

# Ziran Wang

San Jose, CA | (626) 271-3096  
Email: [ryanwang1@hotmail.com](mailto:ryanwang1@hotmail.com)

Website: <http://ziranw.github.io>  
[Google Scholar Link](#)

## EMPLOYMENT

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<b>Research Scientist</b>	<i>Jul. 2019 - Present</i>
Toyota Motor North America R&D, InfoTech Labs, Mountain View, CA (Supervisor: Dr. Prashant Tiwari)	
<b>Graduate Student Researcher</b>	<i>Jun. 2016 - Jun. 2019</i>
Transportation Systems Research Lab, University of California, Riverside (Advisor: Dr. Matthew Barth)	
<b>Research Intern</b>	<i>Jun. 2018 - Sep. 2018</i>
Toyota InfoTechnology Center, Mountain View, CA (Mentors: Dr. BaekGyu Kim & Dr. Kyungtae Han)	
<b>Graduate Student Researcher</b>	<i>Nov. 2015 - Jun. 2016</i>
Cooperative Vehicle Networks Lab, University of California, Riverside (Advisor: Dr. Wei Ren)	
<b>Summer Intern</b>	<i>Jul. 2014 - Aug. 2014</i>
Changan Suzuki (i.e., Suzuki China), Chongqing, China	

## EDUCATION

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<b>Ph.D. in Mechanical Engineering</b>	<i>Sep. 2015 - Jun. 2019</i>
University of California, Riverside (UCR)	
Advisor: Dr. Matthew J. Barth, Yeager Family Chair Professor, Electrical and Computer Engineering	
Dissertation: Developing Agent-Based Distributed Cooperative Vehicle-Infrastructure Systems in the Connected and Automated Vehicle Environment	
<b>B.E. in Mechanical Engineering and Automation</b>	<i>Sep. 2011 - Jun. 2015</i>
College of Automation	
Beijing University of Posts and Telecommunications (BUPT)	

## FUNDED PROJECTS

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### Evaluating Connected Vehicle Applications in a Mixed Traffic Environment using a “Digital Twin” Approach

- Sponsor: Toyota Motor North America
- Partner: University of California, Riverside
- Total fund: \$210,000
- Period: *Oct. 2018 - Present*

### Personalized Driving Assistance for Connected and Automated Vehicles

- Sponsor: Toyota Motor North America
- Partner: University of Virginia
- Total fund: \$230,000
- Period: *Oct. 2018 - Present*

### Traffic Optimization for Signalized Corridors (TOSCo) Small Scale Test & Evaluation Project

- Sponsor: Federal Highway Administration (FHWA), United States Department of Transportation
- Partners: Crash Avoidance Metrics Partners (CAMP) LLC Vehicle to Infrastructure Consortium (Ford, General Motors, Hyundai-Kia, Honda, Mazda, Nissan, Subaru, Volvo Truck, and VW/Audi), IAV GmbH, Texas A&M Transportation Institute (TTI), and The University of Michigan Transportation Institute (UMTRI)
- Total fund: \$757,809
- Period: *Apr. 2015 - Jun. 2019*

### An Innovative Vehicle-Powertrain Eco-Operation System for Efficient Plug-In Hybrid Electric Buses

- Sponsor: Advanced Research Projects Agency-Energy (ARPA-E), United States Department of Energy
- Partners: Oak Ridge National Laboratory, US Hybrid
- Total fund: \$2,799,999
- Period: *Mar. 2017 - Oct. 2020*

## Connected Eco-Driving for Heavy-Duty Conventional and Plug-In Hybrid Electric Trucks

- Sponsor: California Air Resources Board, SCAQMD
- Partners: Volvo Group North America
- Total fund: \$400,000
- Period: Sep. 2017 - Mar. 2019

## Development of Eco-Friendly Ramp Control based on Connected and Automated Vehicle Technology

- Sponsor: National Center for Sustainable Transportation (NCST), United States Department of Transportation
- Total fund: \$ 78,355
- Period: Oct. 2018 - Sep. 2019

## REFEREED PUBLICATIONS

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### Under Review

#### [J32] Digital Twin-Assisted Cooperative Driving at Non-Signalized Intersections

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- *IEEE Transactions on Intelligent Vehicles*, under review

#### [J31] Vision-Cloud Data Fusion for ADAS: A Lane Change Prediction Case Study

- Yongkang Liu, [Ziran Wang](#), Kyungtae Han, Zhenyu Shou, Prashant Tiwari, and John H. L. Hansen
- *IEEE Transactions on Intelligent Vehicles*, under review

#### [J30] Game Theory-Based Ramp Merging for Mixed Traffic with Unity-SUMO Integrated Simulation

- Xishun Liao, Xuanpeng Zhao, [Ziran Wang](#), Kyungtae Han, Prashant Tiwari, Matthew J. Barth, and Guoyuan Wu
- *IEEE Transactions on Systems, Man, and Cybernetics: Systems*, under review

### Journal Publications

#### [J29] Cooperative Ramp Merging Design and Field Implementation: A Digital Twin Approach based on Vehicle-to-Cloud Communication

- Xishun Liao, [Ziran Wang](#), Xuanpeng Zhao, Kyungtae Han, Prashant Tiwari, Matthew J. Barth, and Guoyuan Wu
- *IEEE Transactions on Intelligent Transportation Systems*, accepted

#### [J28] Eco-Approach and Departure along Signalized Corridors

- Guoyuan Wu, Peng Hao, [Ziran Wang](#), Yu Jiang, Kanok Boriboonsomsin, Matthew J. Barth, Michael McConnell, Shuwei Qiang, and John Stark
- *SAE International Journal of Sustainable Transportation, Energy, Environment, & Policy*, accepted

#### [J27] Driver Behavior Modeling using Game Engine: A Learning-Based Approach

- [Ziran Wang](#), Xishun Liao, Chao Wang, David Oswald, Guoyuan Wu, Kanok Boriboonsomsin, Matthew J. Barth, Kyungtae Han, BaekGyu Kim, and Prashant Tiwari
- *IEEE Transactions on Intelligent Vehicles*, vol. 5, no. 4, Dec. 2020, pp. 738–749

#### [J26] Cooperative Eco-Driving along Multiple Signalized Intersections in a Partially Connected and Automated Vehicle Environment

- [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *IEEE Transactions on Intelligent Transportation Systems*, vol.21, no.5, May 2020, pp. 2029–2038

#### [J25] A Survey on Cooperative Longitudinal Motion Control of Multiple Connected Automated Vehicles

- [Ziran Wang](#), Yougang Bian, Steven E. Shladover, Guoyuan Wu, Shengbo E. Li, and Matthew J. Barth
- *IEEE Intelligent Transportation Systems Magazine*, vol. 12, no. 1, Spring 2020, pp. 4–25

#### [J24] Cooperative Ramp Merging System: Agent-Based Modeling and Simulation Using Game Engine (**Best Paper Award**)

- [Ziran Wang](#), Guoyuan Wu, Kanok Boriboonsomsin, Matthew J. Barth, Kyungtae Han, BaekGyu Kim, and Prashant Tiwari
- *SAE International Journal of Connected and Automated Vehicles*, vol.2, no.2, May 2019, pp. 115–128

[J23]Cluster-Wise Cooperative Eco-Approach and Departure Application for Connected and Automated Vehicles along Signalized Arterials

- [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *IEEE Transactions on Intelligent Vehicles*, vol. 3, no. 4, Dec. 2018, pp. 404–413

[J22]Developing a Distributed Consensus-Based Cooperative Adaptive Cruise Control (CACC) System for Heterogeneous Vehicles with Predecessor Following Topology

- [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *Journal of Advanced Transportation*, vol. 2017, Article ID 1023654, Aug. 2017

### **Conference Proceedings**

[C21]Trust-Based Route Planning for Autonomous Vehicles

- Shili Sheng, Erfan Pakdamanian, Kyungtae Han, [Ziran Wang](#), John Lenneman and Lu Feng
- *12<sup>th</sup> ACM/IEEE International Conference on Cyber-Physical Systems (ICCPs)*, May 2021

[C20]Motion Estimation of Connected and Automated Vehicles under Communication Delay and Packet Loss of V2X Communications

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- *SAE World Congress Experience 2021*, Virtual Conference, Apr. 2021

[C19]A Game Theory Based Ramp Merging Strategy for Connected and Automated Vehicles in the Mixed Traffic: A Unity-SUMO Integrated Platform

- Xishun Liao, Xuanpeng Zhao, Guoyuan Wu, Matthew J. Barth, [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- *Transportation Research Board 100<sup>th</sup> Annual Meeting*, Virtual Conference, Jan. 2021

[C18]Augmented Reality-Based Advanced Driver-Assistance System for Connected Vehicles

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- *2020 IEEE International Conference on Systems, Man, and Cybernetics (SMC 2020)*, Virtual Conference, Oct. 2020

[C17]Long-Term Prediction of Lane Change Maneuver through a Multilayer Perceptron

- Zhenyu Shou, [Ziran Wang](#), Kyungtae Han, Yongkang Liu, Prashant Tiwari, and Xuan Di
- *2020 IEEE Intelligent Vehicles Symposium*, Virtual Conference, Oct. 2020

[C16]Sensor Fusion of Camera and Cloud Digital Twin Information for Intelligent Vehicles

- Yongkang Liu, [Ziran Wang](#), Kyungtae Han, Zhenyu Shou, Prashant Tiwari, and John H. L. Hansen
- *2020 IEEE Intelligent Vehicles Symposium*, Virtual Conference, Oct. 2020

[C15]Optimal Control-Based Eco-Ramp Merging System

- Zhouqiao Zhao, Guoyuan Wu, [Ziran Wang](#), and Matthew J. Barth
- *2020 IEEE Intelligent Vehicles Symposium*, Virtual Conference, Oct. 2020

[C14]A Digital Twin Paradigm: Vehicle-to-Cloud Based Advanced Driver Assistance Systems

- [Ziran Wang](#), Xishun Liao, Xuanpeng Zhao, Kyungtae Han, Prashant Tiwari, Matthew J. Barth, and Guoyuan Wu
- *IEEE 91<sup>st</sup> Vehicular Technology Conference (VTC2020-Spring)*, Virtual Conference, May 2020

[C13]Cooperative Ramp Merging with Vehicle-to-Cloud Communications: A Field Experiment

- Xishun Liao, David Oswald, [Ziran Wang](#), Guoyuan Wu, Kanok Boriboonsomsin, Matthew J. Barth, Kyungtae Han, BaekGyu Kim, and Prashant Tiwari
- *Transportation Research Board 99<sup>th</sup> Annual Meeting*, Washington D.C., Jan. 2020

[C12]End-to-End Vision-Based Adaptive Cruise Control (ACC) Using Deep Reinforcement Learning

- Zhensong Wei, Yu Jiang, Xishun Liao, Xuwei Qi, [Ziran Wang](#), Guoyuan Wu, Peng Hao, and Matthew J. Barth,
- *Transportation Research Board 99<sup>th</sup> Annual Meeting*, Washington D.C., Jan. 2020

**[C11]Early Findings from Field Trials of Heavy-Duty Truck Connected Eco-Driving System**

- [Ziran Wang](#), Yuan-Pu Hsu, Alexander Vu, Francisco Caballero, Peng Hao, Guoyuan Wu, Kanok Boriboonsomsin, Matthew J. Barth, Aravind Kailas, Pascal Amar, Eddie Garmon, and Sandeep Tanugula
- *IEEE 22<sup>nd</sup> International Conference on Intelligent Transportation Systems*, Auckland, New Zealand, Oct. 2019

**[C10]The State-of-the-Art of Coordinated Ramp Control with Mixed Traffic Conditions**

- Zhouqiao Zhao, [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *IEEE 22<sup>nd</sup> International Conference on Intelligent Transportation Systems*, Auckland, New Zealand, Oct. 2019

**[C9]Lookup Table-Based Consensus Algorithm for Real-Time Longitudinal Motion Control of Connected and Automated Vehicles**

- [Ziran Wang](#), Kyungtae Han, BaekGyu Kim, Guoyuan Wu, and Matthew J. Barth
- *2019 American Control Conference*, Philadelphia, PA, Jul. 2019

**[C8]Agent-Based Modeling and Simulation of Connected and Automated Vehicles Using Game Engine: A Cooperative On-Ramp Merging Study**

- [Ziran Wang](#), BaekGyu Kim, Hiromitsu Kobayashi, Guoyuan Wu, and Matthew J. Barth
- *Transportation Research Board 98<sup>th</sup> Annual Meeting*, Washington D.C., Jan. 2019

**[C7]Eco-Approach and Departure along Signalized Corridors**

- Guoyuan Wu, Peng Hao, [Ziran Wang](#), Kanok Boriboonsomsin, and Matthew J. Barth
- *Transportation Research Board 98<sup>th</sup> Annual Meeting*, Washington D.C., Jan. 2019

**[C6]A Review on Cooperative Adaptive Cruise Control (CACC) Systems: Architectures, Controls, and Applications**

- [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *IEEE 21<sup>st</sup> International Conference on Intelligent Transportation Systems*, Maui, Hawaii, Nov. 2018

**[C5]Distributed Consensus-Based Cooperative Highway On-Ramp Merging Using V2X Communications**

- [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *SAE Technical Paper*, 2018-01-1177, Apr. 2018

**[C4]Cluster-Wise Cooperative Eco-Approach and Departure Application along Signalized Arterials**

- [Ziran Wang](#), Guoyuan Wu, Peng Hao, and Matthew J. Barth
- *IEEE 20<sup>th</sup> International Conference on Intelligent Transportation Systems*, Yokohama, Japan, Oct. 2017

**[C3]Intra-Platoon Vehicle Sequence Optimization for Eco-Cooperative Adaptive Cruise Control**

- Peng Hao, [Ziran Wang](#), Guoyuan Wu, Kanok Boriboonsomsin, and Matthew J. Barth
- *IEEE 20<sup>th</sup> International Conference on Intelligent Transportation Systems*, Yokohama, Japan, Oct. 2017

**[C2]Developing a Platoon-Wide Eco-Cooperative Adaptive Cruise Control (CACC) System**

- [Ziran Wang](#), Guoyuan Wu, Peng Hao, Kanok Boriboonsomsin, and Matthew J. Barth
- *2017 IEEE Intelligent Vehicles Symposium*, Redondo Beach, CA, Jun. 2017

**[C1]Developing a Distributed Consensus-Based Cooperative Adaptive Cruise Control (CACC) System**

- [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *Transportation Research Board 96<sup>th</sup> Annual Meeting*, Washington D.C., Jan. 2017

## OTHER PUBLICATIONS

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### **Book Chapters**

**[B3]New Simulation Tools for Training and Testing Automated Vehicles**

- Jiaqi Ma, Chris Schwarz, [Ziran Wang](#), Maria Elli, German Ros, and Yiheng Feng
- *Road Vehicles Automation*, vol. 7, pp. 111 – 119, Springer

## **Technical Reports**

### **[R2]**Development of Eco-Friendly Ramp Control for Connected and Automated Electric Vehicles

- Guoyuan Wu, Zhouqiao Zhao, [Ziran Wang](#), and Matthew J. Barth
- *National Center for Sustainable Transportation, U.S. Department of Transportation*, NCST-UCR-RR-20-04, Jan. 2020

### **[R1]**MOVESTAR: An Open-Source Vehicle Fuel and Emission Model based on USEPA MOVES

- [Ziran Wang](#), Guoyuan Wu, and George Scora
- *arXiv Preprint arXiv: 2008.04986*, URL: <https://github.com/ziranw/MOVESTAR-Fuel-and-Emission-Model>, Aug. 2020

## **PATENTS**

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### **[P18]**System and Method for Scheduling Connected Vehicles to Cross Non-Signalized Intersections

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- U.S. patent application, Filed Feb. 2021

### **[P17]**Rural Driving Digital Safety Guard Rails

- Rohit Gupta, [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- U.S. patent application, Filed Feb. 2021

### **[P16]**Personalized Time Gap Setting for Adaptive Cruise Control

- Kyungtae Han, [Ziran Wang](#), Prashant Tiwari, John Lenneman, Chase Violetta, Miles Johnson, and Toshinori Esaka
- U.S. patent application, Filed Feb. 2021

### **[P15]**Motion Estimation of Connected and Automated Vehicles under Communication Delay and Packet Loss of V2X Communications

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- U.S. patent application, Filed Feb. 2021

### **[P14]**Cooperative Driving Systems and Method

- Sergei Avedisov, [Ziran Wang](#), Ahmed Sakr, Kyungtae Han, Rui Guo, and Onur Altintas
- U.S. patent application, Filed Feb. 2021

### **[P13]**Producing, for an Autonomous Vehicle, a Route from an Origination to a Destination

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- U.S. patent application 63/111142, Filed Nov. 2020

### **[P12]**System and Method for Connected Vehicle Lane Merge

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/031095, Filed Sep. 2020

### **[P11]**System and Methods for Providing Guidance to Vehicle Drivers Regarding Predicted Lane-Change Behavior of Vehicle Drivers

- Zhenyu Shou, Kyungtae Han, [Ziran Wang](#), Yongkang Liu, and Prashant Tiwari
- U.S. patent application 16/999332, Filed Aug. 2020

### **[P10]**Rest Stop Recommendation System

- Zhenyu Shou, [Ziran Wang](#), Kyungtae Han, Yongkang Liu, and Prashant Tiwari
- U.S. patent application 16/998529, Filed Aug. 2020

### **[P9]**Identifying a Specific Object in a Two-Dimensional Image of Objects

- Yongkang Liu, [Ziran Wang](#), Kyungtae Han, Zhenyu Shou, and Prashant Tiwari
- U.S. patent application 16/927467, Filed Jul. 2020

### **[P8]**Systems and Methods for Long-Term Prediction of Lane Change Maneuver

- Zhenyu Shou, [Ziran Wang](#), Kyungtae Han, Yongkang Liu, and Prashant Tiwari
- U.S. patent application 16/897386, Filed Jun. 2020

#### [P7]Ramp Merging Assistance

- Ziran Wang, Kyungtae Han, and Prashant Tiwari
- U.S. patent application 16/781211, Filed Feb. 2020

#### [P6]Systems and Methods for Compensating for Driver Speed-Tracking Error

- Ziran Wang, Kyungtae Han, and Prashant Tiwari
- U.S. patent application 16/775772, Filed Jan. 2020

#### [P5]Longitudinal Motion Control of Connected and Automated Vehicles

- Ziran Wang, Hiromitsu Kobayashi, Kyungtae Han, and BaekGyu Kim
- U.S. patent application 16/364851, Filed May 2019, Published Nov. 2020

#### [P4]Adjustable Blind Spot Monitor

- Ziran Wang, Kyungtae Han, and BaekGyu Kim
- U.S. patent application 16/364851, Filed Mar. 2019, Published Oct. 2020

#### [P3]Vehicle-to-Everything Communication-Based Lane Change Collision Avoidance Warning

- Ziran Wang, Kyungtae Han, and BaekGyu Kim
- U.S. patent application 16/295700, Filed Mar. 2019, Published Sep. 2020

#### [P2]Virtualized Driver Assistance

- Ziran Wang, BaekGyu Kim, and Hiromitsu Kobayashi
- U.S. patent application 16/268729, Filed Feb. 2019, Published Aug. 2020

#### [P1]XR-based Slot Reservation System For Connected Vehicles Traveling Through Intersections

- Ziran Wang, Kyungtae Han, and BaekGyu Kim
- U.S. patent application 16/264475, Filed Jan. 2019, Published Aug. 2020

## PROFESSIONAL ACTIVITIES

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### As an Editor

Associate editor of <i>IEEE Intelligent Vehicles Symposium (IV)</i>	Nov. 2020 - Present
Associate editor of <i>SAE International Journal of Connected and Automated Vehicles</i>	Jun. 2020 - Present
Associate editor of <i>IEEE International Conference on Intelligent Transportation Systems (ITSC)</i>	Feb. 2020 - Present

### As a Member

Member of SAE On Road Automated Driving (ORAD) Simulation Task Force	Nov. 2020 - Present
Member of Technical Committee on Industrial CPS, IEEE Industrial Electronics Society	Jul. 2020 - Present
Member of Technical Committee on Smart Cities, IEEE Control Systems Society	Jun. 2020 - Present
Member of Society of Automotive Engineers	Jan. 2018 - Present
Member of Southern California Chinese-American Environmental Protection Association (SCCAEPA)	Feb. 2017 - Present
Member of International Chinese Transportation Professionals Association (ICTPA)	Feb. 2017 - Present
Member of Chinese Overseas Transportation Association (COTA)	Jan. 2017 - Present
Friend of Transportation Research Board (TRB) Standing Committee: Vehicle-Highway Automation	Jan. 2017 - Present
Member of Institute of Electrical and Electronics Engineers	Sep. 2016 - Present

### As an Organizer

Chair of 2020 <i>IEEE Intelligent Vehicles Symposium (IV)</i> , Internet of Things in Intelligent Transportation Systems: Opportunities and Challenges Workshop, Virtual	Oct. 2020
Chair of 23 <sup>rd</sup> IEEE International Conference on Intelligent Transportation Systems (ITSC), Testing and Evaluation Connected and Automated Vehicles Using Emerging Simulation Technologies Workshop, Virtual	Sep. 2020
Co-Chair of 4 <sup>th</sup> IEEE Conference on Control Technology and Applications (CCTA), Automotive Control Invited Sessions, Virtual	Aug. 2020

### **As a Reviewer**

Reviewer of <i>IEEE Transactions on Systems, Man and Cybernetics: Systems</i>	Jan. 2021 - Present
Reviewer of <i>Automatica</i>	Dec. 2020 - Present
Reviewer of <i>IEEE Transactions on Control Systems Technology</i>	Dec. 2020 - Present
Reviewer of <i>Journal of Traffic and Transportation Engineering</i>	Nov. 2020 - Present
Reviewer of <i>IEEE Vehicular Technology Magazine</i>	Nov. 2020 - Present
Reviewer of <i>Transportation Research Part D: Transport and Environment</i>	Nov. 2020 - Present
Reviewer of <i>Information Sciences</i>	Oct. 2020 - Present
Reviewer of <i>Journal of Selected Topics in Signal Processing</i>	Sep. 2020 - Present
Reviewer of <i>Serbian Journal of Electrical Engineering</i>	Aug. 2020 - Present
Reviewer of <i>IEEE Transactions on Control of Network Systems</i>	Jul. 2020 - Present
Reviewer of <i>MDPI Multimodal Technologies and Interaction</i>	May 2020 - Present
Reviewer of <i>MDPI Applied Science</i>	May 2020 - Present
Reviewer of <i>IEEE Forum on Integrated and Sustainable Transportation Systems</i>	Mar. 2020 - Present
Reviewer of <i>International Journal of Automotive Technology</i>	Feb. 2020 - Present
Reviewer of <i>International Journal of Automotive Technology</i>	Feb. 2020 - Present
Reviewer of <i>MDPI Sensors</i>	Feb. 2020 - Present
Reviewer of <i>Journal of Intelligent Transportation Systems</i>	Jan. 2020 - Present
Reviewer of <i>International Journal of Transportation Science and Technology</i>	Jan. 2020 - Present
Reviewer of <i>MDPI Information</i>	Jan. 2020 - Present
Reviewer of <i>IEEE Open Journal of Intelligent Transportation Systems</i>	Dec. 2019 - Present
Reviewer of <i>IEEE Vehicular Technology Conference</i>	Nov. 2019 - Present
Reviewer of <i>MDPI Vehicles</i>	Nov. 2019 - Present
Reviewer of <i>IEEE Transactions on Intelligent Vehicles</i>	Oct. 2019 - Present
Reviewer of <i>IEEE Access</i>	Aug. 2019 - Present
Reviewer of <i>Journal of Control, Automation and Electric Systems</i>	Apr. 2019 - Present
Reviewer of <i>IEEE Conference on Control Technology and Applications</i>	Mar. 2019 - Present
Reviewer of <i>SAE International Journal of Connected and Automated Vehicles</i>	Oct. 2018 - Present
Reviewer of <i>American Control Conference (ACC)</i>	Oct. 2018 - Present
Reviewer of <i>Transportation Research Record (TRR)</i>	Aug. 2018 - Present
Reviewer of <i>International Conference on Computer Science and Application Engineering (CSAE)</i>	Aug. 2018 - Present
Reviewer of <i>Journal of Advanced Transportation</i>	Jul. 2018 - Present
Reviewer of <i>IEEE International Conference on Intelligent Transportation Systems (ITSC)</i>	May 2018 - Present
Reviewer of <i>Case Studies on Transport Policies (CSTP)</i>	May 2018 - Present
Reviewer of <i>IEEE Intelligent Vehicles Symposium</i>	Mar. 2018 - Present
Reviewer of <i>IET Intelligent Transport Systems</i>	Jan. 2018 - Present
Reviewer of <i>ASCE International Conference on Transportation &amp; Development (ICTD)</i>	Dec. 2017 - Present
Reviewer of <i>SAE Technical Papers</i>	Oct. 2017 - Present
Reviewer of <i>TRB Annual Meeting</i>	Sep. 2017 - Present
Reviewer of <i>IEEE Transactions on Intelligent Transportation Systems</i>	Jun. 2017 - Present
Reviewer of <i>COTA International Conference of Transportation Professionals (CICTP)</i>	Feb. 2017 - Present

### **As a Volunteer**

Organizer of 2018 <i>IEEE 21<sup>st</sup> ITSC</i> , Maui, HI	Nov. 2018
Onsite support of Humanplus Intelligent Robotics Technology Co., Ltd. on CES 2018, Las Vegas, NV	Jan. 2018
Organizer of Chinese Institute of Engineers (CIE) So-Cal Chapter Annual Convention, Rowland Heights, CA	Sep. 2017
Organizer of 2017 <i>IEEE IV Symposium</i> , Redondo Beach, CA	Jun. 2017
Onsite support of UISEE Technology Co., Ltd. on CES 2017, Las Vegas, NV	Jan. 2017



## TEACHING EXPERIENCE

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### **Intelligent Transportation Systems (UCR EE 246)**

Oct. 2018

- Conducted 2 hours of lecture independently as a rotating lecturer of the course
- Introduced car-following models, cooperative adaptive cruise control, and simulation tools

### **Feedback Control (UCR ME 121)**

Mar. 2017 - Jun. 2017

- Conducted 20 hours of discussion sessions independently as a teaching assistant of the course
- Introduced the analysis and design of feedback control systems using classical control methods, including block diagrams, closed-loop stability, root locus, Bode plots, and etc.

### **Mechanical Engineering Modeling and Analysis (UCR ME 118)**

Jan. 2017 - Mar. 2017

- Conducted 20 hours of discussion sessions independently as a teaching assistant of the course
- Introduced data analysis and modeling used in engineering through MATLAB, including descriptive and inferential statistics, fitting linear and nonlinear models to observed data, numerical differentiation and integration, etc.

### **Introduction to Engineering Computation (UCR ME 018)**

Sep. 2016 - Dec. 2016

- Conducted 60 hours of lab sessions independently as a teaching assistant of the course
- Introduced the use of MATLAB in engineering computation, including scripts and functions, programming, input/output, two and three-dimensional graphics, elementary numerical analysis, etc.

## MENTORED STUDENTS

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### **Mentored at Toyota**

- Yanbing Wang, *now*: 2021 spring co-op @Toyota, Ph.D. student in Civil Engineering @Vanderbilt
- Jianyu Su, *now*: 2021 spring co-op @Toyota, Ph.D. candidate in System Engineering @UVA
- Zhenyu Shou, *then*: 2020 winter co-op @Toyota, *now*: Ph.D. student in Civil Engineering @Columbia
- Yongkang Liu, *then*: 2020 winter co-op @Toyota, Ph.D. student in EE @UT Dallas, *now*: Research Scientist @Toyota
- Xianguo Liu, *then*: 2019 summer co-op @Toyota, *now*: Ph.D. student in ECE @Northwestern

### **Mentored at UCR**

- Xishun Liao, *then*: M.S. student in ME @Maryland & summer research intern @UCR, *now*: Ph.D. student in ECE @UCR
- Yuan-Pu Hsu, *then*: M.S. student in ECE @UCR, *now*: Software Engineer @Microsoft
- Xuanpeng Zhao, *then*: B.S. & M.S. student in ECE @UCR, *now*: Ph.D. student in ECE @UCR
- Yu Jiang, *then*: B.S. & M.S. student in ECE @UCR, *now*: M.S. student in ECE @UCR
- Pingbo Ruan, *then*: B.S. & M.S. student in ECE @UCR, *now*: M.S. student in ECE @UCR
- Shangrui Liu, *then*: B.S. & M.S. student in ECE @UCR, *now*: M.S. student in ECE @UCR
- Hangquan Zhao, *then*: B.S. student in ECE @UCR, *now*: M.S. student in ECE @UCSD
- Yue You, *then*: B.S. student in ECE @UCR, *now*: M.S. student in ECE @UCR
- Yu Wang, *then*: M.S. student in ME @UCR

## INVITED TALKS

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### **A Digital Twin Paradigm: Vehicle-to-Cloud Based Advanced Driver Assistance Systems**

- 23<sup>rd</sup> COTA Annual Winter Symposium, Washington D.C., Jan. 2020

### **Unity3D-Based AV Simulation with V2X Communication and Human-in-the-Loop Integration**

- Automated Vehicles Symposium, Orlando, FL, Jul. 2019

### **Agent-Based Modeling and Simulation of Connected and Automated Vehicles Using Game Engine**

- Transportation Research Board (TRB) 98<sup>th</sup> Annual Meeting, Washington, D.C., Jan. 2019

### **Eco-Friendly Applications in Connected and Automated Vehicle Technology**

- University of California, Riverside CE-CERT Open House, Riverside, CA, Oct. 2018



## **Connected Eco-Bus: An Innovative Vehicle Powertrain Eco-Operation System for Efficient Plug-In Hybrid Electric Buses**

- ARPA-E NEXTCAR 2018 Annual Meeting, Southfield, MI, Apr. 2018

## **Distributed Consensus-Based Cooperative Highway On-Ramp Merging Using V2X Communications**

- WCX: SAE World Congress Experience, Detroit, MI, Apr. 2018

## **Connected and Automated Vehicle Research at UCR**

- University of California, Riverside Extension, Riverside, CA, Jan. 2018

## **Developing a Platoon-Wide Eco-Cooperative Adaptive Cruise Control (CACC) System**

- Los Angeles Environmental Forum, San Gabriel, CA, Aug. 2017

## **Distributed Consensus-Based Cooperative Adaptive Cruise Control (CACC) Systems**

- TuSimple Technology Co., Ltd., San Diego, CA, Jul. 2017

## **HONORS & AWARDS**

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Vincent Bendix Automotive Electronics Engineering Award (i.e., best paper in 2019), SAE International	<i>Feb. 2020</i>
U.S. Department of Transportation National Center for Sustainable Transportation (NCST) Dissertation Award	<i>Jun. 2018</i>
Best Student Research Paper Award, Los Angeles Environmental Forum	<i>Aug. 2017</i>
UCR Dean's Distinguished Fellowship Award	<i>Fall 2015 - Spring 2017</i>
BUPT Scholarship Award	<i>Jun. 2014 &amp; Jun. 2013</i>
The Honorable Mention, The Mathematical Contest in Modeling (MCM)	<i>Feb. 2014</i>

## **MEDIA EXPOSURES**

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**NCST Partner CE-CERT Takes Eco-Driving Simulator to CES**, National Center for Sustainable Transportation, *Jan. 2020*

**Testing a Connected Eco-Driving System in Field Trials with Heavy-Duty Trucks**, Featured News, Tech Xplore, *Aug. 2019*

**Steering into the Future of Connected and Automated Vehicles**, UCR News, *Jul. 2019*

## **PROFESSIONAL REFERENCES**

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### **Matthew J. Barth**

- Yeager Family Chair Professor
- Electrical and Computer Engineering
- University of California, Riverside
- Email: [barth@ece.ucr.edu](mailto:barth@ece.ucr.edu)

### **Guoyuan Wu**

- Associate Adjunct Professor
- Electrical and Computer Engineering
- University of California, Riverside
- Email: [gywu@cert.ucr.edu](mailto:gywu@cert.ucr.edu)

### **Andreas A. Malikopoulos**

- Terri Connor Kelly and John Kelly Career Development Associate Professor
- Mechanical Engineering
- University of Delaware
- Email: [andreas@udel.edu](mailto:andreas@udel.edu)

**Elisa Franco**

- Associate Professor
- Mechanical Engineering
- University of California, Los Angeles
- Email: [efranco@seas.ucla.edu](mailto:efranco@seas.ucla.edu)

**Jiaqi Ma**

- Associate Professor
- Civil and Environmental Engineering
- University of California, Los Angeles
- Email: [jiaqima@ucla.edu](mailto:jiaqima@ucla.edu)

**Yiheng Feng**

- Assistant Professor
- Civil Engineering
- Purdue University
- Email: [feng333@purdue.edu](mailto:feng333@purdue.edu)

**Li Li**

- Associate Professor
- Department of Automation
- Tsinghua University
- Email: [li-li@mail.tsinghua.edu.cn](mailto:li-li@mail.tsinghua.edu.cn)

**Meng Wang**

- Assistant Professor
- Department of Transport & Planning
- Delft University of Technology
- Email: [m.wang@tudelft.nl](mailto:m.wang@tudelft.nl)