

## Week 3 Review Session

*Focus: rules of matrix multiplication, orthogonal matrices, rotation matrices.*

1. When you multiply an  $n \times m$  matrix by an  $m \times l$  matrix, what are the dimensions of the resulting matrix?

**Solution:**

2. *Zero scalar vs zero vector vs zero matrix.* Let  $A$  be an  $n \times m$  matrix,  $B$  be an  $m \times l$  matrix,  $v$  be a column  $m$ -vector and  $r$  be a row  $m$ -vector, for example:

$$A = \begin{pmatrix} 1 & 2 & 0 \\ 1 & 0 & 2 \end{pmatrix}, B = \begin{pmatrix} 2 & -2 \\ -1 & 1 \\ -1 & 1 \end{pmatrix}, v = \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix}, r = (1 \quad 2 \quad 0).$$

In this case, products  $AB$ ,  $Av$  and  $rv$  are all zero, so we can write  $AB = 0$ ,  $Av = 0$ ,  $rv = 0$ . But would it make sense to write  $AB = Av = rv = 0$ ? Why / why not? Do the results of those operations belong to the same vector space?

**Solution:**

3. Answer the following questions. Provide explanations.
  - a) Is the identity matrix always square? (By the way it can be stored with one parameter.)
  - b) Do rectangular matrices have inverses?
  - c) Do all square matrices have inverses?
  - d) What is the condition for a  $2 \times 2$  matrix to have inverse?

**Solution:**

4. *Parallel planes.*

- a) Consider the set of points  $\begin{pmatrix} x \\ y \\ z \end{pmatrix}$  in  $\mathbb{R}^3$  satisfying condition  $2x + 3y + 4z = 0$ . Describe this geometric object. Find a normal vector to it.
- b) What if we consider the equation  $2x + 3y + 4z = 1$ ? Why is the normal the same?

**Solution:**

5. *Row and column operations as matrix multiplication. (Inspired by problem 2.4.8 from Strang.)*  
Consider the following matrices:

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}, B = \begin{pmatrix} 2 & 0 \\ 0 & -1 \end{pmatrix}, C = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, D = \begin{pmatrix} 0 & 1 \\ 0 & -1 \end{pmatrix}.$$

How is each row of  $BA$ ,  $CA$ ,  $DA$  related to the rows of  $A$ ? How is each column of  $AB$ ,  $AC$ ,  $AD$  related to the columns of  $A$ ?

**Solution:**

6. *(Problem 2.4.5 from Strang.)* Compute  $A^2$  and  $A^3$ . Make a prediction for  $A^5$  and  $A^n$ :

a)  $A = \begin{pmatrix} 1 & b \\ 0 & 1 \end{pmatrix};$

b)  $A = \begin{pmatrix} 2 & 2 \\ 0 & 0 \end{pmatrix}.$

**Solution:**

7. *Binomial formula for matrices. Matrices do not commute. (Problem 2.4.6 from Strang.)* Show that  $(A+B)^2$  is different from  $A^2 + 2AB + B^2$  when

$$A = \begin{pmatrix} 1 & 2 \\ 0 & 0 \end{pmatrix}, B = \begin{pmatrix} 1 & 0 \\ 3 & 0 \end{pmatrix}.$$

Write down the correct rule:  $(A+B)^2 = A^2 + \dots + B^2$ . Can you generalize the rule to  $(A+B)^n$ ?

**Solution:**

8. *(Problem 2.4.7 from Strang.)* Is the following true or false? Give counterexamples when false. Matrices  $A$ ,  $B$  and  $C$  are such that all the operations are well-defined.

- a) If columns 1 and 3 of  $B$  are the same, then so are columns 1 and 3 of  $AB$ .
- b) If rows 1 and 3 of  $B$  are the same, then so are rows 1 and 3 of  $AB$ .
- c) If rows 1 and 3 of  $A$  are the same, then so are rows 1 and 3 of  $ABC$ .
- d)  $(AB)^2 = A^2B^2$ .

**Solution:**

9. *Orthogonal matrices.* Find  $A^T A$  if the columns of  $A$  are unit vectors, all mutually perpendicular (in this situation, we say that the vectors are *orthonormal*). What if we ask that the rows of  $A$  are orthonormal?

**Solution:**

10. *Defining a matrix by its image. Rotation matrices.* Work out these questions for  $2 \times 2$  matrices.

- a) If we want a matrix  $A$  to send vector  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$  to twice itself and vector  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$  to  $\begin{pmatrix} a \\ b \end{pmatrix}$ , then what are the matrix entries of  $A$ ?
- b) If we want a matrix  $B$  to send vector  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$  to  $\begin{pmatrix} a \\ b \end{pmatrix}$  and vector  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$  to twice itself, then what are the matrix entries of  $B$ ?
- c) What are the coordinates of vectors  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$  and  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$  after we rotate them by the angle  $\theta$ ?
- d) How do you write a matrix that rotates every vector in the plane by the angle  $\theta$ ?
- e) Is the matrix in the previous part orthogonal?