

Q1.

$$q_{\lambda}(y, b) \doteq E_{\lambda} \left[ \sum_{k=t+1}^{\infty} (R_k - r(\lambda)) \mid S_t = y, A_t = b \right]$$

$$= E_{\lambda} [R_{t+1} - r(\lambda) + \sum_{k=t+2}^{\infty} (R_k - r(\lambda)) \mid S_t = y, A_t = b]$$

$$= E_{\lambda} [R_{t+1} - r(\lambda) + E_{\lambda} \left[ \sum_{k=t+2}^{\infty} (R_k - r(\lambda)) \mid S_{t+1}, A_{t+1} \right] \mid S_t = y, A_t = b]$$

$$= E_{\lambda} [R_{t+1} - r(\lambda) + E_{\lambda} \left[ \sum_{k=t+2}^{\infty} (R_k - r(\lambda)) \mid S_{t+1}, A_{t+1} \right] \mid S_t = y, A_t = b]$$

(MP)

$$= E_{\lambda} [R_{t+1} - r(\lambda) + q_{\lambda}(y_{t+1}, b_{t+1}) \mid S_t = y, A_t = b]$$

( $q_{\lambda}$  definition)

$$= \sum_{b', y', r} P_{\lambda}(A_t = b', S_t = y', R_{t+1} = r \mid S_t = y) [r - r(\lambda) + q_{\lambda}(y', b')]$$

(LOTUS)

$$= \sum_{y', r} P(y', r \mid y, b) [r - r(\lambda) + \sum_{b'} \lambda(b' \mid y) q_{\lambda}(y', b')]$$

Q2

For the transition  $s, A, R, s'$ , where the action  $A \sim b$  is drawn from policy distribution  $b$ , update the action value like  $b = \pi$  (behavior policy = target policy)

following way:

$$Q(s, A) \leftarrow Q(s, A) + \alpha [R + \gamma \sum_a \pi(a|s') Q(s', a) - Q(s, A)]$$

using greedification such as  $\epsilon$ -greedy.

Q3

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1. Switch line 5 and line 6.
2. Add "Choose  $A'$  from  $S'$  using policy derived from  $Q$ " before line 8.
3. Change line 8 with  
" $Q(S, A) \leftarrow Q(S, A) + \alpha [R + \gamma Q(S', A') - Q(S, A)]$ "
4. Add " $A \leftarrow A'$ " to line 9.

Q4

$$\begin{aligned}
& E_{A \sim b} [p(A|S) (R + rV(S') - V(S)) \mid S=s] \\
&= \sum_{a, s', r} P_b(A=a, S'=s', R=r \mid S=s) p(a|s) (r + rV(s') - V(s)) \\
&= \sum_{a, s', r} b(a|s) p(s', r \mid s, a) \frac{\pi(a|s)}{b(a|s)} (r + rV(s') - V(s)) \\
&= \sum_{a, s', r} p(s', r \mid s, a) \pi(a|s) (r + rV(s') - V(s)) \\
&= E_{A \sim \pi} [R + rV(S') - V(S) \mid S=s]
\end{aligned}$$

On the other hand,

$$E_{A \sim b} [V(S) \mid S=s] = V(s)$$

Therefore,  $E_{A \sim b} [V(S) \mid S=s] = S_{A \sim \pi} [V(S) \mid S=s]$ .

Q5

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$$\begin{aligned}
 \frac{\partial g(a)}{\partial a} &= g(a)(1-g(a)) \\
 &= \frac{1}{1+e^a} \left( 1 - \frac{1}{1+e^a} \right) \\
 &= \frac{1}{1+e^a} \times \frac{e^{-a}}{1+e^{-a}} = \frac{e^{-a}}{(1+e^{-a})^2}
 \end{aligned}$$

$$g(0) = \frac{1}{1+e^0} = \frac{1}{2}$$

$$\frac{\partial \hat{y}_k}{\partial b_{k,j}} = x_j = g(\psi_j) = \frac{1}{1+e^{-\psi_j}}$$

$$\begin{aligned}
 \frac{\partial \hat{y}_k}{\partial A_{i,j}} &= b_{k,i} \frac{\partial x_i}{\partial A_{i,j}} = b_{k,i} \frac{\partial g(\psi_i)}{\partial \psi_i} s_j \\
 &= b_{k,i} (g(\psi_i)(1-g(\psi_i))) s_j \\
 &= b_{k,i} \left( \frac{1}{1+e^{-\psi_i}} \times \frac{e^{-\psi_i}}{1+e^{-\psi_i}} \right) s_j \\
 &= b_{k,i} \cdot \frac{e^{-\psi_i}}{(1+e^{-\psi_i})^2} \cdot s_j
 \end{aligned}$$

$$\psi_i = \sum_l A_{i,l} s_l = 0$$

$$\frac{\partial \hat{y}}{\partial b_{k,j}} = g(\psi_i) = g(0) = \frac{1}{2}$$

And  $B_{k,i} = 0$

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$$\frac{\partial \hat{y}_k}{\partial A_{i,j}} = B_{k,i} g'(\psi_i) S_j = 0 \times (g(\psi_i) \times (1 - g(\psi_i))) S_j$$

$$= 0 \times \left( \frac{1}{2} \times \left( 1 - \frac{1}{2} \right) \right) S_j$$

$$= 0 \times \frac{1}{4} \times S_j = 0$$

Q6.

Vicky zhu

a) Sarsa :

$$Q(S,A) \leftarrow Q(S,A) + \alpha [R + \gamma Q(S',A') - Q(S,A)]$$

$$\begin{aligned} B: Q(S,A) &\leftarrow 1.5 + 0.2 [0 + 0.9 \times 1.5 - 1.5] \\ &= 1.5 + 0.2 [1.35 - 1.5] \\ &= 1.5 + 0.2 \times (-0.15) \\ &= 1.47. \end{aligned}$$

$$\begin{aligned} D: Q(S,A) &\leftarrow 1.5 + 0.2 [4 + 0.9 \times 0 - 1.5] \\ &= 1.5 + 0.2 [4 + 0 - 1.5] \\ &= 1.5 + 0.2 \times 2.5 \\ &= 1.5 + 0.5 \\ &= 2. \end{aligned}$$

b)

$$\begin{aligned} B: Q(s, A) &\leftarrow 1.47 + 0.2[0 + 0.9 \times 2 - 1.47] \\ &= 1.47 + 0.2[1.8 - 1.47] \\ &= 1.536 \end{aligned}$$

$$\begin{aligned} D: Q(s, A) &\leftarrow 2 + 0.2[4 + 0.9 \times 0 - 2] \\ &= 2 + 0.2[4 - 2] \\ &= 2 + 0.2 \times 2 \\ &= 2 + 0.4 \\ &= 2.4 \end{aligned}$$