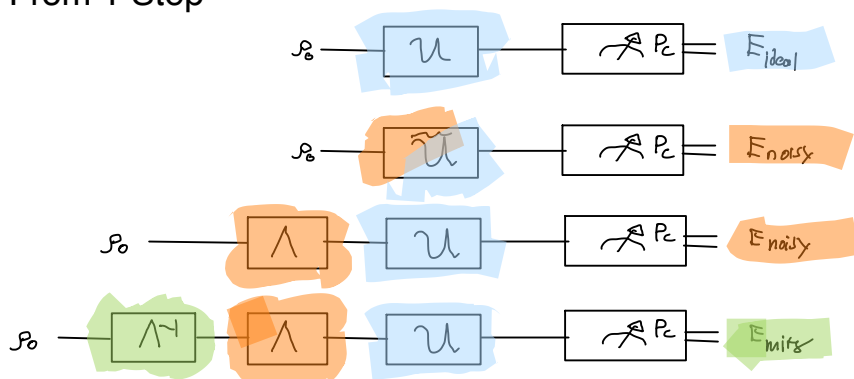


# (C65C) PEC Full Derivation

Friday, July 21, 2023 8:09 AM

## From 1 Step



## Channel definitions

$$U = U \cdot U^\dagger$$

$$\Lambda = \sum_a f_a |p_a\rangle\langle p_a|$$

$$= \sum_b c_b P_b$$

$$\Lambda^{-1} = \sum_a f_a^{-1} |p_a\rangle\langle p_a|$$

$$= \sum_b c_b^{-1} P_b$$

$$\langle P_C | X | \rangle = \langle P_C | \cdot$$

$$-1 \leq f_a \leq 1$$

$$c_b \geq 0, \sum_b c_b = 1$$

$$c_b = \frac{1}{2^n} \sum_a (-1)^{a \cdot b} f_a$$

$$\vec{c}_b = W^{-1} \vec{f}_a \quad \vec{f}_a = W \vec{c}_b$$

$$\vec{c}_b^{-1} = W \vec{f}_a^{-1}$$

$$c_b^{-1} = \frac{1}{2^n} \sum_a (-1)^{a \cdot b} f_a^{-1}$$

$$c_b^{-1} \in \mathbb{R}$$

Need to introduce  
 • Super-op for each unitary  
 • Pauli channel for PTM  
 • Super-op for each unitary  
 • Pauli channel for PTM  
 • SQ to 0/1  
 • 0, 0.5, 1

## Circuit Expectation Value estimators

$$E_{ideal} = \langle P_C \rangle_U$$

$$= \langle P_C | U | \rho_0 \rangle$$

ideal exp value with noiseless unitary

$$E_{noisy} = \langle P_C \rangle_{\tilde{U}}$$

$$= \langle P_C | U \Lambda | \rho_0 \rangle$$

$$= \langle P_C | \tilde{U} | \rho_0 \rangle$$

noisy-gate expectation value

$$E_{mitg} = \langle P_C | U \Lambda \Lambda^{-1} | \rho_0 \rangle$$

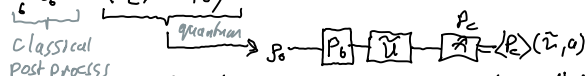
$$= \langle P_C | U \Lambda \left( \sum_a f_a^{-1} |p_a\rangle\langle p_a| \right) | \rho_0 \rangle$$

$$= \langle P_C | U \Lambda \left( \sum_b c_b^{-1} P_b \right) | \rho_0 \rangle$$

$$= \sum_b c_b^{-1} \langle P_C | U \Lambda P_b | \rho_0 \rangle$$

$$= \sum_b c_b^{-1} \langle P_C | (U, b) \rangle$$

sum of trajectories with weight  $c_b^{-1} \in \mathbb{R}$



Quantum circuit we can execute on HW and find exp. value from.

∴ To find noise-free val all we have to do is to compute exp-val of all  $4^n$  b-modified circuits! This would give us ideal exp value.

However,  $|b| = 4^n$  grows exponentially, hence, infeasible.

but what if we could sample from it to approximate full sum. But... can't sample directly from  $c_b^{-1}$  which does not form a valid prob. distribution. Let's solve:

$c_b^{inv}$  can be outside  $[0,1]$

$\sum_b c_b^{inv} = \gamma \geq 1$  generally, for  $\Lambda$  not unitary

eg bit flip channel

$$\Lambda = (-p)I + pX$$

$$\Lambda^\dagger = (+p)I + (-p)X$$

$$c_I^{inv} = 1 + \frac{p}{1-2p}$$

$b \in \{0,1\}$   
classical register

$$c_X^{inv} = -\frac{p}{1-2p}$$

$b \in \{1,0\}$

Turn into probability

$$c_b^{inv} = \underbrace{\text{sgn}(c_b^{inv})}_{\text{sgn} \in \{-1, +1\}} \underbrace{\frac{|c_b^{inv}|}{\gamma}}_{\substack{\text{prob} \in [0,1] \\ \text{scale}}} \gamma$$

$$\bar{c}_b^{inv} := \frac{|c_b^{inv}|}{\|c_b^{inv}\|_1} \rightarrow \|c_b^{inv}\|_1 = \sum_b |c_b^{inv}| \leftrightarrow L_1 \text{ norm}$$

$$= \frac{|c_b^{inv}|}{\gamma}$$

$$E_{mitg} = \sum_b c_b^{inv} \langle \hat{P}_c \rangle(\tilde{u}, b)$$

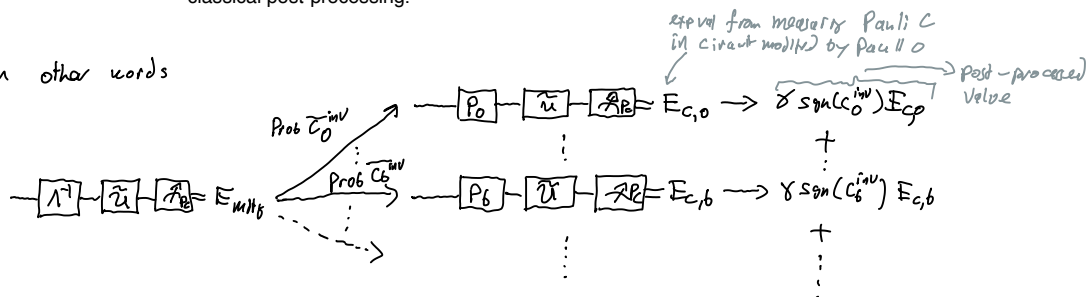
$$= \sum_b \text{sgn}(c_b^{inv}) \frac{|c_b^{inv}|}{\gamma} \gamma \langle \hat{P}_c \rangle(\tilde{u}, b)$$

$$= \gamma \sum_b \underbrace{\text{sgn}(c_b^{inv}) \bar{c}_b^{inv}}_{\text{scale}} \underbrace{\langle \hat{P}_c \rangle(\tilde{u}, b)}_{\text{classical post-processing}}$$

Valid QC circuit can run & find value on HW

In this form, the decomposition of the error error mitigated expectation value is simply a sum over expectation values of Pauli-gate modified circuits, whose value can be obtained from direct quantum computer execution, weighted by a probability,  $c$  bar  $b$  inverse, and the sign. The elements that perform the weighing and rescaling can all be done in classical post-processing.

In other words



$$E_{c,mitg} = \sum_b \gamma \text{sgn}(c_b^{inv}) E_{c,b}$$

mitigated value for Pauli  $c$  obtained from the quasi-prob distribution

From above, we know this is an unbiased estimator, but what about the error and sampling

## Estimator, Sampling, and Error Bounds

Sample circuit of the form

$$\{ \underbrace{\bar{c}_b^{inv}}_{\text{prob}} : \underbrace{P_b}_{\text{Pauli observable single-shot outcome ie e-val}} \underbrace{\tilde{u}}_{\text{Pauli gate}} \underbrace{A_B}_{\text{Pauli gate}} = \gamma \in \{-1, +1\} \} \rightarrow X = \text{sgn}(c_b^{inv}) \gamma$$

post processed value  $X$   
 $X \in \{+1, -1\}$

Let's say we sample  $M$  instances, randomly sample assign value for  $b$  and obtain one-shot value  $x_m$ , i.e. one random instance of  $Y=1$  or  $Y=-1$ , which we then post-process.

The results are thus the classical random variables

$$\{X_1, X_2, \dots, X_M\} \quad \text{or} \quad \{X_m : m=1, \dots, M\}$$

where each  $X_m \in \{1, -1\}$  and is distributed to model.

Bernoulli distribution with same probability which can be any valid value and can vary from shot-to-shot  $m$ .

Our mitigation estimator is then for  $M$  shots:

$$E_M \approx \gamma \frac{1}{M} \sum_{m=1}^M X_m = \frac{1}{M} \sum_{m=1}^M \gamma \text{sgn}(C_{b_m}^{\text{inv}}) Y_{m_s}(\tilde{u}, b_m)$$

Pauli chosen for  $m$ -th shot  
 noisy circuit  
 fixed outcome of measurement for  $b_m$

There are now 2 random processes:

$b_m$ : which pauli  $b$  we pick for shot  $m$

$Y_{b_m}$ : which outcome  $\pm 1$  we get for  $b_m$  circuit of shot  $m$

Unbiased Estimator of the Ideal, noise-free circuit expectation

$$\mathbb{E}[E_M] = \frac{1}{M} \sum_{m=1}^M \mathbb{E}[X_m] \quad \text{iid rand vars}$$

$$= \mathbb{E}[\gamma X_m] \quad \text{no } X_m \text{ is different}$$

$$= \mathbb{E}[\gamma \text{sgn}(C_{b_m}^{\text{inv}}) Y_{b_m}(\tilde{u}, b_m)] \quad \text{where rand var is } b_m \text{ now, not just } m, \text{ so}$$

$$= \mathbb{E}_{b_m}[\gamma \text{sgn}(C_b^{\text{inv}}) Y_b(\tilde{u}, b)] \quad \text{Prob}[b] = \bar{C}_b^{\text{inv}}$$

$$= \sum_b \mathbb{E}[\gamma \text{sgn}(C_b^{\text{inv}}) Y_b] \text{Prob}[b]$$

$$= \sum_b \underbrace{\gamma \text{sgn}(C_b^{\text{inv}})}_{\text{post-process outcome}} \underbrace{\bar{C}_b^{\text{inv}}}_{\text{sample prob}} \underbrace{\mathbb{E}[Y_b]}_{\text{rand outcome}} \rightarrow$$

$$= \sum_b \gamma \text{sgn}(C_b^{\text{inv}}) \frac{C_b^{\text{inv}}}{\gamma} \langle\langle P_C | \mathcal{U} \Lambda \mathcal{P}_b | \mathcal{P}_0 \rangle\rangle$$

$$= \langle\langle P_C | \mathcal{U} \Lambda (\sum_b C_b^{\text{inv}} \mathcal{P}_b) | \mathcal{P}_0 \rangle\rangle$$

$$= \langle\langle P_C | \mathcal{U} \Lambda \Lambda^\dagger | \mathcal{P}_0 \rangle\rangle$$

$$= \langle\langle P_C | \mathcal{U} | \mathcal{P}_0 \rangle\rangle$$

$$= \langle \hat{P}_C \rangle(\mathcal{U}_{\text{ideal}}) \quad \text{without noise?}$$

unbiased estimator of the true noise-free, ideal value of the circuit

$$\text{note: } \langle \hat{P}_C \rangle(\tilde{u}, b) = \langle\langle P_C | \mathcal{U} \Lambda \mathcal{P}_b | \mathcal{P}_0 \rangle\rangle = \mathbb{E}[Y_b]$$

$\hat{P}$  random variable  $\pm 1$  for output of the  $b$ -th pauli circuit.

$\therefore$  for some classical func of  $b$   $f(b)$  which does not depend on the value  $Y_b$  but only on the label  $b$ :

$$\mathbb{E}[f(b) Y_b] = f(b) \langle \hat{P}_C \rangle(\tilde{u}, b)$$

(Optional step) Variance

Variance of  $E_M$

$$\underbrace{V_{\{b_m, X_m\}}}_{\text{with rescaling}}[E_M] = \frac{\gamma^2}{M^2} \sum_{m=1}^M V[X_m]$$

$$= \frac{\gamma^2}{M} V[X(\tilde{u}, b)]$$

$X_m$  iid  
can drop subscript  $m$   
and emphasize  $b$  and value  $X$

Note the same variance is just rescaled by  $\gamma^2$  due to  $\gamma$



