

$$1. A_{z1} = C_1 \frac{e^{-jkr}}{r}, \quad A_{z2} = C_2 \frac{e^{jkr}}{r}$$

$$\therefore \frac{dA_{z1}}{dr} = C_1 e^{-jkr} \frac{(-jkr - 1)}{r^2} = -jk A_{z1} - \frac{A_{z1}}{r} \quad (1)$$

$$\begin{aligned} \frac{d^2 A_{z1}}{dr^2} &= -jk \frac{dA_{z1}}{dr} - \frac{\frac{dA_{z1}}{dr} r - A_{z1}}{r^2} = -jk \left(-jk A_{z1} - \frac{A_{z1}}{r} \right) + \frac{jk A_{z1} + \frac{A_{z1}}{r}}{r} \\ &+ \frac{A_{z1}}{r^2} = A_{z1} \left(-k^2 + \frac{2jk}{r} + \frac{2}{r^2} \right) \quad (2) \end{aligned}$$

$$\frac{dA_{z2}}{dr} = C_2 e^{jkr} \frac{jkr - 1}{r^2} = jk A_{z2} - \frac{A_{z2}}{r} \quad (3)$$

$$\begin{aligned} \frac{d^2 A_{z2}}{dr^2} &= jk \frac{dA_{z2}}{dr} - \frac{\frac{dA_{z2}}{dr} r - A_{z2}}{r^2} = \left(jk - \frac{1}{r} \right) \left(jk A_{z2} - \frac{A_{z2}}{r} \right) + \frac{A_{z2}}{r^2} \\ &= \left(-k^2 - \frac{2jk}{r} + \frac{2}{r^2} \right) A_{z2} \quad (4) \end{aligned}$$

将 (1) (2) 代入方程 3-34, 左边: $A_{z1} \left(-k^2 + \frac{2jk}{r} + \frac{2}{r^2} - \frac{2jk}{r} - \frac{2}{r^2} + k^2 \right) = 0$

同理, 将 (3) (4) 代入方程 3-34, 左边 = 0

\therefore 3-35, 3-36 是方程 3-34 的解

$$2. \nabla \times \vec{E}_1 = -\vec{H}_1 - \vec{M}_1, \quad \nabla \times \vec{H}_1 = \vec{E}_1 + \vec{J}_1$$

$$\nabla \times \vec{E}_2 = -\vec{H}_2 - \vec{M}_2, \quad \nabla \times \vec{H}_2 = \vec{E}_2 + \vec{J}_2$$

$$\vec{H}_2 \cdot \nabla \times \vec{E}_1 = -\vec{H}_2 \cdot \vec{H}_1 - \vec{H}_2 \cdot \vec{M}_1$$

$$\vec{E}_1 \cdot \nabla \times \vec{H}_2 = \vec{E}_1 \cdot \vec{E}_2 + \vec{E}_1 \cdot \vec{J}_2$$

$$\therefore \vec{E}_1 \cdot \nabla \times \vec{H}_2 - \vec{H}_2 \cdot \nabla \times \vec{E}_1 = \vec{E}_1 \cdot \vec{E}_2 + \vec{H}_2 \cdot \vec{H}_1 + \vec{E}_1 \cdot \vec{J}_2 + \vec{H}_2 \cdot \vec{M}_1$$

$$\therefore -\nabla \cdot (\vec{E}_1 \times \vec{H}_2 - \vec{E}_2 \times \vec{H}_1) = \vec{E}_1 \cdot \vec{J}_1 + \vec{H}_2 \cdot \vec{M}_1 - \vec{E}_2 \cdot \vec{J}_1 - \vec{H}_1 \cdot \vec{M}_2 \quad (3-60)$$

对 3-60 两边作体积分, 由散度定理

(3-61)

$$\oiint_S (\vec{E}_1 \times \vec{H}_2 - \vec{E}_2 \times \vec{H}_1) \cdot d\vec{s} = \iiint_V (\vec{E}_1 \cdot \vec{J}_1 + \vec{H}_2 \cdot \vec{M}_1 - \vec{E}_2 \cdot \vec{J}_1 - \vec{H}_1 \cdot \vec{M}_2) dV$$

4.1

$$a. \sin \varphi = \sqrt{1 - \cos^2 \varphi} = \sqrt{1 - (\sin \theta \cos \varphi)^2}$$

$$E_{\varphi} = j\eta \frac{kI_0 l e^{-jkr}}{4\pi r} \cdot \sin \varphi = j\eta \frac{kI_0 l e^{-jkr}}{4\pi r} \sqrt{1 - (\sin \theta \cos \varphi)^2}$$

$$H_x = j \frac{kI_0 l e^{-jkr}}{4\pi r} \sin \varphi = \frac{E_{\varphi}}{\eta}$$

$$b. U = U_0 (1 - \sin^2 \theta \cos^2 \varphi)$$

$$P_{rad} = U_0 \int_0^{2\pi} \int_0^{\pi} (1 - \sin^2 \theta \cos^2 \varphi) \sin \theta d\theta d\varphi$$

$$= U_0 \int_0^{2\pi} \int_0^{\pi} (\sin \theta - \cos^2 \varphi \sin^3 \theta) d\theta d\varphi = \frac{8}{3} \pi U_0$$

$$\therefore D_0 = \frac{4\pi U_0}{P_{rad}} = \frac{4}{8/3} = 1.5$$

4.5

$$(a) \varphi = 0^\circ, \text{ 则 } E_{\varphi} = j\eta \frac{kI_0 l e^{-jkr}}{4\pi r} \sqrt{1 - \sin^2 \theta} = j\eta \frac{kI_0 l e^{-jkr}}{4\pi r} \cos \theta$$

$\therefore E_{\varphi}$ 只有 \hat{e} 方向

4.29

$$(a) \text{ 对于半波偶极子天线, } P_{ad} = P_{in} = 1 \text{ W}, D_0 = 1.643$$

$$\therefore U_0 = \frac{P_{ad}}{4\pi} = \frac{1}{4\pi}, U_{max} : U_0 D_0 = 0.137 \text{ W/rad}$$

$$(b) W_{max} = \frac{U_{max}}{r^2} = \frac{0.137}{(5 \times 10^3)^2} = 5.48 \times 10^{-9} \text{ W/m}^2$$