18.06 - Recitation 4

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1 Lecture review

1.1 Linear systems

There are four possibilities for a linear system Ax = b:

- 1. Ax = b has a unique solution for all b. This can only happen if r = m = n (full column and row rank)
- 2. Ax = b has either a unique solution or no solution, depending on b. This can only happen if r = n, but m > n (full column rank, not full row rank).
- 3. Ax = b has infinitely many solutions for all b. This can only happen if r = m, but n > m (full row rank, not full column rank).
- 4. Ax = b has either no solution or infinitely many solutions, depending on b. This can only happen if $r < \min(m, n)$ (neither full column nor row rank).

1.2 Four fundamental subspaces

- 1. Let $A = U\Sigma V^T$ be the full SVD for the $m \times n$ matrix A.
- 2. The **column space** C(A) is the set of vectors in \mathbb{R}^m which are spanned by the columns of A. Equivalently, it is all vectors $u \in \mathbb{R}^m$ that can be written u = Ax for any $x \in \mathbb{R}^n$. The first r columns of U are a basis for C(A).
- 3. The **row space** row $(A) = C(A^T)$ is the set of vectors in \mathbb{R}^n which are spanned by the rows of A. Equivalently, it is all vectors $v \in \mathbb{R}^n$ that can be written $v = A^T x$ for any $x \in \mathbb{R}^m$. The first r columns of V are a basis for C(A).
- 4. The **null space** N(A) is the set of vectors in \mathbb{R}^n which satisfy Ax = 0. The last n r columns of V are a basis for N(A).
- 5. The **left null space** $N(A^T)$ is the set of vectors in \mathbb{R}^m which satisfy $A^Tx = 0$. The last m r columns of U are a basis for $N(A^T)$.
- 6. Vectors in C(A) are orthogonal to vectors in $N(A^T)$. Vectors in $C(A^T)$ are orthogonal to vectors in N(A).

2 Problems

Problem 1.

Let A be an $m \times m$ invertible matrix. Describe in words as much as you can about the null space and left nullspace (e.g. dimension, possibly a basis, etc.) of the following:

- (a) The matrix A
- (b) The matrix $B = \begin{pmatrix} A \\ A \end{pmatrix}$
- (c) The matrix $C = \begin{pmatrix} A & 2A \end{pmatrix}$
- (d) The matrix $D = \begin{pmatrix} I & A \end{pmatrix}$

Problem 2.

- (a) If AB = 0, then the columns of B are in which fundamental subspace of A? The rows of A are in which fundamental subspace of B? With AB = 0, why can't A and B be 3×3 matrices of rank 2?
- (b) If Ax = b has a solution and $A^Ty = 0$, then which of the following is true: $y^Tx = 0$ or $y^Tb = 0$?
- (c) If $A^TAx = 0$, then why must Ax = 0? Why does this result mean that $N(A^TA) = N(A)$?

Problem 3.

Write down the complete solution to the following linear systems:

1. $A_1 x = b_1$, where:

$$A_{1} = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}, b_{1} = \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \text{ and the full of SVD of } A_{1} \text{ is}$$

$$A_{1} = \begin{pmatrix} 0 & 0.4082 & -0.7071 & 0.5774 \\ 0 & 0.8165 & 0 & -0.5774 \\ 0 & 0.4082 & 0.7071 & 0.5774 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 2.0000 & 0 & 0 \\ 0 & 1.7321 & 0 \\ 0 & 0 & 1.0000 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0.7071 & -0.7071 \\ 0 & 0.7071 & 0.7071 \\ 1.0000 & 0 & 0 \end{pmatrix}^{T}$$

2. $A_2x = b_2$, where

$$A_2 = \begin{pmatrix} 2 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \\ 0 & 1 & 0 & -1 \end{pmatrix}, b_2 = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}, \text{ and the full of SVD of } A_2 \text{ is}$$

$$A_2 = \begin{pmatrix} 0.8411 & -0.3507 & -0.4117 \\ 0.5332 & 0.4105 & 0.7397 \\ 0.0903 & 0.8417 & -0.5323 \end{pmatrix} \begin{pmatrix} 2.8110 & 0 & 0 & 0 \\ 0 & 1.5773 & 0 & 0 \\ 0 & 0 & 0.7813 & 0 \end{pmatrix} \begin{pmatrix} 0.7881 & -0.1844 & -0.1072 & 0.5774 \\ 0.5211 & 0.5716 & -0.2616 & -0.5774 \\ 0.1897 & 0.2603 & 0.9467 & -0.0000 \\ 0.2671 & -0.7560 & 0.1543 & -0.5774 \end{pmatrix}^{T}$$

3. $A_3x = b_3$, where

$$A_{3} = \begin{pmatrix} 1 & 0 & -1 \\ 1 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix}, b_{3} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \text{ and the full of SVD of } A_{3} \text{ is}$$

$$A_{3} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 1.7321 & 0 & 0 \\ 0 & 1.4142 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0.5774 & 0.7071 & 0.4082 \\ 0.5774 & -0.0000 & -0.8165 \\ 0.57747 & -0.7071 & 0.4082 \end{pmatrix}^{T}$$

Problem 4.

Construct matrices with each of the following properties, or explain why it is impossible:

- 1. Column space contains $\begin{pmatrix} 1\\1\\0 \end{pmatrix}$, $\begin{pmatrix} 0\\0\\1 \end{pmatrix}$, and row space contains $\begin{pmatrix} 1\\2 \end{pmatrix}$, $\begin{pmatrix} 2\\5 \end{pmatrix}$.
- 2. Column space has basis $\begin{pmatrix} 1\\1\\3 \end{pmatrix}$, nullspace has basis $\begin{pmatrix} 3\\1\\1 \end{pmatrix}$.
- 3. Dimension of nullspace = 1 + dimension of left nullspace.
- 4. Nullspace contains $\binom{1}{3}$, column space contains $\binom{3}{1}$.
- 5. Row space = column space, null space \neq left null space.

Problem 5. (Challenge problem)

Write down the QR factorization of an arbitrary 3×3 upper triangular matrix:

$$A = \begin{pmatrix} a & b & c \\ 0 & d & e \\ 0 & 0 & f \end{pmatrix}.$$

What conditions are there on possibly a, b, c, d, e and/or f for the QR to exist? How does this generalize to an arbitrary $n \times n$ upper triangular matrix?¹

¹Some hints to get started: Are the columns of A linearly independent? What is the column space of A? Can you identify an orthonormal basis for C(A)?