Estimated Time: 25 min for P1, 15 min for P2, 25 min for P4  $A^{\mathsf{T}}(AA^{\mathsf{T}}\mathsf{L})^{\mathsf{T}} = (A^{\mathsf{T}}A^{\mathsf{L}}\mathsf{L})^{\mathsf{T}}A^{\mathsf{T}}$   $A^{\mathsf{T}} = A^{\mathsf{T}}$ 

- 1. Alternative regularization formulas. This problem is about two alternative ways of solving the  $L_2$ -regularized least squares problem.
  - a) Prove that for any  $\lambda > 0$ , the following matrix identity holds:

$$(\boldsymbol{A}^T\boldsymbol{A} + \lambda \boldsymbol{I})^{-1}\boldsymbol{A}^T = \boldsymbol{A}^T(\boldsymbol{A}\boldsymbol{A}^T + \lambda \boldsymbol{I})^{-1}$$

*Hint:* Start by considering the expression  $\mathbf{A}^T \mathbf{A} \mathbf{A}^T + \lambda \mathbf{A}^T$  and factor it in two different ways (from the right or from the left).

b) The identity proved in part a) shows that there are actually two equivalent formulas for the solution to the  $L_2$ -regularized least squares problem. Suppose  $\mathbf{A} \in \mathbb{R}^{8000 \times 100}$  and  $\mathbf{y} \in \mathbb{R}^{8000}$ , and use this identity to find  $\mathbf{w}$  that minimizes  $||\mathbf{A}\mathbf{w} - \mathbf{y}||_2^2 + \lambda ||\mathbf{w}||_2^2$  in two different ways. Which formula will compute more rapidly? Why? Note: The number of operations required for matrix inversion is proportional to the cube of the matrix dimension. We want a smaller

to inverse  $\rightarrow A^TA = 100 \times 100$ ,  $AA^T = 8000 \times 8000 \rightarrow \text{use } (A^TA \times LI)^TA^T$ c) A breast cancer gene database has approximately 8000 genes from 100 subjects. The label  $y_i$  is the disease state of the ith subject (+1 if no cancer, -1 if breast cancer). Suppose we build a linear classifier that combines the 8000 genes, say  $g_i, i = 1, 2, ..., 100$  to predict whether a subject has cancer  $\hat{y}_i = \text{sign}\{g_i^Tw\}$ . Note that here  $g_i$  and w are 8000-by-1 vectors.

ii. Write down a Tikhonov(ridge)-regression problem for finding the classifier rank(A) cdm(w) weights given 100 labels. Does this problem have a unique solution? Which so no form of the identity in part a) leads to the most computationally efficient solution for the classifier weights? win ||Aw-d||\_2 + \lambda ||w||\_2 \ \sigma \lambda ||w|| \sigma \lambda ||w|| \ \sigma \lambda ||w|| \sigma \sigma \lambda ||w|| \sigma \lambda ||w|| \sigma \sigma \lambda ||w|| \sigma \lambda ||w|| \sigma \sigma \lambda ||w|| \sigma \sigma \lambda ||w|| \sigma \sigma \sigma \lambda ||w|| \sigma \

2. The key idea behind proximal gradient descent is to reformulate the general regularized least-squares problem into a set of simpler scalar optimization problems. Consider the regularized least-squares problem

$$\min_{\boldsymbol{w}} ||\boldsymbol{z} - \boldsymbol{w}||_2^2 + \lambda r(\boldsymbol{w})$$

An upper bound and completing the square was used to simplify the generalized least-squares problem into this form. Let the  $i^{th}$  elements of z and w be  $z_i$  and  $w_i$ , respectively.

- a) Assume  $r(\mathbf{w}) = ||\mathbf{w}||_2^2$ . Write the regularized least-squares problem as a series of separable problems involving only  $w_i$  and  $z_i$ .
- b) Assume  $r(\mathbf{w}) = ||\mathbf{w}||_1$ . Write the regularized least-squares problem as a series of separable problems involving only  $w_i$  and  $z_i$ .

3. A script is available to compute a specified number of iterations of the proximal gradient descent algorithm for solving a Tikhonov-regularized least squares problem

$$\min_{\boldsymbol{w}} ||\boldsymbol{y} - \boldsymbol{X}\boldsymbol{w}||_2^2 + \lambda ||\boldsymbol{w}||_2^2$$

The provided script will get you started displaying the path taken by the weights in the proximal gradient descent iteration superimposed on a contour plot of the squared

error surface. Assume 
$$\boldsymbol{y} = \begin{bmatrix} \sqrt{2} \\ 0 \\ 1 \\ 0 \end{bmatrix}$$
, the 4-by-2  $\boldsymbol{X} = \boldsymbol{U}\boldsymbol{\Sigma}\boldsymbol{V}^T$  has singular value

decomposition 
$$\boldsymbol{U} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$$
,  $\boldsymbol{\Sigma} = \begin{bmatrix} 1 & 0 \\ 0 & 1/2 \end{bmatrix}$ , and  $\boldsymbol{V} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$ . Complete

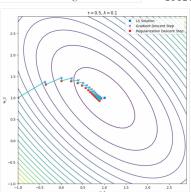
20 iterations of gradient descent in each case specified below.

Include the plots you generate below with your submission.

- a) What is the maximum value for the step size  $\tau$  that will guarantee convergence?
- z has to be between O and  $\frac{1}{\|x\|_{op}^2}$   $= \frac{1}{|x|} = \frac{1}{|x|}$  b) Start proximal gradient descent from the point  $w = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$  using a step size of

 $\tau = 0.5$  and tuning parameter  $\lambda = 0.5$ . How do you explain the trajectory the weights take toward the optimum, e.g., why is it shaped this way? What direction does each iteration move in the regularization step? gradient descent tries to go in the direction of maximum descent, but regularization tries to get ||w||2 closer

c) Repeat the previous case with  $\lambda=0.1$  What happens? How does  $\lambda$  affect each to (0.0) to iteration and why?



with a smaller  $\lambda$ , the regularization step doesn't have as much power, so the solution end sup much cluser to the center of the ellipse.

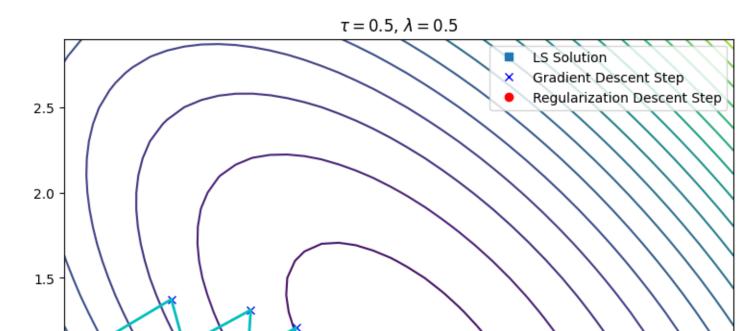
## Activity 17

## ▼ Setup

```
import numpy as np
import matplotlib.pyplot as plt
def prxgraddescent l2(X,y,tau,lam,w init,it):
## compute it iterations of L2 proximal gradient descent starting at w1
\#\# \ w_{k+1} = (w_k - tau * X' * (X*w_k - y)/(1+lam*tau)
## step size tau
    W = np.zeros((w_init.shape[0], it+1))
    Z = np.zeros((w_init.shape[0], it+1))
    W[:,[0]] = w_init
    for k in range(it):
        Z[:,[k+1]] = W[:,[k]] - tau * X.T @ (X @ W[:,[k]] - y);
        W[:,[k+1]] = Z[:,[k+1]]/(1+lam*tau)
    return W, Z
## Proximal gradient descent trajectories
## Least Squares Problem
U = np.array([[1, 0], [0, 1], [0, 0], [0, 0]])
S = np.array([[1, 0], [0, 0.5]])
Sinv = np.linalg.inv(S)
V = 1/np.sqrt(2)*np.array([[1, 1], [1, -1]])
y = np.array([[np.sqrt(2)], [0], [1], [0]])
X = U @ S @ V.T
### Find Least Squares Solution
w_ls = V @ Sinv @ U.T @ y
c = y.T @ y - y.T @ X @ w_ls
### Find values of f(w), the contour plot surface for
w1 = np.arange(-1,3,.1)
w2 = np.arange(-1,3,.1)
fw = np.zeros((len(w1), len(w2)))
for i in range(len(w2)):
    for j in range(len(w1)):
        w = np.array([ [w1[j]], [w2[i]] ])
        fw[i,j] = (w-w_ls).T @ X.T @ X @ (w-w_ls) + c
```

## Question 3b)

```
## Find and display weights generated by gradient descent
w_{init} = np.array([[-1],[1]])
lam = 0.5;
it = 20
tau = 0.5
W,Z = prxgraddescent_12(X,y,tau,lam,w_init,it)
# Concatenate gradient and regularization steps to display trajectory
G = np.zeros((2,0))
for i in range(it):
    G = np.hstack((G,np.hstack((W[:,[i]],Z[:,[i+1]]))))
plt.figure(figsize=(9,9))
plt.contour(w1,w2,fw,20)
plt.plot(w_ls[0],w_ls[1],"s", label="LS Solution")
plt.plot(Z[0,1::],Z[1,1:],'bx',linewidth=2, label="Gradient Descent Step")
plt.plot(W[0,:],W[1,:],'ro',linewidth=2, label="Regularization Descent Step")
plt.plot(G[0,:],G[1,:],'-c',linewidth=2)
plt.legend()
plt.xlabel('w_1')
plt.ylabel('w_2')
plt.title('\$\tau = \$'+str(tau)+', \$\tambda = \$'+str(lam));
```



## Question 3c)

```
## Find and display weights generated by gradient descent
```

```
w_init = np.array([[-1],[1]])
lam = 0.1;
it = 20
tau = 0.5
W,Z = prxgraddescent_12(X,y,tau,lam,w_init,it)
# Concatenate gradient and regularization steps to display trajectory
G = np.zeros((2,0))
for i in range(it):
    G = np.hstack((G,np.hstack((W[:,[i]],Z[:,[i+1]]))))
plt.figure(figsize=(9,9))
plt.contour(w1,w2,fw,20)
plt.plot(w_ls[0],w_ls[1],"s", label="LS Solution")
plt.plot(Z[0,1::],Z[1,1:],'bx',linewidth=2, label="Gradient Descent Step")
plt.plot(W[0,:],W[1,:],'ro',linewidth=2, label="Regularization Descent Step")
plt.plot(G[0,:],G[1,:],'-c',linewidth=2)
plt.legend()
plt.xlabel('w_1')
plt.ylabel('w_2')
plt.title('\$\tau = \$'+str(tau)+', \$\tambda = \$'+str(lam));
```

