view_frames Result

Recorded at time: 1718402153.1318219

map

Broadcaster: /slam_gmapping
Average rate: 20.202
Buffer length: 4.95
Most recent transform: 1718402153.15
Oldest transform: 1718402148.2

Broadcaster: /static_transformer
Average rate: 10.195
Buffer length: 4.904
Most recent transform: 1718402153.166
Oldest transform: 1718402148.262

odom

respeaker_base

Broadcaster: /quori/quori_controller
Average rate: 17.565
Buffer length: 4.953
Most recent transform: 1718402153.1
Oldest transform: 1718402148.147

ramsis/wheel_axle

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 17.565
Buffer length: 4.953
Most recent transform: 1718402153.1
Oldest transform: 1718402148.147

Broadcaster: /robot_state_publisher
Average rate: 17.565
Buffer length: 4.953
Most recent transform: 1718402153.1
Oldest transform: 1718402148.147

ramsis/base_link_diff

ramsis/l_wheel_link

ramsis/r_wheel_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 17.565
Buffer length: 4.953
Most recent transform: 1718402153.1
Oldest transform: 1718402148.147

ramsis/base_laser_scanner

ramsis/turret_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

quori/base_link

ramsis/base_link

Broadcaster: /robot_state_publisher
Average rate: 17.565
Buffer length: 4.953
Most recent transform: 1718402153.1
Oldest transform: 1718402148.147

quori/body_upper

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 17.565
Buffer length: 4.953
Most recent transform: 1718402153.1
Oldest transform: 1718402148.147

Broadcaster: /robot_state_publisher
Average rate: 17.565
Buffer length: 4.953
Most recent transform: 1718402153.1
Oldest transform: 1718402148.147

quori/head

quori/l_shoulder

quori/r_shoulder

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 17.565
Buffer length: 4.953
Most recent transform: 1718402153.1
Oldest transform: 1718402148.147

Broadcaster: /robot_state_publisher
Average rate: 17.565
Buffer length: 4.953
Most recent transform: 1718402153.1
Oldest transform: 1718402148.147

quori/head_camera

quori/head_mic

quori/l_arm_upper

quori/r_arm_upper

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

quori/head_camera_optical

quori/l_arm_upper2lower

quori/l_arm_lower

quori/r_arm_upper2lower

quori/r_arm_lower