Day 5 selected topics

- Gamma MLE and moment estimator
- Memoryless r.v.
- Markov Chain
- Monte-Carlo integration
- Random-effect model
- Examples in population genetics

- Although MLE is "the best" sometimes it is hard to find
 - no closed-form solution (e.g. gamma MLE), and often can only be evaluated numerically
 - computational issue due to dimensionality (to many parameters)
 - the presence of nuisance variables (e.g. mixed effect model)

Memoryless r.v.?

- I arrive at a bus stop. Nobody is there. Let T be the waiting time before the arrival of the next bus. $T \sim Exponential(\lambda)$
- $f_T(t) = \lambda e^{-\lambda t}$ is the pdf
- $F_T(t) = \Pr(T \le t) = 1 e^{-\lambda t}$ is the cdf
- I will be late if a bus does not arrive in the next k minutes. The probability that I will be late for work is
- $Pr(T > k) = 1 Pr(T \le k) = 1 F_{T(k)} = e^{-\lambda k}$

- Next day, I arrive at the same bus stop. "I have been waiting here for s minutes!" a person says to me.
- I am in the same situation, that if I do not get on a bus in the next k minutes then I will be in trouble.
- Pr(T > s + k | T > s) is the probability of being late
 - extra information about the r.v. T is given by the person
 - -s minutes has passed, so it is known that T > s

•
$$\Pr(T > s + k | T > s) = \frac{\Pr(T > s + k \& T > s)}{\Pr(T > s)} = \frac{\Pr(T > s + k)}{\Pr(T > s)} = \frac{e^{-\lambda(s+k)}}{e^{-\lambda s}} = e^{-\lambda k}$$

WHAT???

- Memoryless: Pr(X > m + n | X > m) = Pr(X > n)
 - no extra information given
- Another example is the discrete geometric distribution
 - the number of Bernoulli trials required before getting the first success

Markov chain

- A random process, series of r.v., X(t), X(t+1), X(t+2), ...
- There are several "states" (possible outcomes) that each X(j) can take on
 - states can be discrete or continuous
- Transits from one state to another by chance over time
- The transition probabilities depend only on the current state
- The transition probability can be represented in a matrix form called Markov matrix
- Time-homogeneous Markov chain: A special case of Markov chain whose transition probabilities remain the same over time

• The four states of PonPon the rabbit



Sleeping (S)



Playing (P)



Eating (E)



Grooming (G)

• The Markov matrix the four states is

	S	P	E	\boldsymbol{G}
S	0.5	0.1	0.2	0.2
P	0	0.4	0.3	0.3
E	0.3	0.1	0.6	0
\boldsymbol{G}	0.25	0.25	0.25	0.25

JC69 substitution model

- Nucleotide substitution
 - mutation
 - four states: A, C, T, G

$$P = \begin{pmatrix} \frac{1}{4} + \frac{3}{4}e^{-t\mu} & \frac{1}{4} - \frac{1}{4}e^{-t\mu} & \frac{1}{4} - \frac{1}{4}e^{-t\mu} & \frac{1}{4} - \frac{1}{4}e^{-t\mu} \\ \\ \frac{1}{4} - \frac{1}{4}e^{-t\mu} & \frac{1}{4} + \frac{3}{4}e^{-t\mu} & \frac{1}{4} - \frac{1}{4}e^{-t\mu} & \frac{1}{4} - \frac{1}{4}e^{-t\mu} \\ \\ \frac{1}{4} - \frac{1}{4}e^{-t\mu} & \frac{1}{4} - \frac{1}{4}e^{-t\mu} & \frac{1}{4} + \frac{3}{4}e^{-t\mu} & \frac{1}{4} - \frac{1}{4}e^{-t\mu} \\ \\ \frac{1}{4} - \frac{1}{4}e^{-t\mu} & \frac{1}{4} - \frac{1}{4}e^{-t\mu} & \frac{1}{4} - \frac{1}{4}e^{-t\mu} & \frac{1}{4} + \frac{3}{4}e^{-t\mu} \end{pmatrix}$$

- Other substitution models include
 - Kimura 1980, Felsenstein 1981 etc

Wright-Fisher model as a Markov chain

- For diploids, if the effective population size is N, then the possible number of alleles (states) are $\{0, 1, 2, ..., 2N\}$.
- Assume there are two alleles: A and B
- The dimension of the Markov matrix is (2N + 1) * (2N + 1)
- Genetic drift changes the allele frequency over generations
- If the frequency of allele A is k/2N now, then the number of allele A in the next generation follows binomial(2N,k/2N)

- For instance, for N=2, there are five states: $\{0,1,2,3,4\}$ representing the number of allele A.
- The $\{i,j\}^{th}$ element of the transition matrix is the probability from state i to state j.

Jump to state *j*

```
| Second State | Seco
```

Example

• Given the Wright-Fisher transition matrix of N=2. Let X(t) be the number of allele A at time t.

What is
$$\Pr(X(t+1) = 3|X(t) = 2)$$
? What is $\Pr(X(t+1) = 3|X(t) = 0)$? What is $\Pr(X(t+2) = 3|X(t) = 2)$?

Some properties of Markov matrix

- Non-negative (the elements are probabilities, of course)
- Row sum to one
- If a Markov matrix M is time-homogeneous, then the transition probabilities for T steps ahead is M^T
- We can analyse the long-run behaviour of M. Some Markov chains have limiting distributions, $\lim_{T\to\infty} M^T$ exists.
- Some even have stationary distributions π , where $\pi M = \pi$
- There are some states which you cannot leave once you have entered. They are called the absorbing states. For example, the first row and the last row of the Wright-Fisher model (Why?)



Stationary distribution $\pi = (0.3, 0.175, 0.375, 0.15)$

• For WF model M^{30} looks like this:

```
[,1] [,2] [,3] [,4] [,5]
[1,] 1.0000000 0.000000e+00 0.000000e+00 0.000000e+00 0.0000000
[2,] 0.7499203 5.102345e-05 5.740139e-05 5.102345e-05 0.2499203
[3,] 0.4998937 6.803127e-05 7.653518e-05 6.803127e-05 0.4998937
[4,] 0.2499203 5.102345e-05 5.740139e-05 5.102345e-05 0.7499203
[5,] 0.0000000 0.000000e+00 0.000000e+00 0.0000000e
```

- According to the WF model, all alleles go fixed/extinct in 30 generations if N=2
- Genetic drift reduces genetic variation!

Other Markov processes

- Moran model
 - alternative to Wright-Fisher model
 - allows overlapping generations

- Birth and Death process
 - continuous-time Markov process
 - birth: state+1; death: state-1
 - infinitely many states

Monte Carlo integration

- To evaluate the following integral: $I = \int_0^1 \sqrt{1 x^2} dx$
- Calculate by hand... ☺
- Numerical methods such as quadrature rule
 - counting areas of rectangles / trapeziums
 - integrate() in R

integrate (function (x) { $sqrt(1-x^2)$ }, lower=0, upper=1)

Monte Carlo integration

$$\bullet \ I = \int_0^1 \sqrt{1 - x^2} dx$$

• Sample $\{x_1, x_2, ..., x_n\}$ from uniform(0, 1) distribution

• Compute
$$I_n = \frac{1}{n} \sum_{i=1}^{n} \sqrt{1 - x_i^2}$$

• I_n is an approximation to the integral I, if n is reasonably large

Justification

•
$$I = \int_a^b g(x) dx = \int_a^b \frac{g(x)}{f(x)} f(x) dx = E_X \left[\frac{g(X)}{f(X)} \right]$$

- where X is a r.v. with pdf f and support (a, b). The integral becomes the expectation of the transformed r.v. $\frac{g(X)}{f(X)}$.
- Remember, expectation is the population mean, the average of infinitely many trials, which can be "replicated" by computer
- Draw $\{x_1, \dots, x_n\}$ from f, $I_n = \frac{1}{n} \sum_{i=1}^n \frac{g(x_i)}{f(x_i)}$ is a good approximation to I for sufficiently large n

•
$$\int_0^\infty xe^{-2x}dx$$

•
$$\int_0^\infty x e^{-2x} dx$$

• Let $X \sim Exponential(\lambda = 1)$, $f_X(x) = e^{-x}$

$$\int_0^\infty \frac{xe^{-2x}}{e^{-x}} e^{-x} dx$$

$$= \int_0^\infty xe^{-x} e^{-x} dx$$

$$= E_X[Xe^{-X}]$$

- Sample $\{x_1, x_2, \dots, x_n\}$ from Exponential(1) distribution for some large n
- $I_n = \frac{1}{n} \sum_{i=1}^n x_i e^{-x_i}$ is an approximation to the original integral

```
x<-rexp(1e6, 1)
mean(x*exp(-x))
```

- Stochastic simulation -> no deterministic answers (unlike integrate() in R)
 - "random" answers
- Able to work with ±∞ bounds
 - as long as the chosen r.v. is defined in those bounds (e.g. normal)

Exercise

- Evaluate $\int_{-\infty}^{+\infty} e^{-x^2} dx$ via MC integration
 - which r.v. should you use? Those with ±∞ bounds perhaps?
 - some choices of r.v. are better than the others

- The intrinsic variance of MC integration is unavoidable
 - slow convergence
 - variance $\propto \frac{1}{n}$ as each draw is independent
 - need large n
- Multivariate integrals -> Multivariate distributions
 - requires samples from a multivariate distribution
 - requires even more sampling points
- There are ways to reduce variance (beyond this course)
 - e.g. importance sampling
- It is also possible to use dependent samples
 - Markov Chain Monte Carlo (MCMC)

MCMC integration

- $\int_a^b g(x)dx \approx \frac{1}{n} \sum_{i=1}^{n} \frac{g(x_i)}{f(x_i)}$
- In pure MC integration we assume $\{x_1, \dots, x_n\}$ are independent
- In fact the above approximation still holds for correlated $\{x_1, \dots, x_n\}$
- Sometimes it is easier to generate a series of dependent $\{x_1, \dots, x_n\}$
- One can (smartly) construct a Markov chain, whose stationary distribution is f
 - Gibbs sampling
 - Metropolis-Hastings (MH) algorithm

Example 1.1: Estimating haplotype frequencies and LD

- Two-locus, two-allele setting
- Four haplotypes: AB, Ab, aB, ab
 - with true haplotype frequencies p_{AB} , p_{Ab} , p_{aB} , p_{ab}
 - sum of four haplotype frequencies =1

	В	b	
A	p_{AB}	p_{Ab}	
а	p_{aB}	$p_{ m ab}$	
			1

- If haplotypic data is obtained then the MLE is
 - $\widehat{p_{AB}} = \frac{\text{# of AB haplotype observed}}{\text{total haplotype sample size}}$
 - same for all four haplotype frequencies

•
$$\widehat{r^2} = \frac{(\widehat{p_{AB}}\widehat{p_{ab}} - \widehat{p_{Ab}}\widehat{p_{aB}})^2}{\widehat{p_{A}}.(1 - \widehat{p_{A}}.)\widehat{p_{B}}.(1 - \widehat{p_{B}}.)}$$

- according to the invariant principle, $\widehat{r^2}$ is also the MLE for r^2 , the standardised LD coefficient
- heavily biased for small sample size

Table 1 Expected genotypic frequencies under HWE

	BB	ВЬ	bb
AA	$f_1 = p_{AB}^2$	$f_2 = 2p_{AB}p_{Ab}$	$f_3 = p_{Ab}^2$
Aa	$f_4 = 2p_{AB}p_{aB}$	$f_5 = 2(p_{AB}p_{ab} + p_{Ab}p_{aB})$	$f_6 = 2p_{Ab}p_{ab}$
aa	$f_7 = p_{aB}^2$	$f_8 = 2p_{aB}p_{ab}$	$f_9 = p_{ab}^2$

The expected frequency of genotypes given the haplotype frequencies under HWE [2]. All the expected frequencies $f_1, f_2, ..., f_9$ add up to one

- Sometimes only genotypic information is obtained.
- Nine genotypes, each has an expected frequency under HWE.
- The genotype counts $\{n_1, n_2, ..., n_9\}$ are assumed to follow a multinomial distribution with size n and expected frequencies $\{f_1, f_2, ..., f_9\}$
- The log-likelihood function is

$$l(p_{AB}, p_{Ab}, p_{aB}, p_{ab}) = constant + \sum_{i=1}^{9} n_i \log(f_i)$$

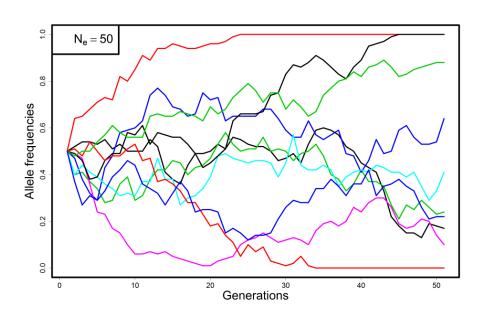
 In theory, we can maximise the above log-likelihood to find the MLE for the four haplotype frequencies, but...

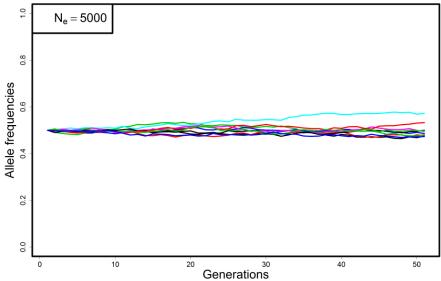
- There are challenges:
 - no closed-form solution
 - The four haplotype frequencies add up to 1; the fourth frequency is redundant. Hence the parameter space is a tetrahedron
 - sometimes there are multiple points with zero gradients (saddle / local points)?

Possible solutions:

- Expectation-Maximisation (EM) algorithm (Excoffier & Slatkin 1995)
- some kind of transformation before maximising the loglikelihood? into a cube? (Hui and Burt, 2020)

Example 2: Drift and population size





- Model: Wright-Fisher model (the Markov matrix)
- Parameter of interest: N, the effective population size
- Data: The allele frequencies at two time points, across many unlinked loci.

So why not MLE???

Transition prob, from WF matrix

•
$$L(N) = \sum_{all\ p_t} \sum_{all\ p_0} f(x_t|p_t) f(p_t|p_0, N) f(x_0|p_0)$$

Sampling at time t Sampling at time 0

- The two sampling $f(x_t|p_t)$ and $f(x_0|p_0)$ are modelled by binomial distributions, independently
- The transition probabilities $f(p_t|p_0,N)$ can be obtained from the WF matrix M^t

- "The likelihood of observing x_0 and x_t , given the true allele frequencies p_0 and p_t , and effective population size N"
 - then sum these likelihood values over all possible p_0 and p_t
 - state-space model
 - from 0 to 2N

Williamson & Slatkin (1999); Hui & Burt (2015)

Summary - MLE

- Day 1: Common r.v. and their pmf/pdf. Expectation.
 Moment generation functions.
- Day 2: Multivariate r.v., independence. Define likelihood functions. The triplet: model, data, parameters. Maximisation via differentiation and optim().
- Day 3: Properties of MLE. Likelihood-ratio test.
 Logistic regression.
- Day 4: C.I. by log-likelihood. C.I. by approximate normality. Joint confidence region. Profile likelihood.
- Day 5: Examples and more examples

Beyond this course

R functions and packages that help implement MLE

```
- mle(), confint()
- {stats4}
```

Alternative optimisation routines

```
- nlm(), nlminb()
- {optimx}, {lbfgsb3}, {BB}, ... etc
```

- Require some 'grammatical' changes
- Multivariate testing

(Possible) solutions

Approximation to the integrals (e.g. Laplace approximation), EM algorithm

Statistical sampling (e.g. Monte Carlo, MCMC)

Approximate Bayesian Computation (ABC)

More Statistics!

MLE is...

Not just a method, but THE method

 A collection of methods that share a common belief towards how "the best parameters" should be

 Many canned software and functions make use of the results from MLE (with or without acknowledging it)