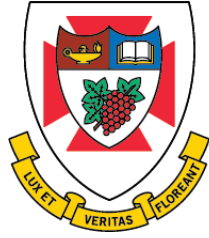


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INTRODUCTION TO MACHINE LEARNING

DIT 45100

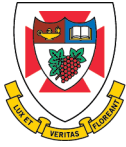


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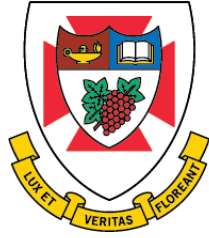
Module 3

Linear Classification Techniques



Classification

- Categorical target feature
- Binary classification
- Multinomial classification
- Logistic regression
- Support Vector Machines (SVM)



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Logistic Regression



Logistic Regression

Scenario

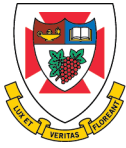
- You work for a power utility company as an AI professional. The company owns a number of power generation stations, where electric generators operate day and night to serve clients uninterrupted. Condition of these generators is continuously monitored by measuring machine features indicative of their “health”.
- You are tasked to develop a classification model to predict the status of generators based on historic sensor measurements in order to avoid any unexpected machine breakdown.
- The objective is to classify generators as “good” or “faulty” based on these feature measurements



Generators dataset

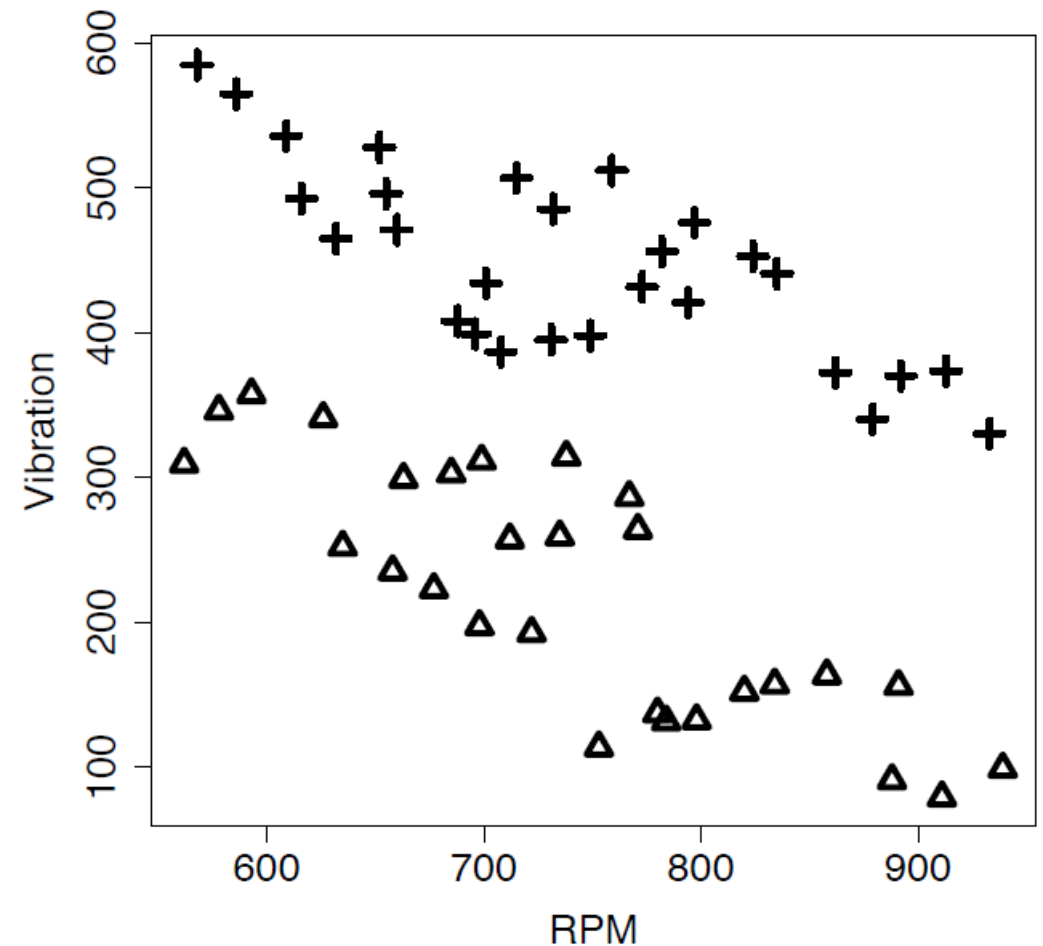
ID	RPM	VIBRATION	STATUS
1	568	585	good
2	586	565	good
3	609	536	good
4	616	492	good
5	632	465	good
6	652	528	good
7	655	496	good
8	660	471	good
9	688	408	good
10	696	399	good
11	708	387	good
12	701	434	good
13	715	506	good
14	732	485	good
15	731	395	good
16	749	398	good
17	759	512	good
18	773	431	good
19	782	456	good
20	797	476	good
21	794	421	good
22	824	452	good
23	835	441	good
24	862	372	good
25	879	340	good
26	892	370	good
27	913	373	good
28	933	330	good

ID	RPM	VIBRATION	STATUS
29	562	309	faulty
30	578	346	faulty
31	593	357	faulty
32	626	341	faulty
33	635	252	faulty
34	658	235	faulty
35	663	299	faulty
36	677	223	faulty
37	685	303	faulty
38	698	197	faulty
39	699	311	faulty
40	712	257	faulty
41	722	193	faulty
42	735	259	faulty
43	738	314	faulty
44	753	113	faulty
45	767	286	faulty
46	771	264	faulty
47	780	137	faulty
48	784	131	faulty
49	798	132	faulty
50	820	152	faulty
51	834	157	faulty
52	858	163	faulty
53	888	91	faulty
54	891	156	faulty
55	911	79	faulty
56	939	99	faulty



Generators dataset

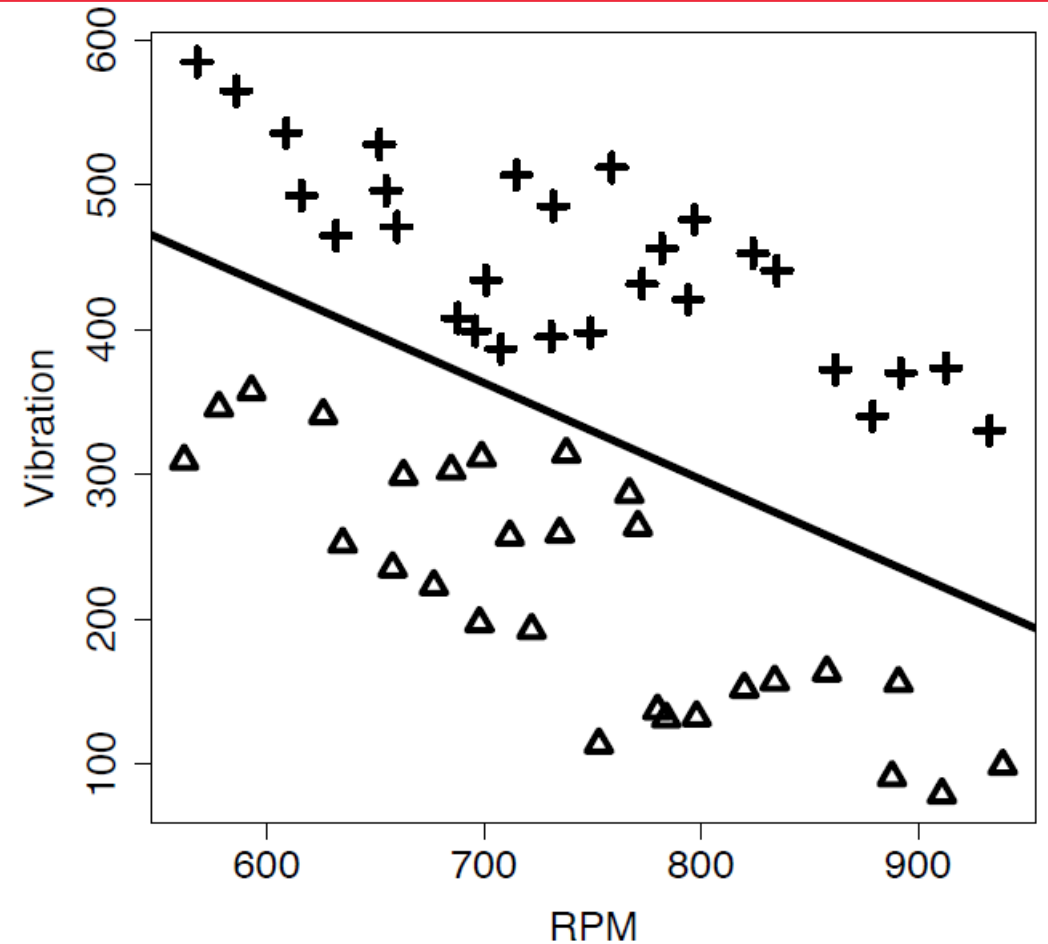
Figure: A scatter plot of the RPM and VIBRATION descriptive features from the generators dataset, where 'good' generators are shown as crosses and 'faulty' generators are shown as triangles.





Generators dataset

Figure: A scatter plot of the RPM and VIBRATION descriptive features from the generators dataset, where 'good' generators are shown as crosses and 'faulty' generators are shown as triangles.





Logistic Regression

- As the decision boundary is a **linear separator** it can be defined using the equation of the line as:

$$\text{VIBRATION} = 830 - 0.667 \times \text{RPM} \quad (1)$$

or

$$830 - 0.667 \times \text{RPM} - \text{VIBRATION} = 0 \quad (2)$$



Logistic Regression

- Applying Equation (2) to the instance $RPM = 810$, $VIBRATION = 495$, which is **above** the decision boundary, gives the following result:

$$830 - 0.667 \times 810 - 495 = -205.27$$

- By contrast, if we apply Equation (2) to the instance $RPM = 650$ and $VIBRATION = 240$, which is **below** the decision boundary, we get

$$830 - 0.667 \times 650 - 240 = 156.45$$



Logistic Regression

- All the data points above the decision boundary will result in a negative value when plugged into the decision boundary equation,
- While all data points below the decision boundary will result in a positive value.



Logistic Regression

- Reverting to our previous notation we have:

$$M_{\mathbf{w}}(\mathbf{d}) = \begin{cases} 1 & \text{if } \mathbf{w} \cdot \mathbf{d} \geq 0 \\ 0 & \text{otherwise} \end{cases} \quad (3)$$

- The surface defined by this rule is known as a **decision surface**.



Logistic Regression

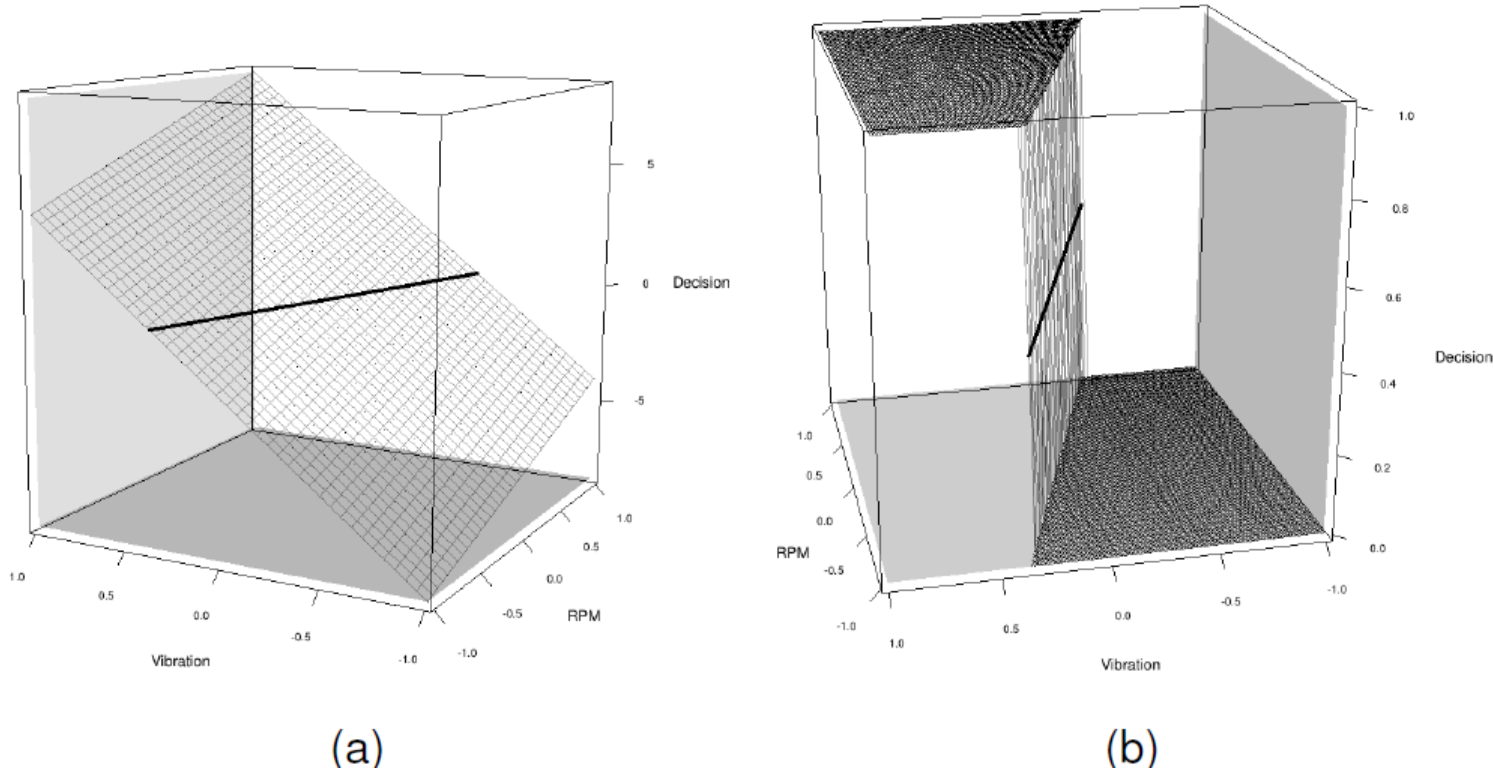
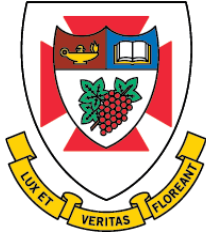


Figure: (a) A surface showing the value of Equation (2) for all values of RPM and VIBRATION. The decision boundary given in Equation (2) is highlighted. (b) The same surface linearly thresholded at zero to operate as a predictor.



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Logistic Regression



Logistic Regression

- The hard decision boundary given in Equation (3) is **discontinuous** so is not differentiable and so we can't calculate the gradient of the error surface.
- Furthermore, the model always makes completely confident predictions of 0 or 1, whereas a little more subtlety is desirable.
- We address these issues by using a more sophisticated threshold function that is continuous, and therefore differentiable, and that allows for the subtlety desired: the **logistic function**

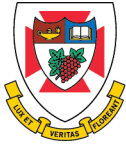


Logistic Regression

logistic function

$$\textit{Logistic}(x) = \frac{1}{1 + e^{-x}} \quad (4)$$

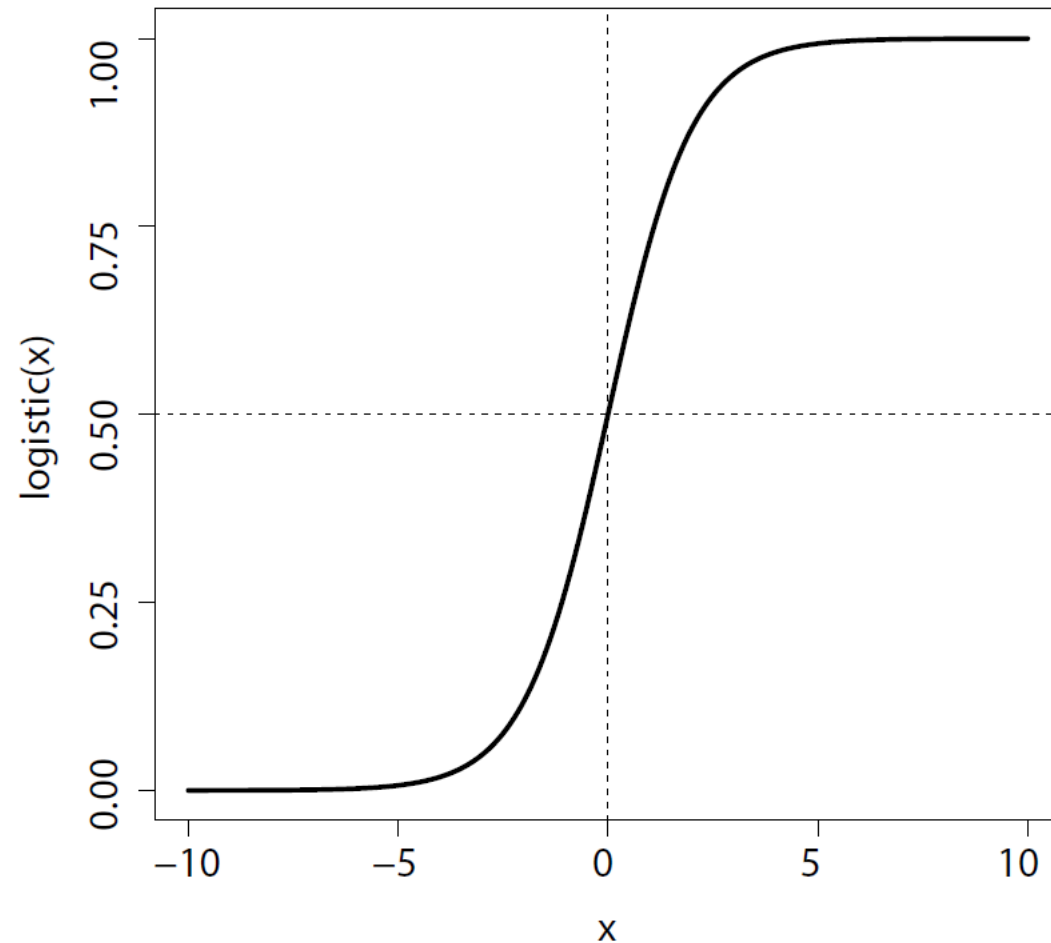
where x is a numeric value and e is **Euler's number** and is approximately equal to 2.7183.

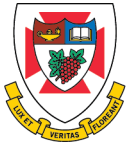


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Logistic Regression





Logistic Regression

- To build a logistic regression model, we simply pass the output of the basic linear regression model through the logistic function

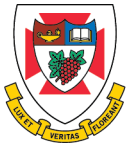
$$\begin{aligned} M_{\mathbf{w}}(\mathbf{d}) &= \text{Logistic}(\mathbf{w} \cdot \mathbf{d}) \\ &= \frac{1}{1 + e^{-\mathbf{w} \cdot \mathbf{d}}} \end{aligned} \quad (5)$$



Logistic Regression

A note on training logistic regression models:

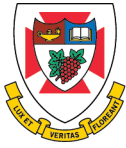
- Before we train a logistic regression model, we map the binary target feature levels to 0 or 1.
- The error of the model on each instance is then the difference between the target feature (0 or 1) and the value of the prediction $[0, 1]$.



Logistic Regression

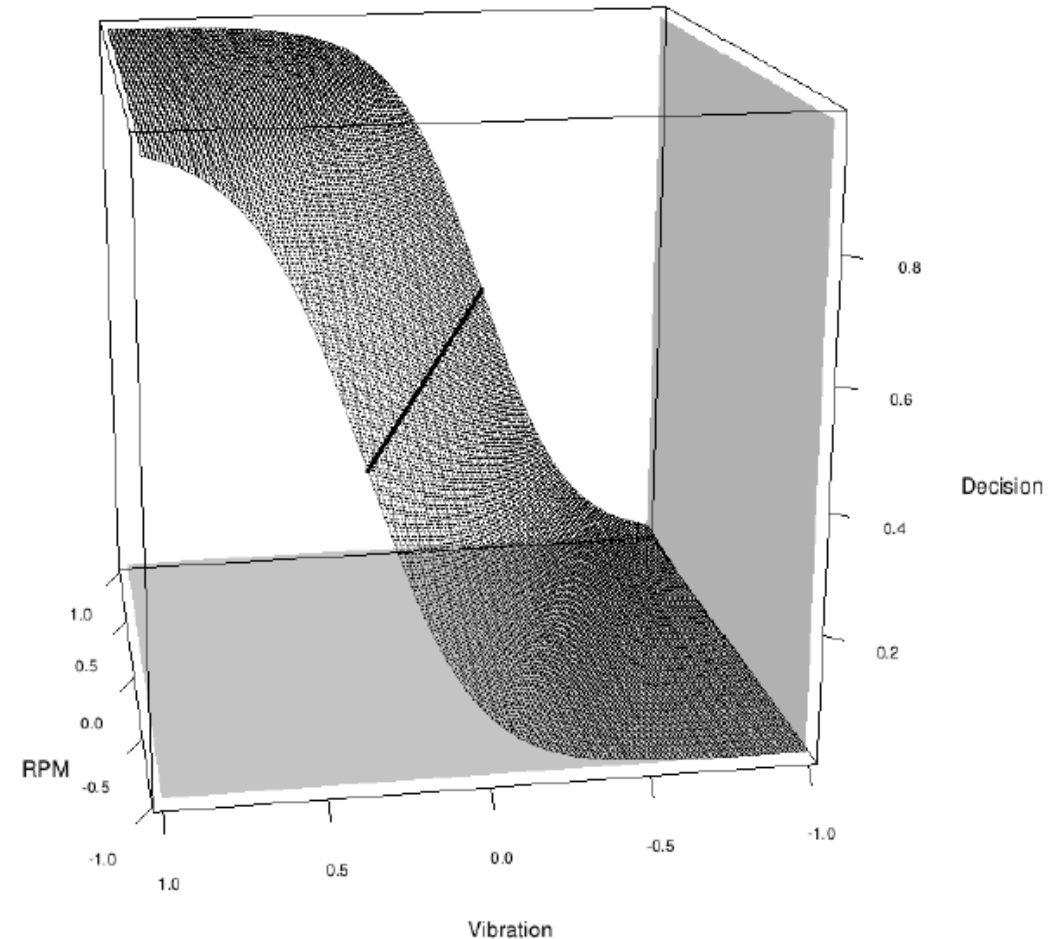
Example

$$M_w(\langle \text{RPM}, \text{VIBRATION} \rangle) \\ = \frac{1}{1 + e^{-(-0.4077 + 4.1697 \times \text{RPM} + 6.0460 \times \text{VIBRATION})}}$$



Logistic Regression

Figure: The decision surface for the example logistic regression model.

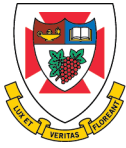




Logistic Regression

$$P(t = \text{'faulty'} | \mathbf{d}) = \mathbb{M}_{\mathbf{w}}(\mathbf{d})$$

$$P(t = \text{'good'} | \mathbf{d}) = 1 - \mathbb{M}_{\mathbf{w}}(\mathbf{d})$$



Logistic Regression

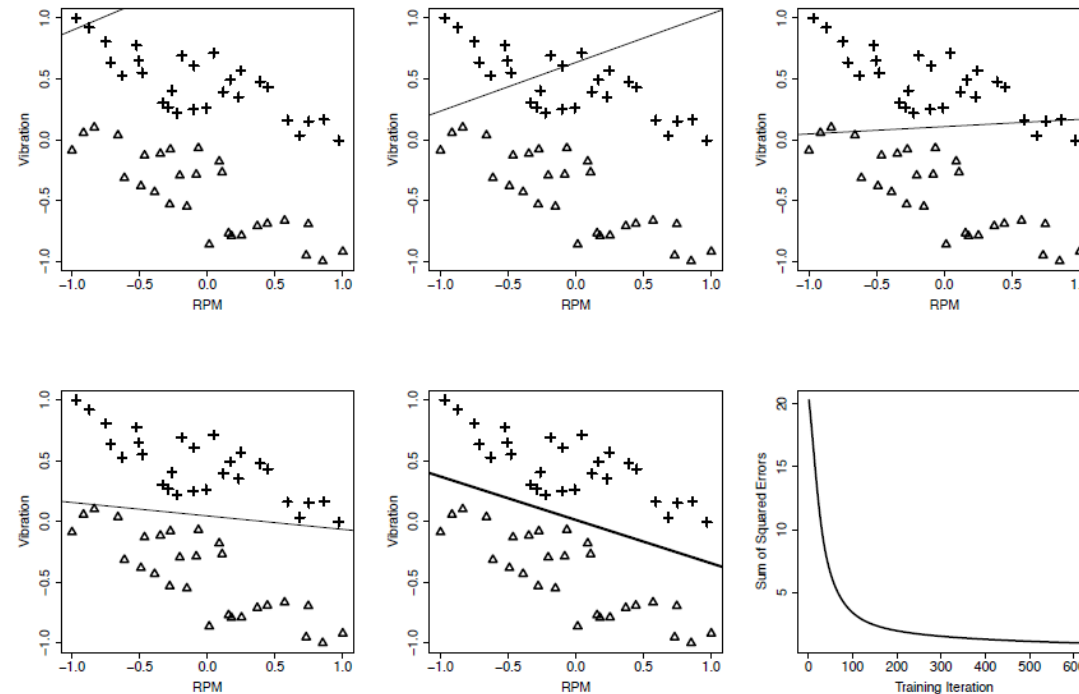


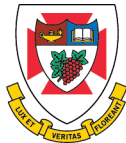
Figure: A selection of the logistic regression models developed during the gradient descent process for the machinery dataset. The bottom-right panel shows the sum of squared error values generated during the gradient descent process.



Logistic Regression

- To repurpose the gradient descent algorithm for training logistic regression models the only change that needs to be made is in the weight update rule.
- The new weight update rule is:

$$\mathbf{w}[j] \leftarrow \mathbf{w}[j] + \alpha \times \sum_{i=1}^n ((t - \mathbb{M}_{\mathbf{w}}(\mathbf{d}_i)) \times \mathbb{M}_{\mathbf{w}}(\mathbf{d}_i) \times (1 - \mathbb{M}_{\mathbf{w}}(\mathbf{d}_i)) \times \mathbf{d}_i[j])$$



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Logistic Regression

ID	RPM	VIBRATION	STATUS	ID	RPM	VIBRATION	STATUS
1	498	604	faulty	35	501	463	good
2	517	594	faulty	36	526	443	good
3	541	574	faulty	37	536	412	good
4	555	587	faulty	38	564	394	good
5	572	537	faulty	39	584	398	good
6	600	553	faulty	40	602	398	good
7	621	482	faulty	41	610	428	good
8	632	539	faulty	42	638	389	good
9	656	476	faulty	43	652	394	good
10	653	554	faulty	44	659	336	good
11	679	516	faulty	45	662	364	good
12	688	524	faulty	46	672	308	good
13	684	450	faulty	47	691	248	good
14	699	512	faulty	48	694	401	good
15	703	505	faulty	49	718	313	good
16	717	377	faulty	50	720	410	good
17	740	377	faulty	51	723	389	good
18	749	501	faulty	52	744	227	good
19	756	492	faulty	53	741	397	good
20	752	381	faulty	54	770	200	good
21	762	508	faulty	55	764	370	good
22	781	474	faulty	56	790	248	good
23	781	480	faulty	57	786	344	good
24	804	460	faulty	58	792	290	good
25	828	346	faulty	59	818	268	good
26	830	366	faulty	60	845	232	good
27	864	344	faulty	61	867	195	good
28	882	403	faulty	62	878	168	good
29	891	338	faulty	63	895	218	good
30	921	362	faulty	64	916	221	good
31	941	301	faulty	65	950	156	good
32	965	336	faulty	66	956	174	good
33	976	297	faulty	67	973	134	good
34	994	287	faulty	68	1002	121	good



Logistic Regression

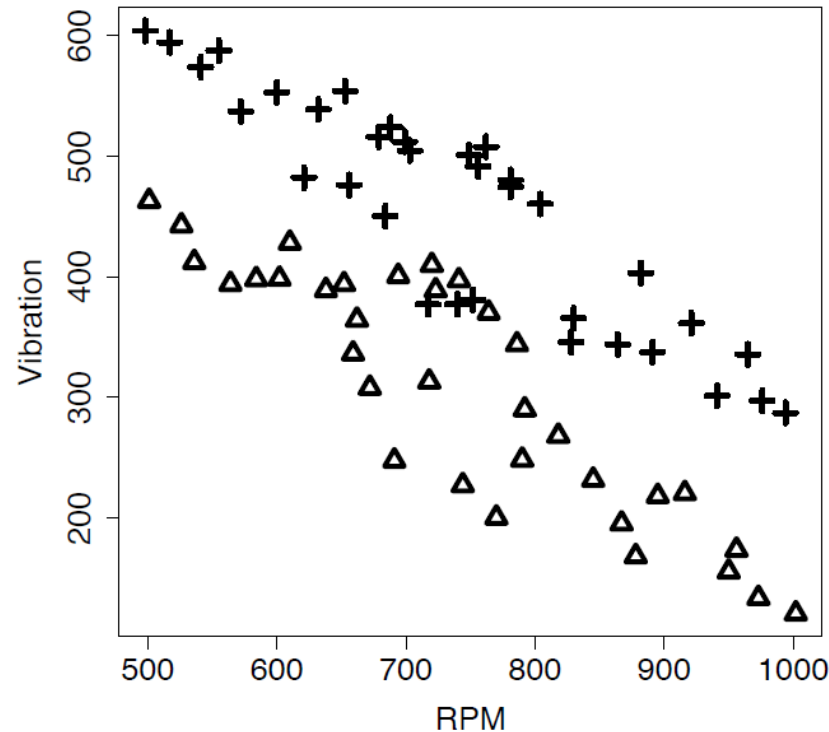


Figure: A scatter plot of the extended generators dataset, which results in instances with the different target levels overlapping with each other. 'good' generators are shown as crosses, and 'faulty' generators are shown as triangles.



Logistic Regression

For logistic regression models we recommend that descriptive feature values always be normalized.

In this example, before the training process begins, both descriptive features are normalized to the range $[-1, 1]$.



Logistic Regression

For this example let's assume that:

- Learning rate:
 - $\alpha = 0.02$
- Initial Weights:
 - $w[0] = -2.9465$
 - $w[1] = -1.0147$
 - $w[2] = 2.1610$



Logistic Regression

Iteration 1							
ID	TARGET	Pred.	Error	Squared Error	errorDelta (\mathcal{D} , $\mathbf{w}[i]$)		
	LEVEL				$\mathbf{w}[0]$	$\mathbf{w}[1]$	$\mathbf{w}[2]$
1	1	0.5570	0.4430	0.1963	0.1093	-0.1093	0.1093
2	1	0.5168	0.4832	0.2335	0.1207	-0.1116	0.1159
3	1	0.4469	0.5531	0.3059	0.1367	-0.1134	0.1197
4	1	0.4629	0.5371	0.2885	0.1335	-0.1033	0.1244
...							
65	0	0.0037	-0.0037	0.0000	0.0000	0.0000	0.0000
66	0	0.0042	-0.0042	0.0000	0.0000	0.0000	0.0000
67	0	0.0028	-0.0028	0.0000	0.0000	0.0000	0.0000
68	0	0.0022	-0.0022	0.0000	0.0000	0.0000	0.0000
Sum				24.4738	2.7031	-0.7015	1.6493
Sum of squared errors (Sum/2)				12.2369			



Logistic Regression

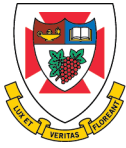
$$\mathbf{w}[j] \leftarrow \mathbf{w}[j] + \alpha \times \sum_{i=1}^n ((t_i - \mathbb{M}_{\mathbf{w}}(\mathbf{d}_i)) \times \mathbb{M}_{\mathbf{w}}(\mathbf{d}_i) \times (1 - \mathbb{M}_{\mathbf{w}}(\mathbf{d}_i)) \times \mathbf{d}_i[j])$$

New Weights (after Iteration 1)

$\mathbf{w}[0] = -2.8924$

$\mathbf{w}[1] = -1.0287$

$\mathbf{w}[2] = 2.1940$



Logistic Regression

Iteration 2							
ID	TARGET	Pred.	Error	Squared Error	errorDelta(\mathcal{D} , $w[i]$)		
	LEVEL				$w[0]$	$w[1]$	$w[2]$
1	1	0.5817	0.4183	0.1749	0.1018	-0.1018	0.1018
2	1	0.5414	0.4586	0.2103	0.1139	-0.1053	0.1094
3	1	0.4704	0.5296	0.2805	0.1319	-0.1094	0.1155
4	1	0.4867	0.5133	0.2635	0.1282	-0.0992	0.1194
...							
65	0	0.0037	-0.0037	0.0000	0.0000	0.0000	0.0000
66	0	0.0043	-0.0043	0.0000	0.0000	0.0000	0.0000
67	0	0.0028	-0.0028	0.0000	0.0000	0.0000	0.0000
68	0	0.0022	-0.0022	0.0000	0.0000	0.0000	0.0000
Sum				24.0524	2.7236	-0.6646	1.6484
Sum of squared errors (Sum/2)				12.0262			



Logistic Regression

$$\mathbf{w}[j] \leftarrow \mathbf{w}[j] + \alpha \times \sum_{i=1}^n ((t_i - \mathbb{M}_{\mathbf{w}}(\mathbf{d}_i)) \times \mathbb{M}_{\mathbf{w}}(\mathbf{d}_i) \times (1 - \mathbb{M}_{\mathbf{w}}(\mathbf{d}_i)) \times \mathbf{d}_i[j])$$

New Weights (after Iteration 2)

$\mathbf{w}[0] = -2.8380$

$\mathbf{w}[1] = -1.0416$

$\mathbf{w}[2] = 2.2271$



Logistic Regression

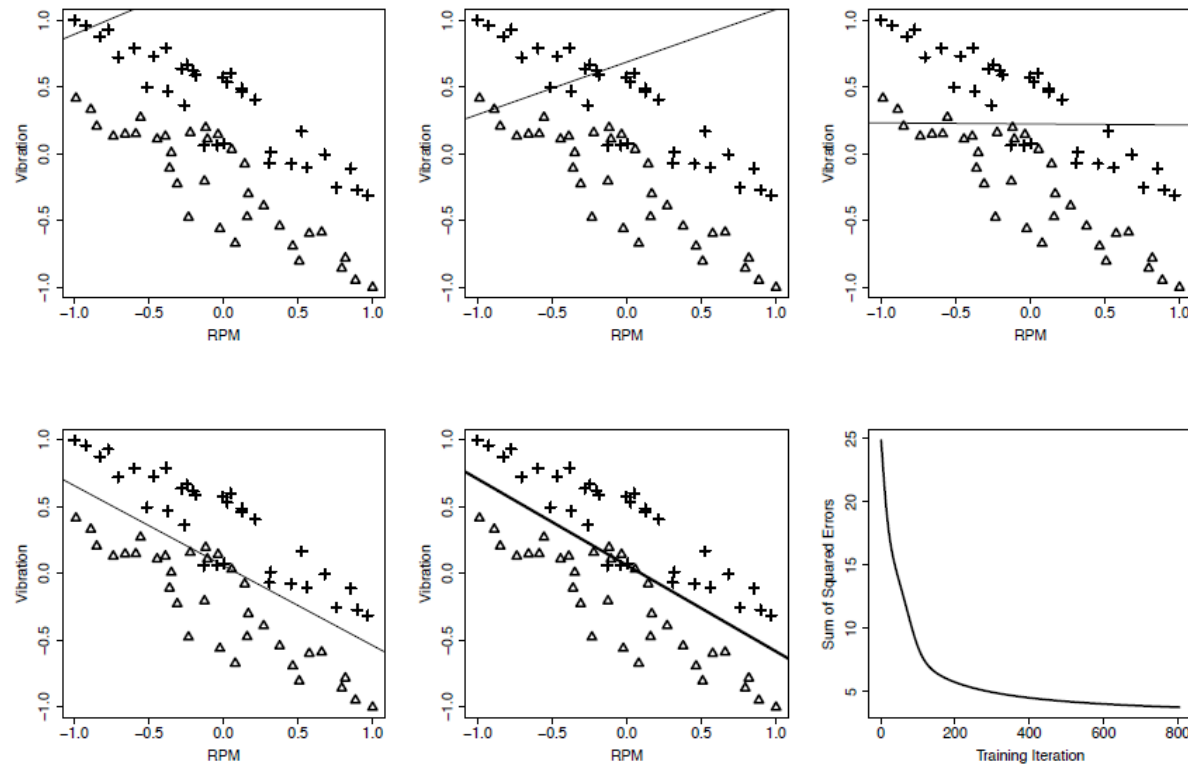
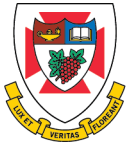


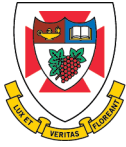
Figure: A selection of the logistic regression models developed during the gradient descent process for the extended generators dataset. The bottom-right panel shows the sum of squared error values generated during the gradient descent process.



Logistic Regression

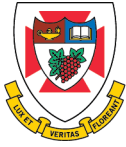
- The final model found is:

$$M_w(\langle \text{RPM}, \text{VIBRATION} \rangle) = \frac{1}{1 + e^{-(-0.4077 + 4.1697 \times \text{RPM} + 6.0460 \times \text{VIBRATION})}}$$



Performance Measures

- Accuracy
- Confusion matrix
- Recall
- Precision
- F1 Score
- ...



Confusion Matrix

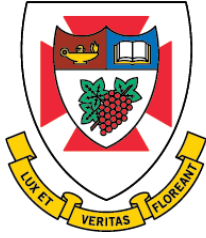
CLASS		Predicted	
		Positive	Negative
A c t u a l	Positive	TP	FN
	Negative	FP	TN

$$Accuracy = \frac{TP + TN}{TP + FP + TN + FN}$$

$$Recall = \frac{TP}{TP + FN}$$

$$Precision = \frac{TP}{TP + FP}$$

$$F1\ Score = \frac{2 \times Precision \times Recall}{Precision + Recall}$$



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Modeling Non-Linear Relationships



Non-Linear Relationships

Table: A dataset showing participants' responses to viewing 'positive' and 'negative' images measured on the EEG P20 and P45 potentials.

ID	P20	P45	TYPE	ID	P20	P45	TYPE
1	0.4497	0.4499	negative	26	0.0656	0.2244	positive
2	0.8964	0.9006	negative	27	0.6336	0.2312	positive
3	0.6952	0.3760	negative	28	0.4453	0.4052	positive
4	0.1769	0.7050	negative	29	0.9998	0.8493	positive
5	0.6904	0.4505	negative	30	0.9027	0.6080	positive
6	0.7794	0.9190	negative	31	0.3319	0.1473	positive
		⋮				⋮	



Non-Linear Relationships

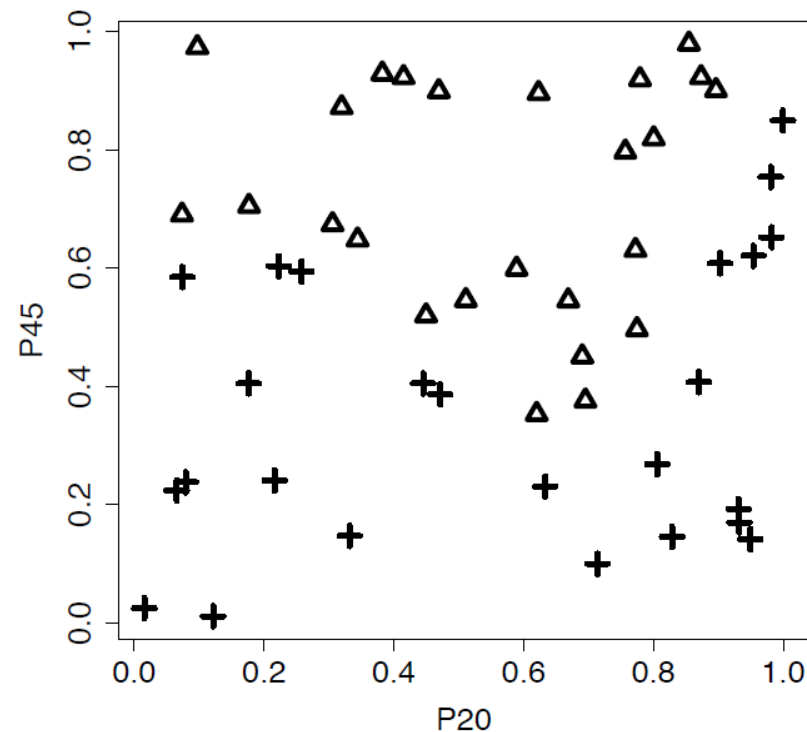
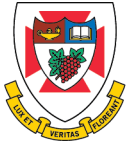


Figure: A scatter plot of the P20 and P45 features from the EEG dataset. '*positive*' images are shown as crosses, and '*negative*' images are shown as triangles.



Non-Linear Relationships

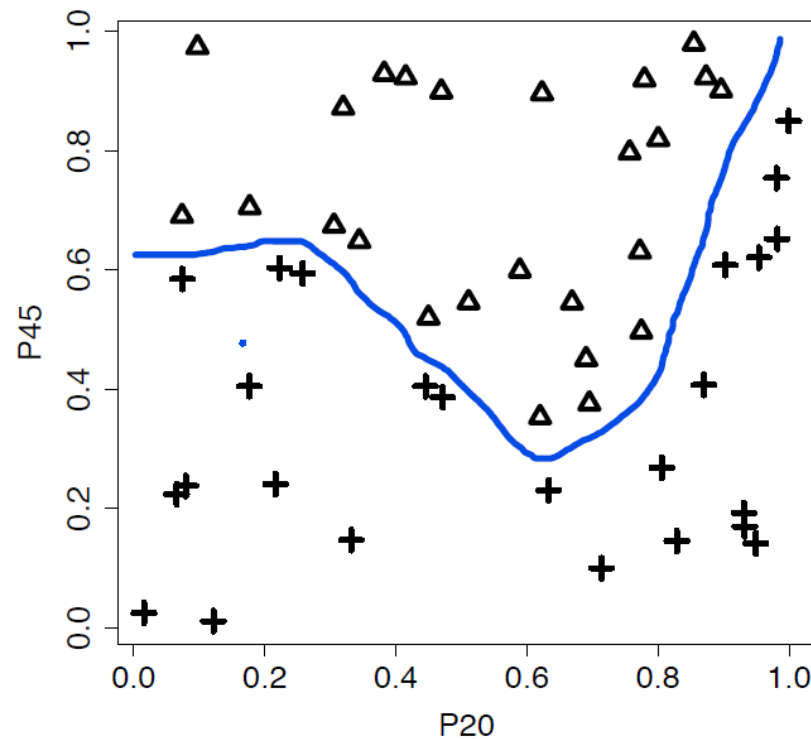


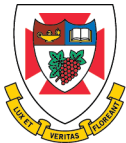
Figure: A scatter plot of the P20 and P45 features from the EEG dataset. '*positive*' images are shown as crosses, and '*negative*' images are shown as triangles.



Non-Linear Relationships

- A logistic regression model using basis functions is defined as follows:

$$M_{\mathbf{w}}(\mathbf{d}) = \frac{1}{1 + e^{-\left(\sum_{j=0}^b \mathbf{w}[j] \phi_j(\mathbf{d})\right)}} \quad (6)$$



Non-Linear Relationships

- We will use the following basis functions for the EEG problem:

$$\phi_0(\langle P20, P45 \rangle) = 1$$

$$\phi_4(\langle P20, P45 \rangle) = P45^2$$

$$\phi_1(\langle P20, P45 \rangle) = P20$$

$$\phi_5(\langle P20, P45 \rangle) = P20^3$$

$$\phi_2(\langle P20, P45 \rangle) = P45$$

$$\phi_6(\langle P20, P45 \rangle) = P45^3$$

$$\phi_3(\langle P20, P45 \rangle) = P20^2$$

$$\phi_7(\langle P20, P45 \rangle) = P20 \times P45$$



Non-Linear Relationships

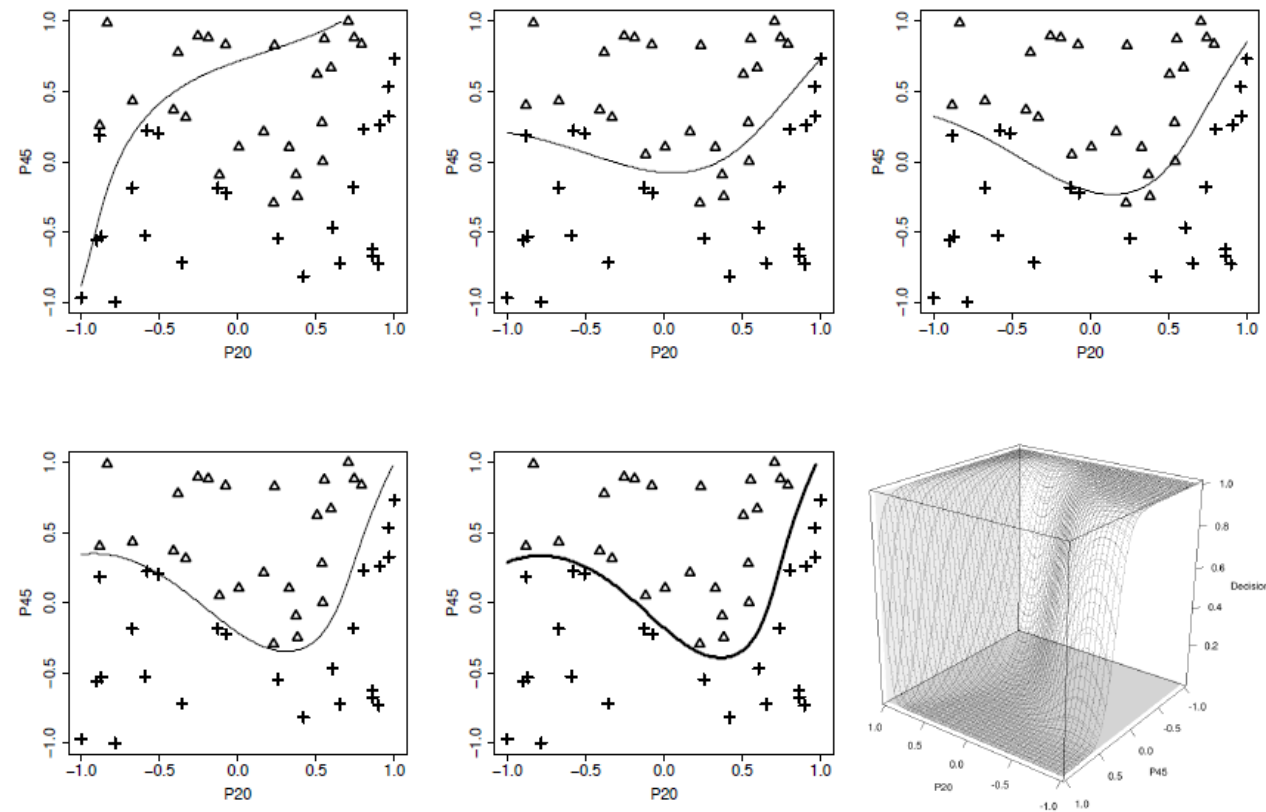


Figure: A selection of the models developed during the gradient descent process for the EEG dataset. The final panel shows the decision surface generated.