

# Ziran Wang

Ph.D. in Mechanical Engineering

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## EDUCATION

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### Ph.D. in Mechanical Engineering

Sep. 2015 - Jun. 2019

University of California, Riverside (UCR)

Advisor: Dr. Matthew J. Barth, Professor, Electrical and Computer Engineering

Dissertation: Developing Agent-Based Distributed Cooperative Vehicle-Infrastructure Systems in the Connected and Automated Vehicle Environment

### B.E. in Mechanical Engineering and Automation

Sep. 2011 - Jun. 2015

Beijing University of Posts and Telecommunications (BUPT)

## PROFESSIONAL EXPERIENCE

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### Research Scientist

Jul. 2019 - Present

Toyota Motor North America, InfoTech Labs, Mountain View, CA

- Involve in the "Digital Twin" project, building an AI-based vehicle-to-cloud platform for cooperative automation and driver behavior modeling of intelligent vehicles

### Graduate Student Researcher

Jun. 2016 - Jun. 2019

Transportation Systems Research Lab, Center for Environmental Research and Technology, UCR

- Developed multiple cooperative automated driving systems in vehicle-to-everything (V2X) environment, including vehicle platooning, cooperative adaptive cruise control (CACC), cooperative eco-approach and departure at signalized intersections, cooperative on-ramp merging, and cooperative lane change
- Proposed distributed consensus-based and optimal control-based motion control algorithms for connected and automated vehicles, addressing issues of safety, mobility, and eco-friendly
- Implemented proposed systems in MATLAB/Simulink, PTV VISSIM (microscopic traffic simulator) driver model API (C++-based), SUMO (microscopic traffic simulator) TraCI API (Python-based), Unity (game engine) scripting API (C#-based), Volvo Truck's on-board .NET framework (C#-based), and Autonomie (vehicle system simulator)

### Research Intern

Jun. 2018 - Sep. 2018

Toyota InfoTechnology Center, Mountain View, CA

- Prototyped cooperative automated driving algorithms using game engine Unity with C# scripting API, allowing them to track trajectory with controlled speed, sense neighboring vehicles and obstacles by on-board sensors, and communicate with each other and infrastructures with V2X communications
- Conducted agent-based modeling and simulation of the proposed cooperative on-ramp merging system, and compared the proposed autonomous system with human-in-the-loop simulations
- Submitted two conference papers and four U.S. patent applications during the 3-month internship

### Graduate Student Researcher

Nov. 2015 - Jun. 2016

Cooperative Vehicle Networks Lab, Department of Electrical and Computer Engineering, UCR

- Implemented distributed consensus algorithm on different information flow topologies by using MATLAB/Simulink
- Researched platoon-based vehicular systems and proposed to apply flocking algorithm to intelligent transportation systems

### Summer Intern

Jul. 2014 - Aug. 2014

Changan Suzuki Co., Ltd., Chongqing, China

- Conducted routine maintenance including testing the machines of the PBS manufacturing monitor system, analyzing the batteries condition of the Yaskawa manipulators, and lubricating the conveyor chains of the YN5 production line
- Analyzed the PLC programs designed by FANUC to control the motion of the welding robots

## PUBLICATIONS

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### Book Chapters

#### [B1] New Simulation Tools for Training and Testing Automated Vehicles

- Jiaqi Ma, Chris Schwarz, [Ziran Wang](#), Maria Elli, German Ros, and Yiheng Feng
- *Road Vehicles Automation*, vol. 7, pp. 111 – 119, Springer

### Journal Papers

#### [J6] Driver Behavior Modeling using Game Engine: A Learning-Based Approach

- [Ziran Wang](#), Xishun Liao, Chao Wang, David Oswald, Guoyuan Wu, Kanok Boriboonsomsin, Matthew J. Barth, Kyungtae Han, BaekGyu Kim, and Prashant Tiwari
- *IEEE Transactions on Intelligent Vehicles*, DOI: 10.1109/TIV.2020.2991948

#### [J5] Cooperative Eco-Driving along Multiple Signalized Intersections in a Partially Connected and Automated Vehicle Environment

- [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *IEEE Transactions on Intelligent Transportation Systems*, vol.21, no.5, May 2020, pp. 2029–2038

#### [J4] A Survey on Cooperative Longitudinal Motion Control of Multiple Connected Automated Vehicles

- [Ziran Wang](#), Yougang Bian, Steven E. Shladover, Guoyuan Wu, Shengbo E. Li, and Matthew J. Barth
- *IEEE Intelligent Transportation Systems Magazine*, vol. 12, no. 1, Spring 2020, pp. 4–25

#### [J3] Cooperative Ramp Merging System: Agent-Based Modeling and Simulation Using Game Engine (Best 2019 Paper Award)

- [Ziran Wang](#), Guoyuan Wu, Kanok Boriboonsomsin, Matthew J. Barth, Kyungtae Han, BaekGyu Kim, and Prashant Tiwari
- *SAE International Journal of Connected and Automated Vehicles*, vol.2, no.2, May 2019, pp. 115–128

#### [J2] Cluster-Wise Cooperative Eco-Approach and Departure Application for Connected and Automated Vehicles along Signalized Arterials

- [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *IEEE Transactions on Intelligent Vehicles*, vol. 3, no. 4, Dec. 2018, pp. 404–413

#### [J1] Developing a Distributed Consensus-Based Cooperative Adaptive Cruise Control (CACC) System for Heterogeneous Vehicles with Predecessor Following Topology

- [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *Journal of Advanced Transportation*, vol. 2017, Article ID 1023654, Aug. 2017

### Conference Papers

#### [C18] Augmented Reality-Based Advanced Driver-Assistance System for Connected Vehicles

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- *2020 IEEE International Conference on Systems, Man, and Cybernetics (SMC 2020)*, Virtual Conference, Oct. 2020

#### [C17] Long-Term Prediction of Lane Change Maneuver through a Multilayer Perceptron

- Zhenyu Shou, [Ziran Wang](#), Kyungtae Han, Yongkang Liu, Prashant Tiwari, and Xuan Di
- *2020 IEEE Intelligent Vehicles Symposium*, Virtual Conference, Oct. 2020

#### [C16] Sensor Fusion of Camera and Cloud Digital Twin Information for Intelligent Vehicles

- Yongkang Liu, [Ziran Wang](#), Kyungtae Han, Zhenyu Shou, Prashant Tiwari, and John Hansen
- *2020 IEEE Intelligent Vehicles Symposium*, Virtual Conference, Oct. 2020

#### [C15] Optimal Control-Based Eco-Ramp Merging System

- Zhouqiao Zhao, Guoyuan Wu, [Ziran Wang](#), and Matthew J. Barth
- *2020 IEEE Intelligent Vehicles Symposium*, Virtual Conference, Oct. 2020

[C14] A Digital Twin Paradigm: Vehicle-to-Cloud Based Advanced Driver Assistance Systems

- [Ziran Wang](#), Xishun Liao, Xuanpeng Zhao, Kyungtae Han, Prashant Tiwari, Matthew J. Barth, and Guoyuan Wu
- *IEEE 91<sup>st</sup> Vehicular Technology Conference (VTC2020-Spring)*, Virtual Conference, May 2020

[C13] Cooperative Ramp Merging with Vehicle-to-Cloud Communications: A Field Experiment

- Xishun Liao, David Oswald, [Ziran Wang](#), Guoyuan Wu, Kanok Boriboonsomsin, Matthew J. Barth, Kyungtae Han, BaekGyu Kim, and Prashant Tiwari
- *Transportation Research Board 99<sup>th</sup> Annual Meeting*, Washington D.C., Jan. 2020

[C12] End-to-End Vision-Based Adaptive Cruise Control (ACC) Using Deep Reinforcement Learning

- Zhensong Wei, Yu Jiang, Xishun Liao, Xuewei Qi, [Ziran Wang](#), Guoyuan Wu, Peng Hao, and Matthew J. Barth,
- *Transportation Research Board 99<sup>th</sup> Annual Meeting*, Washington D.C., Jan. 2020

[C11] Early Findings from Field Trials of Heavy-Duty Truck Connected Eco-Driving System

- [Ziran Wang](#), Yuan-Pu Hsu, Alexander Vu, Francisco Caballero, Peng Hao, Guoyuan Wu, Kanok Boriboonsomsin, Matthew J. Barth, Aravind Kailas, Pascal Amar, Eddie Garmon, and Sandeep Tanugula
- *IEEE 22<sup>nd</sup> International Conference on Intelligent Transportation Systems*, Auckland, New Zealand, Oct. 2019

[C10] The State-of-the-Art of Coordinated Ramp Control with Mixed Traffic Conditions

- Zhouqiao Zhao, [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *IEEE 22<sup>nd</sup> International Conference on Intelligent Transportation Systems*, Auckland, New Zealand, Oct. 2019

[C9] Lookup Table-Based Consensus Algorithm for Real-Time Longitudinal Motion Control of Connected and Automated Vehicles

- [Ziran Wang](#), Kyungtae Han, BaekGyu Kim, Guoyuan Wu, and Matthew J. Barth
- *2019 American Control Conference*, Philadelphia, PA, Jul. 2019

[C8] Agent-Based Modeling and Simulation of Connected and Automated Vehicles Using Game Engine: A Cooperative On-Ramp Merging Study

- [Ziran Wang](#), BaekGyu Kim, Hiromitsu Kobayashi, Guoyuan Wu, and Matthew J. Barth
- *Transportation Research Board 98<sup>th</sup> Annual Meeting*, Washington D.C., Jan. 2019

[C7] Eco-Approach and Departure along Signalized Corridors

- Guoyuan Wu, Peng Hao, [Ziran Wang](#), Kanok Boriboonsomsin, and Matthew J. Barth
- *Transportation Research Board 98<sup>th</sup> Annual Meeting*, Washington D.C., Jan. 2019

[C6] A Review on Cooperative Adaptive Cruise Control (CACC) Systems: Architectures, Controls, and Applications

- [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *IEEE 21<sup>st</sup> International Conference on Intelligent Transportation Systems*, Maui, Hawaii, Nov. 2018

[C5] Distributed Consensus-Based Cooperative Highway On-Ramp Merging Using V2X Communications

- [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *SAE Technical Paper*, 2018-01-1177, Apr. 2018

[C4] Cluster-Wise Cooperative Eco-Approach and Departure Application along Signalized Arterials

- [Ziran Wang](#), Guoyuan Wu, Peng Hao, and Matthew J. Barth
- *IEEE 20<sup>th</sup> International Conference on Intelligent Transportation Systems*, Yokohama, Japan, Oct. 2017

[C3] Intra-Platoon Vehicle Sequence Optimization for Eco-Cooperative Adaptive Cruise Control

- Peng Hao, [Ziran Wang](#), Guoyuan Wu, Kanok Boriboonsomsin, and Matthew J. Barth
- *IEEE 20<sup>th</sup> International Conference on Intelligent Transportation Systems*, Yokohama, Japan, Oct. 2017

[C2] Developing a Platoon-Wide Eco-Cooperative Adaptive Cruise Control (CACC) System

- [Ziran Wang](#), Guoyuan Wu, Peng Hao, Kanok Boriboonsomsin, and Matthew J. Barth
- *2017 IEEE Intelligent Vehicles Symposium*, Redondo Beach, CA, Jun. 2017

## [C1]Developing a Distributed Consensus-Based Cooperative Adaptive Cruise Control (CACC) System

- [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *Transportation Research Board 96<sup>th</sup> Annual Meeting*, Washington D.C., Jan. 2017

## Technical Reports

### [R1]Development of Eco-Friendly Ramp Control for Connected and Automated Electric Vehicles

- Guoyuan Wu, Zhouqiao Zhao, [Ziran Wang](#), and Matthew J. Barth
- *National Center for Sustainable Transportation*, NCST-UCR-RR-20-04, Jan. 2020

## PROJECTS

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### Evaluating Connected Vehicle Applications in a Mixed Traffic Environment using a “Digital Twin” Approach

Sponsor: Toyota Motor North America, InfoTech Labs

- Proposed a feedforward/feedback motion controller for autonomous vehicles to cooperate at on-ramp merging
- Developed an augmented reality (AR) based head-up display (HUD) for the driver on intelligent vehicles in Unity
- Built neural network to model human factor based on historical driver data
- Developed a Unity/Arduino-car integrated system to realize the Digital Twin concept

### Traffic Optimization for Signalized Corridors (TOSCo) Small Scale Test & Evaluation Project

Sponsor: Federal Highway Administration (FHWA), United States Department of Transportation

Partners: Crash Avoidance Metrics Partners (CAMP) LLC Vehicle to Infrastructure Consortium (Ford, General Motors, Hyundai-Kia, Honda, Mazda, Nissan, Subaru, Volvo Truck, and VW/Audi), IAV GmbH, Texas A&M Transportation Institute (TTI), and The University of Michigan Transportation Institute (UMTRI)

- Proposed advanced TOSCo algorithms based on eco-approach and departure and CACC applications
- Compiled C++ code for external driver model API of PTV VISSIM to realize the proposed framework and algorithms

### An Innovative Vehicle-Powertrain Eco-Operation System for Efficient Plug-In Hybrid Electric Buses

Sponsor: Advanced Research Projects Agency-Energy (ARPA-E), United States Department of Energy

- Filtered collected bus data by geofencing methodology using MATLAB and Excel
- Built a hardware-in-the-loop test environment by linking traffic simulation outputs with chassis dyno facility

### Connected Eco-Driving for Heavy-Duty Conventional and Plug-In Hybrid Electric Trucks

Sponsor: Volvo Group North America

- Integrated components in the system architecture including map matching, sensor fusion, speed planning and GUI
- Developed an eco-driving motion control algorithm and implement it on Volvo Truck's .NET framework
- Conducted a real-world demonstration of the system on a Volvo truck using cellular-based V2X communication

### Development of Eco-Friendly Ramp Control based on Connected and Automated Vehicle Technology

Sponsor: National Center for Sustainable Transportation, United States Department of Transportation

- Developed a hierarchical ramp merging control strategy to reduce overall freeway congestion
- Proposed an optimal control algorithm to control the movement of connected and automated vehicles
- Evaluated the mobility and environmental impacts of the proposed strategy by PTV VISSIM

## TALKS

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### A Digital Twin Paradigm: Vehicle-to-Cloud Based Advanced Driver Assistance Systems

- 23<sup>rd</sup> COTA Annual Winter Symposium, Washington D.C., Jan. 2020

### Unity3D-Based AV Simulation with V2X Communication and Human-in-the-Loop Integration

- Automated Vehicles Symposium, Orlando, FL, Jul. 2019

### Agent-Based Modeling and Simulation of Connected and Automated Vehicles Using Game Engine

- Transportation Research Board (TRB) 98<sup>th</sup> Annual Meeting, Washington, D.C., Jan. 2019

## **Eco-Friendly Applications in Connected and Automated Vehicle Technology**

- University of California, Riverside CE-CERT Open House, Riverside, CA, Oct. 2018

## **Connected Eco-Bus: An Innovative Vehicle Powertrain Eco-Operation System for Efficient Plug-In Hybrid Electric Buses**

- ARPA-E NEXTCAR 2018 Annual Meeting, Southfield, MI, Apr. 2018

## **Distributed Consensus-Based Cooperative Highway On-Ramp Merging Using V2X Communications**

- WCX: SAE World Congress Experience, Detroit, MI, Apr. 2018

## **Connected and Automated Vehicle Research at UCR**

- University of California, Riverside Extension, Riverside, CA, Jan. 2018

## **Developing a Platoon-Wide Eco-Cooperative Adaptive Cruise Control (CACC) System**

- Los Angeles Environmental Forum, San Gabriel, CA, Aug. 2017

## **Distributed Consensus-Based Cooperative Adaptive Cruise Control (CACC) Systems**

- TuSimple Technology Co., Ltd., San Diego, CA, Jul. 2017

## **TEACHING EXPERIENCE**

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### **Intelligent Transportation Systems (UCR EE 246)**

Oct. 2018

- Conducted 2 hours of lecture independently as a rotating lecturer of the course
- Introduced car-following models, cooperative adaptive cruise control, and simulation tools

### **Feedback Control (UCR ME 121)**

Mar. 2017 - Jun. 2017

- Conducted 20 hours of discussion sessions independently as a teaching assistant of the course
- Introduced the analysis and design of feedback control systems using classical control methods, including block diagrams, closed-loop stability, root locus, Bode plots, and etc.

### **Mechanical Engineering Modeling and Analysis (UCR ME 118)**

Jan. 2017 - Mar. 2017

- Conducted 20 hours of discussion sessions independently as a teaching assistant of the course
- Introduced data analysis and modeling used in engineering through MATLAB, including descriptive and inferential statistics, fitting linear and nonlinear models to observed data, numerical differentiation and integration, etc.

### **Introduction to Engineering Computation (UCR ME 018)**

Sep. 2016 - Dec. 2016

- Conducted 60 hours of lab sessions independently as a teaching assistant of the course
- Introduced the use of MATLAB in engineering computation, including scripts and functions, programming, input/output, two and three-dimensional graphics, elementary numerical analysis, etc.

## **PROFESSIONAL ACTIVITIES**

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### **As a Member**

Member of Technical Committee on Industrial CPS, IEEE Industrial Electronics Society	Jul. 2020 - Present
Member of Technical Committee on Smart Cities, IEEE Control Systems Society	Jun. 2020 - Present
Member of Society of Automotive Engineers (SAE)	Jan. 2018 - Present
Member of Southern California Chinese-American Environmental Protection Association (SCCAEPA)	Feb. 2017 - Present
Member of International Chinese Transportation Professionals Association (ICTPA)	Feb. 2017 - Present
Member of Chinese Overseas Transportation Association (COTA)	Jan. 2017 - Present
Friend of Transportation Research Board (TRB) Standing Committee: Vehicle-Highway Automation	Jan. 2017 - Present
Member of Institute of Electrical and Electronics Engineers (IEEE)	Sep. 2016 - Present

### **As an Organizer**

Chair of 2020 IEEE Intelligent Vehicles Symposium (IV), Internet of Things in Intelligent Transportation Systems: Opportunities and Challenges Workshop, Virtual Conference	Oct. 2020
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Chair of 23<sup>rd</sup> IEEE International Conference on Intelligent Transportation Systems (ITSC), Testing and Evaluation  
Connected and Automated Vehicles Using Emerging Simulation Technologies Workshop, Virtual Conference  
Sep. 2020

Co-Chair of 4<sup>th</sup> IEEE Conference on Control Technology and Applications (CCTA), Automotive Control Invited Sessions,  
Virtual Conference  
Aug. 2020

### **As an Editor**

Associate editor of *SAE International Journal of Connected and Automated Vehicles* Jun. 2020 - Present

Associate editor of *IEEE International Conference on Intelligent Transportation Systems (ITSC)* Feb. 2020 - Present

### **As a Reviewer**

Reviewer of *Serbian Journal of Electrical Engineering* Aug 2020 - Present

Reviewer of *MDPI Multimodal Technologies and Interaction* May 2020 - Present

Reviewer of *MDPI Applied Science* May 2020 - Present

Reviewer of *IEEE Forum on Integrated and Sustainable Transportation Systems* Mar. 2020 - Present

Reviewer of *International Journal of Automotive Technology* Feb. 2020 - Present

Reviewer of *International Journal of Automotive Technology* Feb. 2020 - Present

Reviewer of *MDPI Sensors* Feb. 2020 - Present

Reviewer of *Journal of Intelligent Transportation Systems* Jan. 2020 - Present

Reviewer of *International Journal of Transportation Science and Technology* Jan. 2020 - Present

Reviewer of *MDPI Information* Jan. 2020 - Present

Reviewer of *IEEE Open Journal of Intelligent Transportation Systems* Dec. 2019 - Present

Reviewer of *IEEE Vehicular Technology Conference* Nov. 2019 - Present

Reviewer of *MDPI Vehicles* Nov. 2019 - Present

Reviewer of *IEEE Transactions on Intelligent Vehicles* Oct. 2019 - Present

Reviewer of *IEEE Access* Aug. 2019 - Present

Reviewer of *Journal of Control, Automation and Electric Systems* Apr. 2019 - Present

Reviewer of *IEEE Conference on Control Technology and Applications* Mar. 2019 - Present

Reviewer of *SAE International Journal of Connected and Automated Vehicles* Oct. 2018 - Present

Reviewer of *American Control Conference (ACC)* Oct. 2018 - Present

Reviewer of *Transportation Research Record (TRR)* Aug. 2018 - Present

Reviewer of *International Conference on Computer Science and Application Engineering (CSAE)* Aug. 2018 - Present

Reviewer of *Journal of Advanced Transportation* Jul. 2018 - Present

Reviewer of *IEEE International Conference on Intelligent Transportation Systems (ITSC)* May 2018 - Present

Reviewer of *Case Studies on Transport Policies (CSTP)* May 2018 - Present

Reviewer of *IEEE Intelligent Vehicles Symposium* Mar. 2018 - Present

Reviewer of *IET Intelligent Transport Systems* Jan. 2018 - Present

Reviewer of *ASCE International Conference on Transportation & Development (ICTD)* Dec. 2017 - Present

Reviewer of *SAE Technical Papers* Oct. 2017 - Present

Reviewer of *TRB Annual Meeting* Sep. 2017 - Present

Reviewer of *IEEE Transactions on Intelligent Transportation Systems* Jun. 2017 - Present

Reviewer of *COTA International Conference of Transportation Professionals (CICTP)* Feb. 2017 - Present

### **As a Volunteer**

Organizer of 2018 IEEE 21<sup>st</sup> ITSC, Maui, HI Nov. 2018

Onsite support of Humanplus Intelligent Robotics Technology Co., Ltd. on CES 2018, Las Vegas, NV Jan. 2018

Organizer of Chinese Institute of Engineers (CIE) So-Cal Chapter Annual Convention, Rowland Heights, CA Sep. 2017

Organizer of 2017 IEEE IV Symposium, Redondo Beach, CA Jun. 2017

## ACADEMIC HONORS

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Vincent Bendix Automotive Electronics Engineering Award (i.e., best paper in 2019), SAE International	Feb. 2020
U.S. Department of Transportation National Center for Sustainable Transportation (NCST) Dissertation Award	Jun. 2018
Best Student Research Paper Award, Los Angeles Environmental Forum	Aug. 2017
UCR Dean's Distinguished Fellowship Award	Fall 2015 - Spring 2017
BUPT Scholarship Award	Jun. 2014 & Jun. 2013
The Honorable Mention, The Mathematical Contest in Modeling (MCM)	Feb. 2014

## MEDIA EXPOSURES

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**NCST Partner CE-CERT Takes Eco-Driving Simulator to CES**, National Center for Sustainable Transportation, Jan. 2020

**Testing a Connected Eco-Driving System in Field Trials with Heavy-Duty Trucks**, Featured News, Tech Xplore, Aug. 2019

**Steering into the Future of Connected and Automated Vehicles**, UCR News, Jul. 2019

**CE-CERT Researchers Open 2019 with a Successful TRB Conference Showing**, UCR CE-CERT News, Feb. 2019

**TSR Group has a Strong Showing at the 2018 IEEE ITSC Conference**, UCR CE-CERT News, Dec. 2018

**CE-CERT and Bourns Host 2018 STEP Conference**, UCR CE-CERT News, Oct. 2018