

# Algorithms and Data Structures



**COMP261**

**Articulation Points 2: Implementation**

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# Outline

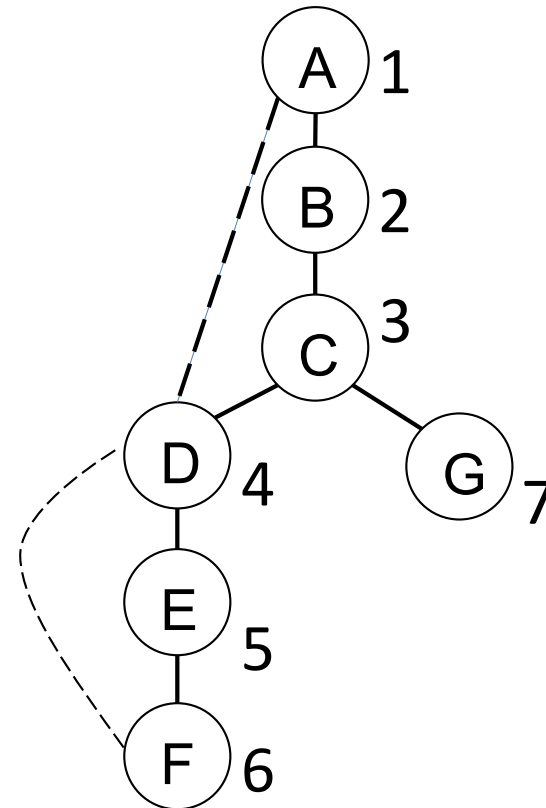
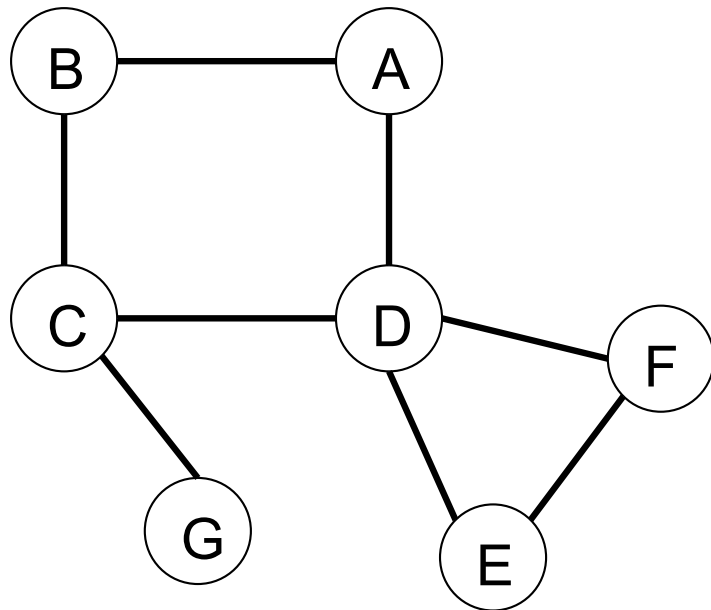
- Idea revisited
- Implementation of the AP algorithm
  - Recursive version
  - Iterative version

# Idea Revisited

- **Articulation point**: a node whose removal will disconnect the graph
- **Brute force search**
  - For each node, run a DFS starting from one neighbour (**one sub-tree**)
  - If **all the nodes are visited (one sub-tree)**, then the node is **not an articulation point**. Otherwise, it is an articulation point.
  - **Complexity:  $O(n \cdot e)$** :  $n$  is number of nodes,  $e$  is number of edges
  - **Very inefficient**, many checks are unnecessarily repeated
- A new efficient algorithm with **a single DFS**
  - Assign **count numbers** to each node during DFS (larger count numbers are children, smaller are parents)
  - Check for **root node**: **number of sub-trees**
  - Check for **other nodes**: **alternative path from children to parents**

# Example of Idea

- A single DFS rooted from node A
  - One single DFS to assign count numbers, record the edges that are in the DFS and not in the DFS: (A, D), and (D, F)
  - A is not articulation point: root node, one sub-tree
  - B is not articulation point: all the children can reach parents via (A, D)
  - C is articulation point: no alternative path from G to parents
  - D is articulation point: no alternative path from E, F to parents
  - E, F, G?



# Implementation

- DFS can be implemented by **recursion** and **iteration**
  - **Recursion**: easy to design/write, hard to debug
  - **Iteration**: easy to debug, hard to design/write
- We also design these two versions of the AP algorithm

```
RecDFS(node) {  
    if (node is unvisited) {  
        set node as visited;  
        for (each neighbour of node) {  
            RecDFS(neighbour);  
        }  
    }  
}
```

```
IterDFS(node) {  
    Initialise fringe as an empty stack;  
    Add node into fringe;  
    while (fringe is not empty) {  
        get&remove n* from the fringe;  
        set n* as visited;  
        add all unvisited neighbour of n* into fringe;  
    }  
}
```

# Recursive AP Algorithm

Initialise count number of all nodes as  $\text{count}(\text{node}) = \infty$ , meaning all nodes are unvisited;  
Initially,  $\text{APs} = \{\}$ , that is, no articulation point is found;  
Randomly select a node as the root node, set  $\text{count}(\text{root}) = 0$ ,  $\text{numSubTrees} = 0$ ;

```
for (each neighbour of root) {  
    if (count(neighbour) =  $\infty$ ) {  
        recArtPts(neighbour, 1, root); // recursive DFS for the neighbour  
        numSubTrees ++;  
    }  
  
    if (numSubTrees > 1) then add root into APs;  
}
```

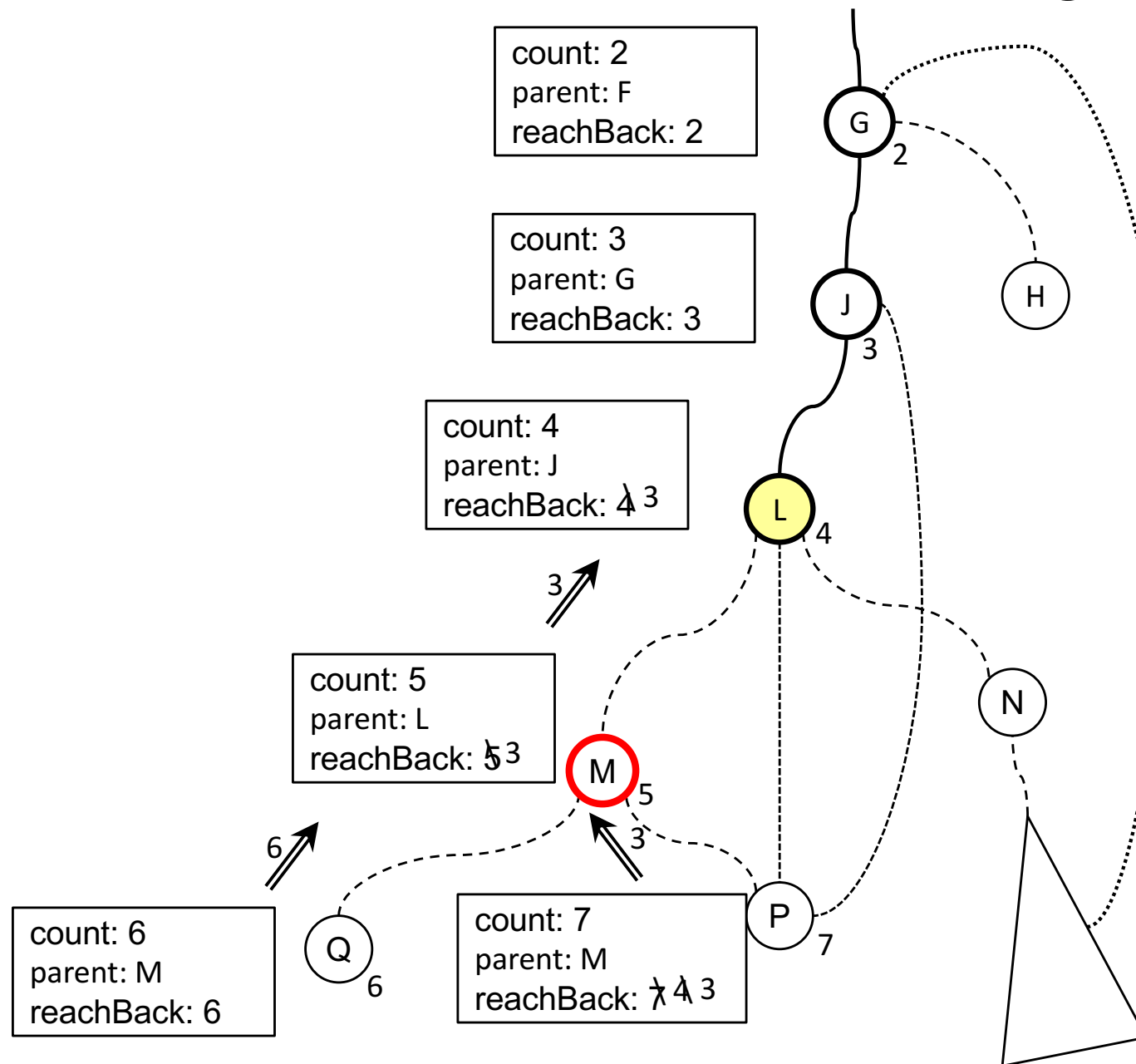
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```
recArtPts(node, count, parent) {  
    ...  
}
```

# Recursive AP Algorithm

```
recArtPts(node, count, parent) {  
    count(node) = count;  
    // store the minimum count number the node can reach back via alternative path  
    reachBack = count;  
    for (each neighbour of node other than parent) {  
        // case 1: direct alternative path: neighbour is visited before  
        if (count(neighbour) <  $\infty$ )  
            reachBack = min(count(neighbour), reachBack);  
        // case 2: indirect alternative path: neighbour is an unvisited child in the same sub-tree  
        else {  
            // calculate alternative paths of the child, which can also be reached by itself  
            childReach = recArtPts(neighbour, count+1, node);  
            reachBack = min(childReach, reachBack);  
            // no alternative path from neighbour to any parent  
            if (childReach >= count) then add node into APs;  
        }  
    }  
    return reachBack;  
}
```

# Example of Recursive AP Algorithm





# Iterative AP Algorithm

Initialise  $\text{count}(\text{node}) = \infty$ ,  $\text{APs} = \{\}$ ;

Randomly select a node as the root node, set  $\text{count}(\text{root}) = 0$ ,  $\text{numSubTrees} = 0$ ;

**for** (each neighbour of root) {

**if** ( $\text{count}(\text{neighbour}) = \infty$ ) {

iterArtPts(neighbour, 1, root);

$\text{numSubTrees}++$ ;

  }

**if** ( $\text{numSubTrees} > 1$ ) **then** add root into APs;

}

The only difference from  
the recursive version

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iterArtPts(node, count, parent) {

  ...

}

# Iterative AP Algorithm

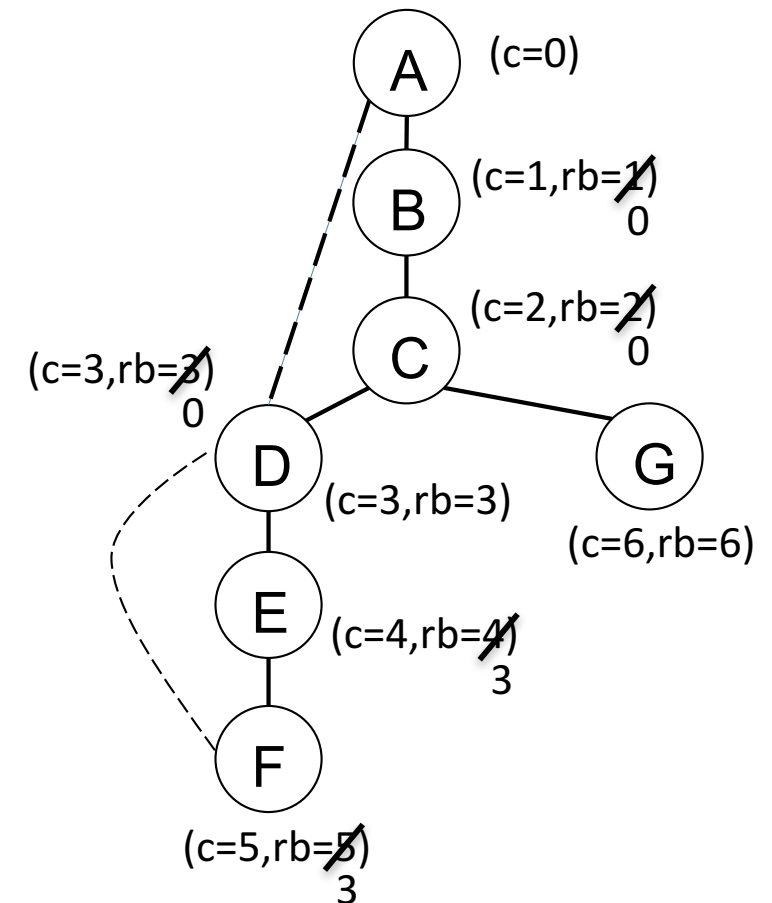
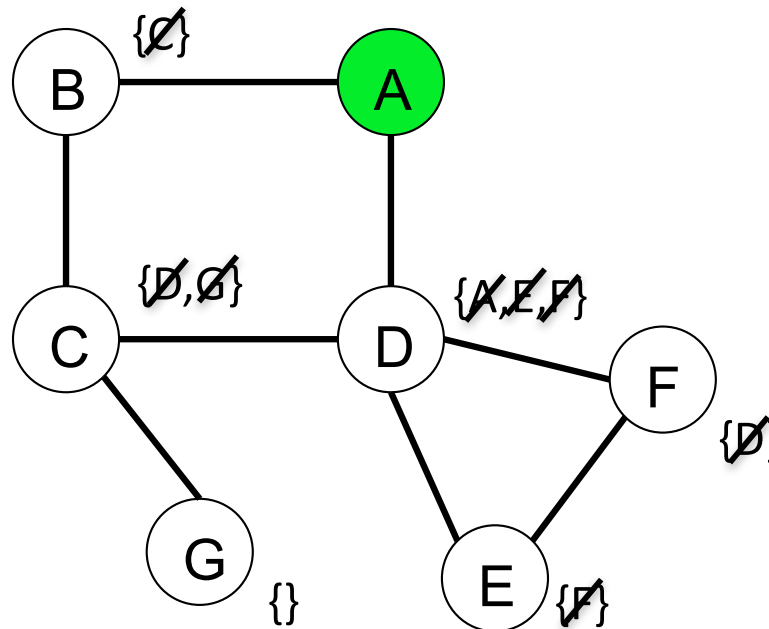
- **Goal:** set/update reachBack of each node in the sub-tree
- For each node, reachBack is set/updated in the following cases:
  - When first visited: reachBack = count
  - When one of its children's reachBack is updated:  
reachBack = min(childReach, reachBack)
  - When all the children have been calculated, update the reachBack of its parent
- Need to update the node information in different stages of DFS
- However, traditional DFS updates node information only once (when visiting the node), and never revisits the node again
- Need a new data structure (modified stack)
  - Last-In-First-Out
  - Traditional stack: pop = get and remove
  - Modified stack: peek = get but not remove

# Iterative AP Algorithm

```
iterArtPts(firstNode, count, root) {  
  Initialise stack as a single element <firstNode, count, root>;  
  repeat until (stack is empty) {  
    peek <n*, count*, parent*> from stack;  
    if (count(n*) =  $\infty$ ) {  
      count(n*) = count, reachBack(n*) = count;  
      children(n*) = all the neighbours of n* except parent*;  
    }  
    else if (children(n*) is not empty) {  
      get a child from children(n*) and remove it from children(n*);  
      if (count(child) <  $\infty$ ) then reachBack(n*) = min(count(child), reachBack(n*));  
      else push <child, count+1, n*> into stack;  
    }  
    else {  
      if (n* is not firstNode) {  
        reachBack(parent*) = min(reachBack(n*), reachBack(parent*));  
        if (reachBack(n*) >= count(parent*)) then add parent* into APs;  
      }  
      remove <n*, count*, parent*> from stack;  
    }  
  }  
}
```

# Example of Iterative AP Algorithm

<B,1,A>
<C,2,B>
<D,3,C>
<E,4,D>
<F,5,E>
<G,6,C>



APs

D	C		
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# Summary

- Two versions of implementing the AP algorithm
  - Recursive
  - Iterative
- DFS can be implemented in two ways
- Recursive is more straightforward to design
- Iterative is more tricky
  - Need to process nodes in different stages
  - A new operation to the fringe: **peek** - process without removing