

3.10 (a) repeat the selection of the first point of a dataset.

$$\text{bias} = E[M] - \mu = \lim_{K \rightarrow \infty} \frac{1}{K} \sum_{k=1}^K M(k) - \mu = 0$$

Where  $M(k)$  is the first point in dataset.

So this method is unbiased.

(b) this method is unbiased, it will generally have large variance,  $E[(X_i - \mu)^2] = \sigma^2$ , the RMS error is independent of  $n$ .

If use  $\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$  to estimate the mean,

$$E[(\bar{X} - \mu)^2] = E\left[\left(\frac{1}{n} \sum_{i=1}^n X_i - \mu\right)^2\right] = \frac{1}{n^2} \sum_{i=1}^n [E[(X_i - \mu)^2]] = \frac{\sigma^2}{n}$$

the RMS error is  $\frac{\sigma}{\sqrt{n}}$  which is much less than  $\sigma$

3.47. (a) For the E step,

$$Q(\theta; \theta^0) = E_{x_{32}} [\ln p(x_g, x_b; \theta) | \theta^0, D_3]$$

$$= \int_{-\infty}^{\infty} (\ln p(x_1 | \theta) + \ln p(x_2 | \theta) + \ln p(x_3 | \theta)) P(x_{32} | \theta^0, x_{31} = 2) dx_{32}$$

$$= \ln p(x_1 | \theta) + \ln p(x_2 | \theta) + \int_{-\infty}^{\infty} \ln p(x_3 | \theta) P(x_{32} | \theta^0, x_{31} = 2) dx_{32}$$

$$= \ln p(x_1 | \theta) + \ln p(x_2 | \theta) + 2E \int_{-\infty}^{\infty} \ln p(x_{32}^2 | \theta) \cdot P(x_{32}^2 | \theta^0) dx_{32}$$

$$= \ln p(x_1 | \theta) + \ln p(x_2 | \theta) + k$$

For the K:

1.  $3 \leq \theta_2 \leq 4$ :



$$k = \frac{1}{4} \int_0^{\theta_2} \ln\left(\frac{1}{\theta_1} e^{-2\theta_1} \frac{1}{\theta_2}\right) dx_2$$

$$= \frac{1}{4} \theta_2 \ln\left(\frac{1}{\theta_1} e^{-2\theta_1} \frac{1}{\theta_2}\right)$$

2,  $\theta_2 > 4$ :

$$k = \frac{1}{4} \int_0^4 \ln\left(\frac{1}{\theta_1} e^{-2\theta_1} \frac{1}{\theta_2}\right) dx_2$$

$$= \frac{1}{4} 4 \ln\left(\frac{1}{\theta_1} e^{-2\theta_1} \frac{1}{\theta_2}\right)$$

$$= \ln\left(\frac{1}{\theta_1} e^{-2\theta_1} \frac{1}{\theta_2}\right)$$

3, otherwise  $k=0$

$$\therefore Q(\theta; \theta^0) = \ln p(x_1|\theta) + \ln p(x_2|\theta) + k$$

$$= \ln\left(\frac{1}{\theta_1} e^{-\theta_1} \frac{1}{\theta_2}\right) + \ln\left(\frac{1}{\theta_1} e^{-3\theta_1} \frac{1}{\theta_2}\right) + k$$

$$= -\theta_1 - \ln(\theta_1 \theta_2) - 3\theta_1 - \ln(\theta_1 \theta_2) + k$$

$$= -4\theta_1 - 2\ln(\theta_1 \theta_2) + k$$

consider the normalization condition  $\int_{-\infty}^{\infty} p(x_1) dx_1 = 1$

$$\int_{-\infty}^{\infty} \frac{1}{\theta_1} e^{-\theta_1 x_1} dx_1 = 1 \quad \therefore \theta_1 = 1$$

(b) 1,  $3 \leq \theta_2 \leq 4$ ,

$$Q(\theta; \theta^0) = -4 - \left(2\ln\theta_2 + \frac{1}{4}\theta_2(2 + \ln\theta_2)\right)$$

$$\arg\max_{\theta_2} Q(\theta; \theta^0) = 3$$



$$2. \theta_2 \geq 4; \quad Q(\theta; \theta^0) = -b - 3 \ln \theta_2$$

$$\arg \max_{\theta_2} Q(\theta; \theta^0) = 4$$

$$\therefore \theta = \cancel{\begin{pmatrix} 1 \\ 4 \end{pmatrix}} \quad \theta = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

(c)

see attached figure.



5.4. (a) to minimize  $\|x - x_a\|^2$  subject to  $g(x) = 0$

the object function  $f(x, \lambda) = \|x - x_a\|^2 + 2\lambda [g(x)]$ .

$\lambda$  is a Lagrange undetermined multiplier, the point  $x_a$  is fixed while

$x$  varies on the hyperplane,

$$f(x, \lambda) = \|x - x_a\|^2 + 2\lambda [w^t x + w_0]$$

$$= (x - x_a)^t (x - x_a) + 2\lambda (w^t x + w_0)$$

$$= x^t x - 2x^t x_a + x_a^t x_a + 2\lambda (x^t w + w_0)$$

$$\frac{\partial f(x, \lambda)}{\partial x} = x - x_a + \lambda w = 0$$



$$\frac{\partial f(x, \lambda)}{\partial \lambda} = w^t x + w_0 = 0$$

$$x = x_a - \lambda w$$

$$w^t x + w_0 = w^t (x_a - \lambda w) + w_0$$

$$= w^t x_a + w_0 - \lambda w^t w$$

$$= 0$$

$$\therefore \lambda w^t w = w^t x_a + w_0$$

$$\lambda = \frac{w^t x_a + w_0}{w^t w}$$

$$x = x_a - \lambda w = \begin{cases} x_a - \left[ \frac{w^t x_a + w_0}{w^t w} \right] w & \text{if } w \neq 0 \\ x_a & \text{if } w = 0 \end{cases}$$

$$\|x - x_a\| = \left\| x_a - \left[ \frac{w^t x_a + w_0}{w^t w} \right] w - x_a \right\|$$

$$= \left\| \left( \frac{w^t x_a + w_0}{w^t w} \right) w \right\|$$

$$= \frac{|g(x_a)| \|w\|}{\|w\|^2} = \frac{|g(x_a)|}{\|w\|}$$

(b) the projection of  $x_a$  onto the hyperplane is

$$x_0 = x_a - \lambda w$$

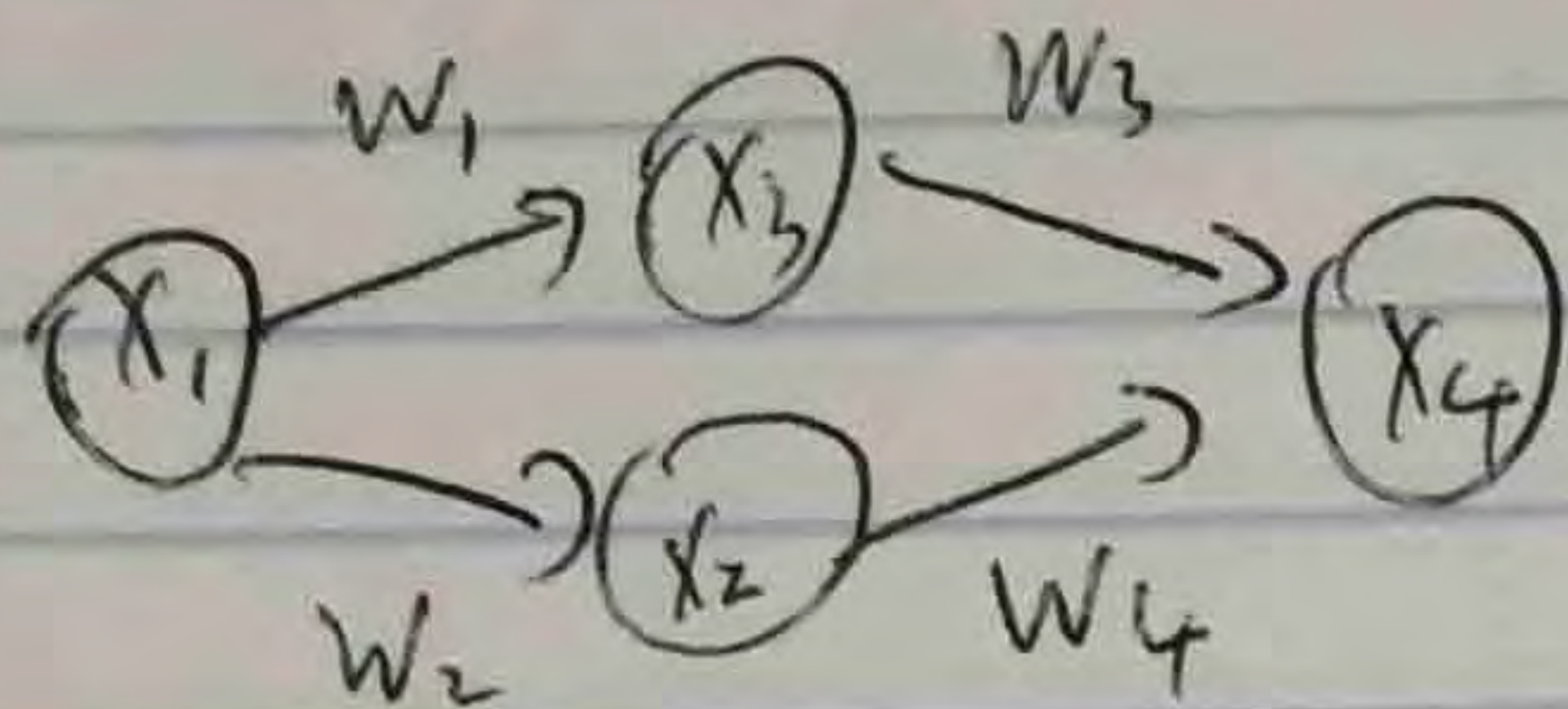
$$= x_a - \frac{g(x_a)}{\|w\|^2} w$$

$$\lambda = \frac{w^t x_a + w_0}{w^t w} = \frac{g(x_a)}{\|w\|^2}$$



$$S(x) = \frac{1}{1+e^{-x}}$$

$$S'(x) = S(x)(1-S(x)) =$$



$$x_3 = S(w_1 \cdot x_1) \quad x_2 = S(w_2 \cdot x_1)$$

$$x_4 = S(x_3 \cdot w_3 + x_2 \cdot w_4)$$

$$\Delta w_1 = \frac{-\partial E}{\partial w_1} \eta \quad \Delta w_3 = \frac{-\partial E}{\partial w_3} \eta \quad \Delta w_4 = \frac{-\partial E}{\partial w_4} \eta \quad \Delta w_2 = \frac{-\partial E}{\partial w_2} \eta$$

$$\Delta w_3 = \frac{-\partial E}{\partial w_3} = \frac{-\partial E}{\partial \text{net}_3} \cdot \frac{\partial \text{net}_3}{\partial w_3} \eta$$

Let  $E = (d - x_4)^2$   $d$  is the desired output.

$$\Delta w_3 = +2(d - x_4) S'(\text{net}_4) x_3 \eta = +2(d - x_4) x_4 (1 - x_4) x_3 \eta$$

$$\Delta w_4 = +2(d - x_4) S'(\text{net}_4) x_2 \eta = +2(d - x_4) x_4 (1 - x_4) x_2 \eta$$

$$\Delta w_1 = \frac{-\partial E}{\partial w_1} \eta = \frac{-\partial E}{\partial \text{net}_3} \cdot \frac{\partial \text{net}_3}{\partial w_1} \eta$$

$$= 2(d - x_4) x_4 (1 - x_4) w_3 x_3 (1 - x_3) x_1 \eta$$

$$\Delta w_2 = (d - x_4) x_4 (1 - x_4) w_4 x_2 (1 - x_2) x_1 \eta$$



