

# Ziran Wang

Assistant Professor, Purdue University

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## SUMMARY

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Currently lead the Purdue Digital Twin Lab at Purdue University as a Tenure-Track Assistant Professor, and previously led the Digital Twin Roadmap at Toyota Motor North America as a Principal Researcher. Published more than 40 refereed papers in premier journals and conference proceedings, and filed more than 50 patent applications worldwide. Serve as the Founding Chair of IEEE technical committee on Internet of Things in Intelligent Transportation Systems, and associated editor of three academic journals. Achievements were demonstrated on Consumer Electronic Show (CES), and acknowledged by the US Department of Transportation NCST Dissertation Award and four best paper awards.

## EMPLOYMENT

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### Purdue University, College of Engineering (West Lafayette, IN)

- Assistant Professor
  - Autonomous and Connected Systems Initiative *Jul. 2022 – Present*
  - Lyles School of Civil Engineering *Jul. 2022 – Present*
  - Center for Innovation in Control, Optimization, and Networks *Jul. 2022 – Present*
  - Center for Intelligent Infrastructure *Jul. 2022 – Present*
  - Center for Aging and the Life Course *Jul. 2022 – Present*

### Toyota Motor North America R&D, InfoTech Labs (Mountain View, CA)

- Principal Researcher (Supervisor: Dr. Prashant Tiwari & Dr. John Kenney) *Jul. 2021 – Jun. 2022*
- Research Scientist (Supervisor: Dr. Prashant Tiwari) *Jul. 2019 – Jun. 2021*
- Research Intern (Mentors: Dr. BaekGyu Kim & Dr. Kyungtae Han) *Jun. 2018 – Sep. 2018*

### University of California, Riverside (Riverside, CA)

- Researcher Assistant, Transportation Systems Research Lab (Advisor: Dr. Matthew Barth) *Jun. 2016 – Jun. 2019*
- Teaching Assistant, Mechanical Engineering, Electrical and Computer Engineering *Sep. 2016 – Jun. 2017*
- Researcher Assistant, Cooperative Vehicle Networks Lab (Advisor: Dr. Wei Ren) *Nov. 2015 – Jun. 2016*

### Changan Suzuki (Chongqing, China)

- Summer Intern *Jul. 2014 – Aug. 2014*

## EDUCATION

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### Ph.D. in Mechanical Engineering

*Sep. 2015 – Jun. 2019*

University of California, Riverside (UCR)

Advisor: Dr. Matthew J. Barth, Yeager Family Chair Professor, Electrical and Computer Engineering

Dissertation: Developing Agent-Based Distributed Cooperative Vehicle-Infrastructure Systems in the Connected and Automated Vehicle Environment

### B.E. in Mechanical Engineering and Automation

*Sep. 2011 – Jun. 2015*

School of Automation, Beijing University of Posts and Telecommunications (BUPT)

### Journal Publications

[J43]Planning for Automated Vehicles with Human Trust

- Shili Sheng, Erfan Pakdamanian, Kyungtae Han, [Ziran Wang](#), John Lenneman, David Parker, and Lu Feng
- *ACM Transactions on Cyber-Physical Systems*, under review

[J42]Gaussian Process-Based Personalized Adaptive Cruise Control

- Yanbing Wang, [Ziran Wang](#), Kyungtae Han, Prashant Tiwari, and Daniel B. Work
- *IEEE Transactions on Intelligent Transportation Systems*, early access

[J41]Mobility Digital Twin: Concept, Architecture, Case Study, and Future Challenges

- [Ziran Wang](#), Rohit Gupta, Kyungtae Han, and Prashant Tiwari
- *IEEE Internet of Things Journal*, early access, DOI: 10.1109/JIOT.2022.3156028

[J40]Game Theory-Based Ramp Merging for Mixed Traffic with Unity-SUMO Integrated Simulation

- Xishun Liao, Xuanpeng Zhao, [Ziran Wang](#), Kyungtae Han, Prashant Tiwari, Matthew J. Barth, and Guoyuan Wu
- *IEEE Transactions on Systems, Man, and Cybernetics: Systems*, early access, DOI: 10.1109/TSMC.2021.3131431

[J39]The Role of Digital Twins in Connected and Automated Vehicles

- Chris Schwarz and [Ziran Wang](#)
- *IEEE Intelligent Transportation Systems Magazine*, early access, DOI: 10.1109/MITS.2021.3129524

[J38]Co-Simulation Platform for Modeling and Evaluating Connected and Automated Vehicles in Mixed Traffic

- Xuanpeng Zhao, Xishun Liao, [Ziran Wang](#), Kyungtae Han, Prashant Tiwari, Matthew J. Barth, and Guoyuan Wu
- *SAE International Journal of Connected and Automated Vehicles*, to appear

[J37]Vision-Cloud Data Fusion for ADAS: A Lane Change Prediction Case Study

- Yongkang Liu, [Ziran Wang](#), Kyungtae Han, Zhenyu Shou, Prashant Tiwari, and John H. L. Hansen
- *IEEE Transactions on Intelligent Vehicles*, early access, DOI: 10.1109/TIV.2021.3103695

[J36]Digital Twin-Assisted Cooperative Driving at Non-Signalized Intersections

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- *IEEE Transactions on Intelligent Vehicles*, early access, DOI: 10.1109/TIV.2021.3100465

[J35]Cooperative Ramp Merging Design and Field Implementation: A Digital Twin Approach based on Vehicle-to-Cloud Communication

- Xishun Liao, [Ziran Wang](#), Xuanpeng Zhao, Kyungtae Han, Prashant Tiwari, Matthew J. Barth, and Guoyuan Wu
- *IEEE Transactions on Intelligent Transportation Systems*, vol. 23, no. 5, May 2022, pp. 4490–4500

[J34]Eco-Approach and Departure along Signalized Corridors (**Best Paper Award**)

- Guoyuan Wu, Peng Hao, [Ziran Wang](#), Yu Jiang, Kanok Boriboonsomsin, Matthew J. Barth, Michael McConnell, Shuwei Qiang, and John Stark
- *SAE International Journal of Sustainable Transportation, Energy, Environment, & Policy*, vol. 1, no. 2, 2021

[J33]Driver Behavior Modeling Using Game Engine and Real Vehicle: A Learning-Based Approach

- [Ziran Wang](#), Xishun Liao, Chao Wang, David Oswald, Guoyuan Wu, Kanok Boriboonsomsin, Matthew J. Barth, Kyungtae Han, BaekGyu Kim, and Prashant Tiwari
- *IEEE Transactions on Intelligent Vehicles*, vol. 5, no. 4, Dec. 2020, pp. 738–749

[J32]Cooperative Eco-Driving along Multiple Signalized Intersections in a Partially Connected and Automated Vehicle Environment

- [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *IEEE Transactions on Intelligent Transportation Systems*, vol.21, no.5, May 2020, pp. 2029–2038

[J31] A Survey on Cooperative Longitudinal Motion Control of Multiple Connected Automated Vehicles

- [Ziran Wang](#), Yougang Bian, Steven E. Shladover, Guoyuan Wu, Shengbo E. Li, and Matthew J. Barth
- *IEEE Intelligent Transportation Systems Magazine*, vol. 12, no. 1, Spring 2020, pp. 4–25

[J30] Cooperative Ramp Merging System: Agent-Based Modeling and Simulation Using Game Engine (**Best Paper Award**)

- [Ziran Wang](#), Guoyuan Wu, Kanok Boriboonsomsin, Matthew J. Barth, Kyungtae Han, BaekGyu Kim, and Prashant Tiwari
- *SAE International Journal of Connected and Automated Vehicles*, vol.2, no.2, May 2019, pp. 115–128

[J29] Cluster-Wise Cooperative Eco-Approach and Departure Application for Connected and Automated Vehicles along Signalized Arterials

- [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *IEEE Transactions on Intelligent Vehicles*, vol. 3, no. 4, Dec. 2018, pp. 404–413

[J28] Developing a Distributed Consensus-Based Cooperative Adaptive Cruise Control (CACC) System for Heterogeneous Vehicles with Predecessor Following Topology

- [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
- *Journal of Advanced Transportation*, vol. 2017, Article ID 1023654, Aug. 2017

### **Conference Proceedings**

[C27] GAPFORMER: Fast Autoregressive Transformers meet RNNs for Personalized Adaptive Cruise Control

- Naveen Sachdeva, [Ziran Wang](#), Kyungtae Han, Rohit Gupta, and Julian McAuley
- *IEEE 25<sup>th</sup> International Conference on Intelligent Transportation Systems*, Macau, China, Oct. 2022

[C26] A Study on Learning and Simulating Personalized Car-Following Driving Style

- Shili Sheng, Erfan Pakdamanian, Kyungtae Han, [Ziran Wang](#), and Lu Feng
- *IEEE 25<sup>th</sup> International Conference on Intelligent Transportation Systems*, Macau, China, Oct. 2022

[C25] Personalized Car Following for Autonomous Driving with Inverse Reinforcement Learning

- Zhouqiao Zhao, [Ziran Wang](#), Kyungtae Han, Rohit Gupta, Prashant Tiwari, Guoyuan Wu, and Matthew J. Barth
- *2022 IEEE International Conference on Robotics and Automation*, Philadelphia, PA, May 2022

[C24] Online Prediction of Lane Change with a Hierarchical Learning-Based Approach

- Xishun Liao, [Ziran Wang](#), Xuanpeng Zhao, Zhouqiao Zhao, Kyungtae Han, Prashant Tiwari, Matthew J. Barth, and Guoyuan Wu
- *2022 IEEE International Conference on Robotics and Automation*, Philadelphia, PA, May 2022

[C23] Personalized Adaptive Cruise Control via Gaussian Process Regression

- Yanbing Wang, [Ziran Wang](#), Kyungtae Han, Prashant Tiwari, and Daniel B. Work
- *IEEE 24<sup>th</sup> International Conference on Intelligent Transportation Systems*, Indianapolis, IN, Sep. 2021

[C22] Digital Twin Simulation of Connected and Automated Vehicles with the Unity Game Engine (**Best Application Award**)

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- *2021 IEEE International Conference on Digital Twin and Parallel Intelligence*, Beijing, China, Jul. 2021

[C21] Trust-Based Route Planning for Autonomous Vehicles

- Shili Sheng, Erfan Pakdamanian, Kyungtae Han, [Ziran Wang](#), John Lenneman and Lu Feng
- *12<sup>th</sup> ACM/IEEE International Conference on Cyber-Physical Systems (ICCPS)*, May 2021

[C20] Motion Estimation of Connected and Automated Vehicles under Communication Delay and Packet Loss of V2X Communications

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- *SAE World Congress Experience 2021*, Virtual Conference, Apr. 2021

- [C19] A Game Theory Based Ramp Merging Strategy for Connected and Automated Vehicles in the Mixed Traffic: A Unity-SUMO Integrated Platform
- Xishun Liao, Xuanpeng Zhao, Guoyuan Wu, Matthew J. Barth, [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
  - *Transportation Research Board 100<sup>th</sup> Annual Meeting*, Virtual Conference, Jan. 2021
- [C18] Augmented Reality-Based Advanced Driver-Assistance System for Connected Vehicles
- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
  - *2020 IEEE International Conference on Systems, Man, and Cybernetics (SMC 2020)*, Virtual Conference, Oct. 2020
- [C17] Long-Term Prediction of Lane Change Maneuver through a Multilayer Perceptron
- Zhenyu Shou, [Ziran Wang](#), Kyungtae Han, Yongkang Liu, Prashant Tiwari, and Xuan Di
  - *2020 IEEE Intelligent Vehicles Symposium*, Virtual Conference, Oct. 2020
- [C16] Sensor Fusion of Camera and Cloud Digital Twin Information for Intelligent Vehicles
- Yongkang Liu, [Ziran Wang](#), Kyungtae Han, Zhenyu Shou, Prashant Tiwari, and John H. L. Hansen
  - *2020 IEEE Intelligent Vehicles Symposium*, Virtual Conference, Oct. 2020
- [C15] Optimal Control-Based Eco-Ramp Merging System
- Zhouqiao Zhao, Guoyuan Wu, [Ziran Wang](#), and Matthew J. Barth
  - *2020 IEEE Intelligent Vehicles Symposium*, Virtual Conference, Oct. 2020
- [C14] A Digital Twin Paradigm: Vehicle-to-Cloud Based Advanced Driver Assistance Systems
- [Ziran Wang](#), Xishun Liao, Xuanpeng Zhao, Kyungtae Han, Prashant Tiwari, Matthew J. Barth, and Guoyuan Wu
  - *IEEE 91<sup>st</sup> Vehicular Technology Conference (VTC2020-Spring)*, Virtual Conference, May 2020
- [C13] Cooperative Ramp Merging with Vehicle-to-Cloud Communications: A Field Experiment
- Xishun Liao, David Oswald, [Ziran Wang](#), Guoyuan Wu, Kanok Boriboonsomsin, Matthew J. Barth, Kyungtae Han, BaekGyu Kim, and Prashant Tiwari
  - *Transportation Research Board 99<sup>th</sup> Annual Meeting*, Washington D.C., Jan. 2020
- [C12] End-to-End Vision-Based Adaptive Cruise Control (ACC) Using Deep Reinforcement Learning
- Zhensong Wei, Yu Jiang, Xishun Liao, Xuwei Qi, [Ziran Wang](#), Guoyuan Wu, Peng Hao, and Matthew J. Barth,
  - *Transportation Research Board 99<sup>th</sup> Annual Meeting*, Washington D.C., Jan. 2020
- [C11] Early Findings from Field Trials of Heavy-Duty Truck Connected Eco-Driving System
- [Ziran Wang](#), Yuan-Pu Hsu, Alexander Vu, Francisco Caballero, Peng Hao, Guoyuan Wu, Kanok Boriboonsomsin, Matthew J. Barth, Aravind Kailas, Pascal Amar, Eddie Garmon, and Sandeep Tanugula
  - *IEEE 22<sup>nd</sup> International Conference on Intelligent Transportation Systems*, Auckland, New Zealand, Oct. 2019
- [C10] The State-of-the-Art of Coordinated Ramp Control with Mixed Traffic Conditions
- Zhouqiao Zhao, [Ziran Wang](#), Guoyuan Wu, and Matthew J. Barth
  - *IEEE 22<sup>nd</sup> International Conference on Intelligent Transportation Systems*, Auckland, New Zealand, Oct. 2019
- [C9] Lookup Table-Based Consensus Algorithm for Real-Time Longitudinal Motion Control of Connected and Automated Vehicles
- [Ziran Wang](#), Kyungtae Han, BaekGyu Kim, Guoyuan Wu, and Matthew J. Barth
  - *2019 American Control Conference*, Philadelphia, PA, Jul. 2019
- [C8] Agent-Based Modeling and Simulation of Connected and Automated Vehicles Using Game Engine: A Cooperative On-Ramp Merging Study
- [Ziran Wang](#), BaekGyu Kim, Hiromitsu Kobayashi, Guoyuan Wu, and Matthew J. Barth
  - *Transportation Research Board 98<sup>th</sup> Annual Meeting*, Washington D.C., Jan. 2019
- [C7] Eco-Approach and Departure along Signalized Corridors
- Guoyuan Wu, Peng Hao, [Ziran Wang](#), Kanok Boriboonsomsin, and Matthew J. Barth

- *Transportation Research Board 98<sup>th</sup> Annual Meeting*, Washington D.C., Jan. 2019
- [C6]A Review on Cooperative Adaptive Cruise Control (CACC) Systems: Architectures, Controls, and Applications
- Ziran Wang, Guoyuan Wu, and Matthew J. Barth
  - *IEEE 21<sup>st</sup> International Conference on Intelligent Transportation Systems*, Maui, Hawaii, Nov. 2018
- [C5]Distributed Consensus-Based Cooperative Highway On-Ramp Merging Using V2X Communications
- Ziran Wang, Guoyuan Wu, and Matthew J. Barth
  - *SAE Technical Paper*, 2018-01-1177, Apr. 2018
- [C4]Cluster-Wise Cooperative Eco-Approach and Departure Application along Signalized Arterials
- Ziran Wang, Guoyuan Wu, Peng Hao, and Matthew J. Barth
  - *IEEE 20<sup>th</sup> International Conference on Intelligent Transportation Systems*, Yokohama, Japan, Oct. 2017
- [C3]Intra-Platoon Vehicle Sequence Optimization for Eco-Cooperative Adaptive Cruise Control
- Peng Hao, Ziran Wang, Guoyuan Wu, Kanok Boriboonsomsin, and Matthew J. Barth
  - *IEEE 20<sup>th</sup> International Conference on Intelligent Transportation Systems*, Yokohama, Japan, Oct. 2017
- [C2]Developing a Platoon-Wide Eco-Cooperative Adaptive Cruise Control (CACC) System
- Ziran Wang, Guoyuan Wu, Peng Hao, Kanok Boriboonsomsin, and Matthew J. Barth
  - *2017 IEEE Intelligent Vehicles Symposium*, Redondo Beach, CA, Jun. 2017
- [C1]Developing a Distributed Consensus-Based Cooperative Adaptive Cruise Control (CACC) System
- Ziran Wang, Guoyuan Wu, and Matthew J. Barth
  - *Transportation Research Board 96<sup>th</sup> Annual Meeting*, Washington D.C., Jan. 2017

## OTHER PUBLICATIONS

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### Book Chapters

- [B3]New Simulation Tools for Training and Testing Automated Vehicles
- Jiaqi Ma, Chris Schwarz, Ziran Wang, Maria Elli, German Ros, and Yiheng Feng
  - *Road Vehicles Automation*, vol. 7, pp. 111 – 119, Springer

### Technical Reports

- [R2]Development of Eco-Friendly Ramp Control for Connected and Automated Electric Vehicles
- Guoyuan Wu, Zhouqiao Zhao, Ziran Wang, and Matthew J. Barth
  - *National Center for Sustainable Transportation, U.S. Department of Transportation*, NCST-UCR-RR-20-04, Jan. 2020
- [R1]MOVESTAR: An Open-Source Vehicle Fuel and Emission Model based on USEPA MOVES
- Ziran Wang, Guoyuan Wu, and George Scora
  - *arXiv Preprint arXiv: 2008.04986*, URL: <https://github.com/ziranw/MOVESTAR-Fuel-and-Emission-Model>, Aug. 2020

## PATENTS

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- [P52]Lane Merging Near-Miss Prevention ADAS
- Rohit Gupta, Ziran Wang, Runjia Du, and Kyungtae Han
  - U.S. patent application, Filed Jul. 2022
- [P51]Software Defined Personalized Speed Limiter
- Rohit Gupta, Ziran Wang, Runjia Du, and Kyungtae Han
  - U.S. patent application, Filed Jul. 2022
- [P50]Systems and Methods for Simulating Connected and Automated Vehicles with Digital Twin
- Rohit Gupta, Ziran Wang, Kyungtae Han, and Runjia Du

- U.S. patent application, Filed Jul. 2022

**[P49]Systems and Methods for Personalized Takeover Prediction with Driver Haptic Inputs**

- Ziran Wang, Rohit Gupta, Kyungtae Han, and Runjia Du
- U.S. patent application, Filed Jul. 2022

**[P48]Systems and Methods for Lane-Change Prediction with Federated Learning**

- Runjia Du, Ziran Wang, Rohit Gupta, and Kyungtae Han
- U.S. patent application, Filed Jul. 2022

**[P47]Senior “Aging” Glaucoma Pedestrian Detection Metaverse ADAS**

- Rohit Gupta, Paul Li, Ziran Wang, Kyungtae Han, and Satoshi Nagashima
- U.S. patent application, Filed Jul. 2022

**[P46]Systems and Methods for Active Road Surface Maintenance with Mobility Digital Twin**

- Ziran Wang, Rohit Gupta, and Kyungtae Han
- U.S. patent application, Filed Jul. 2022

**[P45]Software Driven Multi-Sensory Fusion Mood Based Personalized Adaptive Cruise Control**

- Rohit Gupta, Ziran Wang, Kyungtae Han, Paul Li, Satoshi Nagashima, Pujitha Gunaratne, and Hazem Abdelkawy
- U.S. patent application, Filed Jul. 2022

**[P44]Systems and Methods for Personalized Adaptive Cruise Control with Transformers and RNNs**

- Ziran Wang, Rohit Gupta, and Kyungtae Han
- U.S. patent application, Filed Jul. 2022

**[P43]Systems and Methods for Modeling Personalized Car-Following Driving Styles with Model-Free Inverse Reinforcement Learning**

- Ziran Wang, Rohit Gupta, and Kyungtae Han
- U.S. patent application, Filed Jul. 2022

**[P42]Software Driven User Profile Personalized Adaptive Cruise Control**

- Rohit Gupta, Ziran Wang, and Kyungtae Han
- U.S. patent application 17/872469, Filed Jul. 2022

**[P41]Cloud-Based Mobility Digital Twin for Human, Vehicle, and Traffic**

- Ziran Wang, Rohit Gupta, Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/744452, Filed May 2022

**[P40]Medical Emergency Detection In-vehicle Caretaker**

- Akila Ganlath, Paul Li, Rohit Gupta, Ziran Wang, Satoshi Nagashima, Kyungtae Han, and Nejib Ammar
- U.S. patent application 17/725297, Filed Apr. 2022

**[P39]Personalized Vehicle Lane Change Maneuver Prediction**

- Ziran Wang, Rohit Gupta, Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/715011, Filed Apr. 2022

**[P38]Systems and Methods for Predicting Driver Visual Impairment with Artificial Intelligence**

- Rohit Gupta, Zhouqiao Zhao, Ziran Wang, Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/586593, Filed Jan. 2022

**[P37]Personalized Adaptive Cruise Control based on Steady-State Operation**

- Zhouqiao Zhao, Ziran Wang, Rohit Gupta, Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/578330, Filed Jan. 2022

**[P36]Personalized Vehicle Operation for Autonomous Driving with Inverse Reinforcement Learning**

- Zhouqiao Zhao, Ziran Wang, Rohit Gupta, Kyungtae Han, and Prashant Tiwari

- U.S. patent application 17/572486, Filed Jan. 2022

**[P35]Method and System for Personalized Car Following with Transformers**

- Ziran Wang, Zhouqiao Zhao, Rohit Gupta, Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/567504, Filed Jan. 2022

**[P34]Apparatus and Method for Cooperative Escape Zone Detection**

- Rohit Gupta, Ziran Wang, Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/509711, Filed Oct. 2021

**[P33]Cooperative Artificial Intelligent Assisted Driving**

- Jianyu Su, Rui Guo, and Ziran Wang
- U.S. patent application 17/475306, Filed Sep. 2021

**[P32]Subconscious Big Picture Macro and Split Second Micro Decisions ADAS**

- Rohit Gupta, Ziran Wang, Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/471100, Filed Sep. 2021

**[P31]Systems and Methods for Protecting a Vehicle at an Intersection**

- Rohit Gupta, Ziran Wang, Yanbing Wang, Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/411831, Filed Aug. 2021

**[P30]Driver Classification Systems and Methods for Obtaining an Insurance Rate for a Vehicle**

- Rohit Gupta, Ziran Wang, Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/410536, Filed Aug. 2021

**[P29]Hybrid Deterministic Override of Probabilistic Advanced Driving Assistance Systems (ADAS)**

- Rohit Gupta, Yanbing Wang, Ziran Wang, Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/398666, Filed Aug. 2021

**[P28]Student-T Process for Personalized Adaptive Cruise Control**

- Rohit Gupta, Ziran Wang, Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/388488, Filed Jul. 2021

**[P27]System and Methods for Personalizing Adaptive Cruise Control in a Vehicle**

- Yanbing Wang, Ziran Wang, Kyungtae Han, Rohit Gupta, and Prashant Tiwari
- U.S. patent application 17/387045, Filed Jul. 2021

**[P26]Vehicular Topple Risk Notification**

- Rohit Gupta, Ziran Wang, Yanbing Wang, Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/385012, Filed Jul. 2021

**[P25]Detection, Classification, and Prediction of Bacteria Colony Growth in Vehicle Passenger Cabin**

- Rohit Gupta, Ziran Wang, Yanbing Wang, Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/373050, Filed Jul. 2021

**[P24]Systems and Methods to Reduce Audio Distraction for a Vehicle Driver**

- Rohit Gupta, Ziran Wang, Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/333616, Filed Jun. 2021

**[P23]Methods and Systems for Rideshare Implicit and Explicit Needs Personalization**

- Rohit Gupta, Ziran Wang, Kyungtae Han, and Prashant Tiwari
- China patent application, Filed Mar. 2021

**[P22]Methods and Systems for Rideshare Implicit and Explicit Needs Personalization**

- Rohit Gupta, Ziran Wang, Kyungtae Han, and Prashant Tiwari
- Japan patent application, Filed Mar. 2021

**[P21]Methods and Systems for Rideshare Implicit and Explicit Needs Personalization**

- Rohit Gupta, [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/217358, Filed Mar. 2021

**[P20]Determining a Setting for a Cruise Control**

- Kyungtae Han, [Ziran Wang](#), Prashant Tiwari, John Lenneman, Toshinori Esaka, Miles Johnson, and Chase Violetta
- U.S. patent application 17/216924, Filed Mar. 2021

**[P19]Vehicle Guard Rail System**

- Rohit Gupta, [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/206706, Filed Mar. 2021

**[P18]Systems and Methods for Estimating Motion of an Automated Vehicle for Cooperative Driving**

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/196016, Filed Mar. 2021

**[P17]System and Method for Scheduling Connected Vehicles to Cross Non-Signalized Intersections**

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/193278, Filed Mar. 2021

**[P16]Cooperative Driving Systems and Method**

- Sergei Avedisov, [Ziran Wang](#), Ahmed Sakr, Kyungtae Han, Rui Guo, and Onur Altintas
- U.S. patent application 17/174998, Filed Feb. 2021

**[P15]Producing, for an Autonomous Vehicle, a Route from an Origination to a Destination**

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/168582, Filed Feb. 2021

**[P14]System and Method for Connected Vehicle Lane Merge**

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- U.S. patent application 17/031095, Filed Sep. 2020

**[P13]System and Methods for Providing Guidance to Vehicle Drivers Regarding Predicted Lane-Change Behavior of Vehicle Drivers**

- Zhenyu Shou, Kyungtae Han, [Ziran Wang](#), Yongkang Liu, and Prashant Tiwari
- U.S. patent application 16/999332, Filed Aug. 2020 | U.S. patent 11151880, Granted Oct. 2021

**[P12]Rest Stop Recommendation System**

- Zhenyu Shou, [Ziran Wang](#), Kyungtae Han, Yongkang Liu, and Prashant Tiwari
- U.S. patent application 16/998529, Filed Aug. 2020

**[P11]Identifying a Specific Object in a Two-Dimensional Image of Objects**

- Yongkang Liu, [Ziran Wang](#), Kyungtae Han, Zhenyu Shou, and Prashant Tiwari
- U.S. patent application 16/927467, Filed Jul. 2020 | U.S. patent 11222215, Granted Jan. 2022

**[P10]Systems and Methods for Long-Term Prediction of Lane Change Maneuver**

- Zhenyu Shou, [Ziran Wang](#), Kyungtae Han, Yongkang Liu, and Prashant Tiwari
- U.S. patent application 16/897386, Filed Jun. 2020

**[P9]Adjustable Blind Spot Monitor**

- [Ziran Wang](#), Kyungtae Han, and BaekGyu Kim
- China patent application 202010223851.8, Filed Mar. 2019

**[P8]Adjustable Blind Spot Monitor**

- [Ziran Wang](#), Kyungtae Han, and BaekGyu Kim
- Japan patent application 2020-048606, Filed Mar. 2019



#### [P7]Ramp Merging Assistance

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- U.S. patent application 16/781211, Filed Feb. 2020

#### [P6]Systems and Methods for Compensating for Driver Speed-Tracking Error

- [Ziran Wang](#), Kyungtae Han, and Prashant Tiwari
- U.S. patent application 16/775772, Filed Jan. 2020 | U.S. patent 11087623, Granted Aug. 2021

#### [P5]Longitudinal Motion Control of Connected and Automated Vehicles

- [Ziran Wang](#), Hiromitsu Kobayashi, Kyungtae Han, and BaekGyu Kim
- U.S. patent application 16/364851, Filed May 2019 | U.S. patent 11214253, Granted Jan. 2022

#### [P4]Adjustable Blind Spot Monitor

- [Ziran Wang](#), Kyungtae Han, and BaekGyu Kim
- U.S. patent application 16/364851, Filed Mar. 2019 | U.S. patent 11328605, Granted May 2022

#### [P3]Vehicle-to-Everything Communication-Based Lane Change Collision Avoidance Warning

- [Ziran Wang](#), Kyungtae Han, and BaekGyu Kim
- U.S. patent application 16/295700, Filed Mar. 2019

#### [P2]Virtualized Driver Assistance

- [Ziran Wang](#), BaekGyu Kim, and Hiromitsu Kobayashi
- U.S. patent application 16/268729, Filed Feb. 2019

#### [P1]XR-based Slot Reservation System For Connected Vehicles Traveling Through Intersections

- [Ziran Wang](#), Kyungtae Han, and BaekGyu Kim
- U.S. patent application 16/264475, Filed Jan. 2019 | U.S. patent 11257363, Granted Feb. 2022

## PROFESSIONAL ACTIVITIES

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### As an Editor

Associate editor of <i>IEEE Transactions on Intelligent Vehicles</i>	Jun. 2022 - Present
Guest editor of <i>IEEE Open Journal of Intelligent Transportation Systems</i>	May 2022 - Present
Associate editor of <i>Frontiers in Sustainable Cities-Urban Transportation Systems and Mobility</i>	Sep. 2021 - Present
Handling editor of <i>SAE Non-Event Technical Papers</i>	Apr. 2021 - Present
Associate editor of <i>IEEE Intelligent Vehicles Symposium (IV)</i>	Nov. 2020 - Present
Associate editor of <i>SAE International Journal of Connected and Automated Vehicles</i>	Jun. 2020 - Present
Associate editor of <i>IEEE International Conference on Intelligent Transportation Systems (ITSC)</i>	Feb. 2020 - Present

### As a Committee/Program Chair/Member

Member of Technical Program Committee in the <i>1<sup>st</sup> International Conference on Mobility (MOST)</i>	Jul 2022 - Present
Member of the Advisory Board of the SAE MobilityRxiv	Nov. 2021 - Present
Member of Technical Committee on Artificial Intelligence, SAE China	Oct. 2021 - Present
Member of Technical Program Committee in the <i>2021 IEEE 94th Vehicular Technology Conference: VTC2021-Fall</i>	May 2021 - Present
Member of Technical Program Committee in the <i>2021 IEEE International Conference on Digital Twin and Parallel Intelligence</i>	Apr. 2021 - Present
Founding Chair of Technical Committee on Internet of Things in Intelligent Transportation Systems, IEEE ITS Society	Mar. 2021 - Present
Member of Technical Committee on Cooperative and Connected Vehicles, IEEE ITS Society	Feb. 2021 - Present
Member of SAE On Road Automated Driving (ORAD) Simulation Task Force	Nov. 2020 - Present
Member of Technical Committee on Industrial CPS, IEEE Industrial Electronics Society	Jul. 2020 - Present
Member of Technical Committee on Smart Cities, IEEE Control Systems Society	Jun. 2020 - Present

### **As a Society Member**

Member of Society of Automotive Engineers (SAE)	Jan. 2018 - Present
Member of Southern California Chinese-American Environmental Protection Association (SCCAEPA)	Feb. 2017 - Present
Member of International Chinese Transportation Professionals Association (ICTPA)	Feb. 2017 - Present
Member of Chinese Overseas Transportation Association (COTA)	Jan. 2017 - Present
Friend of Transportation Research Board (TRB) Standing Committee: Vehicle-Highway Automation	Jan. 2017 - Present
Member of Intelligent Transportation Systems Society (ITSS), IEEE	Sep. 2016 - Present
Member of Institute of Electrical and Electronics Engineers (IEEE)	Sep. 2016 - Present

### **As an Organizer**

Tutorial Chair of 59 <sup>th</sup> Design Automation Conference (DAC), Tutorial on Cloud Computing and Edge Computing for Connected and Automated Vehicles, San Francisco, CA	Jul. 2022
Workshop Chair of 24 <sup>th</sup> IEEE International Conference on Intelligent Transportation Systems (ITSC), 2 <sup>nd</sup> Workshop on Internet of Things in Intelligent Transportation Systems: Opportunities and Challenges, Indianapolis, IN	Sep. 2021
Workshop Chair of 2021 IEEE Intelligent Vehicles Symposium (IV), Cooperative Driving in Mixed Traffic Workshop, Nagoya, Japan	Jul. 2021
Workshop Chair of 2020 IEEE Intelligent Vehicles Symposium (IV), Internet of Things in Intelligent Transportation Systems: Opportunities and Challenges Workshop, Virtual	Oct. 2020
Workshop Chair of 23 <sup>rd</sup> IEEE International Conference on Intelligent Transportation Systems (ITSC), Testing and Evaluation Connected and Automated Vehicles Using Emerging Simulation Technologies Workshop, Virtual	Sep. 2020
Workshop Co-Chair of 4 <sup>th</sup> IEEE Conference on Control Technology and Applications (CCTA), Automotive Control Invited Sessions, Virtual	Aug. 2020

### **As a Reviewer**

Reviewer of MDPI Remote Sensing	Apr. 2022 - Present
Reviewer of IEEE Robotics and Automation Letters	Mar. 2022 - Present
Reviewer of IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)	Mar. 2022 - Present
Reviewer of Transportation Research Part B: Methodological	Mar. 2022 - Present
Reviewer of Applied Energy	Oct. 2021 - Present
Reviewer of IEEE Transactions on Industrial Informatics	Sep. 2021 - Present
Reviewer of Physica A: Statistical Mechanics and its Applications	Jul. 2021 - Present
Reviewer of Connection Science	Jul. 2021 - Present
Reviewer of Simulation Modelling Practice and Theory	Jun. 2021 - Present
Reviewer of Transportation Research Part C: Emerging Technologies	Apr. 2021 - Present
Reviewer of IEEE Transactions on Transportation Electrification	Feb. 2021 - Present
Reviewer of IEEE Transactions on Systems, Man and Cybernetics: Systems	Jan. 2021 - Present
Reviewer of Automatica	Dec. 2020 - Present
Reviewer of IEEE Transactions on Control Systems Technology	Dec. 2020 - Present
Reviewer of Journal of Traffic and Transportation Engineering	Nov. 2020 - Present
Reviewer of IEEE Vehicular Technology Magazine	Nov. 2020 - Present
Reviewer of Transportation Research Part D: Transport and Environment	Nov. 2020 - Present
Reviewer of Information Sciences	Oct. 2020 - Present
Reviewer of Journal of Selected Topics in Signal Processing	Sep. 2020 - Present
Reviewer of Serbian Journal of Electrical Engineering	Aug. 2020 - Present
Reviewer of IEEE Transactions on Control of Network Systems	Jul. 2020 - Present
Reviewer of MDPI Multimodal Technologies and Interaction	May 2020 - Present
Reviewer of MDPI Applied Science	May 2020 - Present
Reviewer of IEEE Forum on Integrated and Sustainable Transportation Systems	Mar. 2020 - Present
Reviewer of International Journal of Automotive Technology	Feb. 2020 - Present

Reviewer of <i>MDPI Sensors</i>	Feb. 2020 - Present
Reviewer of <i>Journal of Intelligent Transportation Systems</i>	Jan. 2020 - Present
Reviewer of <i>International Journal of Transportation Science and Technology</i>	Jan. 2020 - Present
Reviewer of <i>MDPI Information</i>	Jan. 2020 - Present
Reviewer of <i>IEEE Open Journal of Intelligent Transportation Systems</i>	Dec. 2019 - Present
Reviewer of <i>IEEE Vehicular Technology Conference</i>	Nov. 2019 - Present
Reviewer of <i>MDPI Vehicles</i>	Nov. 2019 - Present
Reviewer of <i>IEEE Transactions on Intelligent Vehicles</i>	Oct. 2019 - Present
Reviewer of <i>IEEE Access</i>	Aug. 2019 - Present
Reviewer of <i>Journal of Control, Automation and Electric Systems</i>	Apr. 2019 - Present
Reviewer of <i>IEEE Conference on Control Technology and Applications</i>	Mar. 2019 - Present
Reviewer of <i>SAE International Journal of Connected and Automated Vehicles</i>	Oct. 2018 - Present
Reviewer of <i>American Control Conference (ACC)</i>	Oct. 2018 - Present
Reviewer of <i>Transportation Research Record (TRR)</i>	Aug. 2018 - Present
Reviewer of <i>International Conference on Computer Science and Application Engineering (CSAE)</i>	Aug. 2018 - Present
Reviewer of <i>Journal of Advanced Transportation</i>	Jul. 2018 - Present
Reviewer of <i>IEEE International Conference on Intelligent Transportation Systems (ITSC)</i>	May 2018 - Present
Reviewer of <i>Case Studies on Transport Policies (CSTP)</i>	May 2018 - Present
Reviewer of <i>IEEE Intelligent Vehicles Symposium</i>	Mar. 2018 - Present
Reviewer of <i>IET Intelligent Transport Systems</i>	Jan. 2018 - Present
Reviewer of <i>ASCE International Conference on Transportation &amp; Development (ICTD)</i>	Dec. 2017 - Present
Reviewer of <i>SAE Technical Papers</i>	Oct. 2017 - Present
Reviewer of <i>TRB Annual Meeting</i>	Sep. 2017 - Present
Reviewer of <i>IEEE Transactions on Intelligent Transportation Systems</i>	Jun. 2017 - Present
Reviewer of <i>COTA International Conference of Transportation Professionals (CICTP)</i>	Feb. 2017 - Present

### **As a Volunteer**

Organizer of 2018 <i>IEEE 21<sup>st</sup> ITSC</i> , Maui, HI	Nov. 2018
Onsite support of Humanplus Intelligent Robotics Technology Co., Ltd. on CES 2018, Las Vegas, NV	Jan. 2018
Organizer of Chinese Institute of Engineers (CIE) So-Cal Chapter Annual Convention, Rowland Heights, CA	Sep. 2017
Organizer of 2017 <i>IEEE IV Symposium</i> , Redondo Beach, CA	Jun. 2017
Onsite support of UISEE Technology Co., Ltd. on CES 2017, Las Vegas, NV	Jan. 2017

## **TEACHING EXPERIENCE**

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<b>Intelligent Transportation Systems</b> (UCR EE 246)	Oct. 2018
<ul style="list-style-type: none"> <li>Conducted 2 hours of lecture independently as a rotating lecturer of the course</li> <li>Introduced car-following models, cooperative adaptive cruise control, and simulation tools</li> </ul>	
<b>Feedback Control</b> (UCR ME 121)	Mar. 2017 - Jun. 2017
<ul style="list-style-type: none"> <li>Conducted 20 hours of discussion sessions independently as a teaching assistant of the course</li> <li>Introduced the analysis and design of feedback control systems using classical control methods, including block diagrams, closed-loop stability, root locus, Bode plots, and etc.</li> </ul>	
<b>Mechanical Engineering Modeling and Analysis</b> (UCR ME 118)	Jan. 2017 - Mar. 2017
<ul style="list-style-type: none"> <li>Conducted 20 hours of discussion sessions independently as a teaching assistant of the course</li> <li>Introduced data analysis and modeling used in engineering through MATLAB, including descriptive and inferential statistics, fitting linear and nonlinear models to observed data, numerical differentiation and integration, etc.</li> </ul>	
<b>Introduction to Engineering Computation</b> (UCR ME 018)	Sep. 2016 - Dec. 2016
<ul style="list-style-type: none"> <li>Conducted 60 hours of lab sessions independently as a teaching assistant of the course</li> </ul>	

- Introduced the use of MATLAB in engineering computation, including scripts and functions, programming, input/output, two and three-dimensional graphics, elementary numerical analysis, etc.

## MENTORED STUDENTS

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### Mentored at Purdue

- Zihao Li, *now*: M.S. student in Civil Engineering @Purdue

### Mentored at Toyota

- Runjia Du, 2022 summer intern @Toyota, *now*: Ph.D. student in Civil Engineering @Purdue
- Zhouqiao Zhao, 2021 summer intern @Toyota, *now*: Ph.D. candidate in ECE @UCR
- Yanbing Wang, 2021 spring intern @Toyota, *now*: Ph.D. student in Civil Engineering @Vanderbilt
- Jianyu Su, 2021 spring intern @Toyota, *now*: ML Engineer @JD.com
- Yongkang Liu, 2020 winter intern @Toyota, Ph.D. student in EE @UT Dallas, *now*: ML Engineer @Toyota
- Zhenyu Shou, 2020 winter intern @Toyota, *now*: Ph.D. student in Civil Engineering @Columbia
- Xianguo Liu, 2019 summer intern @Toyota, *now*: Ph.D. candidate in ECE @Northwestern

### Mentored at UCR

- Xishun Liao, M.S. student in ME @UMD & summer research intern @UCR, *now*: Ph.D. candidate in ECE @UCR
- Yuan-Pu Hsu, M.S. student in ECE @UCR, *now*: Software Engineer @Cruise
- Francisco Caballero, B.S. student in CS @CSUSB
- Xuanpeng Zhao, B.S. & M.S. student in ECE @UCR, *now*: Ph.D. candidate in ECE @UCR
- Yu Jiang, B.S. & M.S. student in ECE @UCR, *now*: Algorithm Engineer @IQHi Inc
- Pingbo Ruan, B.S. & M.S. student in ECE @UCR, *now*: M.S. student in ECE @UCR
- Shangrui Liu, B.S. & M.S. student in ECE @UCR, *now*: M.S. student in ECE @UCR
- Hangquan Zhao, B.S. student in ECE @UCR, *now*: Software Engineer @Toyota
- Yue You, B.S. student in ECE @UCR, *now*: Software Engineer @WeRide
- Yu Wang, M.S. student in ME @UCR

## HONORS & AWARDS

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First Prize in the 2021 "Shape the Future of ITS" Competition, IEEE Intelligent Transportation Systems Society	May 2022
Arch T. Colwell Merit Award (i.e., best paper in 2021), SAE International	Jan. 2022
Best Application Award, 2021 IEEE International Conference on Digital Twins and Parallel Intelligence (DTPI)	Sep. 2021
Vincent Bendix Automotive Electronics Engineering Award (i.e., best paper in 2019), SAE International	Feb. 2020
U.S. Department of Transportation National Center for Sustainable Transportation (NCST) Dissertation Award	Jun. 2018
Best Student Research Paper Award, Los Angeles Environmental Forum	Aug. 2017
UCR Dean's Distinguished Fellowship Award	Fall 2015 - Spring 2017
BUPT Scholarship Award	Jun. 2014 & Jun. 2013
The Honorable Mention, The Mathematical Contest in Modeling (MCM)	Feb. 2014

## INVITED TALKS

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### Digital Twin for Future Mobility

- IEEE 18<sup>th</sup> International Conference on Intelligent Environments (IE2022), Biarritz, France, Jun. 2022

### Mobility Digital Twin: An AI-Based Data-Driven Vehicle-Edge-Cloud Framework

- NSF Workshop: The Frontiers of Artificial Intelligence-Empowered Methods and Solutions to Urban Transportation Challenges, Seattle, WA, Jun. 2022

### The Role of Digital Twins in Connected and Automated Vehicles

- ASCE International Conference on Transportation & Development (ICTD), Seattle, WA, Jun. 2022

### **Mobility Digital Twin for Connected Vehicles and Edge/Cloud Computing**

- Design, Automation, and Test in Europe Conference (DATE 2022), Mar. 2022

### **Mobility Digital Twin for Connected and Automated Vehicles**

- 25<sup>th</sup> COTA Annual Winter Symposium, Washington D.C., Jan. 2022

### **Mobility Digital Twin with Connected Vehicles and Cloud Computing**

- Columbia University NSF Project Meeting, Dec. 2021

### **Cooperative Motion Planning and Control at Ramp Merging: A Field Experiment**

- 2021 Conference on Control Technology and Applications (CCTA) Workshop, Aug. 2021

### **AI and Transportation Technology - Panel Discussion**

- The ITE Virtual Student Leadership Summit, Feb. 2021

### **A Digital Twin Paradigm: Vehicle-to-Cloud Based Advanced Driver Assistance Systems**

- 23<sup>rd</sup> COTA Annual Winter Symposium, Washington D.C., Jan. 2020

### **Unity3D-Based AV Simulation with V2X Communication and Human-in-the-Loop Integration**

- Automated Vehicles Symposium, Orlando, FL, Jul. 2019

### **Eco-Friendly Applications in Connected and Automated Vehicle Technology**

- University of California, Riverside CE-CERT Open House, Riverside, CA, Oct. 2018

### **Connected Eco-Bus: An Innovative Vehicle Powertrain Eco-Operation System for Efficient Plug-In Hybrid Electric Buses**

- ARPA-E NEXTCAR 2018 Annual Meeting, Southfield, MI, Apr. 2018

### **Connected and Automated Vehicle Research at UCR**

- University of California, Riverside Extension, Riverside, CA, Jan. 2018

### **Developing a Platoon-Wide Eco-Cooperative Adaptive Cruise Control (CACC) System**

- Los Angeles Environmental Forum, San Gabriel, CA, Aug. 2017

### **Distributed Consensus-Based Cooperative Adaptive Cruise Control (CACC) Systems**

- TuSimple Technology Co., Ltd., San Diego, CA, Jul. 2017

## **MEDIA EXPOSURES**

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NCST Partner CE-CERT Takes Eco-Driving Simulator to CES, National Center for Sustainable Transportation, *Jan. 2020*

Testing a Connected Eco-Driving System in Field Trials with Heavy-Duty Trucks, Featured News, Tech Xplore, *Aug. 2019*

Steering into the Future of Connected and Automated Vehicles, UCR News, *Jul. 2019*