



Coherence and Transfer Function Estimation

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Coherence and Transfer Function Estimation

System Example



Functions of interest

- A. Transfer Function - The relationship between $x(n)$ and $y(n)$
- B. Coherence Function - The degree of causality between $x(n)$ and $y(n)$



Coherence and Transfer Function Estimation

II. Components and Their Definitions

A. Auto-Power Spectra

$$G_{xx}(\omega) \rightarrow \overline{\hat{G}_{xx}(k)} = \overline{X(k) X^*(k)}$$

conventional power spectral estimation

where

$X(k) = \text{DFT} \{x(n)\}$

$$G_{yy}(\omega) \rightarrow \overline{\hat{G}_{yy}(k)} = \overline{Y(k) Y^*(k)}$$

where

$Y(k) = \text{DFT} \{y(n)\}$

B. Cross-Power Spectra

$$G_{yx}(\omega) \rightarrow \overline{\hat{G}_{yx}(k)} = \overline{Y(k) X^*(k)}$$

$$G_{yx}(\omega) = H(\omega) G_{xx}(\omega) + G_{nx}(\omega)$$

$$= H(\omega) G_{xx}(\omega) \quad \text{assume } G_{nx}(\omega) = 0$$



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$$\begin{aligned}\hat{G}_{yx}(\omega) &= \overline{Y(k) X^*(k)} \\ &= \overline{[H(k) X(k) + N(k)] X^*(k)} \\ &= H(k) \overline{X(k) X^*(k)} + \overline{N(k) X^*(k)} \\ &= H(k) \hat{G}_{xx}(k) + \overline{N(k) X^*(k)}\end{aligned}$$

Not zero on a
single estimate
basis



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Cross-Correlation / Normalized Cross-Correlation

$$R_{yx}(n) = h(n) * R_{xx}(n) + R_{nx}(n)$$

$$= h(n) * R_{xx}(n) \quad \text{when } R_{nx}(n) = 0$$

$$\hat{R}_{yx}(n) = h(n) * \hat{R}_{xx}(n) + \hat{R}_{nx}(n)$$

↑
not zero when sample size
is small

$$\rho_{yx}(n) = \frac{R_{yx}(n)}{(R_{yy}(0) R_{xx}(0))^{1/2}} \quad \text{Note } |\rho_{yx}(n)| \leq 1$$

$$\hat{\rho}_{yx}(n) = \frac{\hat{R}_{yx}(n)}{(\hat{R}_{yy}(0) \hat{R}_{xx}(0))^{1/2}} \quad \text{Note significance of } \hat{\rho}_{yx}(n) \text{ not equal to } 0 \text{ or } \pm 1 \text{ is not clear}$$



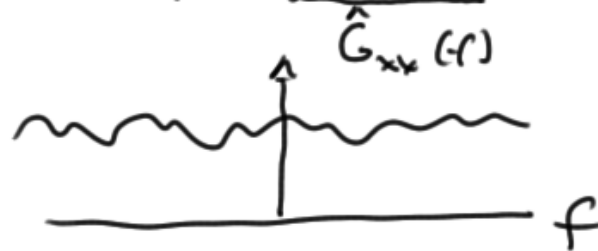
Coherence and Transfer Function Estimation

Transfer Function Estimation

$$H(\omega) = \frac{G_{yx}(\omega)}{G_{xx}(\omega)}$$

$$\hat{H}(\omega) = \frac{\hat{G}_{yx}(\omega)}{\hat{G}_{xx}(\omega)} = \frac{H(k) \hat{G}_{xx}(k) + N(k) X^*(k)}{\hat{G}_{xx}(k)}$$

- Note:
- (1) removes $N(k) X^*(k)$ component by averaging
 - (2) removes effects of non-white $G_{xx}(\omega)$ (determinative)
 - (3) removes effects of statistical fluctuation in $\hat{G}_{xx}(k)$





Coherence and Transfer Function Estimation

Coherence Function Estimation

$\hat{G}_{yx}(k)$ will not answer question of causality between $x(n)$ and $y(n)$ since $\overline{N(k)X^*(k)} \approx 0$.

magnitude squared coherence

$$\gamma^2(\omega) = \frac{|G_{yx}(\omega)|^2}{G_{xx}(\omega) G_{yy}(\omega)} = \frac{|H(\omega)|^2 G_{xx}(\omega)}{|H(\omega)|^2 G_{xx}(\omega) + G_{nn}(\omega)}$$

Note $0 \leq \gamma^2(\omega) \leq 1$ (assuming $G_{nx}(\omega) = 0$)

$$\hat{\gamma}^2(\omega) = \frac{|\hat{G}_{yx}(k)|^2}{\hat{G}_{xx}(k) \hat{G}_{yy}(k)}$$



Coherence and Transfer Function Estimation

Power Spectrum at Output

Due to system input (i.e. $x(n)$) $\gamma^2(\omega) G_{yy}(\omega)$
"coherent output power"

Due to additive noise (i.e. $n(n)$) $(1 - \gamma^2(\omega)) G_{yy}(\omega)$