

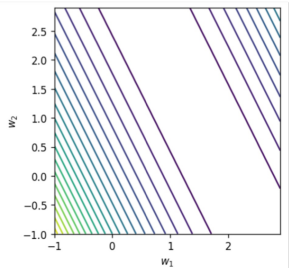
CS/ECE/ME532 Activity 18

Estimated time: 15 mins for P1, 20 mins for P2, 15 mins for P3, 20 mins for P4

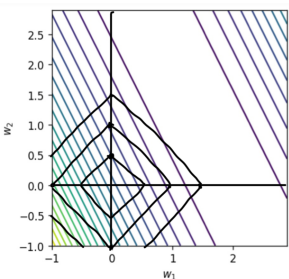
1. A breast cancer gene database has approximately 8000 genes from 100 subjects. The label y_i is the disease state of the i th subject (+1 if no cancer, -1 if breast cancer). Suppose we build a linear classifier that combines the 8000 genes, say $\mathbf{g}_i, i = 1, 2, \dots, 100$ to predict whether a subject has cancer $\hat{y}_i = \text{sign}\{\mathbf{g}_i^T \mathbf{w}\}$. Note that here \mathbf{g}_i and \mathbf{w} are 8000-by-1 vectors. You recall from the previous period that the least-squares problem for finding classifier weights has no unique solution.

Your hypothesis is that a relatively small number of the 8000 genes are predictive of the cancer state. Identify a regularization strategy consistent with this hypothesis and justify your choice.

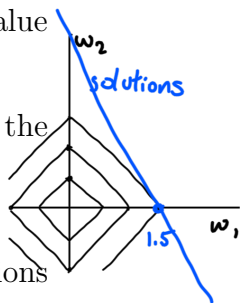
- L1 norm regularization will find a sparse solution that makes unimportant features/genes have a weight of 0. Thus only a small number of genes are chosen.*
2. Consider the least-squares problem $\min_{\mathbf{w}} \|\mathbf{y} - \mathbf{X}\mathbf{w}\|_2^2$ where $\mathbf{y} = 4$ and $\mathbf{X} = \begin{bmatrix} 2 & 1 \end{bmatrix}$.



- a) Does this problem have a unique solution? Why or why not? *No, the rank of X is 1 which will be less than the dimensions of w.*
- b) Sketch the contours of the cost function $f(\mathbf{w}) = \|\mathbf{y} - \mathbf{X}\mathbf{w}\|_2^2$ in the $w_1 - w_2$ plane.



- c) Now consider the LASSO $\min_{\mathbf{w}} \|\mathbf{w}\|_1$ subject to $\|\mathbf{y} - \mathbf{X}\mathbf{w}\|_2^2 < 1$. Find the solution using the following steps.
 - i. Repeat your sketch from part b).
 - ii. Add a sketch of $\|\mathbf{w}\|_1 = c$
 - iii. Find the \mathbf{w} that satisfies $\|\mathbf{y} - \mathbf{X}\mathbf{w}\|_2^2 = 1$ with the minimum possible value of $\|\mathbf{w}\|_1$. *$\mathbf{w} \approx [1.5, 0]^T$*
- d) Use your insight from the previous part to sketch the set of solutions to the problem $\min_{\mathbf{w}} \|\mathbf{y} - \mathbf{X}\mathbf{w}\|_2^2 + \lambda \|\mathbf{w}\|_1$ for $0 < \lambda < \infty$.



3. The script provided has a function that will compute a specified number of iterations of the proximal gradient descent algorithm for solving the ℓ_1 -regularized least-squares problem

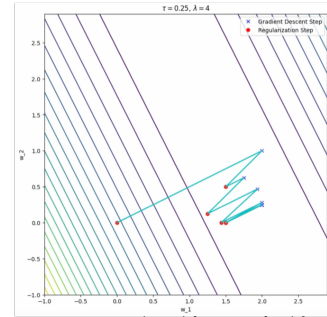
$$\min_{\mathbf{w}} \|\mathbf{y} - \mathbf{X}\mathbf{w}\|_2^2 + \lambda \|\mathbf{w}\|_1$$

The script will get you started displaying the path taken by the weights in the proximal gradient descent iteration superimposed on a contour plot of the squared error surface

for the cost function defined in problem 2. part b) starting from $\mathbf{w}^{(0)} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$. The

script assumes $\lambda = 4$ and $\tau = 1/4$.

Include the plots you generate below with your submission.



- a) How many iterations does it take for the algorithm to converge to the solution?

What is the converged value for w ? After 5 iterations the algorithm converges

$$w = [1.5, 0]^T$$

- b) Change to $\lambda = 2$. How many iterations does it take for the algorithm to converge to the solution? What is the converged value for w ? Converges after 8 iterations

$$w = [1.75, 0]^T$$

- c) Explain what happens to the weights in the regularization step.

Any weights from gradient descent that are between $-\frac{\lambda z}{2}$ and $\frac{\lambda z}{2}$ become 0. This means that a smaller λ will decrease this interval

4. Use the proximal gradient algorithm to solve $\min_w \|y - Xw\|_2^2 + 4\|w\|_1$ for the parameters defined in problem 2.

- a) What is the maximum value for the step size in the negative gradient direction,

$$\tau? \quad \frac{2}{\|A\|_{\text{op}}^2} = \frac{2}{5} = 0.4$$

- b) Suppose $\tau = 0.1$ and you start at $w^{(0)} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$. Calculate the first two complete

iterations of the proximal gradient algorithm and depict $w^{(0)}, z^{(1)}, w^{(1)}, z^{(2)}$ and $w^{(2)}$ on a sketch of the cost function identical to the one you created in problem

2.b).

$$z^k = w^k - \tau X^T (X w^k - y)$$

$$w^{(k+1)} = \min_w \sum (z_i^k - w_i)^2 + \lambda \sum |w_i|$$

$$w_i^{(k+1)} = (|z_i| - \frac{\lambda z}{2})_+ \text{sgn}(z_i)$$

$$\frac{\lambda z}{2} = \frac{4(0.1)}{2} = 0.2$$

$$z' = \begin{bmatrix} 0 \\ 0 \end{bmatrix} - 0.1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} (0 - 4) = \begin{bmatrix} 0.8 \\ 0.4 \end{bmatrix}$$

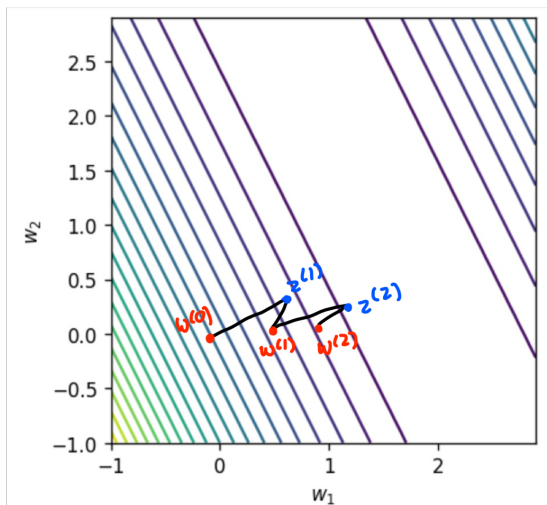
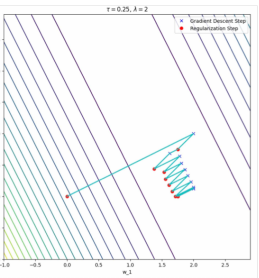
$$w' = \begin{bmatrix} (0.8 - 0.2)(1) \\ (0.4 - 0.2)(1) \end{bmatrix} = \begin{bmatrix} 0.6 \\ 0.2 \end{bmatrix}$$

$$z^2 = \begin{bmatrix} 0.6 \\ 0.2 \end{bmatrix} - 0.1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} (1.4 - 4) = \begin{bmatrix} 1.12 \\ 0.46 \end{bmatrix}$$

$$\begin{bmatrix} 0.52 \\ -0.26 \end{bmatrix}$$

$$w^2 = \begin{bmatrix} (1.12 - 0.2)(1) \\ (0.46 - 0.2)(1) \end{bmatrix} = \begin{bmatrix} 0.92 \\ 0.26 \end{bmatrix}$$

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▼ Activity 18

▼ Setup

```
import numpy as np
import matplotlib.pyplot as plt

def prxgraddescent_l1(X,y,tau,lam,w_init,it):

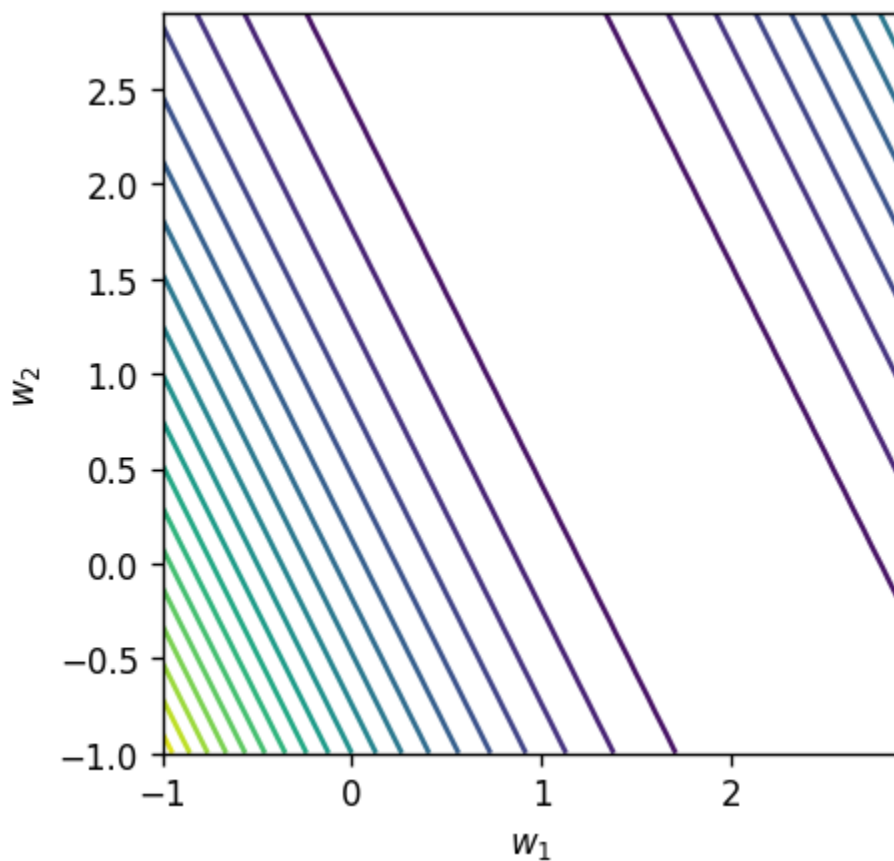
    ## compute it iterations of L2 proximal gradient descent starting at w1
    ##  $w_{k+1} = (w_k - \tau X'(Xw_k - y)) / (1 + \lambda \tau)$ 
    ## step size tau
    W = np.zeros((w_init.shape[0], it+1))
    Z = np.zeros((w_init.shape[0], it+1))
    W[:,0] = w_init
    for k in range(it):
        Z[:,k+1] = W[:,k] - tau * X.T @ (X @ W[:,k] - y);
        W[:,k+1] = np.sign(Z[:,k+1]) * np.clip(
            np.abs(Z[:,k+1]) - lam*tau/2, 0, float("inf"))

    return W,Z

## Proximal gradient descent trajectories
## Least Squares Problem
X = np.array([[2, 1]])
y = np.array([[4]])

### Find values of  $f(w)$ , the contour plot surface for
w1 = np.arange(-1,3,.1)
w2 = np.arange(-1,3,.1)
fw = np.zeros((len(w1), len(w2)))
for i in range(len(w2)):
    for j in range(len(w1)):
        w = np.array([ w1[j], w2[i] ])
        fw[i,j] = (X @ w - y)**2

### Plot the countours
plt.figure(num=None, figsize=(4, 4), dpi=120)
plt.contour(w1,w2,fw,20)
plt.xlim([-1,3])
plt.ylim([-1,3])
plt.xlabel('$w_1$')
plt.ylabel('$w_2$')
plt.axis('square');
```



▼ Question 3a)

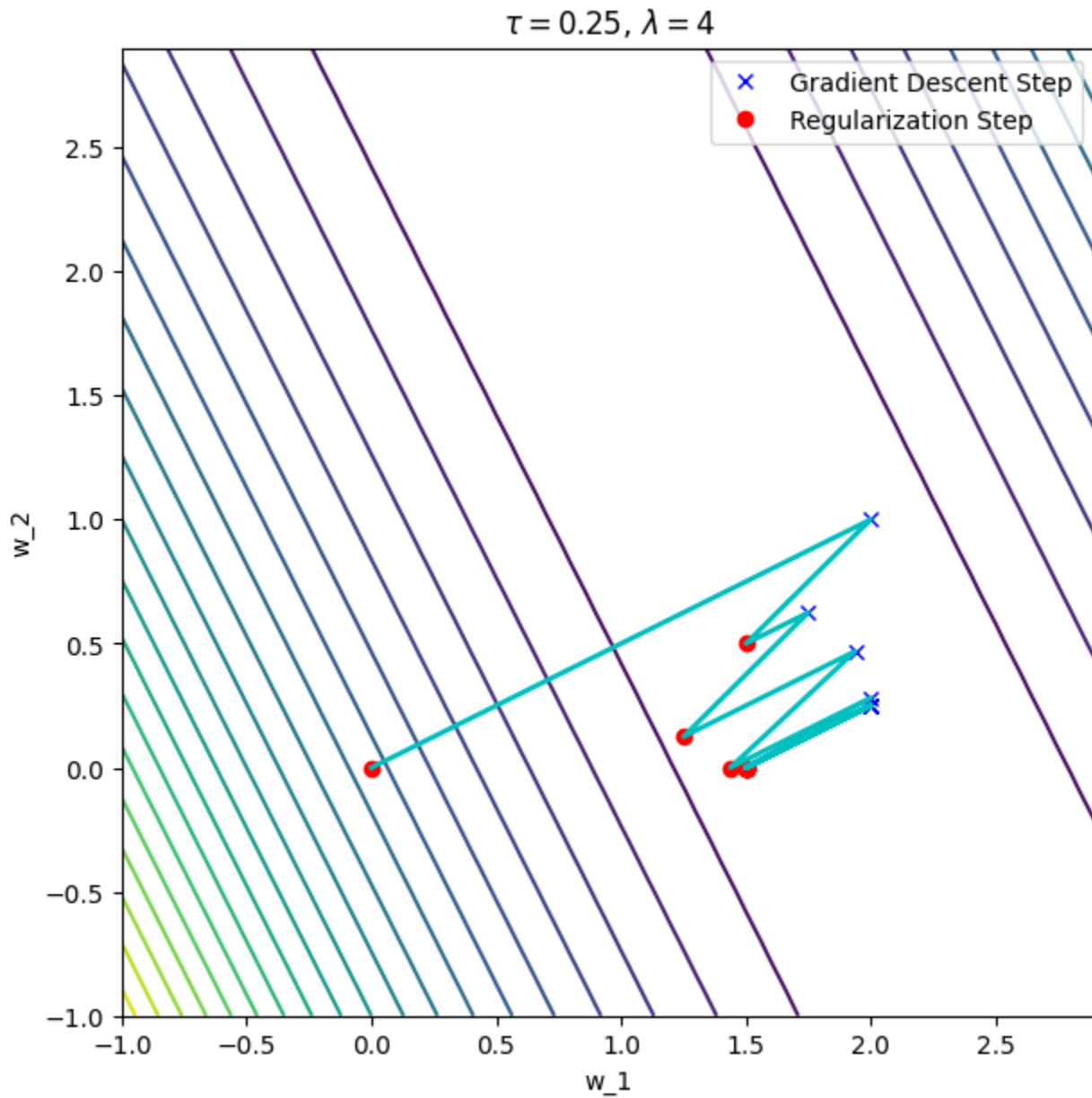
```
## Find and display weights generated by gradient descent

w_init = np.array([[0],[0]])
lam = 4;
it = 10
tau = 0.25
W,Z = prxgraddescent_l1(X,y,tau,lam,w_init,it)
# Concatenate gradient and regularization steps to display trajectory
G = np.zeros((2,0))
for i in range(it):
    G = np.hstack((G,np.hstack((W[:,[i]],Z[:,[i+1]]))))

print(W)
print(W[:, it])

plt.figure(figsize=(7,7))
plt.contour(w1,w2,fw,20)
plt.plot(Z[0,1:],Z[1,1:], 'bx',linewidth=2, label="Gradient Descent Step")
plt.plot(W[0,:],W[1,:], 'ro',linewidth=2, label="Regularization Step")
plt.plot(G[0,:],G[1,:], '-c',linewidth=2)
plt.legend()
plt.xlabel('w_1')
plt.ylabel('w_2')
plt.title('$\tau = $'+str(tau)+' , $\lambda = $'+str(lam));
```

```
[[0.    1.5    1.25    1.4375 1.5    1.5    1.5    1.5    1.5    1.5
  1.5   ]
 [0.    0.5    0.125  0.     0.     0.     0.     0.     0.     0.
  0.    ]]
[1.5 0. ]
```



Question 3b)

```
## Find and display weights generated by gradient descent
```

```
w_init = np.array([[0],[0]])
lam = 2;
it = 10
tau = 0.25
```

```

W,Z = prxgraddescent_l1(X,y,tau,lam,w_init,it)
# Concatenate gradient and regularization steps to display trajectory
G = np.zeros((2,0))
for i in range(it):
    G = np.hstack((G,np.hstack((W[:,[i]],Z[:,[i+1]]))))

print(W)
print(W[:, it])

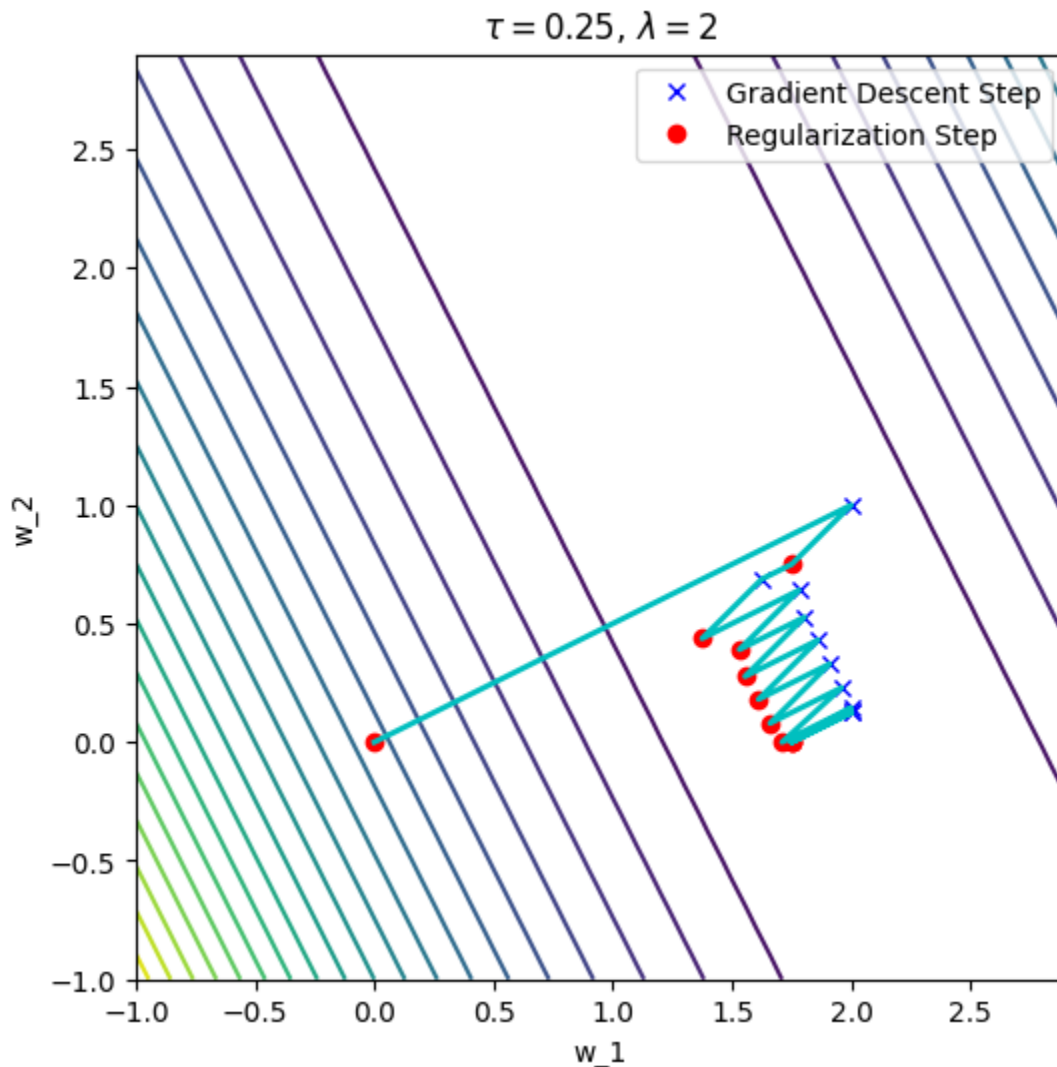
plt.figure(figsize=(6,6))
plt.contour(w1,w2,fw,20)
plt.plot(Z[0,1:],Z[1,1:], 'bx',linewidth=2, label="Gradient Descent Step")
plt.plot(W[0,:],W[1,:], 'ro',linewidth=2, label="Regularization Step")
plt.plot(G[0,:],G[1,:], '-c',linewidth=2)
plt.legend()
plt.xlabel('w_1')
plt.ylabel('w_2')
plt.title('$\tau = $'+str(tau)+' , $ \lambda = $'+str(lam));

```

```

[[0.          1.75         1.375         1.53125        1.5546875    1.61132812
  1.65966797  1.71008301  1.75          1.75          1.75          ]
 [0.          0.75         0.4375        0.390625        0.27734375  0.18066406
  0.07983398  0.          0.          0.          0.          ]]
[1.75  0.  ]

```



▼ Question 4)

```
## Find and display weights generated by gradient descent

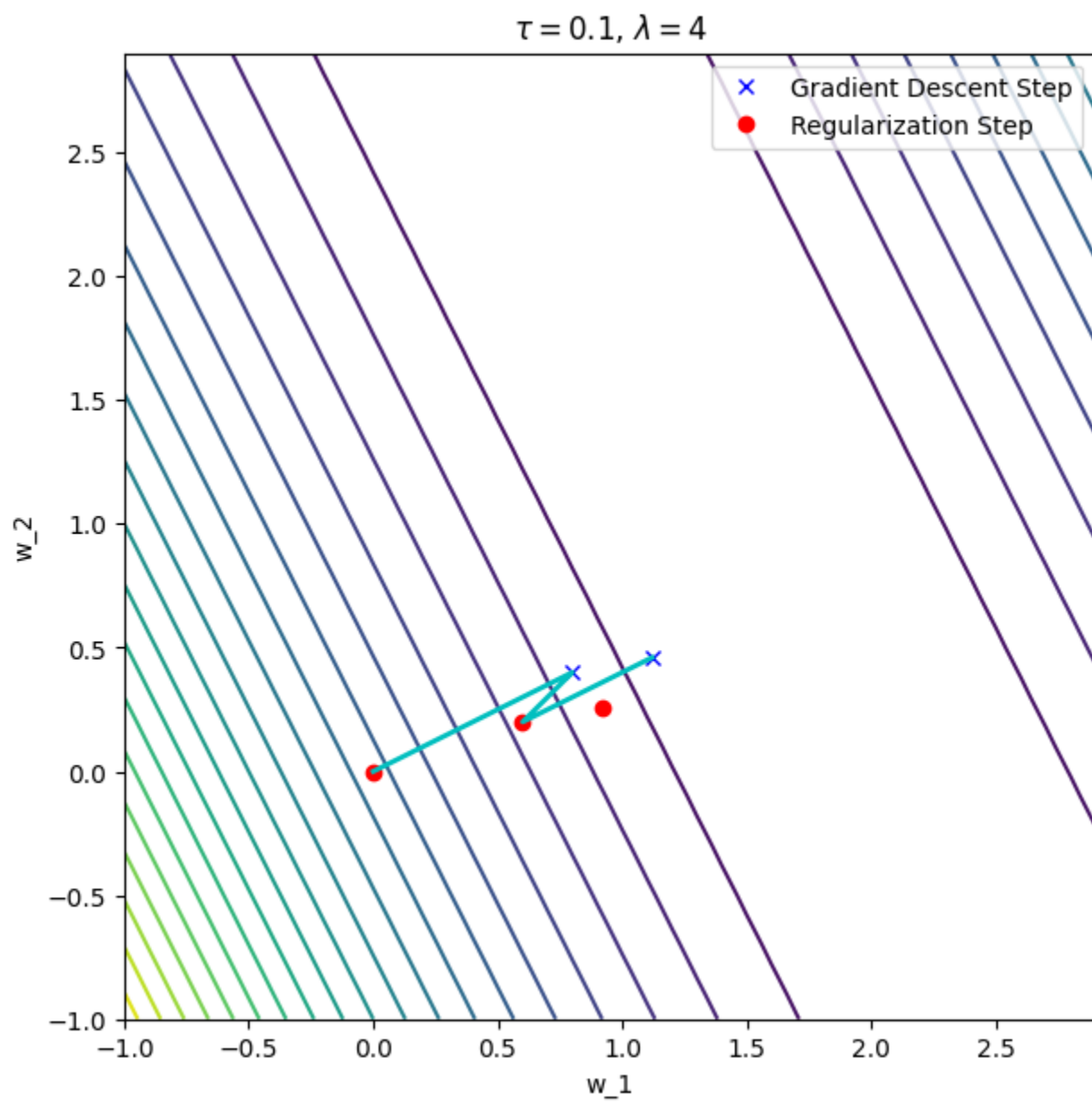
w_init = np.array([[0],[0]])
lam = 4;
it = 2
tau = 0.1
W,Z = prxgraddescent_l1(X,y,tau,lam,w_init,it)
# Concatenate gradient and regularization steps to display trajectory
G = np.zeros((2,0))
for i in range(it):
    G = np.hstack((G,np.hstack((W[:,[i]],Z[:,[i+1]]))))

print(W)
print(W[:, it])

plt.figure(figsize=(7,7))
plt.contour(w1,w2,fw,20)
plt.plot(Z[0,1:],Z[1,1:], 'bx',linewidth=2, label="Gradient Descent Step")
plt.plot(W[0,:],W[1,:], 'ro',linewidth=2, label="Regularization Step")
plt.plot(G[0,:],G[1,:], '-c',linewidth=2)
plt.legend()
plt.xlabel('w_1')
plt.ylabel('w_2')
plt.title('$\\tau = $'+str(tau)+' , $\\lambda = $'+str(lam));
```



```
[[0.  0.6  0.92]  
 [0.  0.2  0.26]]  
[0.92 0.26]
```



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