



# Conventional Power Spectral Estimation

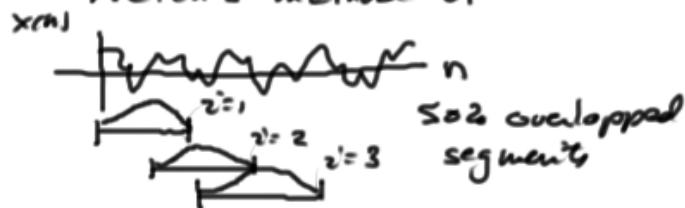
## Normalization Factors for Broadband Power Spectra

$$P_{xx}(\omega) = \sum_{m=-\infty}^{\infty} \phi_{xx}(m) e^{-j\omega m}$$

Refs: Oppenheim & Schaffer (2010)  
Ch. 10.2 Window functions  
Ch. 10.5 Periodogram

$$\sigma^2 = \phi_{xx}(0) = \frac{1}{2\pi} \int_{-\pi}^{\pi} P_{xx}(\omega) d\omega = \int_{-0.5}^{0.5} P_{xx}(f) df$$

Welch's method of windowed and overlapped FFTs



$$\hat{P}_{xx}(f) = \frac{1}{f_s M U} |X(k)|^2$$

Power/Hz

$f_s$  = sample rate

$$U = \frac{1}{M} \sum_{n=0}^{M-1} w^2(n)$$

$$X(k) = \sum_{n=0}^{M-1} w(n) x(n) e^{-j\left(\frac{2\pi}{M}\right)nk}$$

$M$  = FFT length

$$\omega_k = 2\pi f_k = \left(\frac{2\pi}{M}\right)k$$



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Periodogram

$$\bar{I}_N(\omega) = \frac{1}{N} |X(e^{j\omega})|^2 = \sum_{m=-(N-1)}^{N-1} c_{xx}(m) e^{-j\omega m}$$

$$\phi_{xx}(m) = \begin{cases} \sigma^2, & m=0 \\ 0, & m \neq 0 \end{cases}$$

Consider uncorrelated Gaussian noise  $x(n) \sim N(0, \sigma^2)$   $\uparrow$

$$E[\bar{I}_N(\omega)] = E\left[\frac{1}{N} |X(e^{j\omega})|^2\right] = \sum_{m=-(N-1)}^{N-1} E[c_{xx}(m)] e^{-j\omega m} = \sigma^2$$

$$X(e^{j\omega}) = \sum_{n=0}^{N-1} x(n) e^{-j\omega n}$$

$$|X(e^{j\omega})|^2 = \sum_{n=0}^{N-1} \sum_{m=0}^{N-1} x(n) x(m) e^{-j\omega n} e^{j\omega m}$$



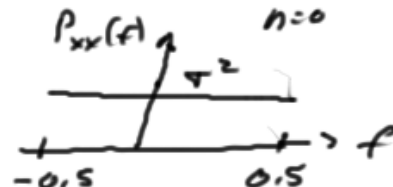
If a window  $w(n)$  had been used, this factor would be  $\sum_{n=0}^{N-1} w^2(n)$

$$E[|X(e^{j\omega})|^2] = \sum_{n=0}^{N-1} \sum_{m=0}^{N-1} E[x(n)x(m)] e^{-j\omega n} e^{j\omega m}$$

$$= \sum_{n=0}^{N-1} \sigma^2 = N \sigma^2$$

$$E[x^2(n)] = \sigma^2 \quad n=m$$

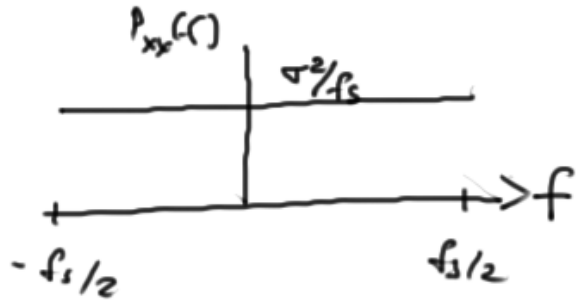
$$E[x(n)] E[x(m)] = 0 \quad n \neq m$$



$$P_{\text{avg}} = \int_{-0.5}^{0.5} P_{xx}(f) df = \int_{-0.5}^{0.5} \sigma^2 df = \sigma^2$$



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$$\text{then } \int_{-f_s/2}^{f_s/2} P_{xx}(f) df = \int_{-f_s/2}^{f_s/2} \frac{\sigma^2}{f_s} df = \sigma^2$$

$$\hat{P}_{xx}(f) = \frac{1}{f_s M U} \overline{|X(k)|^2}$$

"Power"/Hz  
 ↑  
 Volts<sup>2</sup>  
 (A/D counts)<sup>2</sup>  
 (physical units)<sup>2</sup>

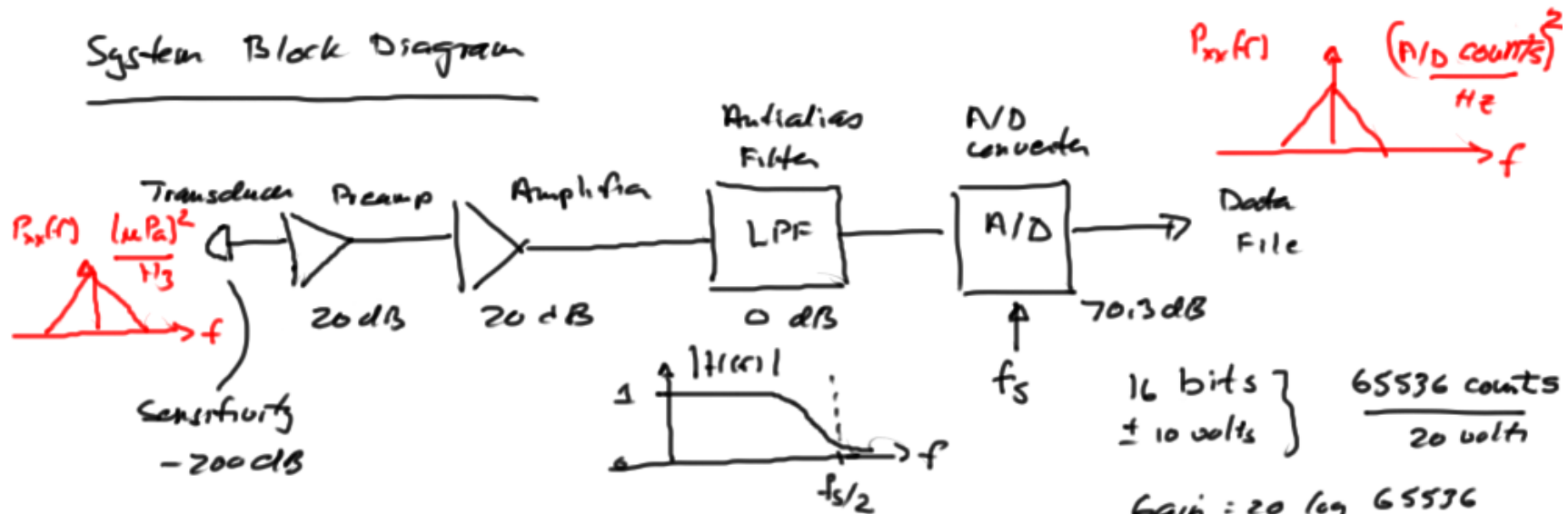
$$\omega_k = 2\pi f_k \left(\frac{2\pi}{M}\right) k$$

$U$  is the normalization corrects for the distortion (tapering) of the segment time series by the window function



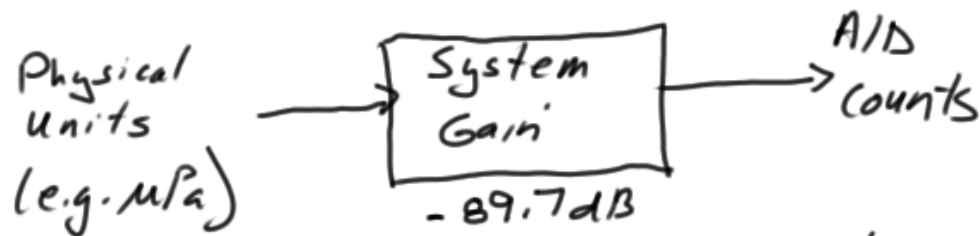
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## System Block Diagram



$$\text{System Gain} = -200 dB + 20 dB + 20 dB + 70.3 dB$$

$$= -89.7 dB$$



Thus, to go from  $P_{xx}(f)$  in  $(A/D \text{ counts})^2 / Hz$  to  $P_{xx}(f)$  in  $(\mu Pa)^2 / Hz$  must add  $89.7 dB$