

# 调制性质讲义

## ① 调制性质

$$\text{若 } x_1(t) \xrightarrow{F} X_1(j\omega)$$

$$x_2(t) \xrightarrow{F} X_2(j\omega)$$

$$\text{则 } x_1(t)x_2(t) \xrightarrow{F} \frac{1}{2\pi} X_1(j\omega) * X_2(j\omega)$$

$$\text{证明: 设 } X(j\omega) = \frac{1}{2\pi} X_1(j\omega) * X_2(j\omega)$$

$$= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X_1(j\tau) X_2(j(\omega-\tau)) d\tau$$

$$\text{则 } x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\omega) e^{j\omega t} d\omega$$

$$= \frac{1}{2\pi} \int_{-\infty}^{+\infty} \left[ \frac{1}{2\pi} \int_{-\infty}^{+\infty} X_1(j\tau) X_2(j(\omega-\tau)) d\tau \right] e^{j\omega t} d\omega$$

$$= \left[ \frac{1}{2\pi} \int_{-\infty}^{+\infty} X_1(j\tau) e^{j\tau t} d\tau \right] \left[ \frac{1}{2\pi} \int_{-\infty}^{+\infty} X_2(j(\omega-\tau)) e^{j(\omega-\tau)t} d\omega \right]$$

$$\text{设 } \begin{cases} \tau' = \tau \\ \omega' = \omega - \tau \end{cases}, \text{ 则用二元积分换元得}$$

$$= \left[ \frac{1}{2\pi} \int_{-\infty}^{+\infty} X_1(j\tau') e^{j\tau' t} d\tau' \right] \left[ \frac{1}{2\pi} \int_{-\infty}^{+\infty} X_2(j\omega') e^{j\omega' t} d\omega' \right]$$

$$\cdot \begin{vmatrix} \frac{\partial \tau}{\partial \tau'} & \frac{\partial \omega}{\partial \tau'} \\ \frac{\partial \tau}{\partial \omega'} & \frac{\partial \omega}{\partial \omega'} \end{vmatrix}$$

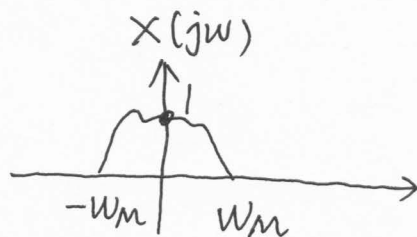
$$= X_1(t) X_2(t)$$

② 应用: P198 双边带正弦载波幅度调制与解调  
调制:

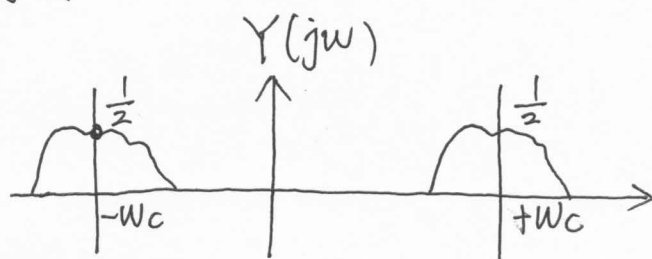
$$x(t) \xrightarrow{\text{调制}} y(t) = x(t) \cos(\underbrace{\omega_c t}_{\text{载波 (Carrier)}})$$

载波 (Carrier)

若



则有:

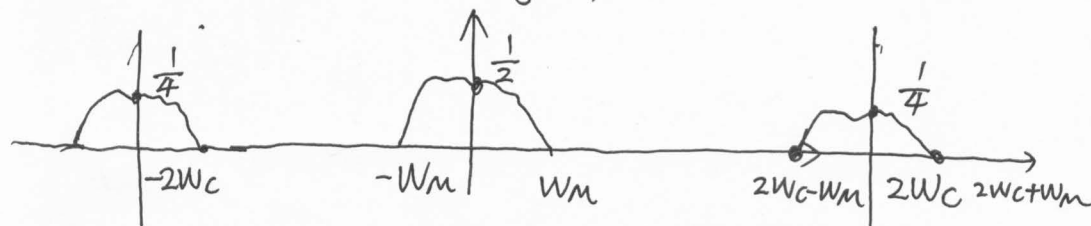


解调:

$$w(t) = y(t) \cos(\omega_c t)$$

则有:

$$W(j\omega)$$



$$(\omega_c > \omega_m)$$



(低通滤波器)

$$(\omega_m < \omega_1 < 2\omega_c - \omega_m)$$

则有:

$$X(j\omega) = W(j\omega) H(j\omega)$$

$$\text{即: } x(t) = w(t) * h(t)$$

$$= [x(t) \cos^2(\omega_c t)] * \left[ \frac{2 \sin(\omega_1 t)}{\pi t} \right]$$

③ 另一个角度看调制解调(时域观点)

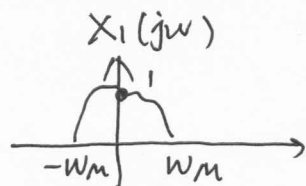
$$w(t) = x(t) \cos^2(\omega_c t)$$

$$= \frac{1}{2} x(t) + \frac{1}{2} x(t) \cos(2\omega_c t)$$

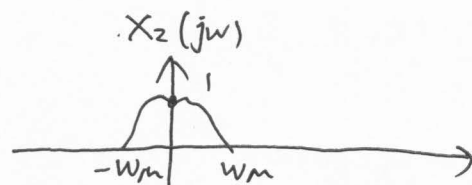
保留项

低通滤波滤掉了

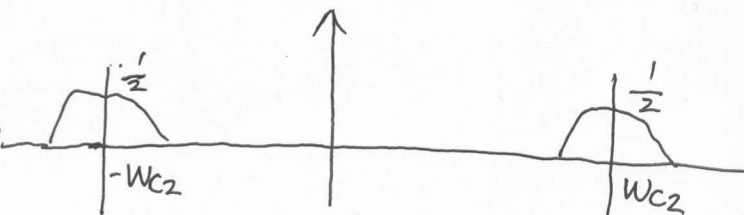
# ④ 多个信号的调制与解调



$$Y_1(j\omega) \quad (y_1(t) = x_1(t) \cos(\omega_{c1}t))$$



$$Y_2(j\omega) \quad (y_2(t) = x_2(t) \cos(\omega_{c2}t))$$



$$x(t) = x_1(t) \cos(\omega_{c1}t) + x_2(t) \cos(\omega_{c2}t)$$

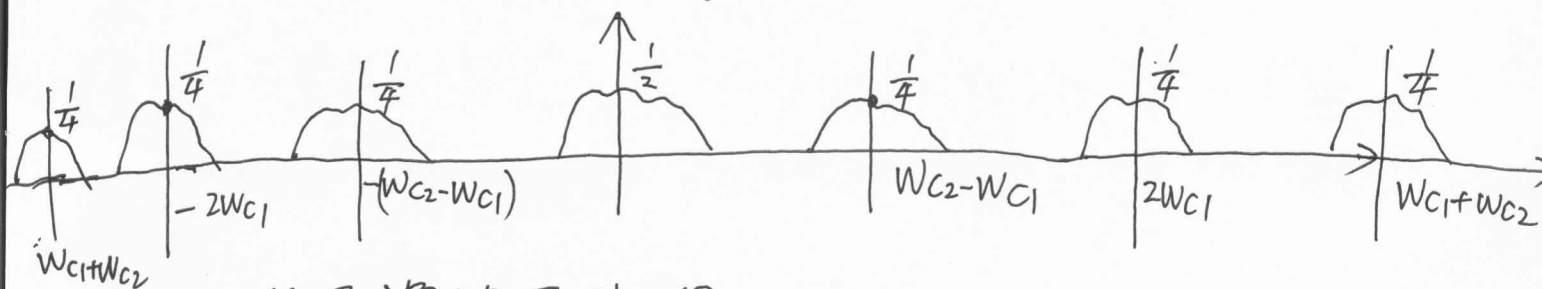
$$X(j\omega)$$



## ① 恢复 $x_1(t)$

$$w_1(t) = x(t) \cos(\omega_{c1}t)$$

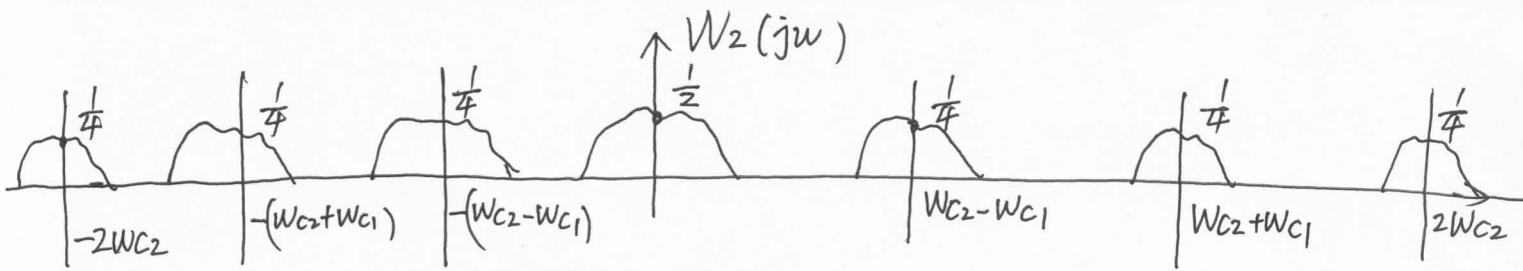
$$W_1(j\omega)$$



低通滤波后获得  $x_1(t)$

## ② 恢复 $x_2(t)$

$$w_2(t) = x(t) \cos(\omega_{c2}t)$$



低通滤波后获得  $x_2(t)$