# JL32xx – I2C Host Interface

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## **Revision History**

Revision	Description of Changes	Date
0.1	Preliminary release	Mar/08/2018



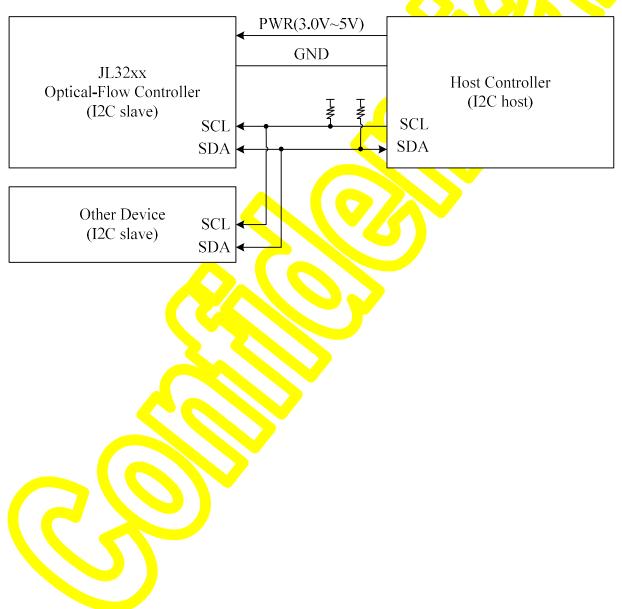


#### Introduction

This document describes slave mode I2C host interface of JL32xx. The "JL32xx" represents JL3283, JL3285 and JL3287.

The binary code of 7-bits I2C slave address is "0001001" and the maximum I2C clock rate is 400 KHz.

#### **I2C Wire Connection**





#### I2C Read/Write timing chart

#### Legend:

S Start bit
Stop bit
A Acknowledge bit from host CPU
A Acknowledge bit form JL32xx
Data wirte bit
Data read bit
Delay Time

#### Register write sequence

S	7 bit SLAVE_ADDR	nW	Α	Reg_Addr	Α	Reg_Data	Α	Р	

#### Register read sequence

٠	(Ogi	otor roda cot	44011												
	S	7-bit SLAVE_ADDR	nW	А	Reg_Addr	A	Р	Delay >80us	S	7 bit SLAVE_ADDR	R	А	DATA	А	Р

<sup>\*</sup>Please insert 80us delay between Stop-bit and Start-Bit for JL32xx to prepare read data.



#### **Register Descriptions**

#### • Info Registers (Read only)

Address	Name	Descriptions										
0x02	ROM ID	The revision number of internal mask ROM										
0x03	Chip ID	The Chip ID of JL32xx:										
		• JL3283A: 0x0F										
		● JL3285A: 0x0E										
		● JL3287A: 0x0D										

#### • Light Frequency (Read/Write)

Address	Name	<b>D</b> escriptions
0x11	Light Frequency	Set light frequency:
		0: 50Hz (Default)
		1: 60Hz

#### Motion Data Ready flag (Read only)

Address	Name	Descriptions
0x08	Motion Data Ready	This register indicates whether motion data is ready or
		not, Before reading motion data, host CPU should wait
		until motion data ready.
		0: Motion data not ready
		1: Motion data ready

#### Motion data (Read only)

There are 2 types of motion data format, i.e. short motion data and long motion data. Short motion data is a 6-byte burst data which provides surface quality information and X-Y motion value. Long motion data is a 16-byte burst data which provides full optical flow motion information.

Motion data register accumulate motion value from previous reading to current reading, the register will be cleared after reading. If host CPU miss the reading time, motion value will be accumulated to next frame. Host CPU should read motion data in burst sequence, describes as follows:

#### **Short Motion data:**

Address	Name	Descriptions
0x20	Short Motion data	The read address of short motion burst



## Timing chart:

														_			
S	7 bit SLAVE_ADDR	nW	Α	0x20	Α	P	Delay >80us	S	7 bit SLAVE_ADDR	R	Α	Byte(0)	Α		Byte(5)	Α	P

#### Motion burst description:

Monon our	st description.	
B[0]	Quality	This value tells the positioning quality of surface feature, the bigger
		the better.
		• Quality between 128~255 indicates surface feature is strong
		• Quality between 64~127 indicates surface feature is normal
		• Quality between 32~63 indicates surface feature is weak, it
		is not suggest for high speed motion over these surfaces.
		• Quality between 0~31 indicates surface feature is poor or
		ambient light is very low. Motion over these surfaces may
		with accumulated errors.
		Value range: 0~255
B[1]	Delta-XL	The accumulated X-axis motion value.
B[2]	Delta-XH	Value rang: -32768 ~32767 pixel
B[3]	Delta-YL	The accumulated Y-axis motion value.
B[4]	Delta-YH	Value rang: -32768 ~32767 pixel
B[5]	Checksum	The checksum value of byte 0~4.
		Host CPU detects check sum error if the check sum from B[0] to
		B[5] is not 0.

## Long Motion data:

Address	Name		Descriptions
0x21	Long Motion data	7	The read address of long motion burst

## Timing chart:

ſ	s	76a SLAVE_ADDR	nW	Α	0x21	Α	P	Delay >80us	S	75a SLAVE_ADDR	R	Α	Byte(0)	Α	 Byte(15)	Α	P

## Motion burst description:

B[0]	Quality	This v	This value tells the positioning quality of surface feature, the bigger					
		the bet	tter.					
		•	Quality between 128~255 indicates surface feature is strong					
		•	Quality between 64~127 indicates surface feature is normal					

#### JL32xx - I2C Host Interface

	The state of the s	Ouglity between 32~63 indicates surface feature is weak it					
		• Quality between 32~63 indicates surface feature is weak, it is not suggest for high speed motion over these surfaces.					
		• Quality between 0~31 indicates surface feature is poor or					
		ambient light is very low. Motion over these surfaces may					
		with accumulated errors.					
		Value range: 0~255					
B[1]	Delta-XL	The accumulated X-axis motion value.					
B[2]	Delta-XH	Value rang: -32768 ~32767 pixel					
B[3]	Delta-YL	The accumulated Y-axis motion value.					
B[4]	Delta-YH	Value rang: -32768 ~32 <mark>767 pixel</mark>					
B[5]	Delta-ZL	The accumulated Z-axis motion value.					
B[6]	Delta-ZH	Value rang: -32768 ~32767					
B [7]	Reference number	Reference search images update counter. This value will auto wrap					
		to 0 after reaching 255.					
		Value range: 0~255					
B[8]	Lightness	This value indicates the lightness of ambient. Low light environment					
		will cause poor positioning outcomes.					
		Value rang: 0~255					
B[9]	Sub_XL	The sub-view X-axis motion value.					
B[10]	Sub_XH	Value rang: -32768 ~32767 pixel					
B[11]	Sub_YL	The sub-view Y-axis motion value.					
B[12]	Sub_YH	Value rang: -32768 ~32767 pixel					
B[13]	Interval_L	The time interval (ms) from previous reading to current reading.					
B[14]	Interval_H	Value rang: 0~65535					
B[15]	Checksum	The checksum value of byte 0~14.					
		Host CPU detects check sum error if the check sum from B[0] to					
		B[15] is not 0.					



#### • Special Function Register (Read/Write)

The Special Function Register, i.e. SFR, is for host CPU to update initial code or poll hardware status. Since I2C is 8bit addressing, SFR registers are extended by adding Bank addressing. Host CPU should specify Bank + Address to access SFR registers.

Address	Name		
0x80	Reg_Bank	SFR bank	
0x81	Reg_Addr	SFR address	
0x82	Reg_Data	SFR data	110

#### Write data to SFR:

#### Timing Chart:

S	7 bit SLAVE_ADDR	пW	A	0x80	A	Reg_Bank	A	Reg_Addr	Α	Reg_Data	A	Р

#### Read data from SFR:

Step 1: Specify the Reg Bank + Reg Addr of SFR to be read



#### Step 2: Read specified SFR data







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