

# Mobilized Construction

Refined Project Proposal

# Agenda

- Context
- Problem
- Approach
- Related Work
- Work Plan

# Context

**Road infrastructure maintenance** in sub saharan Africa.

**International Roughness Index** as the standard by which road conditions are measured.

# Problem

**Damage and discomfort:** Rough roads may cause more **damage to vehicles** and **discomfort for vehicle occupants**. They can also damage transport goods.

**Expensive and fairly fragile equipment** not suited for emerging markets with constrained budgets and minor companies.

**Vast areas to measure**, taking a lot of time. Possibly more valuable to get more measurements of a lesser quality.

# Project Description / Scope

Designing and implementing a prototype of a **robust, low-cost device** to mount in a government vehicle to gather **GPS- and accelerometer-data**.

**Power will be sourced from the vehicle**, either directly from the battery or from the 12V plug.

The gathered data will be **sent in bundles over wifi**, once a connection to a known wifi network is established (e.g. when the vehicle is returned to the garage).

The device and its function should preferably **be invisible to**, and not need the intervention from **the driver** of the vehicle.

**Configuration and installation** of the device can be handled by a professional mechanic or it-specialist if necessary.

# Approach I

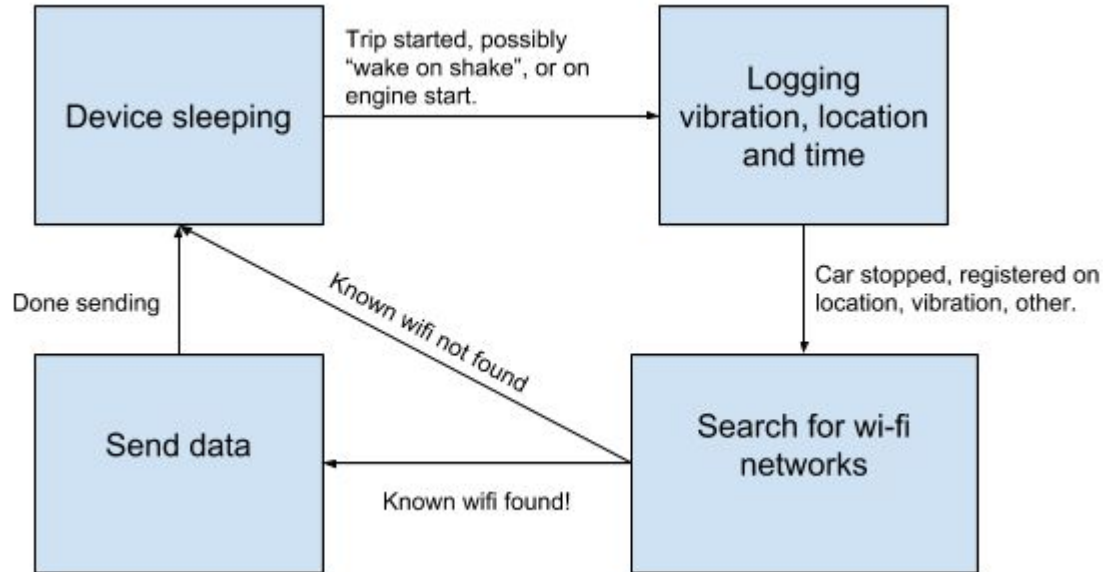
**“Crowdsourcing”:** This is the inspiration for the method, although at first only vehicles from the client organisation will be included.

**Non-reliance on smartphones:** Not optimal due to device loss and interference.

**Low-cost IoT device:** Our goal, in order to maximize scalability and robustness.

**Data transfer once a day, approx:** Real-time data is not necessary for the measurements.

# Approach II



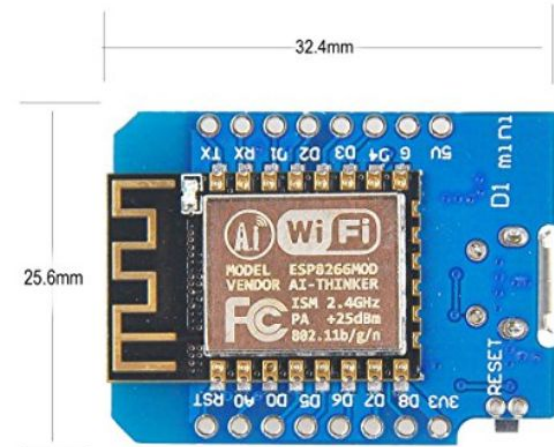
# Technical specifications

[WeMos D1 mini MCU w/WiFi](#) (Arduino-C or Lua-Script)

[WeMos D1 mini shield SD card adapter](#)

GPS Module ([GY-NEO6MV2](#))

Accelerometer+Gyroscope ([6DOF GY-521](#)) 3 axis



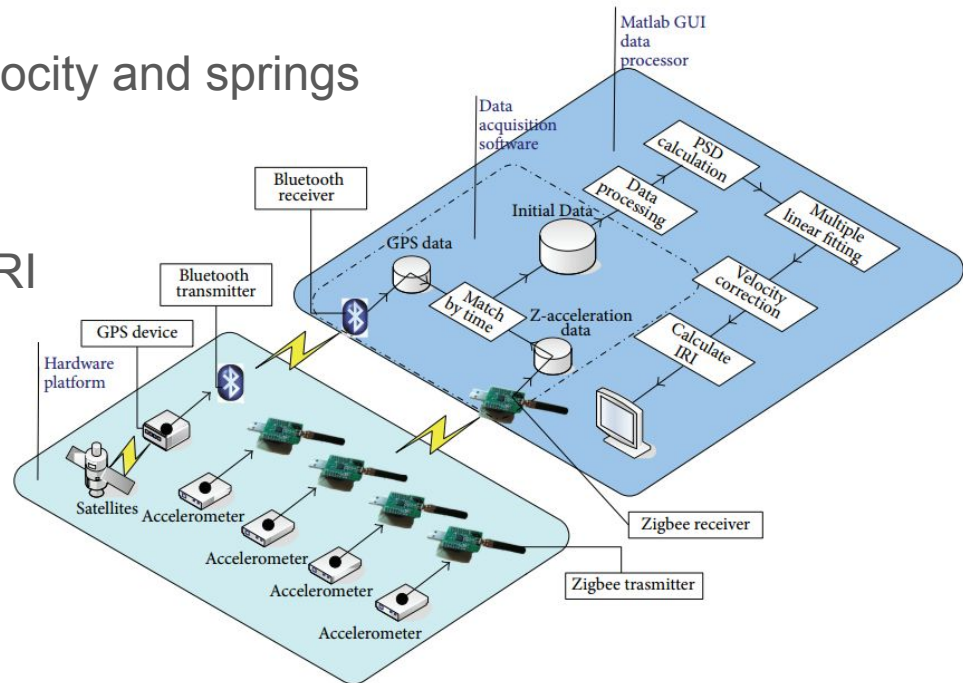


# Related Works

# Related Work I

## Measurement of International Roughness Index by Using Z-Axis Accelerometers and GPS

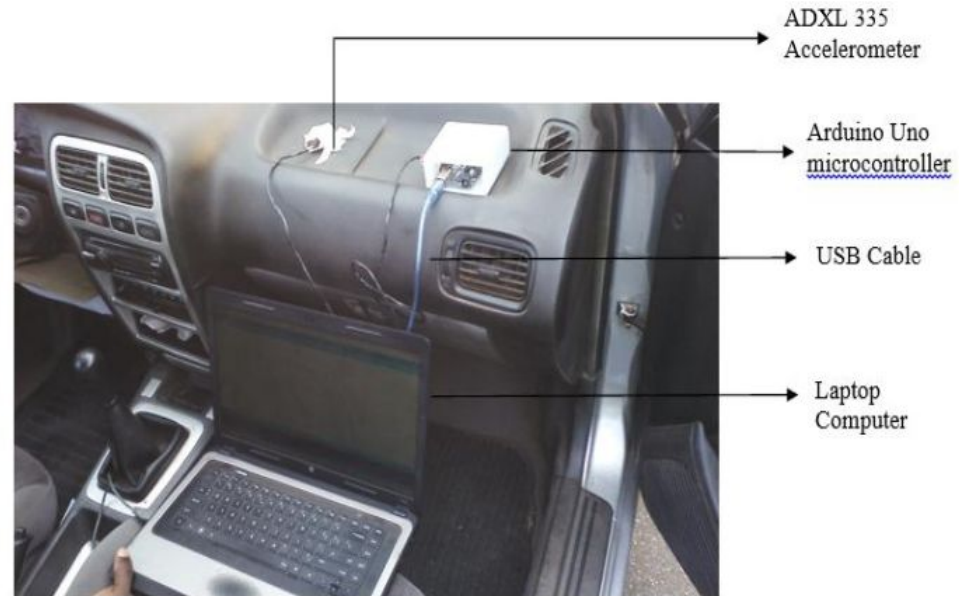
- Heavy calculations of effects of velocity and springs
- Shanghai (urban environment)
- 4 Accelerometers, Z-Axis
- Fairly accurate measurements of IRI
  - Relative error < 15%
- Uses a lot of equipment
  - Expensive
- Only short range wireless transfer



# Related Work II

## Development of a Decision Support System for Road Maintenance Scheduling

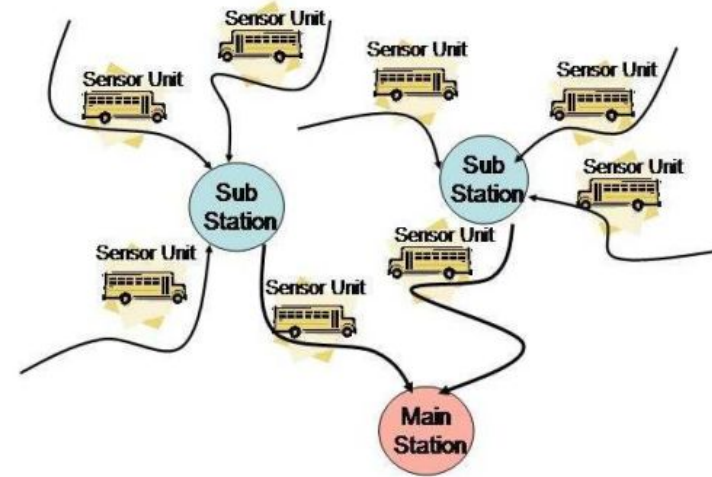
- Usage of Arduino microprocessor and 3-axis accelerometer
- Nigeria, mixed road environment
- No wireless transfer, data is transferred by cable to a computer and processed locally.



# Related Work III

## A public transport system based sensor network for road surface condition monitoring

- Sensor-nodes distributed on buses in Colombo, Sri Lanka, to sense environmental conditions and potentially road roughness.
- Uses “sub-stations” to transfer data from bus to bus until it reaches the main station.
- Has no implementation of road roughness sensing yet, but protocol for data-transfer could be useful.



# Workplan I

Our **preparation** includes clarification on scope and parts, and prototyping.

- **Skype call** with client for scope and requirements clarification [*Completed 19th September*]
- **Order parts** [*Completed 19th September*]
- Start **prototyping** w/ parts [*Completed 26th September*]
- Possible **meeting** with client for clarification or demonstration [*3rd October*]

# Workplan II

Functionality is split into **three iterative prototypes**:

1. Gather GPS and Sensor-data (Deadline October 10th)
2. Transfer data bundle on wifi-connect (Deadline October 31th)
3. Source power from vehicle and casing/installation (Deadline November 14th)

Each of these iterations will also **include general improvements** derived from evaluation of the earlier iteration. Beside these construction deadlines we have **concurrent report-writing** deadlines.