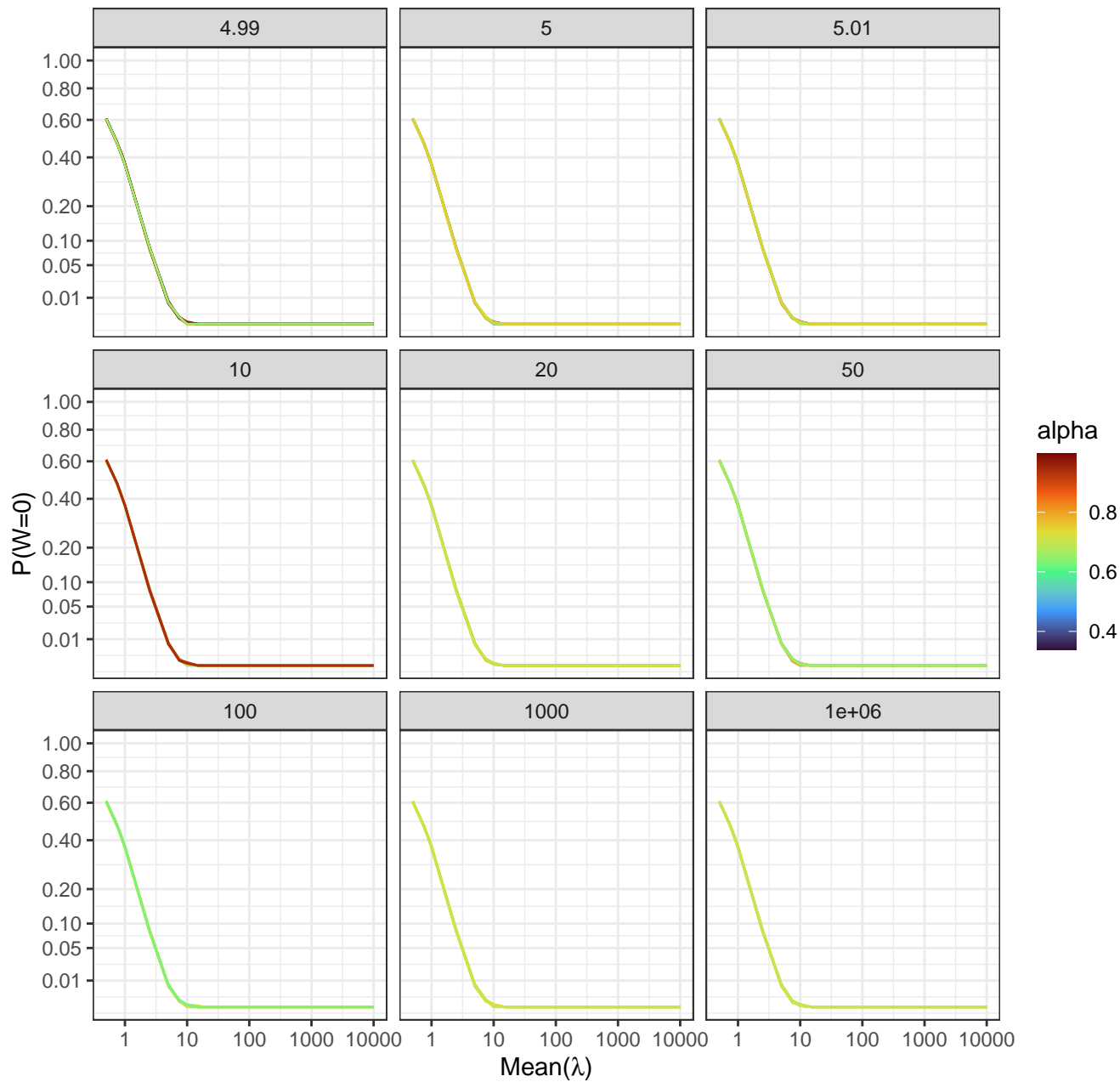
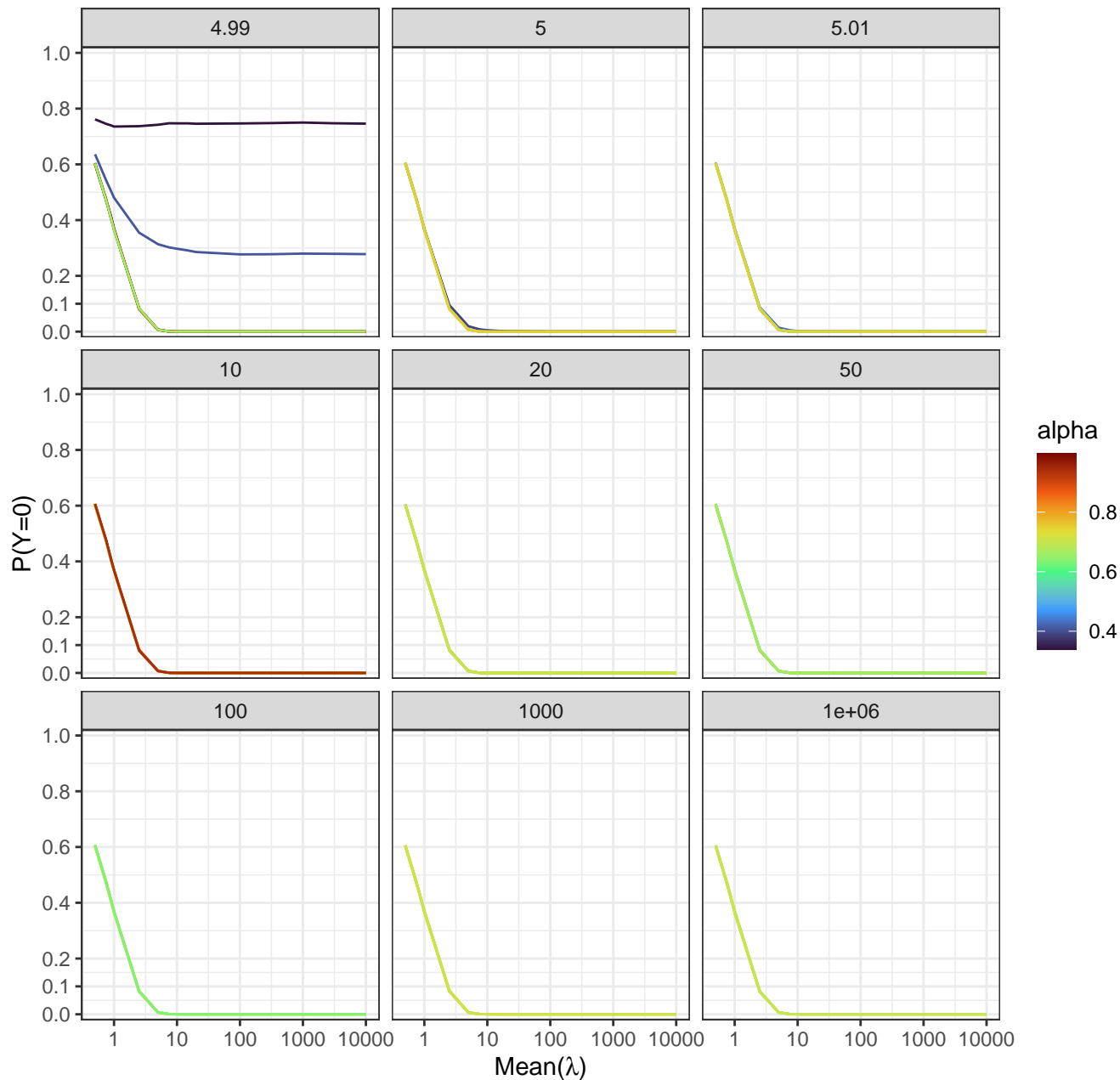
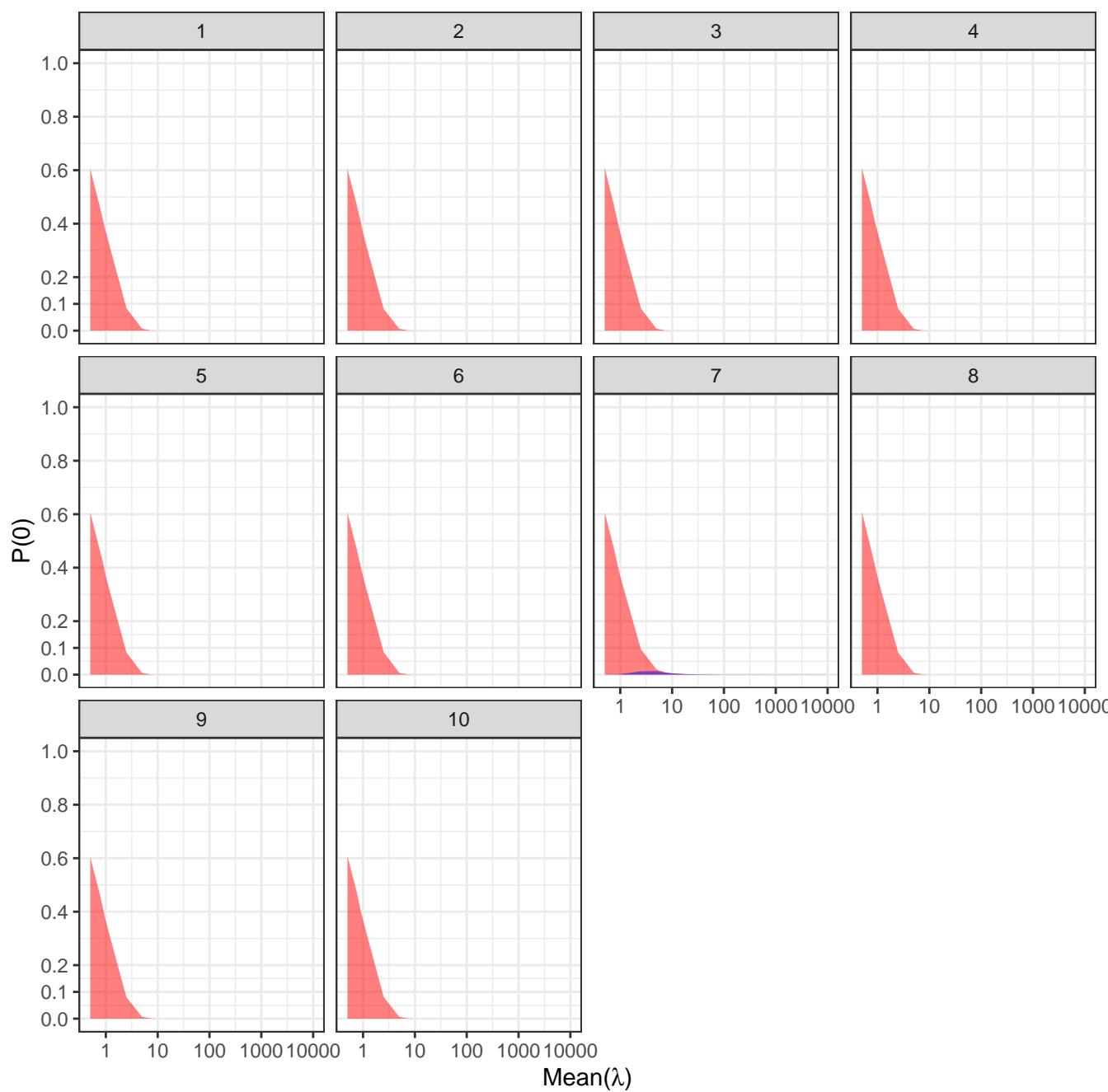
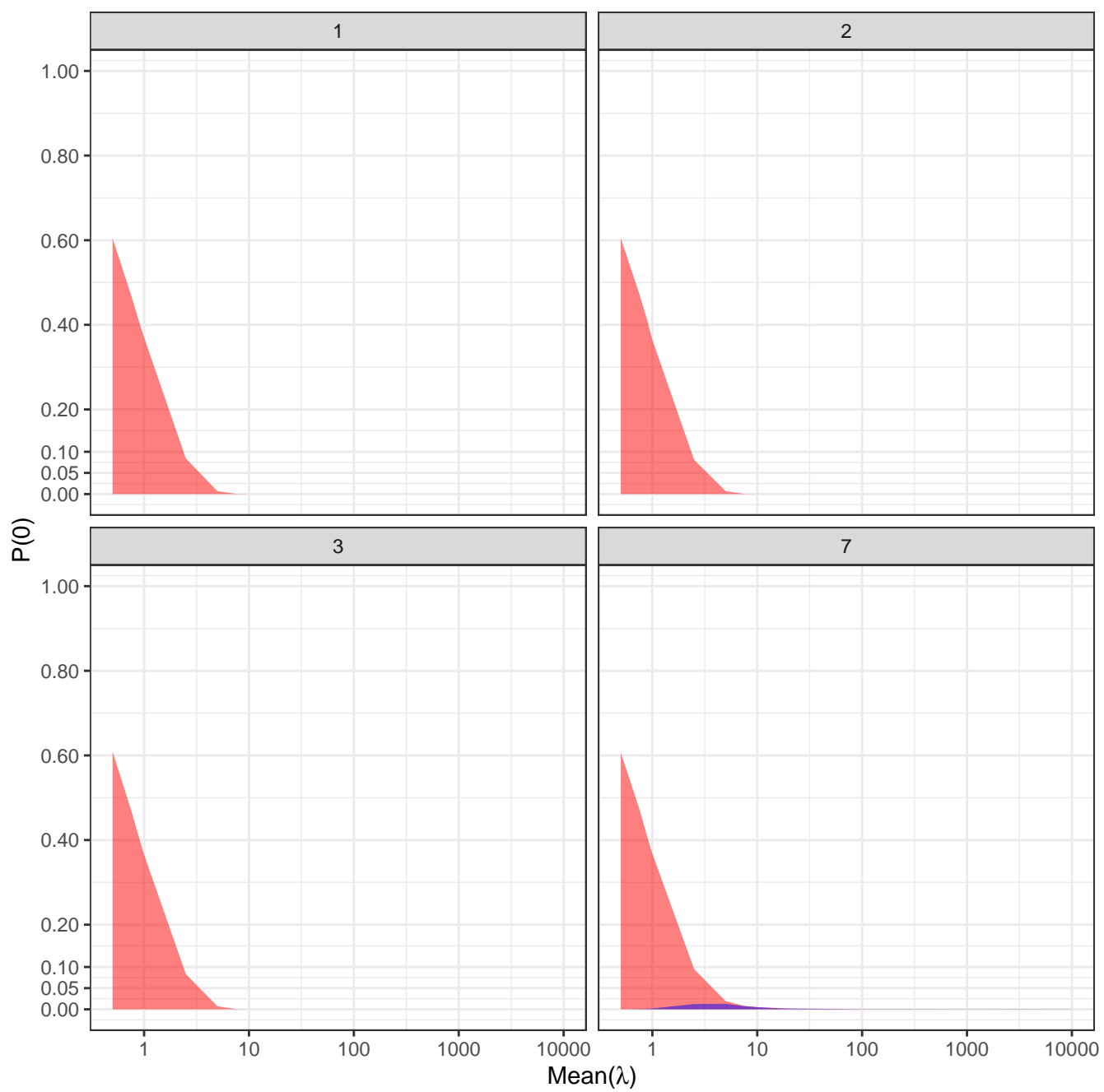


$P(0)$ 

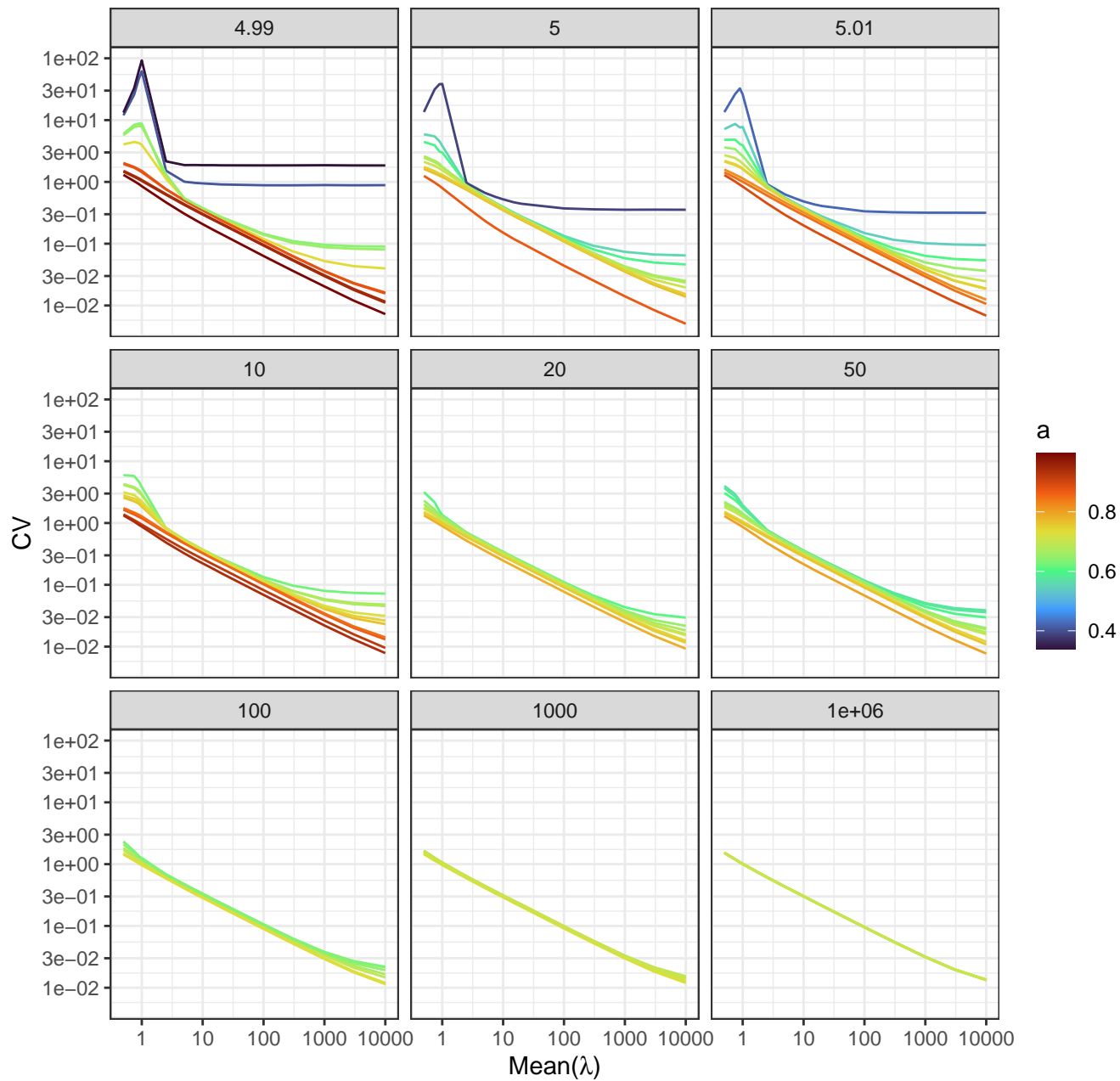
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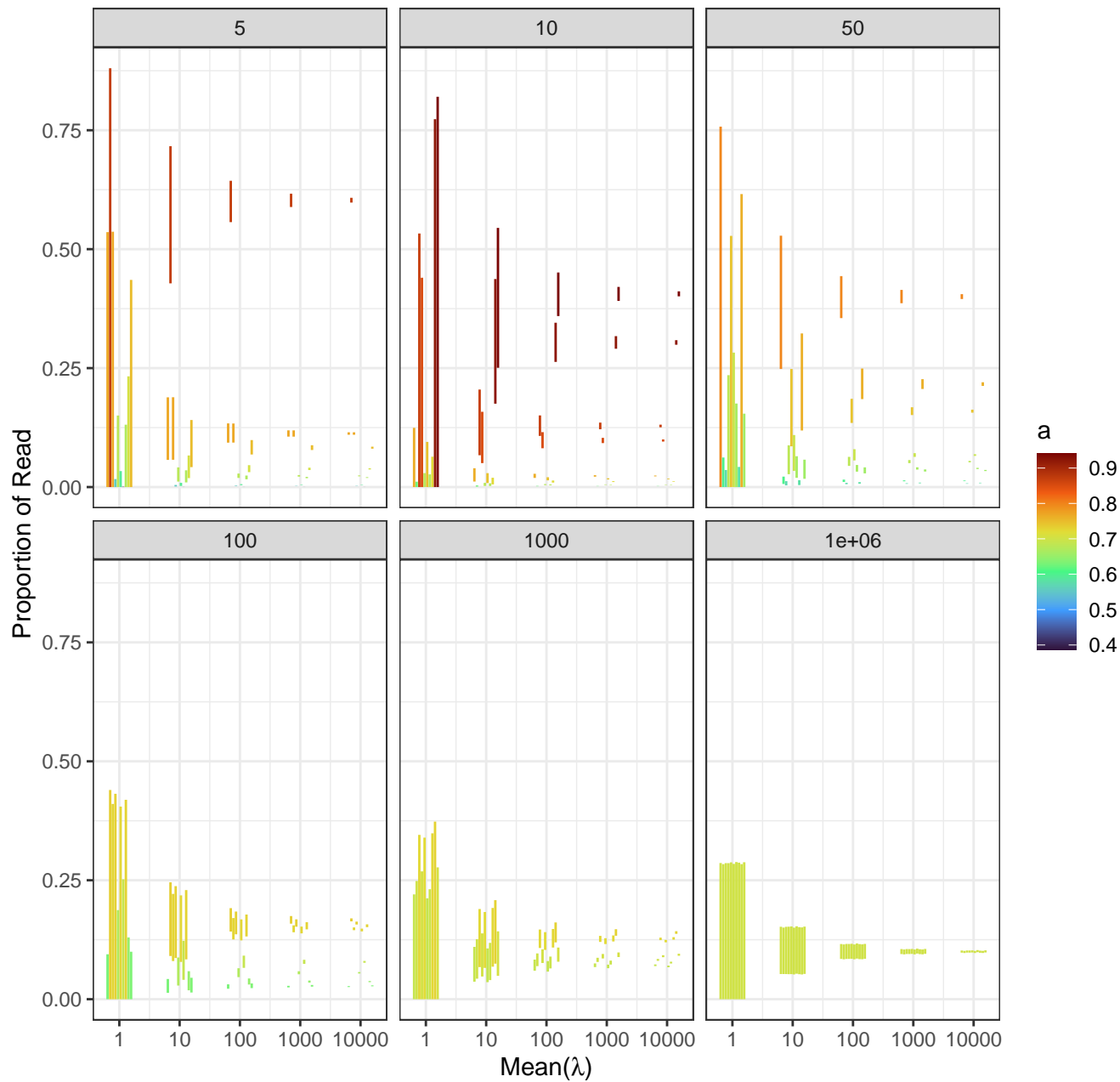




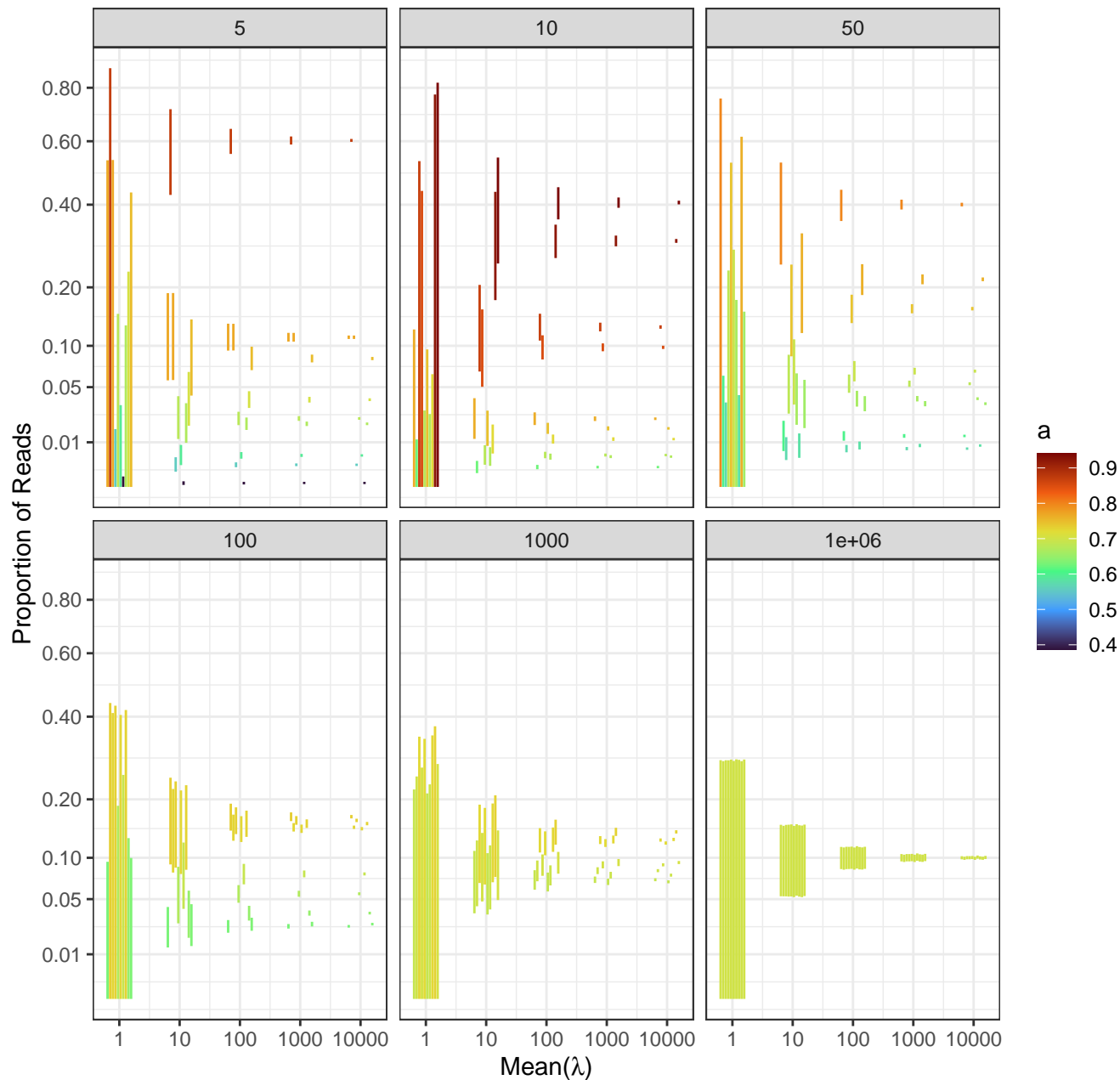
CV



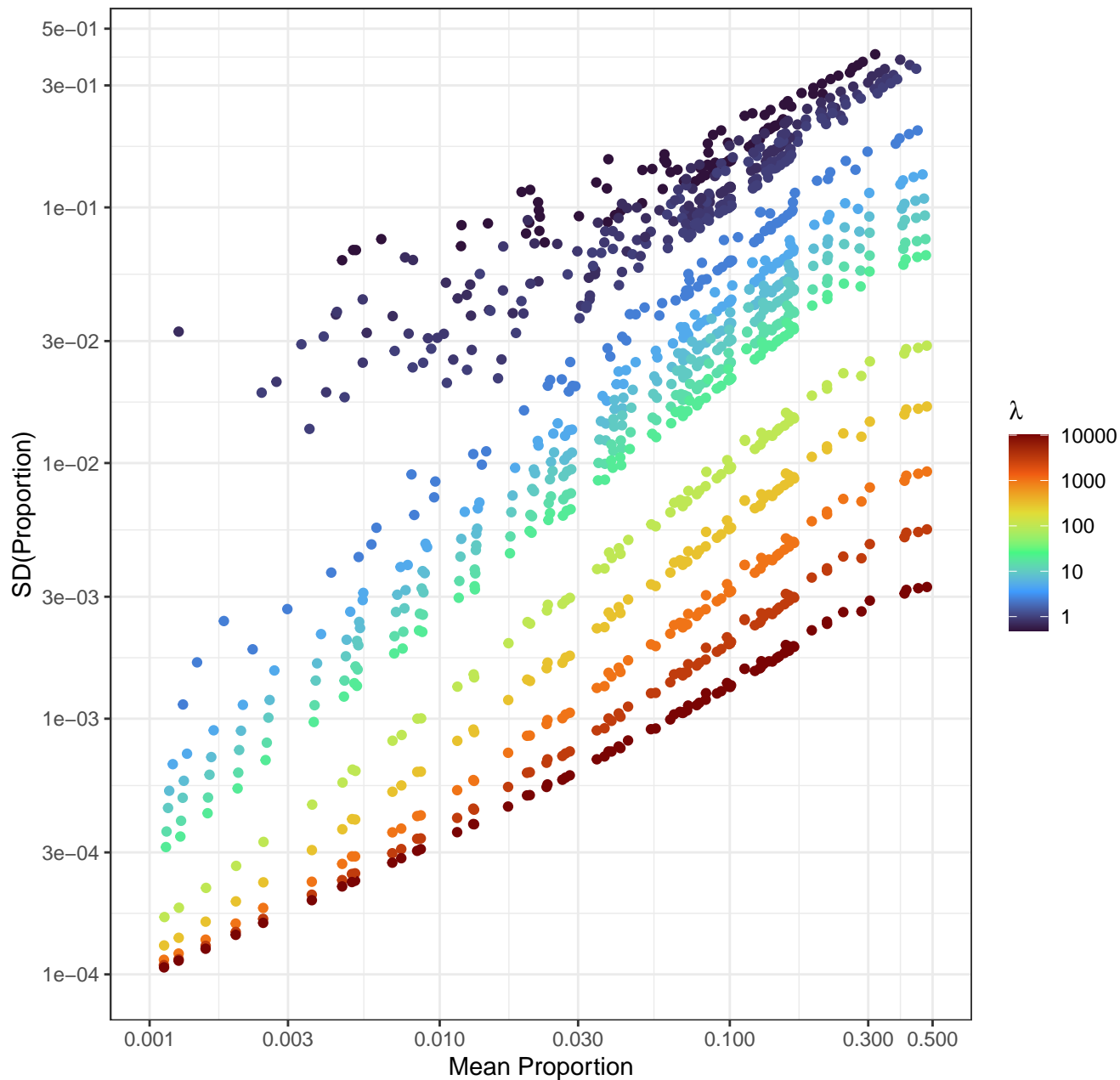
Range observed by a_scenario



Range observed by a_scenario



SD v Mean



SD v Mean

