

## 主要修改内容

注：一、六的修改不知道会不会对网络产生影响

### 一.self.network()无bias\_layers这一属性

问题：core/model/replay/bic.py 中 \_stage1\_training 和 \_stage2\_bias\_correction 用到：

```
def _stage1_training(self, train_loader, test_loader):
    """
    if self.cur_task_id == 0:
        loaded_dict = torch.load('./dict_0.pkl')
        self.network.load_state_dict(loaded_dict['model_state_dict'])
        self.network.to(self.device)
        return
    """

    ignored_params = list(map(id, self.network.bias_layers.parameters()))
```

但self.network()无bias\_layers这一属性

解决方法：

注释了ignored\_params、base\_params、ignored\_params, network\_params, 把 optim.SGD 的第一个参数由 network\_params 改成了 self.network.parameters

```
def _stage1_training(self, train_loader, test_loader):
    """
    if self.cur_task_id == 0:
        loaded_dict = torch.load('./dict_0.pkl')
        self.network.load_state_dict(loaded_dict['model_state_dict'])
        self.network.to(self.device)
        return
    """
    ...

    ignored_params = list(map(id, self.network.bias_layers.parameters()))
    base_params = filter(lambda p: id(p) not in ignored_params, self.network.parameters())
    network_params = [
        {"params": base_params, "lr": self.lr, "weight_decay": self.weight_decay},
        {
            "params": self.network.bias_layers.parameters(),
            "lr": 0,
            "weight_decay": 0,
        },
    ]
    ...

    #optimizer = optim.SGD(network_params, lr=self.lr, momentum=self.momentum, weight_decay=self.weight_decay)
    optimizer = optim.SGD(self.network.parameters(), lr=self.lr, momentum=self.momentum, weight_decay=self.weight_decay)
    scheduler = optim.lr_scheduler.MultiStepLR(optimizer=optimizer, milestones=self.milestones, gamma=self.gamma)

    self.network.to(self.device)
    if self.old_network is not None:
        self.old_network.to(self.device)

    self._run(train_loader, test_loader, optimizer, scheduler, stage="training")
```

core/mode/backbone/resnet.py 中：

```

class CifarResNet(nn.Module):
    """
    ResNet optimized for the Cifar Dataset, as specified in
    https://arxiv.org/abs/1512.03385.pdf
    """

    def __init__(self, block, depth, channels=3):
        super(CifarResNet, self).__init__()

        # Model type specifies number of layers for CIFAR-10 and CIFAR-100
        assert (depth - 2) % 6 == 0, 'depth should be one of 20, 32, 44, 56, 68, 80'
        layer_blocks = (depth - 2) // 6

        self.conv_1_3x3 = nn.Conv2d(channels, 16, kernel_size=3, stride=1, padding=1)
        self.bn_1 = nn.BatchNorm2d(16)

```

二.cifarresnet的输出特征维度与bic.py中定义的classifier的feat\_dim不匹配

解决方法:

bic.yaml 里把 feat\_dim 改为64

```

#feat_dim: 256
feat_dim: 64
epoch: 250

```

三.bic类初始化时kwargs里无epoch等属性

解决方法: 把epoch等属性再抄一遍放在bic.yaml的classifier的kwargs里

```

classifier:
  name: bic
  kwargs:
    num_class: 100
    #feat_dim: 256
    feat_dim: 64
    epoch: 250
    init_cls_num: 10
    inc_cls_num: 10
    task_num: 10
    gamma: 0.5
    lr: 0.1
    weight_decay: 2e-4
    momentum: 0.9
    milestones: [60, 100, 140]

```

四. File `"/home/bzx_yjy/LibContinual/core/model/replay/bic.py"`, line 178, in `_run image, label = image.to(self.device), label.to(self.device)` `AttributeError: 'str' object has no attribute 'to'`

解决方法:

将原先的

```

for i, (image, label) in enumerate(train_loader):
    image, label = image.to(self.device), label.to(self.device)

```

改为

```

for i, batch in enumerate(train_loader):
    image = batch['image']
    label = batch['label']
    image, label = image.to(self.device), label.to(self.device)

```

## 五.inference里传的是一个不支持索引的数据加载器

解决方法:

```
File "/home/bzx_yjy/LibContinual/core/model/replay/bic.py", line 216, in _run
    train_acc = self.inference(train_loader)
File "/home/bzx_yjy/LibContinual/core/model/replay/bic.py", line 113, in inference
    x, y = data['image'], data['label']
TypeError: 'DataLoader' object is not subscriptable
```

修改216行的推理过程传递的内容, 把train\_loader换成batch, batch的含义如下:

```
for i, batch in enumerate(train_loader):

    image = batch['image']
    label = batch['label']
    image, label = image.to(self.device), label.to(self.device)
    logits = self.network(image)
```

## 六.buffer.reduce\_old\_data(self.cur\_task\_id, self.accu\_cls\_num) AttributeError: 'LinearBuffer' object has no attribute 'reduce\_old\_data'

解决方法:

bic.py 中:

```
def after_task(self, task_idx, buffer, train_loader, test_loaders):
    # freeze old network as KD teacher
    self.old_network = deepcopy(self.network)
    self.old_network.eval()
    self.prev_cls_num = self.accu_cls_num
    ...

    # update buffer
    buffer.reduce_old_data(self.cur_task_id, self.accu_cls_num)
    val_transform = test_loaders[0].dataset.trfms
    buffer.update(self.network, train_loader, val_transform,
                  self.cur_task_id, self.accu_cls_num, self.cur_cls_indexes,
                  self.device)

    # compute class mean vector via samples in buffer
    self.class_means = self.calc_class_mean(buffer,
                                              train_loader,
                                              val_transform,
                                              self.device).to(self.device)
    ...

    self.cur_task_id += 1
    self.lamda = self.prev_cls_num / self.accu_cls_num
```

七. File "/home/bzx\_yjy/LibContinual/core/model/replay/bic.py", line 201, in \_run distill\_loss = -torch.mean(torch.sum(hat\_pai\_k \* log\_pai\_k, dim=1)) RuntimeError: The size of tensor a (100) must match the size of tensor b (10) at non-singleton dimension 1

解决方法:

在bic.py的\_run中修改hat\_pai\_k

```
#hat_pai_k = F.softmax(old_logits / self.T, dim=1)
hat_pai_k = F.softmax(old_logits[:, : self.prev_cls_num] / self.T, dim=1)
log_pai_k = F.log_softmax(logits[:, : self.prev_cls_num] / self.T, dim=1)
distill_loss = -torch.mean(torch.sum(hat_pai_k * log_pai_k, dim=1))
```

## 部分结果

这是before\_task跑了250个epoch的截图 (不是很快)

```
=====Task 0 Start!=====
stage : training, => Task 0, Epoch 1/250 => Loss 2.399, train_acc : 0.219, test_acc : 0.219
stage : training, => Task 0, Epoch 2/250 => Loss 1.794, train_acc : 0.312, test_acc : 0.312
stage : training, => Task 0, Epoch 3/250 => Loss 1.605, train_acc : 0.375, test_acc : 0.375
stage : training, => Task 0, Epoch 4/250 => Loss 1.459, train_acc : 0.469, test_acc : 0.469
stage : training, => Task 0, Epoch 5/250 => Loss 1.319, train_acc : 0.688, test_acc : 0.688
stage : training, => Task 0, Epoch 6/250 => Loss 1.227, train_acc : 0.500, test_acc : 0.500
stage : training, => Task 0, Epoch 7/250 => Loss 1.162, train_acc : 0.594, test_acc : 0.594
stage : training, => Task 0, Epoch 8/250 => Loss 1.084, train_acc : 0.625, test_acc : 0.625
stage : training, => Task 0, Epoch 9/250 => Loss 1.041, train_acc : 0.719, test_acc : 0.719
stage : training, => Task 0, Epoch 10/250 => Loss 0.951, train_acc : 0.844, test_acc : 0.844
stage : training, => Task 0, Epoch 11/250 => Loss 0.904, train_acc : 0.875, test_acc : 0.875
stage : training, => Task 0, Epoch 12/250 => Loss 0.813, train_acc : 0.781, test_acc : 0.781
stage : training, => Task 0, Epoch 13/250 => Loss 0.741, train_acc : 0.750, test_acc : 0.750
stage : training, => Task 0, Epoch 14/250 => Loss 0.691, train_acc : 0.875, test_acc : 0.875
stage : training, => Task 0, Epoch 15/250 => Loss 0.638, train_acc : 0.875, test_acc : 0.875
stage : training, => Task 0, Epoch 16/250 => Loss 0.592, train_acc : 0.875, test_acc : 0.875
stage : training, => Task 0, Epoch 17/250 => Loss 0.504, train_acc : 0.906, test_acc : 0.906
stage : training, => Task 0, Epoch 18/250 => Loss 0.481, train_acc : 0.969, test_acc : 0.969
stage : training, => Task 0, Epoch 19/250 => Loss 0.461, train_acc : 0.938, test_acc : 0.938
stage : training, => Task 0, Epoch 20/250 => Loss 0.358, train_acc : 0.938, test_acc : 0.938
stage : training, => Task 0, Epoch 21/250 => Loss 0.416, train_acc : 0.812, test_acc : 0.812
stage : training, => Task 0, Epoch 22/250 => Loss 0.381, train_acc : 0.969, test_acc : 0.969
stage : training, => Task 0, Epoch 23/250 => Loss 0.363, train_acc : 0.969, test_acc : 0.969
stage : training, => Task 0, Epoch 24/250 => Loss 0.287, train_acc : 1.000, test_acc : 1.000
stage : training, => Task 0, Epoch 25/250 => Loss 0.264, train_acc : 0.906, test_acc : 0.906
stage : training, => Task 0, Epoch 26/250 => Loss 0.295, train_acc : 1.000, test_acc : 1.000
stage : training, => Task 0, Epoch 27/250 => Loss 0.273, train_acc : 0.906, test_acc : 0.906
stage : training, => Task 0, Epoch 28/250 => Loss 0.233, train_acc : 0.938, test_acc : 0.938
stage : training, => Task 0, Epoch 29/250 => Loss 0.229, train_acc : 0.969, test_acc : 0.969
stage : training, => Task 0, Epoch 30/250 => Loss 0.186, train_acc : 1.000, test_acc : 1.000
stage : training, => Task 0, Epoch 31/250 => Loss 0.222, train_acc : 1.000, test_acc : 1.000
stage : training, => Task 0, Epoch 32/250 => Loss 0.169, train_acc : 0.969, test_acc : 0.969
stage : training, => Task 0, Epoch 33/250 => Loss 0.206, train_acc : 1.000, test_acc : 1.000
stage : training, => Task 0, Epoch 34/250 => Loss 0.205, train_acc : 0.969, test_acc : 0.969
stage : training, => Task 0, Epoch 35/250 => Loss 0.169, train_acc : 1.000, test_acc : 1.000
stage : training, => Task 0, Epoch 36/250 => Loss 0.211, train_acc : 1.000, test_acc : 1.000
stage : training, => Task 0, Epoch 37/250 => Loss 0.163, train_acc : 0.969, test_acc : 0.969
stage : training, => Task 0, Epoch 38/250 => Loss 0.165, train_acc : 0.938, test_acc : 0.938
stage : training, => Task 0, Epoch 39/250 => Loss 0.150, train_acc : 1.000, test_acc : 1.000
stage : training, => Task 0, Epoch 40/250 => Loss 0.131, train_acc : 1.000, test_acc : 1.000
stage : training, => Task 0, Epoch 41/250 => Loss 0.179, train_acc : 1.000, test_acc : 1.000
stage : training, => Task 0, Epoch 42/250 => Loss 0.184, train_acc : 1.000, test_acc : 1.000
stage : training, => Task 0, Epoch 43/250 => Loss 0.166, train_acc : 1.000, test_acc : 1.000
```

不小心中止了训练, 为节约时间, 把before\_task里的epoch设成5跑

