

# Concurrent Erlang



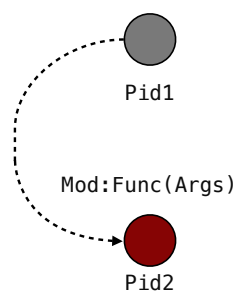
## Overview: concurrent Erlang I

- Concurrent Erlang I
  - Creating Processes
  - Message Passing
  - Receiving Messages
  - Data in Messages
- Concurrent Erlang II



## Creating Processes

`spawn(Mod, Func, Args)`

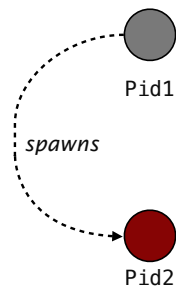


- Before
  - Code executed by Process 1
  - **process identifier** is Pid1
  - `Pid2 = spawn(M, F, A)`
- After
  - A new process with Pid2 is created
  - Pid2 is only known to Pid1
  - Pid2 runs `M:F(A)`
  - `M:F/Arity` must be exported
- Convention: we identify processes by their process ids (pids)



## Creating Processes

`spawn(Mod, Func, Args)`



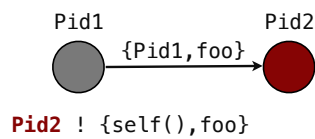
- The BIF **spawn** never fails
- A process terminates
  - **abnormally** when run-time errors occur
  - **normally** when there is no more code to execute



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## Message Passing



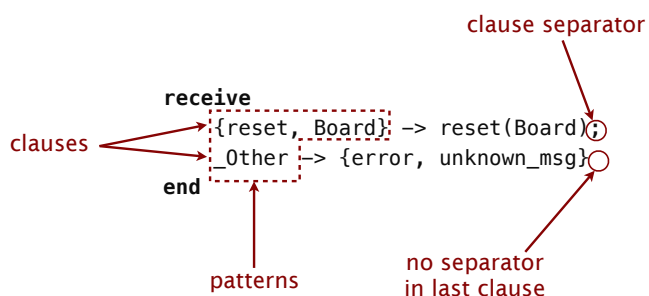
- Messages are sent using the **Pid ! Msg** expression
  - **Msg** is any valid Erlang data type
- Sending a message will never fail
- Messages sent to non-existing processes are thrown away
- Received messages are stored in the process' mailbox



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## Message Passing



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## Receiving Messages

### receive

```
Pattern1 ->  
  <expression 1>,  
  <expression 2>,  
  ...,  
  <expression N>;  
Pattern2 ->  
  <expression 1>,  
  ...,  
  <expression N>;  
...;  
PatternN ->  
  <expression 1>,  
  ...  
  <expression N>
```

end

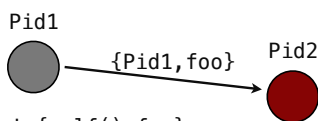


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- Messages are retrieved using a **receive** clause
- **receive** suspends the process until a message is received
- Message passing is asynchronous

## Receiving Messages



**Pid2** ! {self(),foo}

```
receive  
  start -> ...  
  stop  -> ...  
  {Pid, foo} ->  
  ...  
end
```

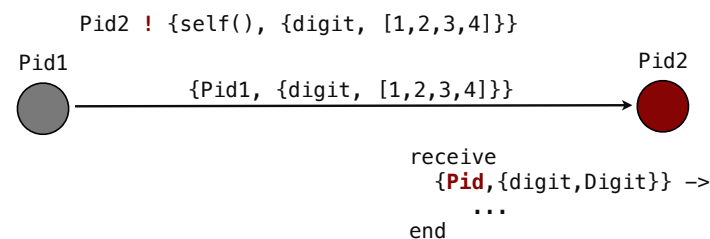


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- Messages can be matched and selectively retrieved
- Messages are received when a message matches a clause
- Mailboxes are scanned sequentially.

## Receiving Messages



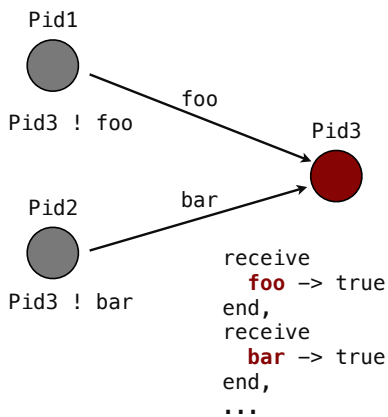
- If **Pid** is bound before receiving the message, then only data tagged with that pid can be pattern matched
- The variable **Digit** is bound when receiving the message



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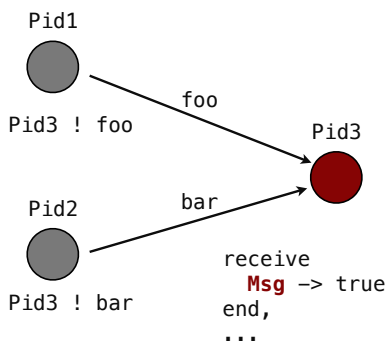
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## Receiving Messages: **selective**



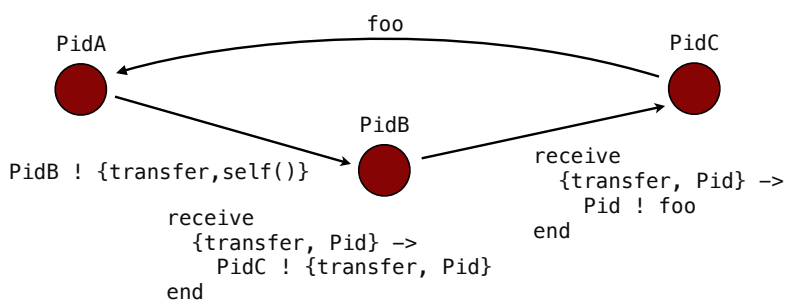
- The message **foo** is received, followed by the message **bar**
- This is irrespective of the order in which they were sent or stored in the mailbox

## Receiving Messages: **non-selective**



- The first message to arrive at the process **Pid3** will be processed
- The variable **Msg** in the process **Pid3** will be bound to one of the atoms **foo** or **bar** depending on which arrives first.

## Receiving Messages



- PidA sends a message to PidB containing its own Pid
- PidB binds it to variable A and sends a message to PidC
- PidC receives the message and replies directly to PidA

## Data in Messages: **example**

```
-module(echo).
-export([go/0, loop/0]).

go() ->
  Pid= spawn(echo, loop, []),
  Pid ! {self(), hello},
  receive
    {Pid, Msg} ->
      io:format("~w~n", [Msg])
  end,
  Pid ! stop.

loop() ->
  receive
    {From, Msg} ->
      From ! {self(), Msg},
      loop();
  stop ->
    true
  end.
```



## Summary: **concurrent Erlang I**

- Concurrent Erlang I
  - Creating Processes
  - Message Passing
  - Receiving Messages
  - Data in Messages
- Concurrent Erlang II



## Overview: **concurrent Erlang II**

- Concurrent Erlang I
- Concurrent Erlang II
  - Registered Processes
  - Timeouts
  - More on Processes
  - The Process Manager



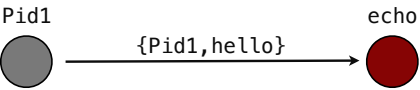
## Registered Processes

```
register(Alias, Pid)  
Alias ! Message
```

- Registers the process **Pid** with the name **Alias**
- Any process can send a message to a registered process
- The BIF **registered/0** returns all registered process names
- The BIF **whereis(Alias)** returns the Pid of the process with the name **Alias**.



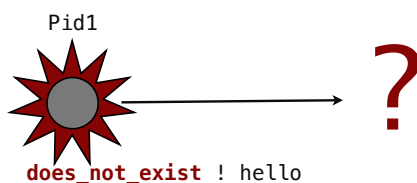
## Registered Processes



```
echo ! {self(), hello}    receive {From, Msg} -> ... end  
  
go() -> register(echo, spawn(echo, loop, [])).  
  
loop() ->  
  receive  
    {From, Msg} ->  
      From ! {self(), Msg},  
      loop();  
  stop -> true  
end.
```



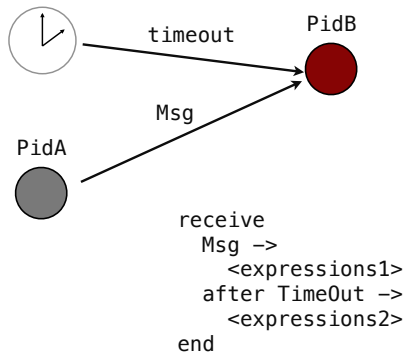
## Message Passing



- Sending messages to non-existing registered processes causes the calling process to terminate with a **badarg** error



## Timeouts



- If the message **Msg** is received within the time **TimeOut**, <expressions1> will be executed
- If not, <expressions2> will be executed
- TimeOut is an integer denoting the time in milliseconds or the atom **infinity**



## Timeouts

```

read(Key) ->
  flush(),
  db ! {self(), {read, Key}},
  receive
    {read, R} ->
      {ok, R};
    {error, Reason} ->
      {error, Reason}
  after 1000 ->
    {error, timeout}
  end.

```

- If the server takes more than a second to handle the request, a timeout is generated
- Do not forget to handle messages received after a timeout



## Timeouts

```

send_after(Time, Msg) ->
  spawn(timer,
    send,
    [self(), Time, Msg]).

send(Pid, Time, Msg) ->
  receive
  after Time ->
    Pid ! Msg
  end.

sleep(T) ->
  receive
  after T ->
    true
  end.

```

- **send\_after(T, What)** sends the message **What** to the current process after **T** milliseconds
- The **sleep(T)** function will suspend the calling process for **T** milliseconds



## Timeouts

```
flush() ->  
  receive  
  _ -> flush()  
  after 0 ->  
    ok  
end.
```

- **flush()** will clear the mailbox from all messages, stopping when it is empty.



## More on Processes: definitions

### Process

A concurrent activity. The system may have many concurrent processes executing at the same time

### Message

A method of communication and sharing data between processes

### Timeout

A mechanism for waiting for a given period of time for an incoming message



## More on Processes: definitions

### Registered Processes

Processes which have been given a name with BIFs such as **register/2**.

### Termination

A process is said to terminate normally when it has no more code to execute.

It terminates abnormally if a run time error occurs or if someone makes it exit with a non-normal reason.





## More on Processes: **process skeleton**

```
start(Args) -> spawn(server, init, [Args])
```

```
init(Args) ->  
  State = initialize_state(Args),  
  loop(State).
```

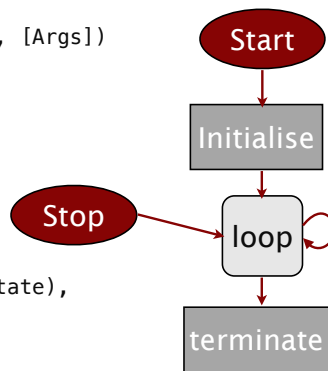
```
loop(State) ->  
  receive  
    {handle, Msg} ->  
      NewState = handle(Msg, State),  
      loop(NewState);  
  stop -> terminate(State)  
  end.
```

```
terminate(State) -> clean_up(State).
```



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## The Process Manager

- Used to inspect the state of processes in a local or distributed Erlang system
- Trace output for messages sent & received
- Trace output for process events such as spawn, exit and link
- Trace output for BIF and function calls

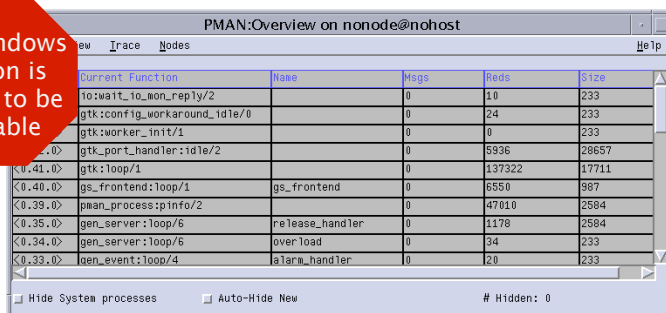


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## The Process Manager

The windows version is known to be unstable



Current Function	Name	Msgs	Reds	Size
io:wait_io_mon_reply/2		0	10	233
gtk:config_workaround_idle/0		0	24	233
gtk:worker_init/1		0	0	233
gtk_port_handler:idle/2		0	5936	28657
<0.41.0> gtk:loop/1		0	137322	17711
<0.40.0> gs_frontend:loop/1	gs_frontend	0	6550	987
<0.39.0> pman_process:pinfno/2		0	47010	2584
<0.35.0> gen_server:loop/6	release_handler	0	1178	2584
<0.34.0> gen_server:loop/6	overload	0	34	233
<0.33.0> gen_event:loop/4	alarm_handler	0	20	233

Hide System processes    Auto-Hide New    # Hidden: 0

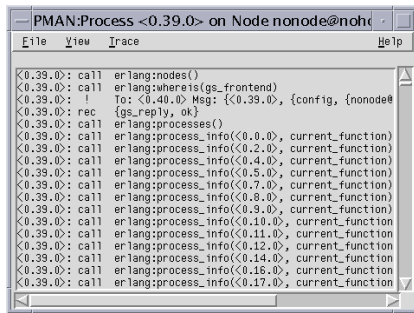
- `pman:start()`



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## Process Manager: **processes**

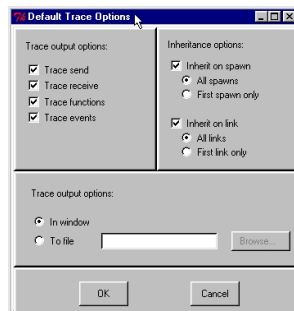


```
PMAN:Process <0.39.0> on Node nonode@nohc
File View Trace Help
<0.39.0>: call erlang:nodes()
<0.39.0>: call erlang:whereis(gs_frontend)
<0.39.0>: ! To: <0.40.0> Msg: {<0.39.0>, {config, {nonode#
<0.39.0>: rec {gs_reply, ok}
<0.39.0>: call erlang:processes()
<0.39.0>: call erlang:process_info(<0.0.0>, current_function)
<0.39.0>: call erlang:process_info(<0.2.0>, current_function)
<0.39.0>: call erlang:process_info(<0.4.0>, current_function)
<0.39.0>: call erlang:process_info(<0.5.0>, current_function)
<0.39.0>: call erlang:process_info(<0.7.0>, current_function)
<0.39.0>: call erlang:process_info(<0.8.0>, current_function)
<0.39.0>: call erlang:process_info(<0.9.0>, current_function)
<0.39.0>: call erlang:process_info(<0.10.0>, current_function)
<0.39.0>: call erlang:process_info(<0.11.0>, current_function)
<0.39.0>: call erlang:process_info(<0.12.0>, current_function)
<0.39.0>: call erlang:process_info(<0.14.0>, current_function)
<0.39.0>: call erlang:process_info(<0.16.0>, current_function)
<0.39.0>: call erlang:process_info(<0.17.0>, current_function)
```

- Prints the trace messages and process state



## Process Manager: **options**



- Pick what trace messages you want to view
- Pick the inheritance level when spawning



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