```
import numpy as np
import matplotlib.pyplot as plt
class TwoLayerNet(object):
  A two-layer fully-connected neural network. The net has an input dimension of
  N, a hidden layer dimension of H, and performs classification over C classes.
  We train the network with a softmax loss function and L2 regularization on the
  weight matrices. The network uses a ReLU nonlinearity after the first fully
  connected layer.
  In other words, the network has the following architecture:
  input - fully connected layer - ReLU - fully connected layer - softmax
  The outputs of the second fully-connected layer are the scores for each class.
  def __init__(self, input_size, hidden_size, output_size, std=le-4):
    Initialize the model. Weights are initialized to small random values and
    biases are initialized to zero. Weights and biases are stored in the
    variable self.params, which is a dictionary with the following keys:
    W1: First layer weights; has shape (H, D)
    b1: First layer biases; has shape (H,)
    W2: Second layer weights; has shape (C, H)
    b2: Second layer biases; has shape (C,)
    Inputs:
    - input size: The dimension D of the input data.
    - hidden size: The number of neurons H in the hidden layer.
    - output size: The number of classes C.
    self.params = {}
    self.params['W1'] = std * np.random.randn(hidden size, input size)
    self.params['b1'] = np.zeros(hidden size)
    self.params['W2'] = std * np.random.randn(output_size, hidden_size)
    self.params['b2'] = np.zeros(output size)
  def loss(self, X, y=None, reg=0.0):
    Compute the loss and gradients for a two layer fully connected neural
    network.
    Inputs:
    - X: Input data of shape (N, D). Each X[i] is a training sample.
    - y: Vector of training labels. y[i] is the label for X[i], and each y[i] is
      an integer in the range 0 \le y[i] < C. This parameter is optional; if it
      is not passed then we only return scores, and if it is passed then we
      instead return the loss and gradients.
    - reg: Regularization strength.
    Returns:
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If y is None, return a matrix scores of shape (N, C) where scores[i, c] is

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the score for class c on input X[i].
If y is not None, instead return a tuple of:
- loss: Loss (data loss and regularization loss) for this batch of training
 samples.
- grads: Dictionary mapping parameter names to gradients of those parameters
 with respect to the loss function; has the same keys as self.params.
# Unpack variables from the params dictionary
W1, b1 = self.params['W1'], self.params['b1']
W2, b2 = self.params['W2'], self.params['b2']
N, D = X.shape
# Compute the forward pass
scores = None
# YOUR CODE HERE:
# Calculate the output scores of the neural network. The result
# should be (N, C). As stated in the description for this class,
# there should not be a ReLU layer after the second FC layer.
# The output of the second FC layer is the output scores. Do not
# use a for loop in your implementation.
#b1 = b1.reshape([len(b1),1])
\#b2 = b2.reshape([len(b2),1])
layer10ut = W1.dot(X.T) + b1[:,None]
ReluOut = np.maximum(0,layer10ut)
layer20ut = W2.dot(Relu0ut) + b2[:,None]
scores = layer20ut.T
# END YOUR CODE HERE
# If the targets are not given then jump out, we're done
if v is None:
 return scores
# Compute the loss
loss = None
# YOUR CODE HERE:
# Calculate the loss of the neural network. This includes the
# softmax loss and the L2 regularization for W1 and W2. Store the
# total loss in teh variable loss. Multiply the regularization
# loss by 0.5 (in addition to the factor reg).
# scores is num examples by num classes
soft = np.exp(scores)
sums = np.sum(soft,axis=1)
probs = soft / sums[:,None]
predsForClass = probs[np.arange(y.shape[0]),y]
SoftmaxLoss = np.mean(-np.log(predsForClass))
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l2regularization = np.sum(W1**2) + np.sum(W2**2)
 l2regularization = 0.5*reg*l2regularization
 loss=SoftmaxLoss+l2regularization
 # END YOUR CODE HERE
 qrads = \{\}
 # YOUR CODE HERE:
   Implement the backward pass. Compute the derivatives of the
 # weights and the biases. Store the results in the grads
 # dictionary. e.g., grads['W1'] should store the gradient for
 # W1, and be of the same size as W1.
 \#A1 = W1X+B1
 \#A2 = RELU(A1)
 #A3 = W2A2+B2
 #A4 = SOFTMAX(A3)
 #DL/DA3 = PREDICTIONS-LABELSONEHOT
 \#DA3/DW2 = A2
 \#DA3/DA2 = W2
 \#DA2/DA1 = 0 OR 1
 \#DA1/DW1 = A1
 grad = probs.copy()
 grad[np.arange(y.shape[0]),y] -= 1
 dLA3=qrad/X.shape[0]
 dA3W2=ReluOut.copy()
 b2grad = np.sum(dLA3,axis=0)
 w2grad = np.dot(dLA3.T, dA3W2.T) + reg*W2
 dA3A2 = W2
 dA2dA1 = layer10ut.copy()
 dA2dA1[dA2dA1<0]=0
 dA2dA1[dA2dA1>0]=1
 dA1dW1 = X.copy()
 kronecker = ((dLA3.dot(dA3A2)).T*dA2dA1)
 blgrad = np.sum(kronecker.T,axis=0)
 wlgrad = (kronecker.dot(dA1dW1)) + reg*W1
 grads["W1"]=w1grad
 grads["b1"]=b1grad
 grads["W2"]=w2grad
 grads["b2"]=b2grad
 # END YOUR CODE HERE
 return loss, grads
def train(self, X, y, X_val, y_val,
       learning rate=1e-3, learning rate decay=0.95,
       reg=1e-5, num_iters=100,
       batch size=200, verbose=False):
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Train this neural network using stochastic gradient descent.

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Inputs:
- X: A numpy array of shape (N, D) giving training data.
- y: A numpy array f shape (N,) giving training labels; y[i] = c means that
 X[i] has label c, where 0 \le c < C.
- X val: A numpy array of shape (N val, D) giving validation data.
- y val: A numpy array of shape (N val,) giving validation labels.
- learning rate: Scalar giving learning rate for optimization.
- learning rate decay: Scalar giving factor used to decay the learning rate
 after each epoch.
- reg: Scalar giving regularization strength.
- num iters: Number of steps to take when optimizing.
- batch size: Number of training examples to use per step.
- verbose: boolean; if true print progress during optimization.
num train = X.shape[0]
iterations per epoch = max(num train / batch size, 1)
# Use SGD to optimize the parameters in self.model
loss history = []
train acc history = []
val acc history = []
for it in np.arange(num iters):
 X batch = None
 y batch = None
 # YOUR CODE HERE:
 # Create a minibatch by sampling batch size samples randomly.
 indices = np.random.choice(np.arange(num train),batch size)
 X batch = X[indices]
 y batch = y[indices]
 # END YOUR CODE HERE
 # Compute loss and gradients using the current minibatch
 loss, grads = self.loss(X_batch, y=y_batch, reg=reg)
 loss history.append(loss)
 # YOUR CODE HERE:
 # Perform a gradient descent step using the minibatch to update
 # all parameters (i.e., W1, W2, b1, and b2).
 self.params['W1'] = self.params['W1'] - grads['W1']* learning_rate
 self.params['b1'] = self.params['b1'] - grads['b1']* learning_rate
 self.params['W2'] = self.params['W2'] - grads['W2']* learning rate
 self.params['b2'] = self.params['b2'] - grads['b2']* learning rate
 # END YOUR CODE HERE
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if verbose and it % 100 == 0:
     print('iteration {} / {}: loss {}'.format(it, num iters, loss))
   # Every epoch, check train and val accuracy and decay learning rate.
   if it % iterations per epoch == 0:
     # Check accuracy
     train acc = (self.predict(X batch) == y batch).mean()
     val acc = (self.predict(X val) == y val).mean()
     train acc history.append(train acc)
     val acc history.append(val acc)
     # Decay learning rate
     learning rate *= learning rate decay
 return {
   'loss history': loss history,
   'train acc history': train acc history,
   'val acc history': val acc history,
 }
def predict(self, X):
 Use the trained weights of this two-layer network to predict labels for
 data points. For each data point we predict scores for each of the C
 classes, and assign each data point to the class with the highest score.
 Inputs:
 - X: A numpy array of shape (N, D) giving N D-dimensional data points to
   classify.
 Returns:
 - y pred: A numpy array of shape (N,) giving predicted labels for each of
   the elements of X. For all i, y pred[i] = c means that X[i] is predicted
   to have class c, where 0 \ll c < C.
 y pred = None
 # YOUR CODE HERE:
 # Predict the class given the input data.
 layer10ut = self.params['W1'].dot(X.T) + self.params['b1'][:,None]
 ReluOut = np.maximum(0,layer10ut)
 layer20ut = self.params['W2'].dot(ReluOut) + self.params['b2'][:,None]
 y pred = np.argmax(layer20ut,axis = 0)
 # END YOUR CODE HERE
 return y_pred
```