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import numpy as np
import pdb
class KNN(object):
 def init (self):
   pass
 def train(self, X, y):
   Inputs:
   - X is a numpy array of size (num examples, D)
   - y is a numpy array of size (num examples, )
   self.X train = X
   self.y_train = y
 def compute distances(self, X, norm=None):
   Compute the distance between each test point in X and each training point
   in self.X_train.
   Inputs:
   - X: A numpy array of shape (num test, D) containing test data.
   - norm: the function with which the norm is taken.
   Returns:
   - dists: A numpy array of shape (num test, num train) where dists[i, j]
    is the Euclidean distance between the ith test point and the jth training
   point.
   if norm is None:
    norm = lambda x: np.sqrt(np.sum(x**2))
    \#norm = 2
   num test = X.shape[0]
   num_train = self.X train.shape[0]
   dists = np.zeros((num test, num train))
   for i in np.arange(num test):
    for j in np.arange(num train):
      # YOUR CODE HERE:
      # Compute the distance between the ith test point and the ith
      # training point using norm(), and store the result in dists[i, j].
      # ----- #
        trainSample=self.X_train[j]
        testSample = X[i]
        distance = norm(trainSample-testSample)
        dists[i, j] = distance
      # END YOUR CODE HERE
      # ----- #
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return dists
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def compute L2 distances vectorized(self, X):
 Compute the distance between each test point in X and each training point
 in self.X train WITHOUT using any for loops.
 Inputs:
 - X: A numpy array of shape (num test, D) containing test data.
 - dists: A numpy array of shape (num test, num train) where dists[i, j]
   is the Euclidean distance between the ith test point and the jth training
  point.
 num test = X.shape[0]
 num train = self.X train.shape[0]
 dists = np.zeros((num test, num train))
 # YOUR CODE HERE:
 # Compute the L2 distance between the ith test point and the jth
   training point and store the result in dists[i, j]. You may
   NOT use a for loop (or list comprehension). You may only use
 # numpy operations.
 #
 #
   HINT: use broadcasting. If you have a shape (N,1) array and
 # a shape (M,) array, adding them together produces a shape (N, M)
 trainsquared = np.sum(self.X train**2, axis=1, keepdims=True)
 testsquared = np.sum(X**2, axis=1)
 multiplied = np.dot(self.X train, X.T)
 dists = np.sqrt(trainsquared - 2*multiplied + testsquared)
 dists = dists.T
 # END YOUR CODE HERE
 return dists
def compute L1 distances vectorized(self, X):
 Compute the distance between each test point in X and each training point
 in self.X train WITHOUT using any for loops.
 Inputs:
 - X: A numpy array of shape (num test, D) containing test data.
 Returns:
 - dists: A numpy array of shape (num test, num train) where dists[i, j]
   is the Euclidean distance between the ith test point and the jth training
   point.
 num\_test = X.shape[0]
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num train = self.X train.shape[0]
 dists = np.zeros((num test, num train))
 # YOUR CODE HERE:
   Compute the L2 distance between the ith test point and the jth
   training point and store the result in dists[i, j]. You may
   NOT use a for loop (or list comprehension). You may only use
   numpy operations.
   HINT: use broadcasting. If you have a shape (N,1) array and
   a shape (M,) array, adding them together produces a shape (N, M)
 for i in range(0,num_test):
   # find the nearest training image to the i'th test image
   # using the L1 distance (sum of absolute value differences)
   distances = np.sum(np.abs(self.X train - X[i,:]), axis = 1)
   dists[i]=distances
 # END YOUR CODE HERE
 return dists
def compute Linf distances vectorized(self, X):
 Compute the distance between each test point in X and each training point
 in self.X train WITHOUT using any for loops.
 - X: A numpy array of shape (num test, D) containing test data.
 Returns:
 - dists: A numpy array of shape (num test, num train) where dists[i, j]
   is the Euclidean distance between the ith test point and the jth training
 point.
 num test = X.shape[0]
 num train = self.X train.shape[0]
 dists = np.zeros((num test, num train))
 # YOUR CODE HERE:
   Compute the L2 distance between the ith test point and the jth
   training point and store the result in dists[i, j]. You may
   NOT use a for loop (or list comprehension). You may only use
 #
   numpy operations.
   HINT: use broadcasting. If you have a shape (N,1) array and
 # a shape (M,) array, adding them together produces a shape (N, M)
 # array.
 # ----- #
 for i in range(0, num test):
  # find the nearest training image to the i'th test image
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# using the L1 distance (sum of absolute value differences)
   distances = np.sum(np.linalg.norm(self.X train - X[i,:],ord="inf"), axis = 1)
   dists[i]=distances
 # END YOUR CODE HERE
 return dists
def predict_labels(self, dists, k=1):
 Given a matrix of distances between test points and training points,
 predict a label for each test point.
 Inputs:
 - dists: A numpy array of shape (num test, num train) where dists[i, j]
   gives the distance betwen the ith test point and the jth training point.
 - y: A numpy array of shape (num test,) containing predicted labels for the
  test data, where y[i] is the predicted label for the test point X[i].
 num test = dists.shape[0]
 y pred = np.zeros(num test)
 for i in np.arange(num test):
   # A list of length k storing the labels of the k nearest neighbors to
   # the ith test point.
   closest y = []
   # YOUR CODE HERE:
   # Use the distances to calculate and then store the labels of
   # the k-nearest neighbors to the ith test point. The function
    numpy.argsort may be useful.
   # After doing this, find the most common label of the k-nearest
   # neighbors. Store the predicted label of the ith training example
   # as y_pred[i]. Break ties by choosing the smaller label.
   distance = dists[i]
   sortIndices = np.argsort(distance)
   bestOnes = sortIndices[0:k]
   closest_y = self.y_train[best0nes]
   counts = np.bincount(closest y)
   y pred[i]=np.argmax(counts)
   # END YOUR CODE HERE
```

return y pred