

mmpf: Monte-Carlo Methods for Prediction Functions

by Zachary M. Jones

Abstract Machine learning methods can often learn high-dimensional functions which generalize well but are not human interpretable. `mmpf` marginalizes prediction functions using Monte-Carlo methods, allowing users to investigate the behavior of these learned functions on subsets of input features: partial dependence and variations thereof. This makes machine learning methods more useful in situations where accurate prediction is not the only goal.

Many methods for estimating prediction functions produce estimated functions which are not directly human-interpretable because of their complexity: they may include high-dimensional interactions and/or complex nonlinearities. Additionally, with many machine learning methods, the resulting prediction function is difficult to interpret even when the function it represents is simple enough to be human-interpretable (e.g., a random forest fit to data from a linear and additive statistical model). While a learning method's capacity to automatically learn interactions and nonlinearities is attractive when the goal is prediction, there are many cases where users want good predictions *and* the ability to understand how predictions depend on the features. `mmpf` implements general methods for interpreting prediction functions using Monte-Carlo methods (Friedman, 2001). These methods allow any function which generates predictions to be interpreted. `mmpf` is currently used in other packages for machine learning like `edarf` and `mlr` (Jones and Linder, 2016; Bischl et al., 2016).

Machine learning has found application in a number of areas where, correspondingly, this package may be of use. Within economics and political science, for example, useful areas of application might include the estimation of treatment effects and their heterogeneity (Imbens, 2004; Athey and Imbens, 2017), exploratory analysis wherein the goal is to uncover predictively important features for future study (Lupu and Jones, 2018; Hill and Jones, 2014), and in the analysis of forecast models (Berk et al., 2009; Blair et al., 2017).

Marginalizing Prediction Functions

The core function of `mmpf`, `marginalPrediction`, allows marginalization of a prediction function so that it depends on a subset of the features. Say the matrix of features \mathbf{X} is partitioned into two subsets, \mathbf{X}_u and \mathbf{X}_{-u} , where the former is of primary interest. A prediction function f which in the regression case maps $\mathbf{X} \rightarrow \mathbf{y}$, where \mathbf{y} is a real-valued vector, might not be additive or linear in the columns of \mathbf{X}_u , making f difficult to interpret directly. To obtain the marginal relationship between \mathbf{X}_u and f we could marginalize the joint distribution so that we obtain a function f_u which only depends on the relevant subset of the features.

$$f_u(\mathbf{X}_u) = \int f(\mathbf{X}_u, \mathbf{X}_{-u}) \mathbb{P}(\mathbf{X}_u | \mathbf{X}_{-u}) \mathbb{P}(\mathbf{X}_{-u}) d\mathbf{X}_{-u}$$

This however, can distort the relationship between \mathbf{X}_u and f because of the inclusion of dependence between \mathbf{X}_u and \mathbf{X}_{-u} (specifically $\mathbf{X}_u | \mathbf{X}_{-u}$), which is not directly related to f .¹ An alternative is to instead integrate against the marginal distribution of \mathbf{X}_{-u} as in 2.1, as suggested by (Friedman, 2001).

$$\tilde{f}_u(\mathbf{X}_u) = \int f(\mathbf{X}_u, \mathbf{X}_{-u}) \mathbb{P}(\mathbf{X}_{-u}) d\mathbf{X}_{-u}$$

To illustrate this point, suppose data are generated from an additive model, $f(\cdot) = \mathbf{x}_1 + \mathbf{x}_2$ and $(\mathbf{x}_1, \mathbf{x}_2) \sim \text{MVN}(\mathbf{0}, \Sigma)$ where the diagonal entries of Σ are 1 and the off-diagonals are .5. That is, $(\mathbf{x}_1, \mathbf{x}_2)$ are correlated by construction. Now if we want to understand how f depends on \mathbf{x}_1 we could integrate against the true joint distribution as in 2.1. However, this distorts the relationship between \mathbf{x}_1 and f because the conditional probability of \mathbf{x}_1 given \mathbf{x}_2 is higher at values of $(\mathbf{x}_1, \mathbf{x}_2)$ which are more extreme (due to their correlation). Since \mathbf{x}_2 is related to f this has the effect of distorting the relationship between \mathbf{x}_1 and f , and, in this case, makes the relationship appear more extreme than it is, as can be seen in the left panel of Figure 1. This distortion of the relationship between \mathbf{x}_1 and f can be made more misleading if \mathbf{x}_2 interacts with \mathbf{x}_1 to produce f , or if \mathbf{x}_2 has a nonlinear relationship with f , as can be seen in the right panel of Figure 1.

Integrating against the marginal distribution of \mathbf{x}_1 recovers the true additive effect (left panel) and

¹As noted by Hooker (2004) being able to separate f into components additive in \mathbf{X}_u and \mathbf{X}_{-u} does not mean that \mathbf{X}_u and \mathbf{X}_{-u} are independent.

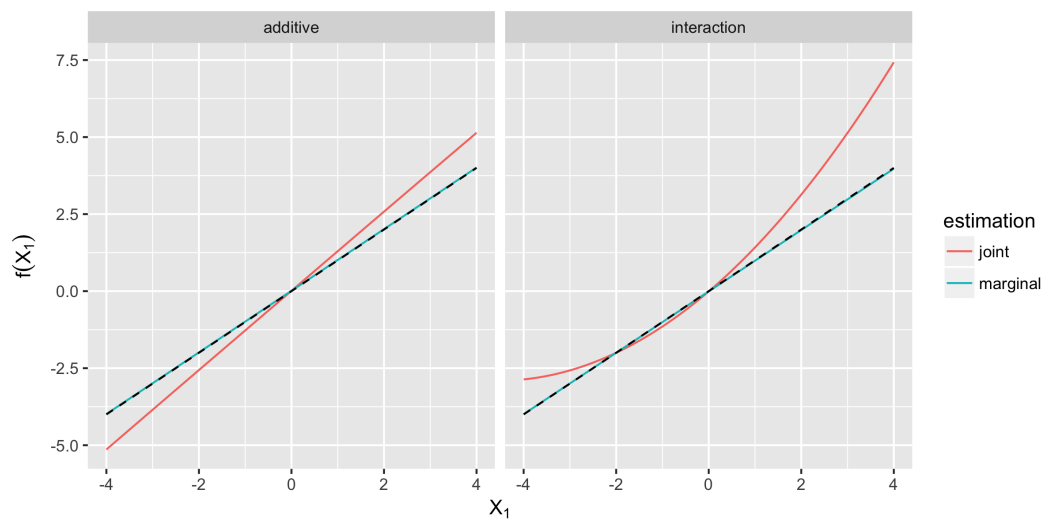


Figure 1: The marginal relationship between x_1 and f as estimated by integrating against the marginal distribution of x_2 (the blue line) or the joint distribution of (x_1, x_2) (the red line). The true relationship is shown by the dashed line. In the left panel f is an additive function of x_1 and x_2 and in the right panel x_1 and x_2 interact via multiplication to produce f .

the average marginal effect ($x_1 + .5x_1\bar{x}_2$, in the right panel) respectively.

Using mmpf

In practical settings we do not know $\mathbb{P}(\mathbf{X})$ or f . Using \hat{f} , estimated from (\mathbf{X}, \mathbf{y}) as a plug-in estimator for f and treating the training data as a realization from $\mathbb{P}(\mathbf{X})$ allows us to estimate the *partial dependence* of X_u on \hat{f} [Friedman \(2001\)](#).

$$\hat{f}_u(\mathbf{X}_u) = \sum_{i=1}^N \hat{f}(\mathbf{X}_u, \mathbf{X}_{-u}^{(i)})$$

This is the behavior of the prediction function at a vector or matrix of values for \mathbf{X}_u , averaged over the empirical marginal distribution of \mathbf{X}_{-u} , which is an application of Monte-Carlo integration ([Metropolis and Ulam, 1949](#); [Hammersley and Handscomb, 1964](#)).

The core function of `mmpf`, `marginalPrediction`, allows users to compute partial dependence and many variations thereof easily. The key arguments of `marginalPrediction` are the prediction function (`predict.fun`), the training data (`data`), the names of the columns of the training data which are of interest (`vars`), the number of points to use in the grid for \mathbf{X}_u and the number of points to sample from \mathbf{X}_{-u} (`n`, an integer vector of length 2). Additional arguments control how the grid is constructed (e.g., uniform sampling, user chosen values, non-uniform sampling), allow the use of weights (e.g., to exclude certain regions of the feature space), and how aggregation is done (e.g., deviations from partial dependence). Below is an example using the Iris data ([Anderson, 1936](#)).

```
library(mmpf)
library(randomForest)

data(iris)
iris.features = iris[, -ncol(iris)] # exclude the species column
fit = randomForest(iris.features, iris$Species)

mp = marginalPrediction(data = iris.features,
  vars = "Petal.Width",
  n = c(10, nrow(iris)), model = fit, uniform = TRUE,
  predict.fun = function(object, newdata) predict(object, newdata, type = "prob"))
print(mp)
##      Petal.Width      setosa versicolor virginica
## 1:  0.1000000 0.6374133 0.2337733 0.1288133
## 2:  0.3666667 0.6374133 0.2337733 0.1288133
```

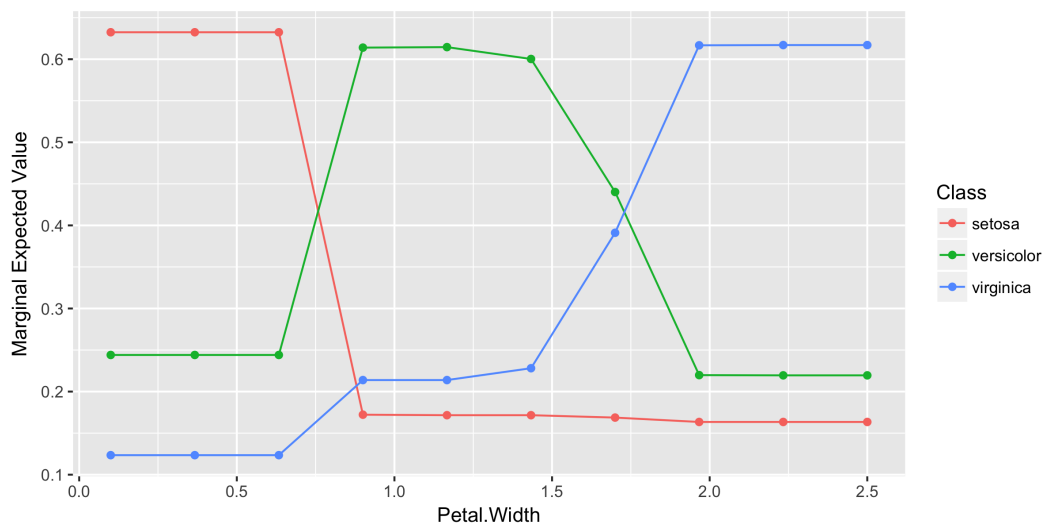


Figure 2: The expected value of \hat{f} estimated by a random forest and marginalized by Monte-Carlo integration to depend only on “Petal.Width.”

```
## 3: 0.6333333 0.6356267 0.2350533 0.1293200
## 4: 0.9000000 0.1707200 0.5997333 0.2295467
## 5: 1.1666667 0.1688267 0.6016267 0.2295467
## 6: 1.4333333 0.1688133 0.5880800 0.2431067
## 7: 1.7000000 0.1640400 0.4242800 0.4116800
## 8: 1.9666667 0.1619867 0.2066667 0.6313467
## 9: 2.2333333 0.1619867 0.2047867 0.6332267
## 10: 2.5000000 0.1619867 0.2047867 0.6332267
```

In this case \hat{f} returns a probability of membership in each class for each values of the variable “Petal.Width” which is computed based on the average prediction for each value of “Petal.Width” shown and all the observed values of the other variables in the training data. As can be readily observed, partial dependence can be easily visualized, as in Figure 2.

In fact, *any* function of the marginalized function \hat{f}_u can be computed, including vector-valued functions. For example the expectation and variance of \hat{f}_u can be simultaneously computed, the results of which are shown in Figures 3 and 4. Computing the variance of \hat{f}_u can be used for detecting interactions between X_u and X_{-u} (Goldstein et al., 2015). If the variance of $\hat{f}_u(X_u)$ is constant then this indicates that X_{-u} does not interact with X_u , since, if it did, this would make \hat{f} more variable in regions of the joint distribution wherein there is interaction between X_u and X_{-u} . An additional result of this capacity is the ability to propagate estimates of sampling uncertainty to the output of marginalPrediction.

```
mp.int = marginalPrediction(data = iris.features,
  vars = c("Petal.Width", "Petal.Length"),
  n = c(10, nrow(iris)), model = fit, uniform = TRUE,
  predict.fun = function(object, newdata) predict(object, newdata, type = "prob"),
  aggregate.fun = function(x) list("mean" = mean(x), "variance" = var(x)))
```

```
head(mp.int)
## Petal.Width Petal.Length setosa.mean setosa.variance versicolor.mean
## 1: 0.1 1.000000 0.9549867 0.0011619193 0.04448000
## 2: 0.1 1.655556 0.9549867 0.0011619193 0.04448000
## 3: 0.1 2.311111 0.9530933 0.0011317899 0.04637333
## 4: 0.1 2.966667 0.4574667 0.0003524653 0.52818667
## 5: 0.1 3.622222 0.4550400 0.0002619447 0.53061333
## 6: 0.1 4.277778 0.4550400 0.0002619447 0.52472000
## versicolor.variance virginica.mean virginica.variance
## 1: 0.001141889 0.0005333333 0.00000239821
## 2: 0.001141889 0.0005333333 0.00000239821
## 3: 0.001112236 0.0005333333 0.00000239821
## 4: 0.001154918 0.0143466667 0.00054076492
## 5: 0.001016158 0.0143466667 0.00054076492
```

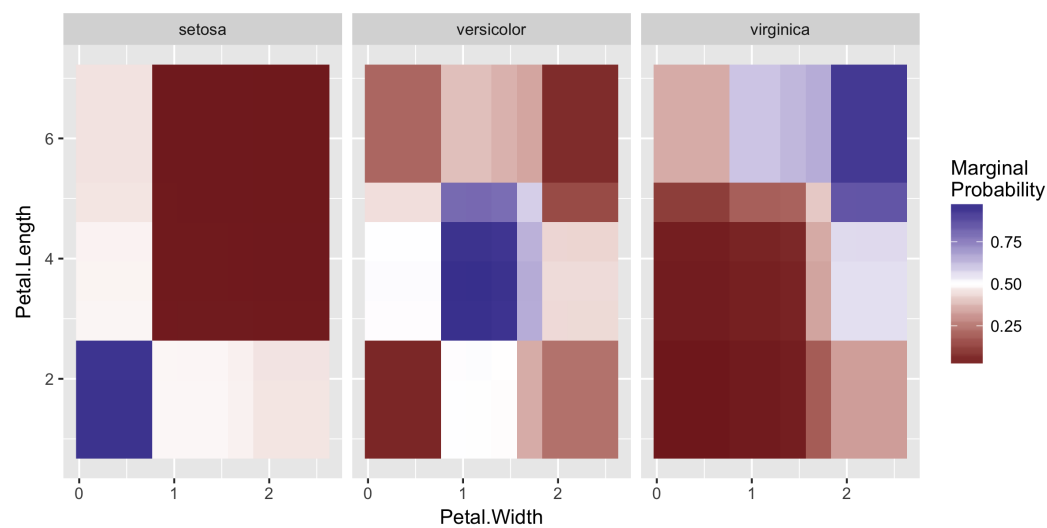


Figure 3: The expected value of \hat{f} estimated by a random forest and marginalized by Monte-Carlo integration to depend only on "Petal.Width" and "Petal.Length."

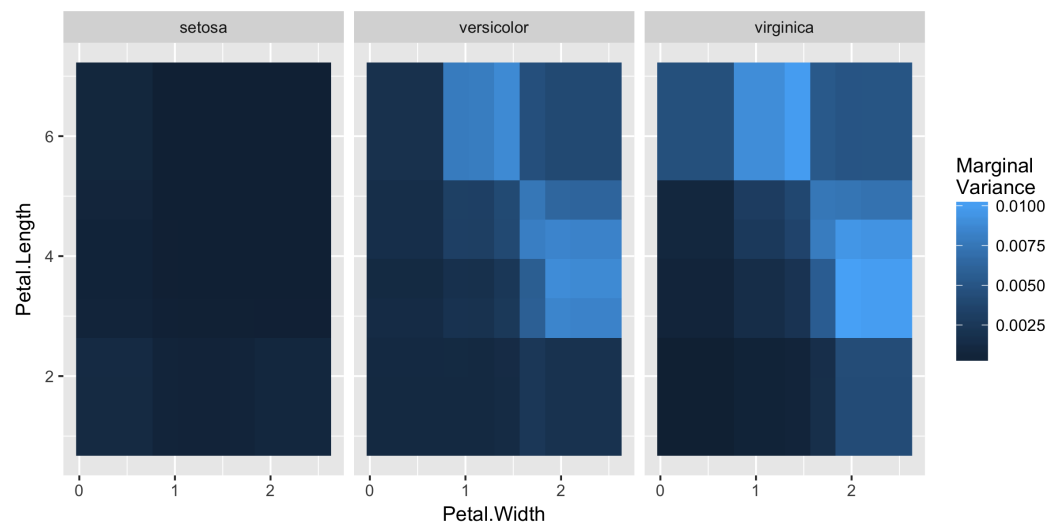


Figure 4: The variance of \hat{f} estimated by a random forest and marginalized by Monte-Carlo integration to depend only on "Petal.Width" and "Petal.Length." Non-constant variance indicates interaction between these variables and those marginalized out of \hat{f} .

6: 0.001556364 0.0202400000 0.00093196886

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