- 2、commander app:从eeprom 中加载(load)参数,将参数保存(save) 到 eeprom 中。
- 3、Mavlink app:通常参数是由地面站软件设置的。地面站软件与 Mavlink app 通信,查询并修改参数。
- 4、all apps:访问参数。

通常,当你要添加一个自定义参数时,你需要修改第1条对应的代码;如果你需要访问该参数,你当然需要修改第4条对应的代码;然而,修改第2条和第3条对应的代码是非必须的。

## 蜂鸣器驱动(Tone Alarm Driver)

参考链接: http://pixhawk.org/dev/tone\_alarm

蜂鸣器驱动可以使用蜂鸣器来播放各种频率的声音,这些声音以 QBasic PLAY/ANSI 格式存储。

默认的一些音调被存储在蜂鸣器驱动文件中(src/drivers/stm32/tone\_alarm),可以通过如下命令进行播放任何声音:

tone\_alarm MFT22503L8GL8GL8GL2E-P8L8FL8FL8FMLL2DL2DMNP8

注意:为了使得 tone\_alarm 程序识别,传递给该 app 的声音序列需要以"M" 开头。有些 ANSI 格式的声音文件在其头部和尾部包含跳出序列,这个需要移除,否则会导致出错。

## 默认的声音的含义如下:

| Index | Short name | Description            |
|-------|------------|------------------------|
| 0     | STOP       | Stops the current tune |

| 1 | воот       | 'PX4 startup sound'. Is auto-played by the tone alarm driver on system startup  |
|---|------------|---------------------------------------------------------------------------------|
| 2 | BATT_LOW   | The battery is low, but not fully empty. Running on reserve.                    |
| 3 | BATT_EMPTY | The battery is completely flat, the system is not able to maintain safe flight. |
| 4 | CMD_ACK    | The last command has been accepted                                              |
| 5 | CMD_REJ    | The last command has been rejected                                              |
| 6 | POS_LOCK   | The position estimator obtained a valid position (emitted once on first lock)   |
| 7 | ARMING     | Emitted on the transition to armed                                              |
| 8 | DISARMING  | Emitted on the transition to disarmed                                           |
| 9 | EMERGENCY  | General, potentially fatal error. NOT due to battery. Land immediately.         |

注:常用的生成 ANSI 格式声音文件的软件为 Melody Master。