

Exotic Options (Review)

$$V(t) = \tilde{\mathbb{E}}(e^{-r(T-t)} V(T) | \mathcal{F}(t))$$

European: $V(T) = \max(S(T) - K, 0)$ \$S(T) > K\$
"\$n" < d_-\$

$$V(t) = S(t) N(d_+) - K e^{-r(T-t)} N(d_-)$$

Knockout (up & out)

$$V(T) = \max(S(T) - K, 0) \quad \text{iff} \quad S(0) e^{\sigma \tilde{W}(T)} \leq B$$

$$V(T) = (S(0) \exp(\sigma \tilde{W}(T) - K)) \cdot \mathbb{1}_{\{\tilde{W}(T) \geq k, \tilde{M}(T) \leq b\}}$$

$$k = \frac{1}{\sigma} \log \frac{K}{S(0)}, \quad b = \frac{1}{\sigma} \log \frac{B}{S(0)}$$

$$\tilde{\mathbb{P}}(\tilde{M}(T) \leq m, \tilde{W}(T) \leq w) = \int_{-\infty}^w \int_{-\infty}^m e^{xy - \frac{1}{2}x^2T - \frac{1}{2T}(ym-w)^2} \cdot \frac{d(m-w)}{T\sqrt{2\pi T}} dm dw$$

$$\begin{aligned} \Rightarrow V(t) &= S(t) (N(d_{1+}) - N(d_{2+})) \\ &\quad - e^{-r(T-t)} K (N(d_{1-}) - N(d_{2-})) \\ &\quad - B \left(\frac{S(t)}{B} \right)^{-\frac{2r}{\sigma^2}} (N(d_{3+}) - N(d_{4+})) \\ &\quad + e^{-r(T-t)} K \left(\frac{S(t)}{B} \right)^{-\frac{2r}{\sigma^2} + 1} (N(d_{3-}) - N(d_{4-})) \end{aligned}$$

$$d_{1\pm} = \frac{t}{\sigma\sqrt{T-t}} \left(\log \frac{S(t)}{K} + (r \pm \frac{1}{2}\sigma^2)(T-t) \right)$$

$$d_{2\pm} = \frac{t}{\sigma\sqrt{T-t}} \left(\log \frac{S(t)}{B} + (r \pm \frac{1}{2}\sigma^2)(T-t) \right)$$

$$d_{3\pm} = \frac{t}{\sigma\sqrt{T-t}} \left(\log \frac{B^2}{KS(t)} + (r \pm \frac{1}{2}\sigma^2)(T-t) \right)$$

$$d_{4\pm} = \frac{t}{\sigma\sqrt{T-t}} \left(\log \frac{B}{S(t)} + (r \pm \frac{1}{2}\sigma^2)(T-t) \right)$$

Look Back:

$$V(T) = \max_{t \in [0, T]} S(t) - S(T)$$

$$= S(0) \exp(\sigma \tilde{W}(t)) - S(T)$$

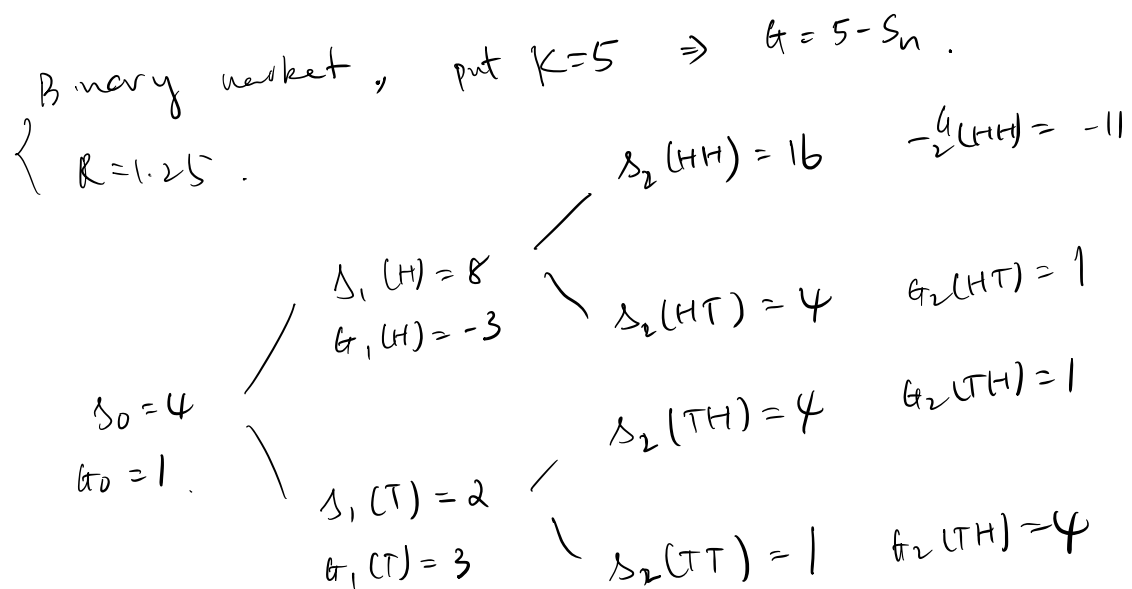
$$V(t) = \tilde{\mathbb{E}}(e^{-r(T-t)} V(T) \mid \mathcal{F}(t))$$

$$V(t, y) \quad y(t) = \max_{u \in [0, t]} S(u)$$

$$= \left(1 + \frac{\sigma^2}{2r}\right) S(t) N(d_+) + e^{-r(T-t)} y N(-d_-) - \frac{\sigma^2}{2r} e^{-r(T-t)} \left(\frac{y}{S(t)}\right)^{\frac{2r}{\sigma^2}} S(t) N(+d_-) - S(t);$$

$$d_{\pm} = \frac{1}{\sigma \sqrt{T-t}} \left(\log \frac{S(t)}{y} + (r \pm \frac{1}{2} \sigma^2) (T-t) \right)$$

American Options



Stopping time