximal invariant set

$$Inv(N, f) := \{ x \in N \mid f^n(x) \in N \text{ for all } n \in \mathbb{Z} \}$$

is contained in int N, the interior of N. An invariant set S of f is said to be isolated if there is an isolating neighborhood N such that Inv(N, f) = S.

Note that the linearity of Tf in fibers of TM implies that if there exists a non-trivial bounded orbit of $Tf:T\Lambda\to T\Lambda$, then any neighborhood of the image of the zero-section must contain a non-trivial bounded orbit. Therefore, the definition of quasi-hyperbolicity is equivalent to saying that the image of the zero section of $T\Lambda$ is an isolated invariant set with respect to $Tf:T\Lambda\to T\Lambda$. To confirm that Λ is quasi-hyperbolic, in fact, it suffices to find an isolating neighborhood containing the image of the zero section.

Proposition 10 ([1], Proposition 2.5). Assume that $N \subset T\Lambda$ is an isolating neighborhood with respect to $Tf: T\Lambda \to T\Lambda$ and N contains the image of the zero-section of $T\Lambda$. Then Λ is quasi-hyperbolic.

Next, we check that the hypothesis of Theorem 9 is satisfied in the case of the complex Hénon map. Let us define

$$R(a,c) := \frac{1}{2}(1+|a|+\sqrt{(1+|a|)^2+4c}),$$

$$S(a,c) := \{(x,y) \in \mathbb{C}^2 : |x| \le R(a,c), |y| \le R(a,c)\}.$$

Then the following holds as in the case of the real Hénon map [1, Lemma 4.1].

Lemma 11. The chain recurrent set $\mathcal{R}(H_{a,c})$ is contained in S(a,c). Furthermore, $H_{a,c}$ restricted to $\mathcal{R}(H_{a,c})$ is chain recurrent.

To prove Lemma 5, therefore, it suffices to show that $\mathcal{R}(H_{a,c})$ is quasi-hyperbolic for $(a,c) \in L$. By Proposition 10, all we have to do is to find an isolating neighbourhood that contains the image of the zero-section of $T\mathcal{R}(H_{a,c})$. More precisely, it is enough to find $N \subset TM$ such that

$$\mathcal{R}(H_{a,c}) \subset N$$
 and $\operatorname{Inv}(N, TH_{a,c}) \subset \operatorname{int} N$

hold. Here we identify $\mathcal{R}(H_{a,c})$ and its image by the zero-section of TM. Since there are algorithms [1, Proposition 3.3] that efficiently compute rigorous outer approximations of $\mathcal{R}(H_{a,c})$ and $\text{Inv}(N, TH_{a,c})$, these conditions can be checked on computers rigorously.

In practice, we fix the parameter a to +1 (or 0, 25, -0.375, -1) and regard $\{H_{1,c}\}$ as a parametrized family with a single complex parameter $c \in \mathbb{C}$. In the parameter plane, we define

$$C := \{c \in \mathbb{C} : |\operatorname{Im} c| \leq 8 \text{ and } |\operatorname{Re} c| \leq 8\}.$$

If $c \notin C$ then $(1,c) \in \mathsf{HOV}$, and thus we do not need to check the hyperbolicity for such c. Furthermore, our computation can be restricted to the case when Im $c \geq 0$ because $H_{1,c}$ and $H_{1,\bar{c}}$ are conjugate via ϕ and hence the hyperbolicity of these two maps are equivalent.

Finally, we perform Algorithm 3.6 of [1] for the family $\{H_{1,c}\}$ with the initial parameter set $C \cap \{\text{Im } c \geq 0\}$. The algorithm inductively subdivide the initial parameter set and outputs a list of parameter cubes on which

the quasi-hyperbolicity is verified. This proves the quasi-hyperbolicity of $\mathcal{R}(H_{1,c})$ for $(1,c) \in L_p$. The quasi-hyperbolicity for L_q , L_r and L_s is also obtained by applications of the same algorithm.

Performed on a single 2.5GHz PowerPC G5 CPU, the computation takes 1496.5 hours, 1348.6 hours, 1496.1 hours and 1288.7 hours for L_p , L_q , L_r and L_s , respectively.

4. Monodromy

In this section, we develop an algorithm for computing the monodromy homomorphism ρ .

Let $\gamma:[0,1]\to\mathcal{H}_0^{\mathbb{C}}$ be a loop based at $\gamma(0)=\gamma(1)=(a_0,c_0)\in\mathsf{DN}$. Since $\rho(\gamma)$ is defined in terms of conjugacies $h_t=h_t^{\gamma}:K_{\gamma(t)}^{\mathbb{C}}\to\Sigma_2$ along γ , we first discuss how to compute them.

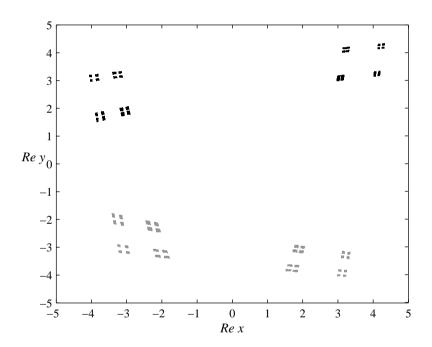


FIGURE 7. At t = 0: the initial partition N_0^0 and N_0^1 .

Let us recall the definition of h_t . Define

$$K_0^0 := \{(x,y) \in K_{\gamma(0)}^{\mathbb{C}} : \mathrm{Re} \ y \leq 0\}, \quad K_0^1 := \{(x,y) \in K_{\gamma(0)}^{\mathbb{C}} : \mathrm{Re} \ y \geq 0\}.$$

By the argument of Devaney and Nitecki [12], we have $K_0^0 \cap K_0^1 = \emptyset$ and the partition $K_{\gamma(0)}^{\mathbb{R}} = K_0^0 \cup K_0^1$ induces a topological conjugacy h_0 . The continuation of this partition along γ is defined by

$$\begin{split} K_t^0 &:= \{z \in K_{\gamma(t)}^{\mathbb{C}}: \text{ the continuation of } z \text{ along } \gamma \text{ at } t = 0 \text{ is in } K_0^0\}, \\ K_t^1 &:= \{z \in K_{\gamma(t)}^{\mathbb{C}}: \text{ the continuation of } z \text{ along } \gamma \text{ at } t = 0 \text{ is in } K_0^1\}. \end{split}$$

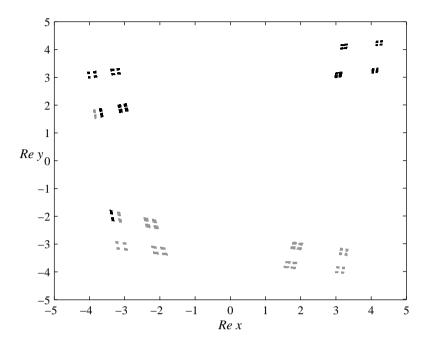


FIGURE 8. At t=1: the partition N_1^0 and N_1^1 , obtained by continuing N_0^0 and N_0^1 along γ_q .

The conjugacy h_t is, by definition, the symbolic coding with respect to this partition. Namely,

$$(h_t(z))_i := \begin{cases} 0 & \text{if} \quad H^i_{\gamma(t)}(z) \in K^0_t \\ 1 & \text{if} \quad H^i_{\gamma(t)}(z) \in K^1_t. \end{cases}$$

To determine this conjugacy, however, we do not need to compute K_t^0 and K_t^1 exactly. It suffices to have rigorous outer approximations of them. That is, if N_t^0 and N_t^1 are disjoint subsets of \mathbb{C}^2 such that $K_t^0 \subset N_t^0$ and $K_t^1 \subset N_t^1$ hold for all $t \in [0,1]$, then $k_t : K_{\gamma(t)}^{\mathbb{C}} \to \Sigma_2$ defined by

$$(k_t(z))_i := \begin{cases} 0 & \text{if } H^i_{\gamma(t)}(z) \in N^0_t \\ 1 & \text{if } H^i_{\gamma(t)}(z) \in N^1_t \end{cases}$$

is identical to h_t .

Here is an algorithm to construct such N_t^0 and N_t^1 .

- step 1. Subdivide the interval [0,1] into n closed intervals I_1, I_2, \ldots, I_n of equal length.
- step 2. Using interval arithmetic, we compute a cubical set \mathcal{N}_k for each $1 \leq k \leq n$ such that $K_{a,c}^{\mathbb{C}} \subset \mathcal{N}_k$ rigorously holds for all $(a,c) \in \gamma(I_k)$. Define $N_t := \mathcal{N}_k$ for $t \in I_k$.
- step 3. Consider the set

$$N := \bigcup_{t \in [0,1]} \{t\} \times N_t \subset [0,1] \times \mathbb{C}^2.$$

Let N^0 and N^1 be the unions of the components of N which intersect with $\{0\} \times \{\text{Re } y \leq 0\}$ and $\{0\} \times \{\text{Re } y \geq 0\}$, respectively. If $N^0 \cap N^1 = \emptyset$, define $N_t^0 = N_t \cap N^0$ and $N_t^1 = N_t \cap N^1$ then stop. If this is not the case, we refine the subdivision of [0,1] and the grid of \mathbb{C}^2 , and then go back to step 1.

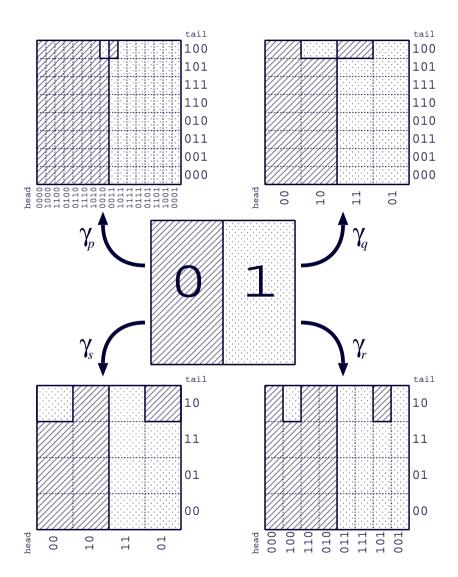


FIGURE 9. The change of the partition along $\gamma_p, \gamma_q, \gamma_r$ and γ_s .

Applying the algorithm above to the loop γ_q , we obtain Figures 7 and 8. The interval [0,1] is decomposed into $n=2^8$ sub-intervals, and the size of the grid for \mathbb{C}^2 is 2^{-8} in each direction. The lightly and darkly shaded regions in Figure 7 are N_0^0 and N_0^1 . Similarly, Figure 8 illustrates N_1^0 and N_1^1 . Notice that two partitions differ only in four blocks on the left hand side: two blocks of each of N_0^0 and N_0^1 are interchanged. Using rigorous interval arithmetic, these blocks are identified as blocks corresponding to the symbol sequences 10.100 and 11.100 where the dot separates the head

and the tail of a sequence. By the *head* of $s = (s_i)_{i \in \mathbb{Z}}$ we mean the sequence $\{\ldots s_{-3}s_{-2}s_{-1}s_0\}$ and by the $tail\ \{s_1s_2s_3\ldots\}$.

We execute the same computation also for loops γ_p , γ_r and γ_s . This yields Figure 9, which shows a schematic picture of the change along these loops. Notice that "head" and "tail" labels in the figure indicates the symbol coding according to the initial partition N_0^0 and N_0^1 , illustrated in the central square.

Now, we can compute the image of $\gamma = \gamma_p$ (or $\gamma_q, \gamma_r, \gamma_s$) by ρ as follows: Choose a symbol sequence $s = (s_i)_{i \in \mathbb{Z}} \in \Sigma_2$. Then $z := h_0(s)$ is located in the central square of Figure 9. By definition, $\rho(\gamma_p)(s)$ is the symbolic coding of the same point z, but with respect to the partition on the top left corner of Figure 9. Since two partitions differ only on blocks 0010.100 and 0011.100, it follows that $(\rho(\gamma(s)))_i \neq s_i$ if and only if $H^i_{\gamma(0)}(z)$ is contained in these bocks. Namely,

$$(\rho(\gamma(s)))_i = \begin{cases} 0 & \text{if } s_{i-3}s_{i-2}s_{i-1}s_is_{i+1}s_{i+2}s_{i+3} = 0011100 \\ 1 & \text{if } s_{i-3}s_{i-2}s_{i-1}s_is_{i+1}s_{i+2}s_{i+3} = 0010100 \\ s_i & otherwise. \end{cases}$$

Similarly we can compute $\rho(\gamma_q)$, $\rho(\gamma_r)$ and $\rho(\gamma_s)$. This proves Proposition 7.

COUNTING PERIODIC ORBITS

In this appendix, we prove Theorem 1 directly from Corollary 6, without any monodromy argument. Instead of using Theorem 3, we show that the number of periodic points in $K_{a,c}^{\mathbb{R}}$ is different from that of a full horseshoe. Specifically, we claim that the number of points in $\operatorname{Fix}(H_{a,c}^n) \cap \mathbb{R}^2$ is exactly as in Figure 10.

	DN	$L_p \cap \mathbb{R}^2$	$L_q \cap \mathbb{R}^2$	$L_r \cap \mathbb{R}^2$	$L_s \cap \mathbb{R}^2$	EMP
n=3	8	8	8	2	2	0
n=4	16	16	16	16	8	0
n=5	32	22	22	22	12	0
n=6	64	52	40	52	28	0
n=7	128	114	72	72	44	0

FIGURE 10. The number of points in $Fix(H_{a,c}^n) \cap \mathbb{R}^2$.

We use the Conley index theory to prove the claim. The reader not familiar with the Conley index may consult [17, 19].

Assume (a,c) is in one of I_p , I_q , I_r or I_s . We remark that the uniform hyperbolicity of $K_{a,c}^{\mathbb{R}}$ implies that the number of periodic points in $K_{a,c}^{\mathbb{R}}$ is constant on these intervals.

First we compute a lower bound for the number of periodic points. We begin with finding periodic points numerically. Since periodic points are of saddle type and hence are numerically unstable, we apply the subdivision algorithm [11] to find them. For each periodic orbit found numerically, we then construct a cubical index pair [17]. The existence of a periodic point in this index pair is then proved by the following Conley index version of Lefschetz fixed point theorem.

Theorem 12 ([17, Theorem 10.102]). Let (P_1, P_0) be an index pair for f and f_{P*} the homology index map induced by f. If $\sum_k (-1)^k \operatorname{tr} f_{P*k}^n \neq 0$ then $\operatorname{Inv}(\operatorname{cl}(P_1 \setminus P_0), f)$ contains a fixed point of f^n .

This theorem assures that there exists at least one periodic orbit in each index pair, and therefore we obtain a lower bound for the number of points in $\operatorname{Fix}(H_{a.c}^n) \cap \mathbb{R}^2$.

To compute an upper bound, we have two methods.

One is to prove the uniqueness of the periodic orbit in each index pair. As long as the size of the grid used in the subdivision algorithm was fine enough, we can expect that each index pair isolates exactly one periodic orbit of period n. Since periodic points are hyperbolic, uniqueness can be achieved by a Hartman-Grobman type theorem [2, Proposition 4.1].

The other one is to use the fact that the number of fixed points of $H_{a,c}^n$: $\mathbb{C}^2 \to \mathbb{C}^2$ is independent of the parameter, in fact it is 2^n , counted with multiplicity [13, Theorem 3.1]. In our case, the uniform hyperbolicity implies that the multiplicity is always 1 and hence there are exactly 2^n distinct points in $\operatorname{Fix}(H_{a,c}^n)$. Therefore, if we find k distinct fixed points of $H_{a,c}^n$ outside \mathbb{R}^2 , then the cardinality of $\operatorname{Fix}(H_{a,c}^n) \cap \mathbb{R}^2$ must be less than or equal to $2^n - k$. Again, we can apply Theorem 12 to establish the existence of fixed points in $\mathbb{C}^2 \setminus \mathbb{R}^2$. This gives an upper bound.

For all cases shown in Figure 10, the lower and upper bounds obtained by methods above coincide. Thus our claim follows.

References

- [1] Z. Arai, On Hyperbolic Plateaus of the Hénon map, to appear in Experimental Mathematics.
- [2] Z. Arai and K. Mischaikow, Rigorous computations of homoclinic tangencies, SIAM Journal on Applied Dynamical Systems 5 (2006), 280–292.
- [3] E. Bedford, M. Lyubich and J. Smillie, Polynomial diffeomorphisms of C^2 . IV: The measure of maximal entropy and laminar currents, *Invent. math.* **112** (1993), 77–125.
- [4] E. Bedford and J. Smillie, Polynomial diffeomorphisms of C²: currents, equilibrium measure and hyperbolicity, *Invent. math.* 103 (1991), 69–99.
- [5] E. Bedford and J. Smillie, The Hénon family: The complex horseshoe locus and real parameter values, *Contemp. Math.* 396 (2006), 21–36.
- [6] P. Blanchard, R. L. Devaney and L. Keen, The dynamics of complex polynomials and automorphisms of the shift, *Invent. Math.* 104 (1991), 545–580.
- [7] M. Boyle, D. Lind and D. Rudolph, The automorphism group of a shift of finite type, Trans. Amer. Math. Soc. 306 (1988), 71–114.
- [8] R. C. Churchill, J. Franke and J. Selgrade, A geometric criterion for hyperbolicity of flows, Proc. Amer. Math. Soc. 62 (1977), 137–143.
- [9] P. Cvitanović, Periodic orbits as the skeleton of classical and quantum chaos, Physica D 51 (1991), 138–151.
- [10] M. J. Davis, R. S. MacKay and A. Sannami, Markov shifts in the Hénon family, Physica D 52 (1991), 171–178.
- [11] M. Dellnitz and O. Junge, Set oriented numerical methods for dynamical systems, Handbook of dynamical systems II, North-Holland, 2002, 221–264.
- [12] R. Devaney and Z. Nitecki, Shift automorphisms in the Hénon mapping, Commun. Math. Phys. 67 (1979), 137–146.
- [13] S. Friedland and J. Milnor, Dynamical properties of plane polynomial automorphisms, Ergodic Theory Dynam. Systems 9 (1989), 67–99.
- [14] G. A. Hedlund, Endomorphisms and automorphisms of the shift dynamical system, *Mathematical Systems Theory* **3** (1969), 320–375.

- [15] S. L. Hruska, A numerical method for constructing the hyperbolic structure of complex H'enon mappings, Found. Comput. Math. 6 (2006), 427–455.
- [16] S. L. Hruska, Rigorous numerical models for the dynamics of complex H'enon mappings on their chain recurrent sets, *Discrete Contin. Dyn. Syst.* 15 (2006), 529–558.
- [17] T. Kaczynski, K. Mischaikow and M. Mrozek, Computational Homology, Applied Mathematical Sciences, 157, Springer-Verlag, 2004.
- [18] B. P. Kitchens, Symbolic Dynamics, Springer-Verlag, 1998.
- [19] K. Mischaikow and M. Mrozek, The Conley index theory, Handbook of Dynamical Systems II, North-Holland, 2002, 393–460.
- [20] S. Morosawa, Y. Nishimura, M. Taniguchi and T. Ueda, *Holomorphic Dynamics*, Cambridge University Press, 2000.
- [21] R. J. Sacker and G. R. Sell, Existence of dichotomies and invariant splitting for linear differential systems I, J. Differential Equations 27 (1974) 429–458.
- [22] M. Shub, Global stability of dynamical systems, Springer-Verlarg, New York, 1987.

DEPARTMENT OF MATHEMATICS, KYOTO UNIVERSITY, KYOTO 606-8502, JAPAN, AND PRESTO, JAPAN SCIENCE AND TECHNOLOGY AGENCY

E-mail address: arai@math.kyoto-u.ac.jp
URL: http://www.math.kyoto-u.ac.jp/~arai/