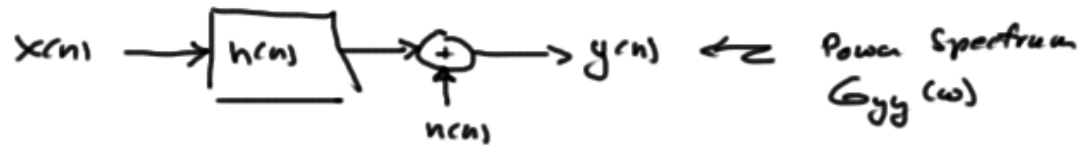




Coherence and Transfer Function Estimation

Coherence and Transfer Function Estimation



Note: In H/W assignment, $x(n)$ is used as the measurement and $y(n)$ used to denote the linear system output

Note $\gamma^2(\omega) < 1$ when

- (1) noise contaminating measurement
- (2) system nonlinearity (transfer power from one frequency to another frequency)
- (3) other inputs to system

Measured power spectrum $G_{yy}(\omega)$

(1) Component due to system input $\gamma^2(\omega) G_{xx}(\omega)$

(2) Component due to additive noise $(1 - \gamma^2(\omega)) G_{yy}(\omega)$

Signal to noise ratio in $y(n)$:

$$SNR = \frac{|H(\omega)|^2 G_{xx}(\omega)}{G_{nn}(\omega)} = \frac{\gamma^2(\omega)}{1 - \gamma^2(\omega)}$$



Coherence and Transfer Function Estimation

Coherence Function Estimate is Biased - Reduce Bias and Variance by Averaging

(1) For $\gamma^2(\omega) = 0$ and $K \geq 32$ ($K = \# \text{ averages}$)

$$\text{bias} [\hat{\gamma}^2(\omega)] \approx \frac{1}{K}$$

$$\text{var} [\hat{\gamma}^2(\omega)] \approx \frac{1}{K^2}$$

① ^{Refs} C. Carter et al, "Estimation of the magnitude-squared coherence function via overlapped Fast Fourier Transform processing," *IEEE Trans. Audio and Electroacoust.* AU-21(4): 337-344 (1973).

(2) For $0 < \gamma^2(\omega) \leq 1$ and $K \geq 32$

$$\text{bias} [\hat{\gamma}^2(\omega)] \approx \frac{1}{K} (1 - \gamma^2(\omega))^2$$

$$\text{var} [\hat{\gamma}^2(\omega)] \approx \frac{2}{K} \gamma^2(\omega) (1 - \gamma^2(\omega))^2$$

Note Averaging is critical

$$\hat{\gamma}^2(K) = \frac{\left| \hat{G}_{yx}(K) \right|^2}{\hat{G}_{xx}(K) \hat{G}_{yy}(K)} = 1 \quad \text{when} \quad K=1$$

↑
averages

② J. Bendat and A. Piersol (1993)

③ J. Bendat and A. Piersol (2000)

④ C. Carter (Proc. IEEE, 1987)



Coherence and Transfer Function Estimation

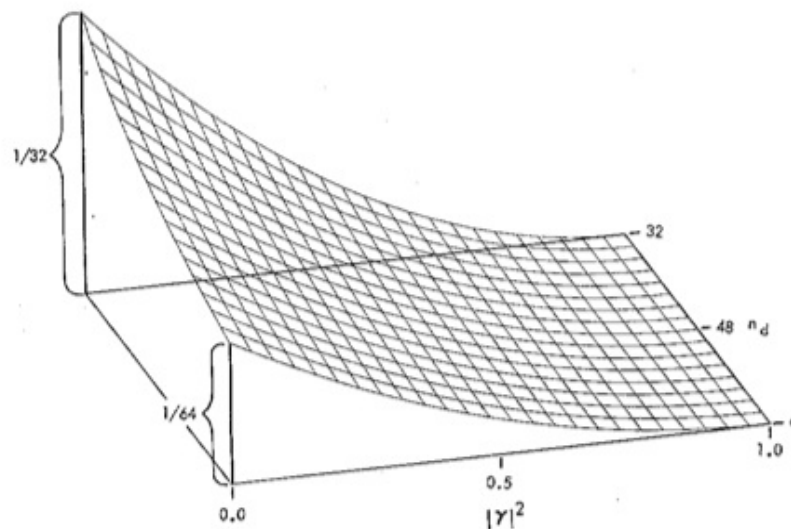


Fig. 5. Bias of $\hat{\gamma}^2$ versus $|\gamma|^2$ and n_d .

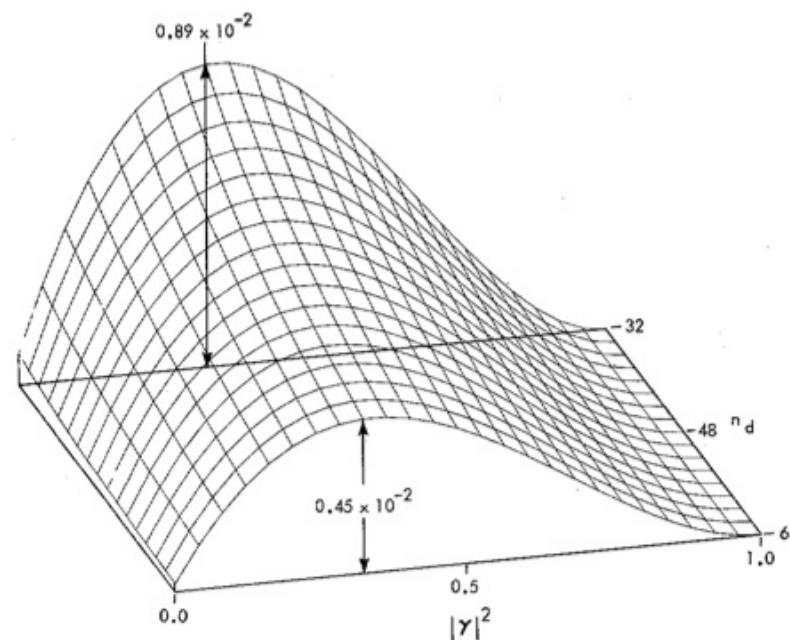


Fig. 6. Variance of $\hat{\gamma}^2$ versus $|\gamma|^2$ and n_d .

Note: n_d is the number of independent segments used in computing the MSC.



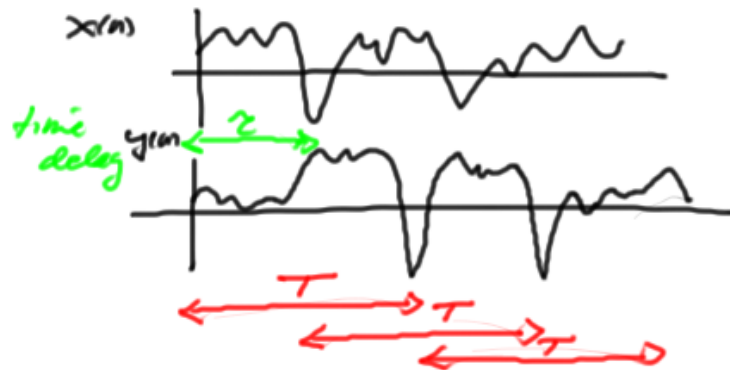
Coherence and Transfer Function Estimation

Bias due to time delay between sample records of $x(n)$ and $y(n)$

$$\hat{\gamma}^2(\omega) \approx \gamma^2(\omega) \left(1 - \frac{\tau}{T}\right)$$

τ = time delay

T = segment length of each FFT



In order to minimize this effect, first compute cross-correlation of $x(n)$ and $y(n)$ then delay/advance $y(n)$ with respect to $x(n)$ to minimize the lag in the peak correlation