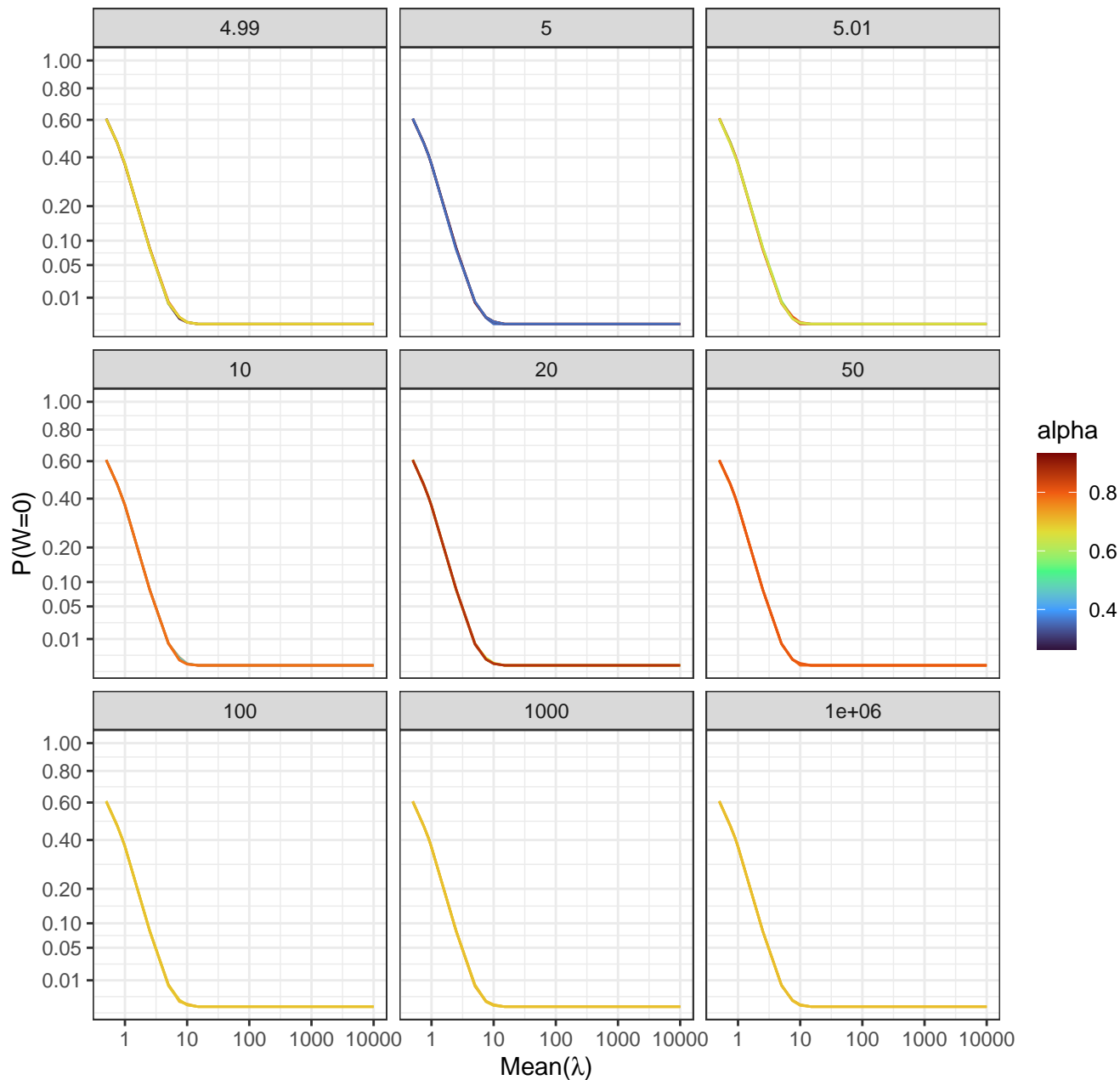
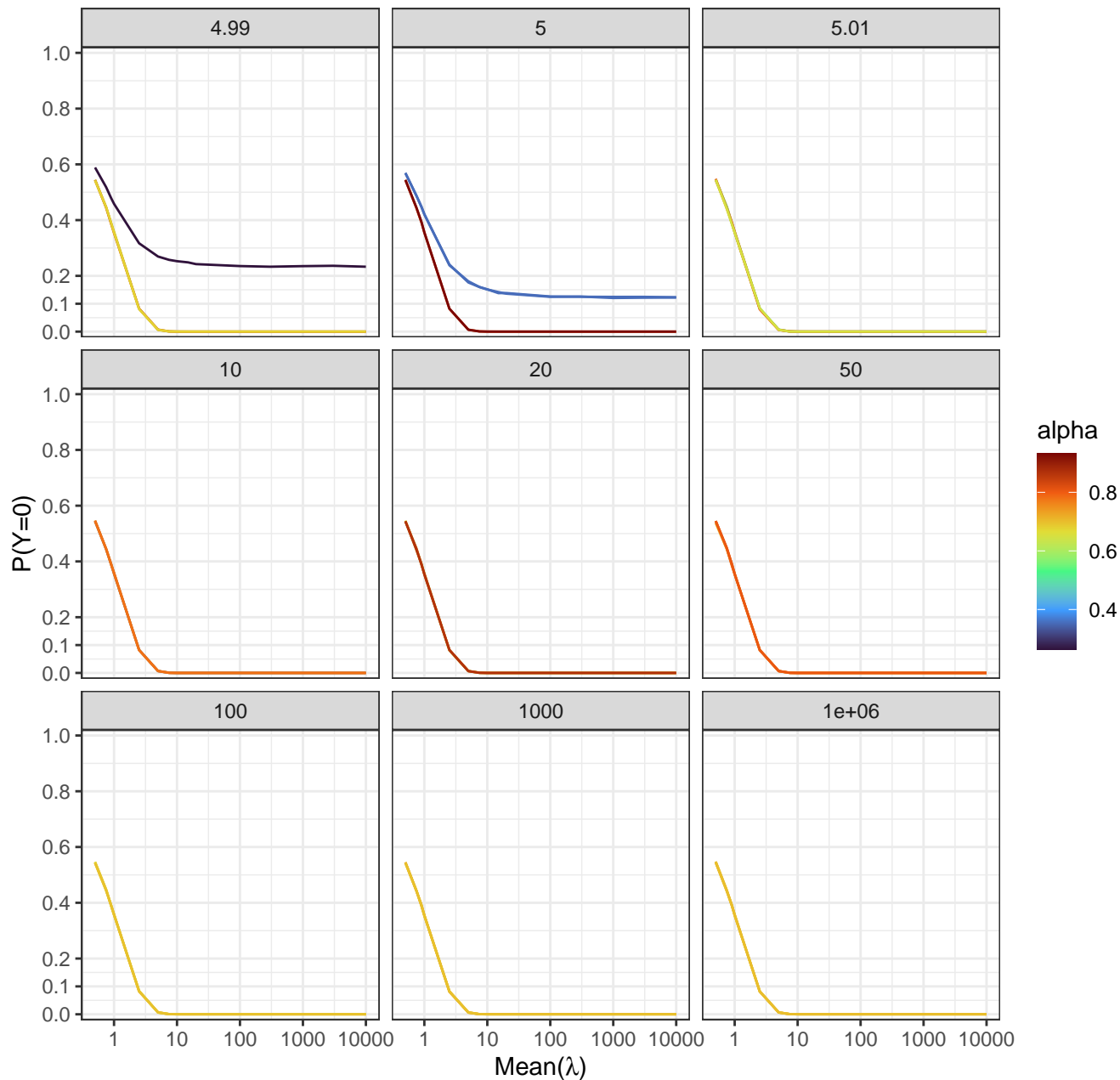
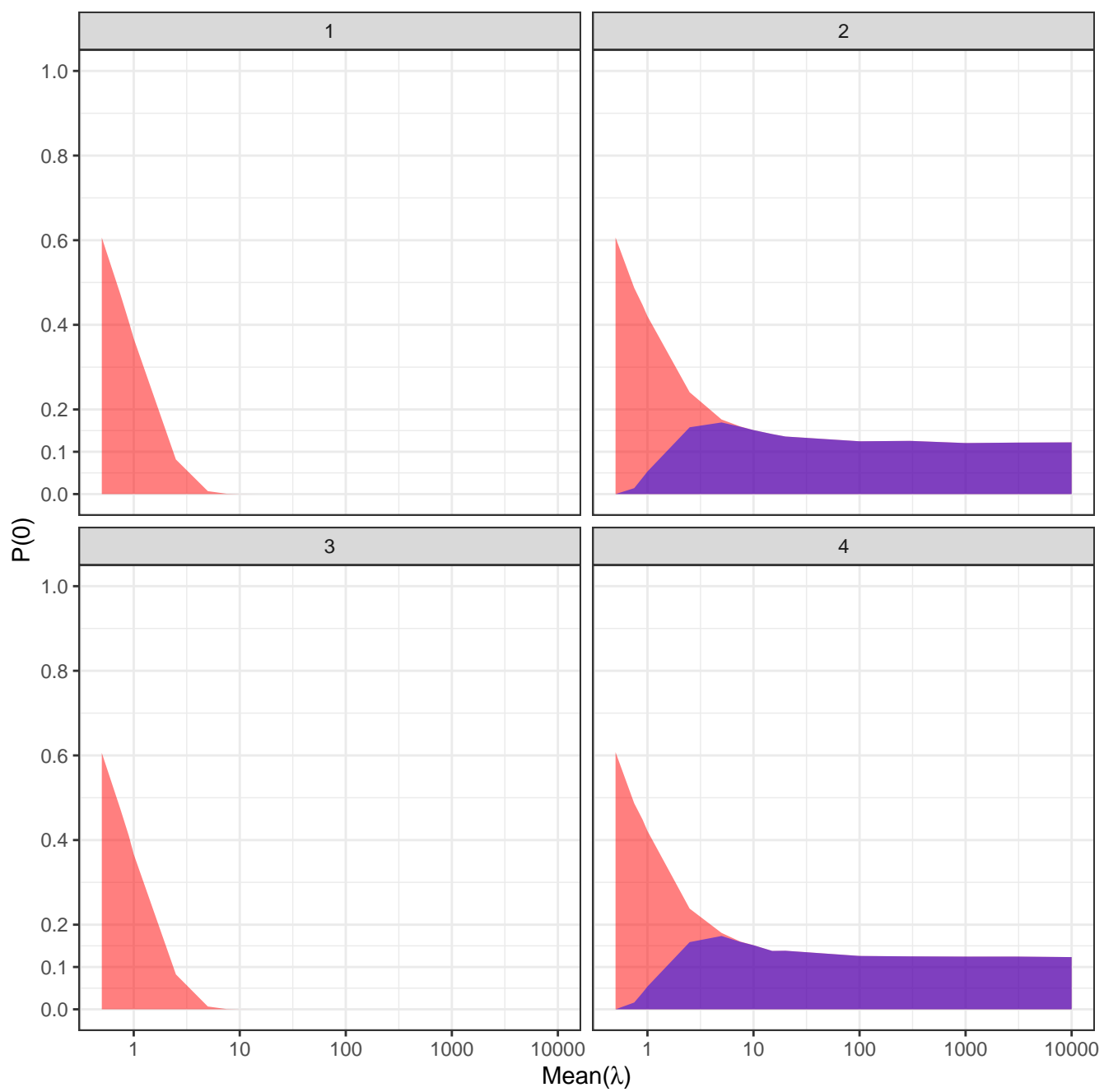
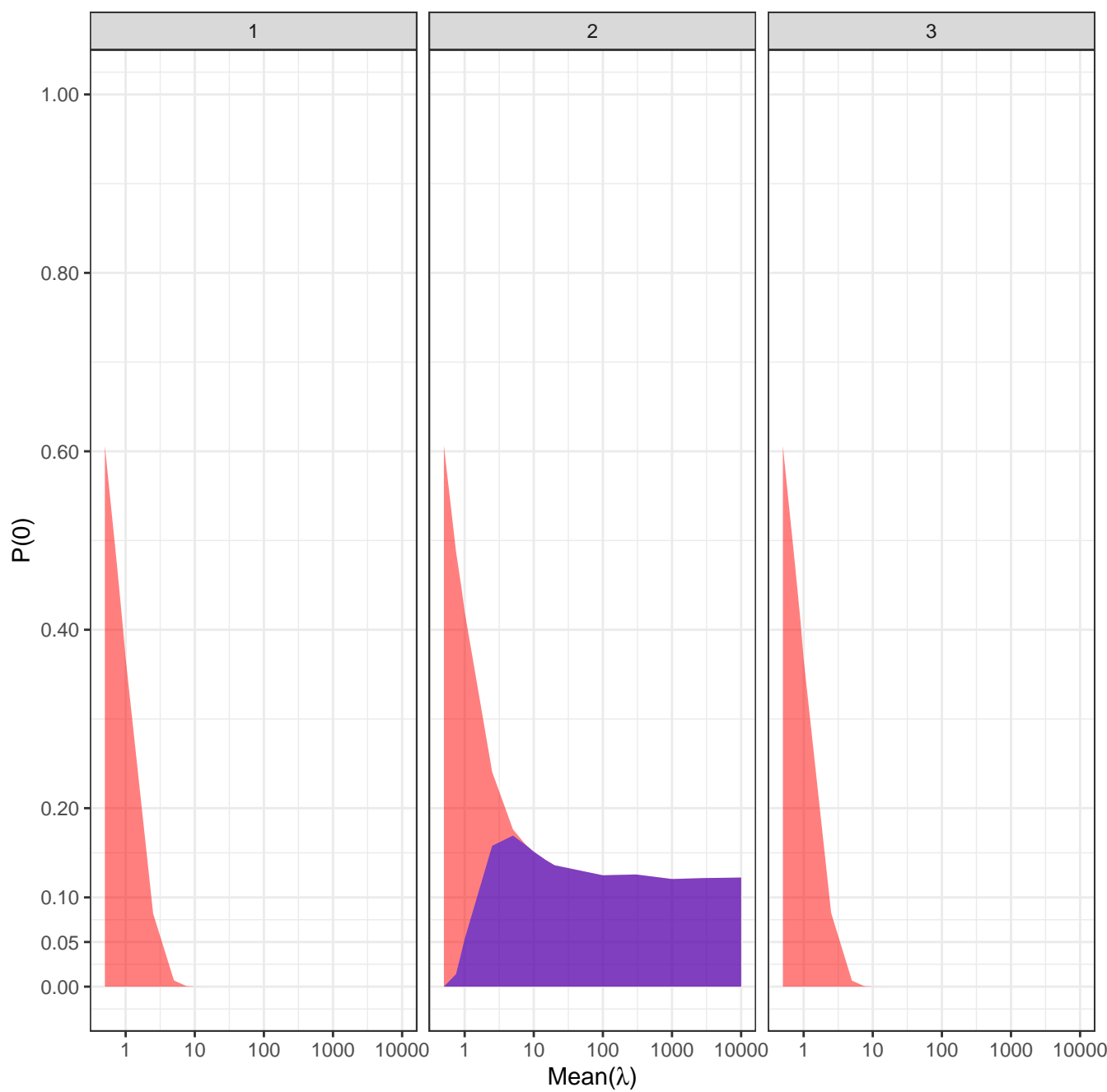


$P(0)$

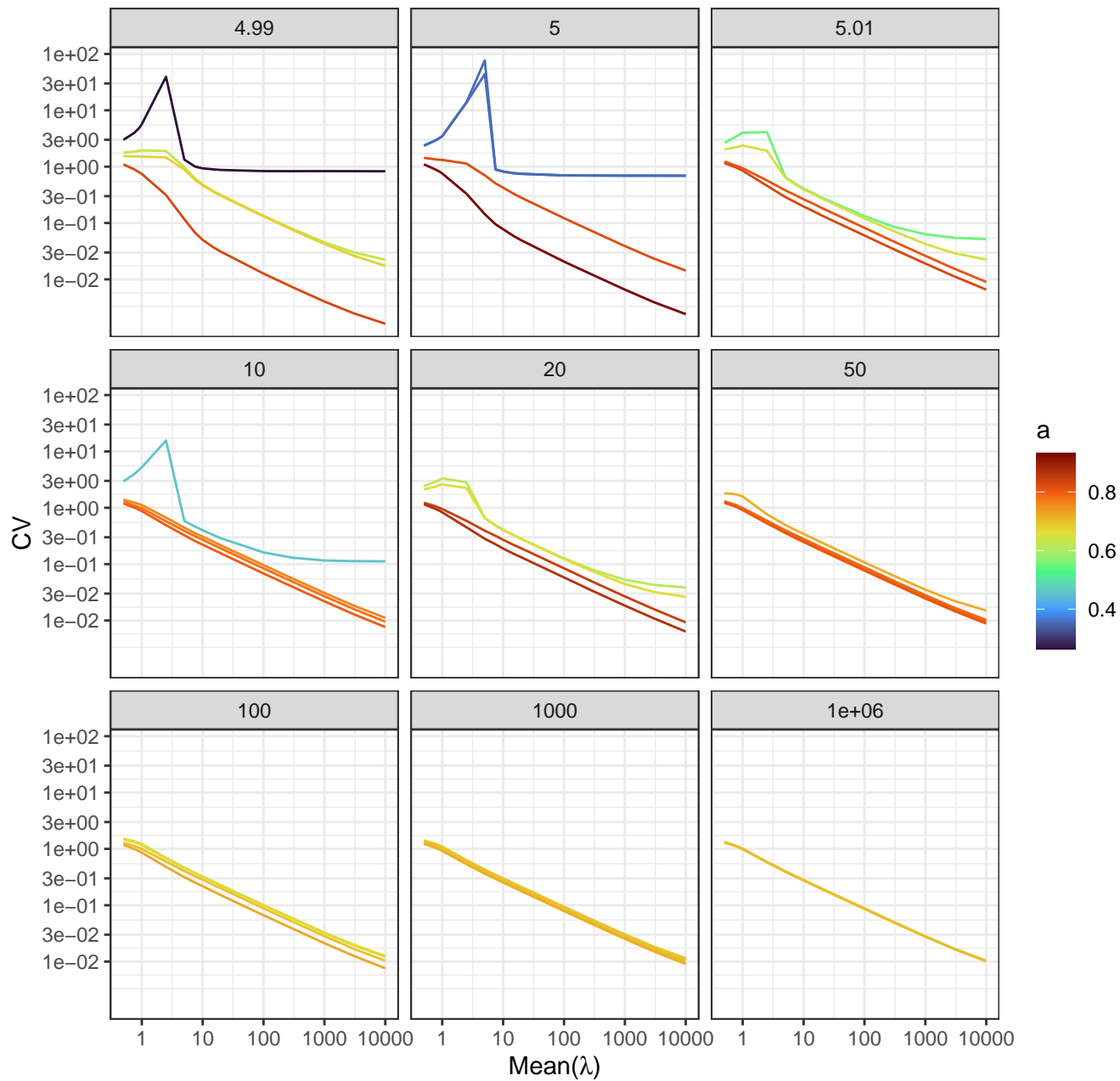


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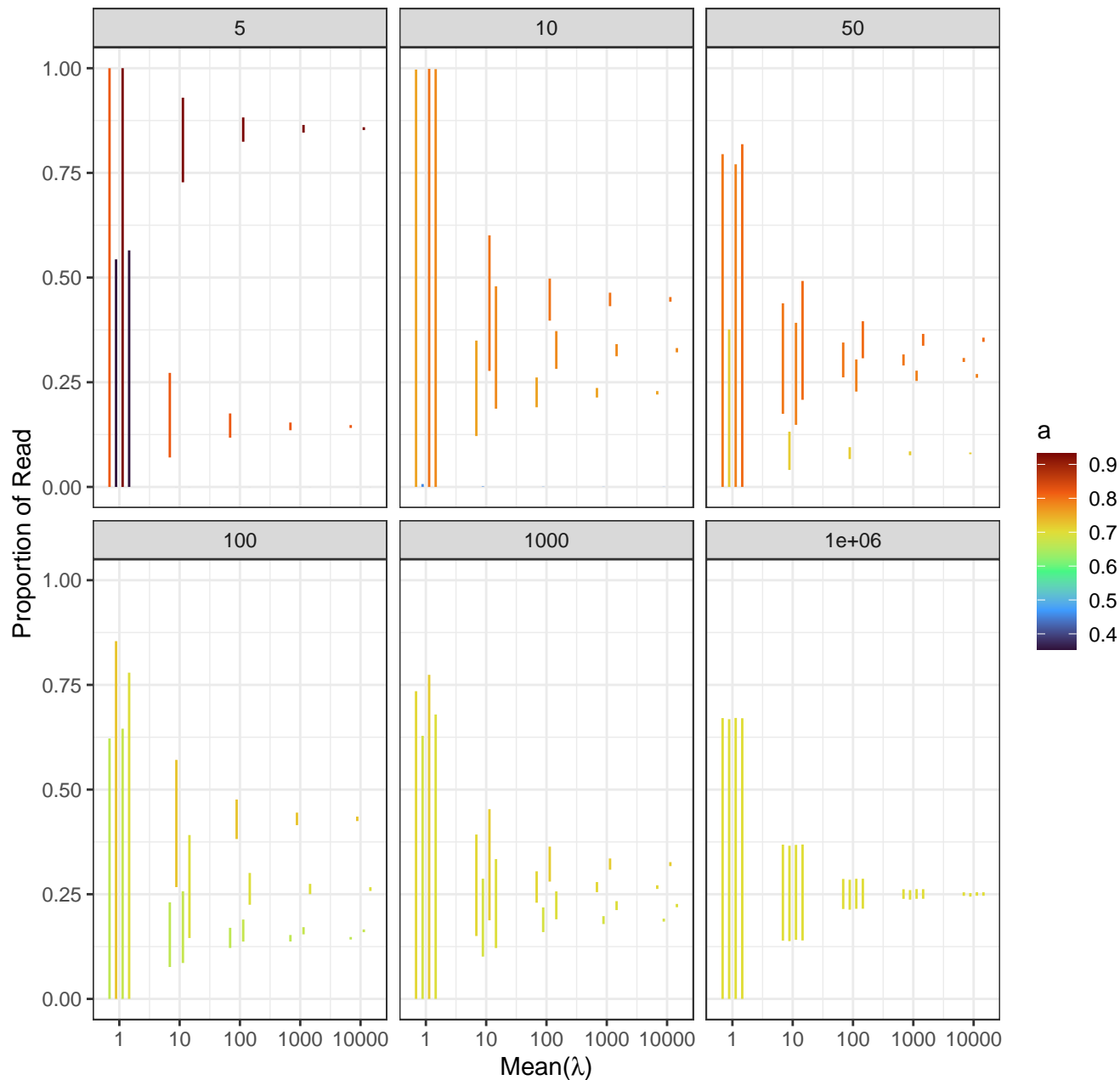




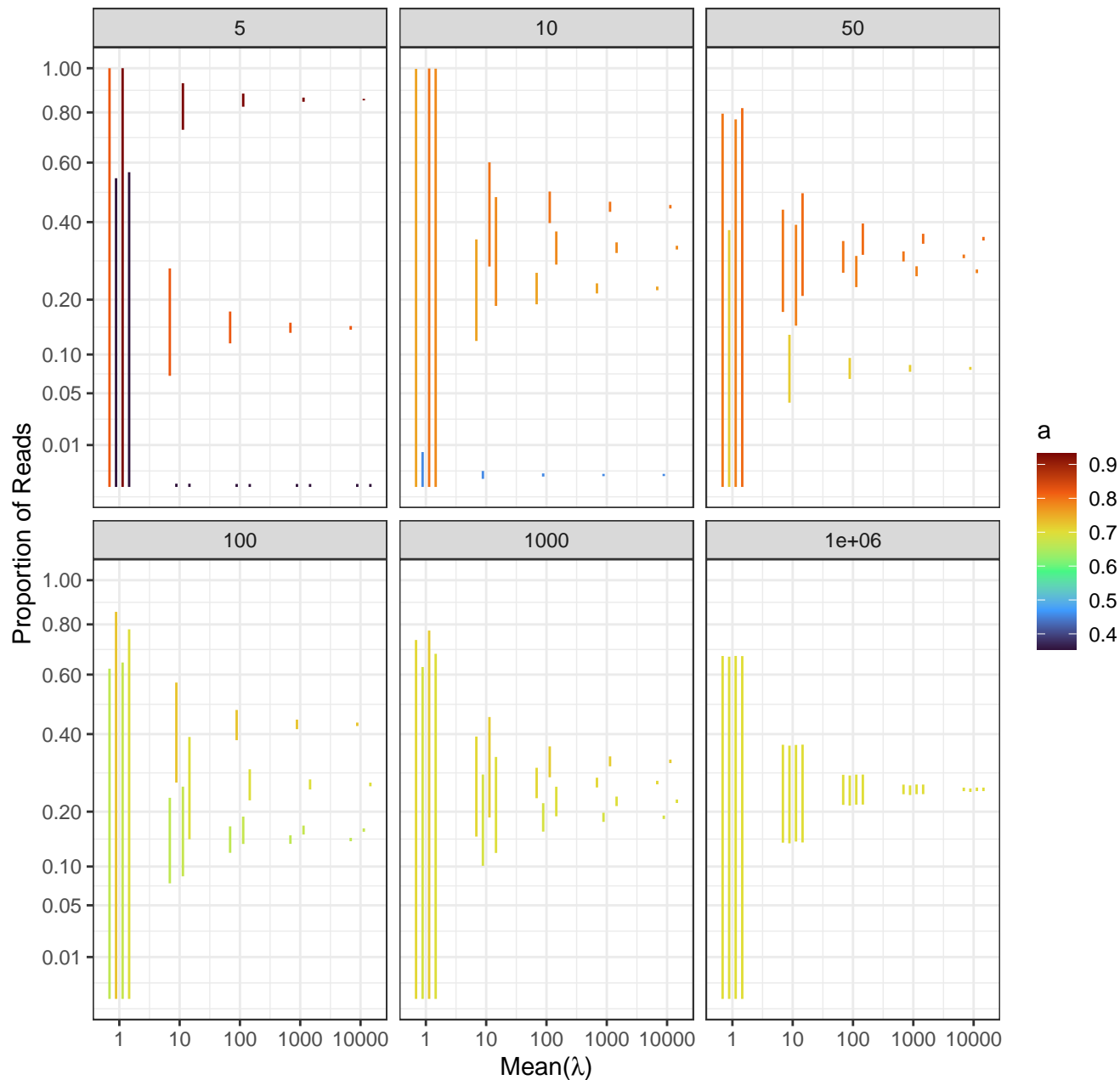
CV



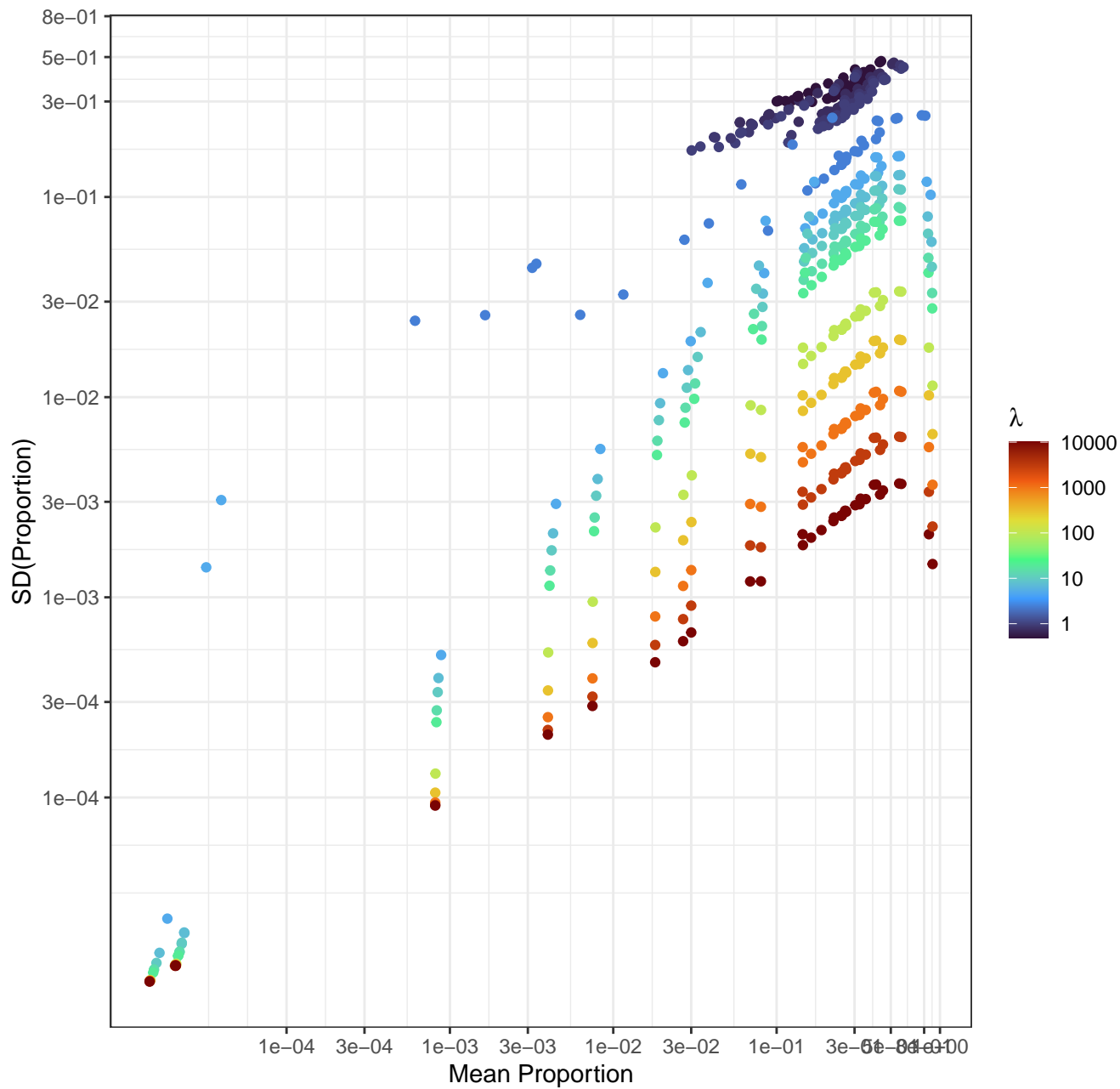
Range observed by a\_scenario



Range observed by a\_scenario



SD v Mean





# SD v Mean

