



## Report

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# Assignment 1

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Course:

Deep Learning for Medical Imaging

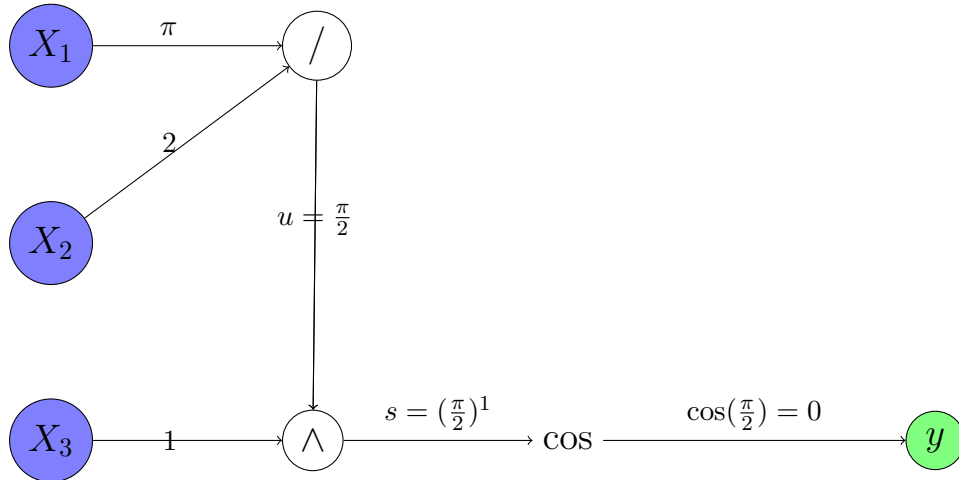
Course code:

XM.0151

## 1 Exercice 2 - Feedforward loop calculation by pen

A

Forward pass



Backward pass

We define  $y$ ,  $s$ , and  $u$  as follows:

$$y = \cos(s)$$

$$u = \frac{x_1}{x_2}$$

$$s = u^{x_3} = e^{x_3 \ln \frac{x_1}{x_2}}$$

This yields in the following derivatives:

$$\frac{dy}{dx_1} = \frac{dy}{ds} \cdot \frac{ds}{du} \cdot \frac{du}{dx_1} = \frac{d \cos(s)}{ds} \cdot \frac{du^{x_3}}{du} \cdot \frac{d \frac{x_1}{x_2}}{dx_1} = -\sin(s) \cdot x_3 \cdot u^{x_3-1} \cdot \frac{1}{x_2} = -\sin\left(\left(\frac{\pi}{2}\right)^1\right) \cdot 1 \cdot \left(\frac{\pi}{2}\right)^0 \cdot \frac{1}{2} = -1 \cdot 1 \cdot 1 \cdot \frac{1}{2} = -\frac{1}{2}$$

$$\frac{dy}{dx_2} = \frac{dy}{ds} \cdot \frac{ds}{du} \cdot \frac{du}{dx_2} = -\sin(s) \cdot x_3 \cdot u^{x_3-1} \cdot \left(-\frac{x_1}{x_2^2}\right) = -1 \cdot 1 \cdot 1 \cdot \left(-\frac{\pi}{4}\right) = \frac{\pi}{4}$$

$$\frac{dy}{dx_3} = \frac{dy}{ds} \cdot \frac{ds}{dx_3} = -\sin(s) \cdot s \cdot \left(\ln u + \frac{x_3 du}{u dx_3}\right) = -\sin(s) \cdot s \cdot s(\ln u + 0) = -1 \cdot \frac{\pi}{2} \cdot \ln \frac{\pi}{2}$$

B

Defining  $y$  as follows:

$$y = \cos\left(\left(\frac{x_1}{x_2}\right)^{x_3}\right)$$

Yields in the following derivatives:

$$\frac{dy}{dx_1} = -\sin\left(\left(\frac{x_1}{x_2}\right)^{x_3}\right) \cdot x_3 \cdot \left(\frac{x_1}{x_2}\right)^{x_3-1} \cdot \frac{1}{x_2}$$

$$\frac{dy}{dx_2} = -\sin\left(\left(\frac{x_1}{x_2}\right)^{x_3}\right) \cdot x_3 \cdot \left(\frac{x_1}{x_2}\right)^{x_3-1} \cdot \frac{x_1}{x_2^2}$$

$$\frac{dy}{dx_3} = -\sin\left(\left(\frac{x_1}{x_2}\right)^{x_3}\right) \cdot \left(\frac{x_1}{x_2}\right)^{x_3} \cdot \ln \frac{x_1}{x_2} + \frac{x_3 d \frac{x_1}{x_2}}{\frac{x_1}{x_2} dx_3}$$

C

$$\begin{aligned} z &= W^T x + b \\ &= \begin{bmatrix} 2 & 1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} -2 \\ 3 \end{bmatrix} + \begin{bmatrix} 1 \\ 2 \end{bmatrix} \\ &= \begin{bmatrix} -1 \\ 8 \end{bmatrix} + \begin{bmatrix} 1 \\ 2 \end{bmatrix} \\ &= \begin{bmatrix} 0 \\ 10 \end{bmatrix} \end{aligned}$$

$$a = \text{ReLU}(z) = \max(0, z) = \begin{bmatrix} 0 \\ 10 \end{bmatrix}$$

$$\begin{aligned} \text{Output layer: } y &= v^T a = \begin{bmatrix} 3 & 2 \end{bmatrix} \begin{bmatrix} 0 \\ 10 \end{bmatrix} \\ &= 20 \end{aligned}$$

D

We know that:

$$y = 20, y_{true} = 22$$

$$L = (y - y_{true})^2 = (20 - 22)^2 = (-2)^2 = 4$$

$$y = v_1 a_1 + v_2 a_2$$

$$a_2 = \sigma(x_2 W_{2,2} + x_1 W_{1,2})$$

From this it follows that:

$$\frac{dL}{dy} = 2(y - y_{true}) = 2(20 - 22) = -4$$

$$\frac{dy}{da_2} = v_2 = 2$$

$$\frac{da_2}{dW_{2,2}} = x_2 = 3$$

Thus:

$$\frac{dL}{dW_{2,2}} = \frac{dL}{dy} \cdot \frac{dy}{da_2} \cdot \frac{da_2}{dW_{2,2}} = -4 \cdot 2 \cdot 3 = -24$$