view frames Result Recorded at time: 1722384067.7058184 map Broadcaster: /slam gmapping Average rate: 20.202Buffer length: 4.95 Most recent transform: 1722384067.708 Oldest transform: 1722384062.758 odom Broadcaster: /quori/quori controller Average rate: 16.424 Buffer length: 4.932 Most recent transform: 1722384067.663 Oldest transform: 1722384062.732 ramsis/wheel axle Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $16.6\overline{2}6$ Average rate: $1000\overline{0}.0$ Average rate: $16.6\overline{2}6$ Buffer length: 0.0 Buffer length: 4.932 Buffer length: 4.932 Most recent transform: 1722384067.663 Most recent transform: 0.0 Most recent transform: 1722384067.663 Oldest transform: 1722384062.732 Oldest transform: 1722384062.732 Oldest transform: 0.0 ramsis/l wheel link ramsis/base link diff ramsis/r wheel link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Average rate: $16.6\overline{2}6$ Buffer length: 0.0 Buffer length: 4.932 Most recent transform: 0.0 Most recent transform: 1722384067.663 Oldest transform: 1722384062.732 Oldest transform: 0.0 ramsis/turret link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 ramsis/base_link quori/base_link Broadcaster: /robot state publisher Average rate: $16.6\overline{2}6$ Buffer length: 4.932 Most recent transform: 1722384067.663 Oldest transform: 1722384062.732 quori/body_upper Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $16.6\overline{2}6$ Average rate: $16.6\overline{2}6$ Buffer length: 4.932 Buffer length: 4.932 Most recent transform: 1722384067.663 Most recent transform: 1722384067.663 Oldest transform: 1722384062.732 Oldest transform: 1722384062.732 quori/l shoulder quori/r shoulder Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $16.6\overline{2}6$ Average rate: $16.6\overline{2}6$ Buffer length: 4.932 Buffer length: 4.932 Most recent transform: 1722384067.663 Most recent transform: 1722384067.663 Oldest transform: 1722384062.732 Oldest transform: 1722384062.732 quori/l arm upper quori/r arm upper Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.0 Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 quori/r_arm_upper2lower quori/l arm lower quori/r arm lower

ramsis/base laser scanner

Broadcaster: /robot state publisher

Average rate: $1000\overline{0}.0$

Buffer length: 0.0

Most recent transform: 0.0

Oldest transform: 0.0

Average rate: $1000\overline{0}.0$

Buffer length: 0.0

Most recent transform: 0.0

Oldest transform: 0.0

Broadcaster: /robot state publisher

Average rate: $1000\overline{0}.0$

Buffer length: 0.0

Most recent transform: 0.0

Oldest transform: 0.0

quori/head

Broadcaster: /robot state publisher | Broadcaster: /robot state publisher

quori/head mic

quori/l arm upper2lower

Average rate: $1000\overline{0}.0$

Buffer length: 0.0

Most recent transform: 0.0

Oldest transform: 0.0

Broadcaster: /robot state publisher

Average rate: $1000\overline{0}.0$

Buffer length: 0.0

Most recent transform: 0.0

Oldest transform: 0.0

quori/head camera

quori/head camera optical