Improved Dropout for Shallow and Deep Learning

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- Introduction and Problem Setup
- 2 Improved Dropout for Shallow Learning
- 3 Improved Dropout for Deep Learning
- 4 Experimental Results
- 6 Conclusion

Outline

- 1 Introduction and Problem Setup
- 2 Improved Dropout for Shallow Learning
- Improved Dropout for Deep Learning
- 4 Experimental Results
- Conclusion

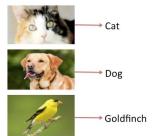
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The success of deep learning

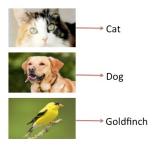
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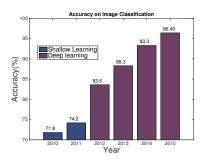
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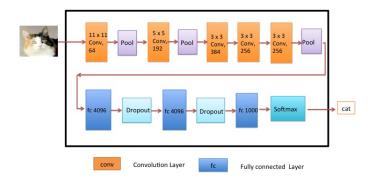
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Deep Neural Network

The classical example: AlexNet [A Krizhevsky, et .al, 2012]



Dropout Layer

• Dropout Layer: Uniformly at randomly drop out features.



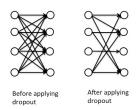
Before applying dropout



After applying dropout

Dropout Layer

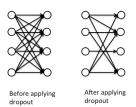
Dropout Layer: Uniformly at randomly drop out features.



• Is uniformly dropout optimal?

Dropout Layer

Dropout Layer: Uniformly at randomly drop out features.



- Is uniformly dropout optimal?
 - Answered the above question in this work.

Improved Dropout

Improved Dropout

• Dropping out the output of the neuron based on multinomial distribution computed from the training data.

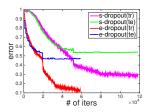


Figure: Evolutional dropout vs standard dropout on CIFAR100 datasets for deep learning

• Let (\mathbf{x}, y) denote a feature vector and a label, where $\mathbf{x} \in \mathbb{R}^d$ and $y \in \mathcal{Y}$.

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- Denote by P the joint distribution of (x, y) and by D the marginal distribution of x.
- The goal is to learn a linear prediction function $(f(x) = \mathbf{w}^{\top}\mathbf{x})$ that minimizes the expected risk (considering loss function $\ell(\cdot, y)$):

$$\min_{\mathbf{w} \in \mathbb{R}^d} \mathcal{L}(\mathbf{w}) \triangleq \mathrm{E}_{\mathcal{P}}[\ell(\mathbf{w}^\top \mathbf{x}, y)] \tag{1}$$

• Denote by $\epsilon \sim \mathcal{M}$ a dropout noise vector of dimension d.

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- Denote by $\widehat{\mathcal{P}}$ the joint distribution of the new data $(\widehat{\mathbf{x}}, y)$ and by $\widehat{\mathcal{D}}$ the marginal distribution of $\widehat{\mathbf{x}}$.
- With the corrupted data, the risk minimization becomes

$$\min_{\mathbf{w} \in \mathbb{R}^d} \widehat{\mathcal{L}}(\mathbf{w}) \triangleq \mathrm{E}_{\widehat{\mathcal{P}}}[\ell(\mathbf{w}^\top (\mathbf{x} \circ \boldsymbol{\epsilon}), y)]$$
 (2)

Definition 1

A **multinomial dropout** is defined as $\hat{\mathbf{x}} = \mathbf{x} \circ \boldsymbol{\epsilon}$, where $\epsilon_i = \frac{m_i}{kp_i}, i \in [d]$ and $\{m_1, \dots, m_d\}$ follow a multinomial distribution $Mult(p_1, \dots, p_d; k)$ with $\sum_{i=1}^d p_i = 1$ and $p_i \geq 0$.

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- Ability of using non-uniformly sampling probabilities for different features.
- Easy to control the level of dropout by varying the value of k.

• Dropout is a data-dependent regularizer.

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Proposition 1

If
$$\ell(z,y) = \log(1 + \exp(-yz))$$
, then

$$\mathrm{E}_{\widehat{\mathcal{P}}}[\ell(\mathbf{w}^{\top}\widehat{\mathbf{x}}, y)] = \mathrm{E}_{\mathcal{P}}[\ell(\mathbf{w}^{\top}\mathbf{x}, y)] + R_{\mathcal{D}, \mathcal{M}}(\mathbf{w})$$

where ${\mathcal M}$ denotes the distribution of ϵ and

$$R_{\mathcal{D},\mathcal{M}}(\mathbf{w}) = \mathrm{E}_{\mathcal{D},\mathcal{M}} \left[\log \frac{\exp(\mathbf{w}^{\top} \frac{\mathbf{x} \circ \epsilon}{2}) + \exp(-\mathbf{w}^{\top} \frac{\mathbf{x} \circ \epsilon}{2})}{\exp(\mathbf{w}^{\top} \mathbf{x}/2) + \exp(-\mathbf{w}^{\top} \mathbf{x}/2)} \right].$$

Learning with Multinomial Dropout

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• Give the initial solution \mathbf{w}_1 .

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- Give the initial solution w₁.
- Update the model at tth iteration:

$$\mathbf{w}_{t+1} = \mathbf{w}_t - \eta_t \nabla \ell(\mathbf{w}_t^{\top}(\mathbf{x}_t \circ \epsilon_t), y_t)$$
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Learning with Multinomial Dropout

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Output the final solution:

$$\widehat{\mathbf{w}}_n = \frac{1}{n} \sum_{t=1}^n \mathbf{w}_t$$

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Theorem 1:

Let $\mathcal{L}(\mathbf{w})$ be the expected risk of \mathbf{w} defined in (1). Assume $\mathrm{E}_{\widehat{\mathcal{D}}}[\|\mathbf{x}\circ\boldsymbol{\epsilon}\|_2^2] \leq B^2$ and $\ell(z,y)$ is convex and G-Lipschitz continuous. For any $\|\mathbf{w}_*\|_2 \leq r$, by appropriately choosing η , we can have

$$E[\mathcal{L}(\widehat{\mathbf{w}}_n) + R_{\mathcal{D},\mathcal{M}}(\widehat{\mathbf{w}}_n)] \leq \mathcal{L}(\mathbf{w}_*) + R_{\mathcal{D},\mathcal{M}}(\mathbf{w}_*) + \frac{GBr}{\sqrt{n}}$$

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How to prove the above theorem?

- Standard SGD analysis.
- Dropout is a data-dependent regularizer.

• Minimizing the term $E_{\widehat{\mathcal{D}}}[\|\mathbf{x} \circ \boldsymbol{\epsilon}\|_2^2]$ and the relaxed upper bound of term $R_{\mathcal{D},\mathcal{M}}(\mathbf{w}_*)$ yields the optimal sampling probabilities:

$$p_i^* = \frac{\sqrt{\mathrm{E}_{\mathcal{D}}[x_i^2]}}{\sum_{j=1}^d \sqrt{\mathrm{E}_{\mathcal{D}}[x_j^2]}}, i = 1, \dots, d$$
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 Practically, we use the empirical second-order statistics to compute the probabilities:

$$p_{i} = \frac{\sqrt{\frac{1}{n} \sum_{j=1}^{n} [[\mathbf{x}_{j}]_{i}^{2}]}}{\sum_{i'=1}^{d} \sqrt{\frac{1}{n} \sum_{j=1}^{n} [[\mathbf{x}_{j}]_{i'}^{2}]}}, i = 1, \dots, d$$
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- How to address this issue?
 - Use a mini-batch of examples to calculate the dropout probablity.

• Let $X^l = (\mathbf{x}_1^l, \dots, \mathbf{x}_m^l)$ denote the outputs of the l^{th} layer for a mini-batch of m examples, calculate the probabilities for dropout by

$$p_{i}^{l} = \frac{\sqrt{\frac{1}{m} \sum_{j=1}^{m} [[\mathbf{x}_{j}^{l}]_{i}^{2}]}}{\sum_{i'=1}^{d} \sqrt{\frac{1}{m} \sum_{j=1}^{m} [[\mathbf{x}_{j}^{l}]_{i'}^{2}]}}, i = 1, \dots, d$$
 (6)

Evolutional Dropout for Deep Learning

Input: a batch of outputs of a layer:
$$X^l = (\mathbf{x}_1^l, \dots, \mathbf{x}_m^l)$$
 and dropout level parameter $k \in [0, d]$

Output: $\widehat{X}^l = X^l \circ \Sigma^l$

Compute sampling probabilities by (6)

For $j = 1, \dots, m$

Sample $\mathbf{m}_j^l \sim Mult(p_1^l, \dots, p_d^l; k)$

Construct $\epsilon_j^l = \frac{\mathbf{m}_j^l}{k\mathbf{p}^l} \in \mathbb{R}^d$, where $\mathbf{p}^l = (p_1^l, \dots, p_d^l)^\top$

Let $\Sigma^l = (\epsilon_1^l, \dots, \epsilon_m^l)$ and compute $\widehat{X}^l = X^l \circ \Sigma^l$

Figure: Evolutional Dropout applied to a layer over a mini-batch

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Experimental Results for Shallow Learning

Training/test error between standard and improved dropout

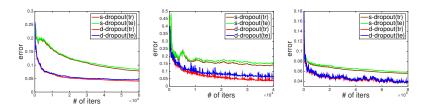


Figure: data-dependent dropout vs. standard dropout on three datasets (real-sim, news20 and RCV1) for logistic regression

Implemented in CudaConvNet Library.

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- Using four benchmark datasets: MNIST, SVHN, CIFAR10, CIFAR100.
- Different neural network stuctures from the existing literatures.
- Training strategy.

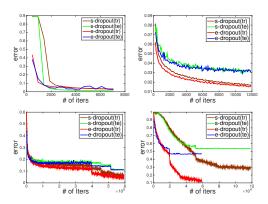


Figure: Evolutional dropout vs. standard dropout on four benchmark datasets (MNIST, SVHN, CIFAR-10 and CIFAR-100) for deep learning

Compared to Batch Normalization

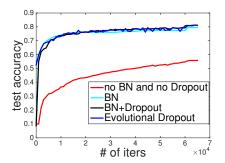


Figure: Evolutional dropout vs BN on CIFAR-10.

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- Proposed a multinomial dropout for shallow learning.
- Demonstrated that this proposed distribution-dependent dropout leads to a faster convergence and a smaller generalization error through the risk bound analysis.
- Proposed an efficient evolutional dropout for deep learning.
- Justified the proposed dropouts for both shallow and deep learning empirically.

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Question?