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Turing Machines

(Part 3)

Lecture 17 - 1
Day 20/31

CS 154
Formal Languages and Computability
Spring 2018

Agenda of Day 20

- Collecting Quiz 6 (Take-Home Exam)
- About Teams
- Summary of Lecture 16
- Lecture 17: Teaching ...
 - Turing Machines (Part 3)
 - Other Models of TMs (Part 1)

Summary of Lecture 16: We learned ...

TMs

- A **standard** Turing machine M is defined by the **septuple**:

$$M = (Q, \Sigma, \Gamma, \delta, q_0, \square, F)$$

$$\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\}$$

- $\square \in \Gamma$ is a special symbol called blank.
- $\delta(q_1, a) = (q_2, b, R)$

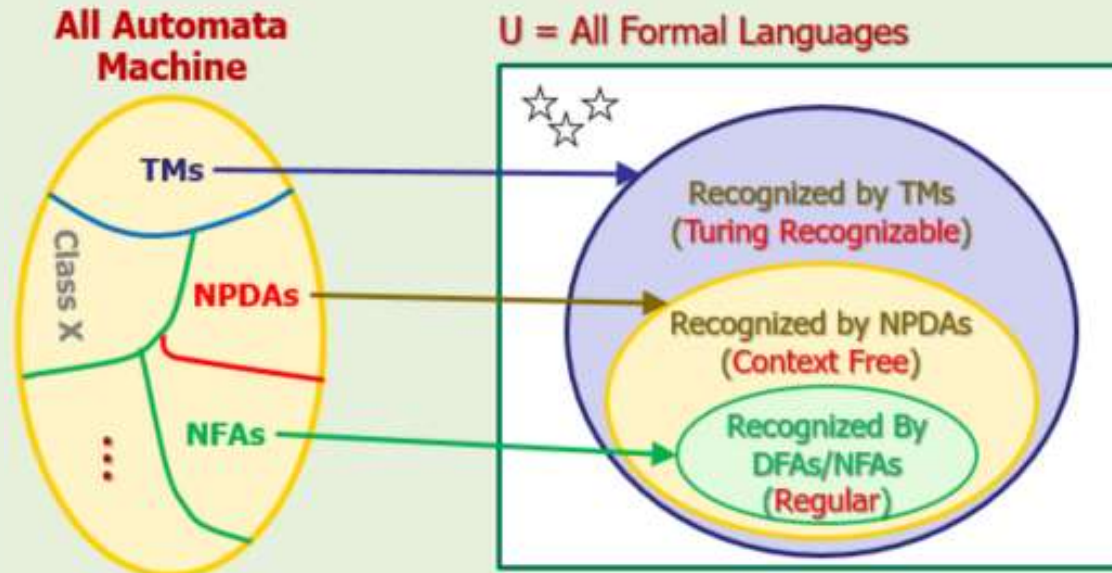
TMs vs NPDAs

- Another way to compare classes of automata is "simulation".
- We can **simulate** whatever **NPDAs** do with **TMs**.
- But not vice versa!
 - At least we know **some languages** for which we could not construct NPDAs but could construct TMS
 - such as: **$a^n b^n c^n$** and **ww**
- So, **TMs** are more powerful than **NPDAs**.

Any Question

Summary of Lecture 16: **We learned ...**

Machines and Languages Association



- TMs recognize some other non-regular languages called "Turing recognizable".

Any Question

TMs as Transducers

What are transducers?

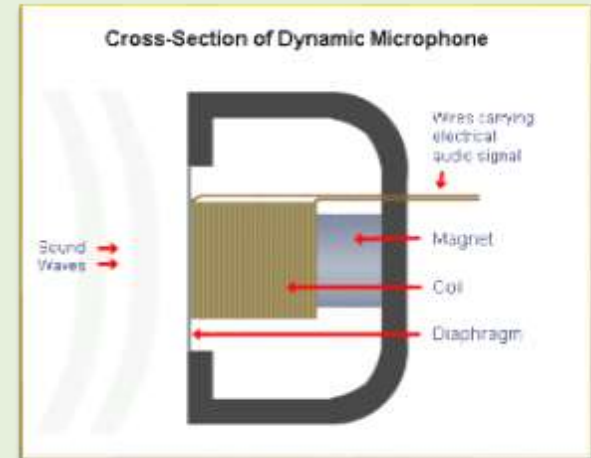
- In physics, transducer is a device that converts the variation in a physical quantity into an electrical signal, or vice versa.
 - The variation could be movement, pressure, brightness, or so forth.
- In a nutshell, transducer is a device that converts an input to an output.



Examples of Transducers

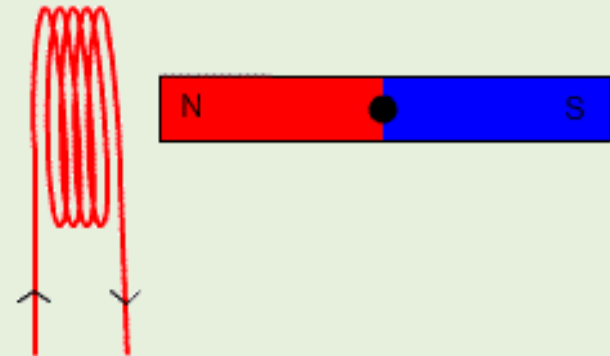
Example 11: Microphone

- A microphone converts your voice to electrical signals.



Example 12: Electric Generator

- An electric generator converts movement to electrical power.



Reference

- Bo Krantz Simonsen at [da.wikipedia](https://da.wikipedia.org)

Mathematical Model of Transducers

- What is the mathematical model for transducers?
- Functions!
- Recall that a function ...
- ... converts (aka maps) an input (a member of its domain) to an output (a member of its range) based on a rule.

TMs as Transducers

- A TM can act like a transducer. Why?
 - Because it can transform an input to an output.
- What are the input and output of a TM when we run TMs in transducer mode?

Input

- All or part of the nonblank symbols on the tape at the initial time.

Output

- Ⓢ ▪ In fact, it's designer's responsibility to define the input and output.

How JFLAP Shows TMs' Outputs

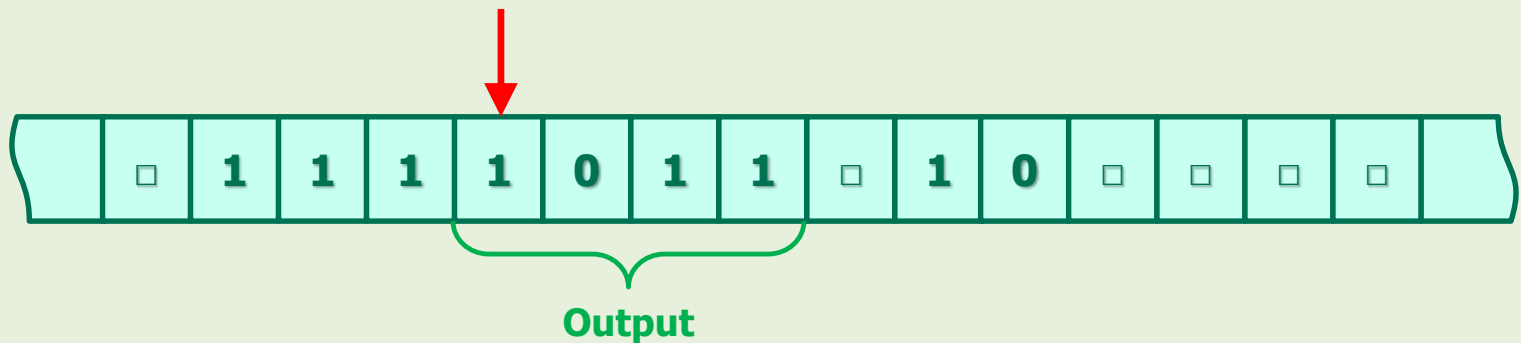
- JFLAP can run TMs in two modes:
 - Regular mode
 - Transducer mode
- In regular mode, JFLAP shows "Accept" or "Reject" for accepting/rejecting strings.
- In transducer mode, it shows the output of the computation too.
- We'll follow how JFLAP shows the output of TMs when we run them in transducer mode.
- Let's explain it through an example.



How JFLAP Shows TMs Outputs in Transducer Mode

Example 13

- When the TM halts in an accepting state, if the content of the tape is what the following schematic shows , ...



- ... what would be the output?
- Output = 1 0 1 1
- So, the output starts from the symbol at which the head is pointing, to the right, until the first blank.

Turing Computable Functions



Definition

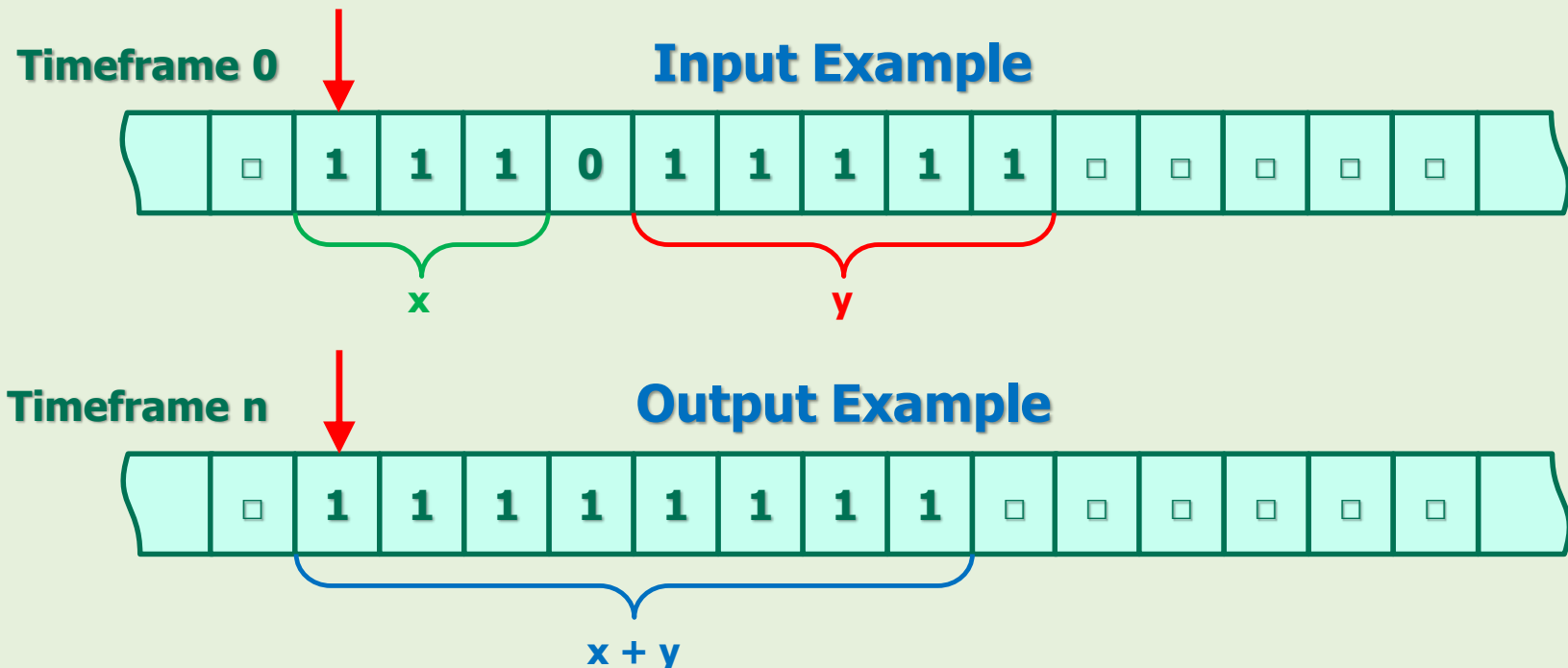
- A function is said to be "Turing-computable" (or just "computable") if there exists a TM that implements it.
- It has been proved that all common mathematical functions, no matter how complicated, are Turing-computable.
- Let's take some practical examples (basic operations of computers) such as:
 - adding numbers
 - copying strings
 - simple comparisons



TMs as Transducers

Example 14

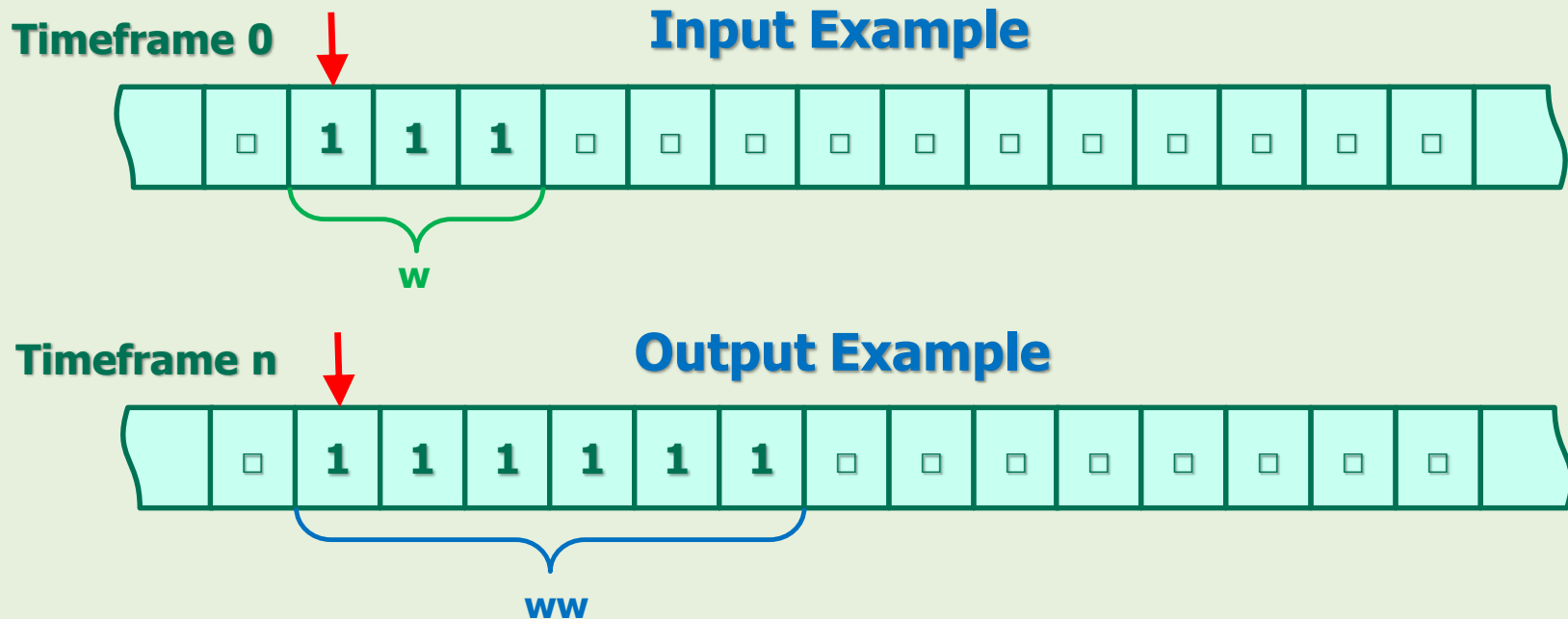
- Given two non-zero positive integers x and y , represented in unary notation, separated by a single 0 (zero).
- Design a TM that computes $x + y$.



Homework



- Given a string $w \in L = \{1\}^+$.
- Design a TM that **writes a copy of w** at the end of the w .



- At the end of the execution, we'll have "**ww**" on the tape.

Homework



- Given two non-zero positive integers x and y (x goes first), represented in **unary notation** separated by a single 0 (zero).
- Design a TM that halts in an **accepting** state if $x \geq y$, **otherwise** it halts in a **non-accepting** state.

Combining TMs

Combining TMs

- How to combine TMs to solve more complex problems?

Example 15

- Given two non-zero positive integers x and y , represented in unary notation, and separated by a zero.
- Design a TM to compute the following function:

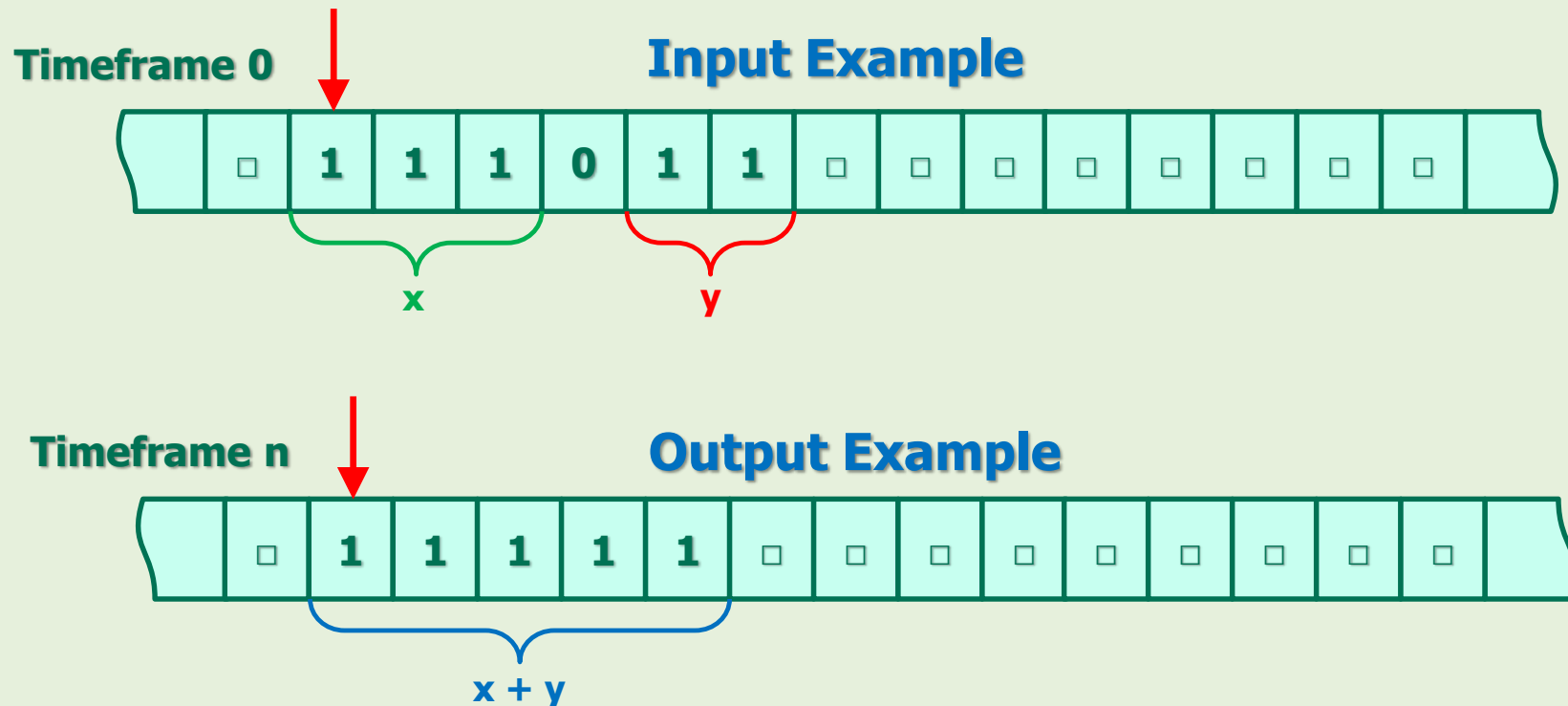
$$f(x, y) = \begin{cases} x + y & \text{if } x \geq y \\ 0 & \text{if } x < y \end{cases}$$

- Let's visualize what would be the output in different situations ...

TM as Transducer

Example 15: When $x \geq y$

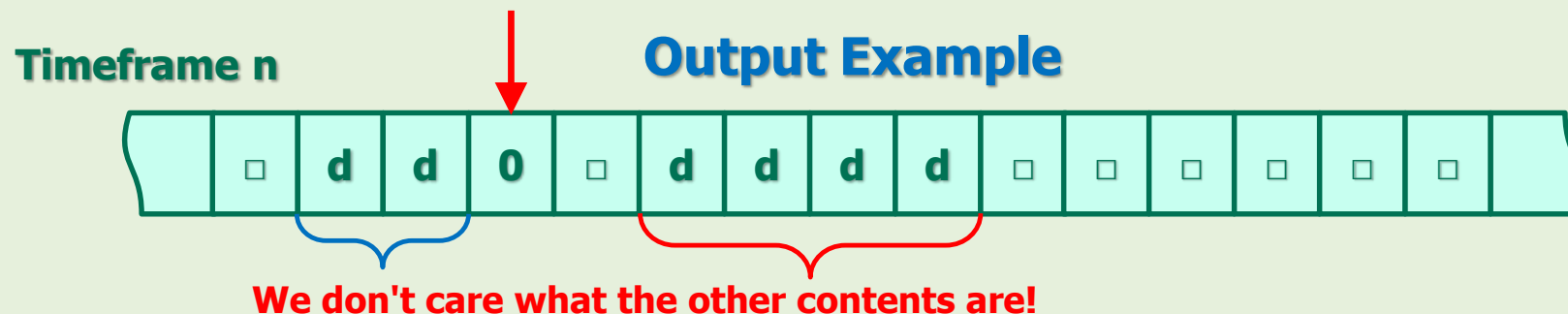
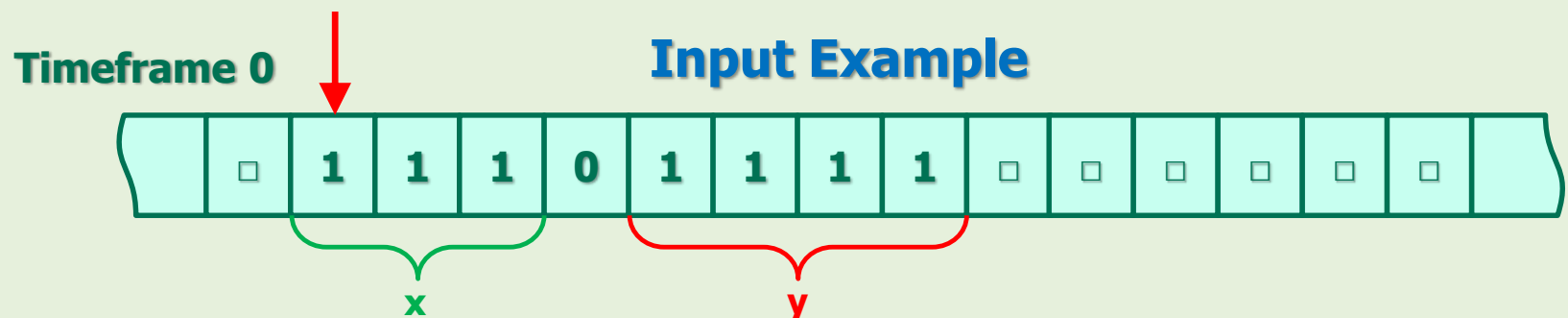
$$f(x, y) = \begin{cases} x + y & \text{if } x \geq y \\ 0 & \text{if } x < y \end{cases}$$



TM as Transducer

Example 15: When $x < y$

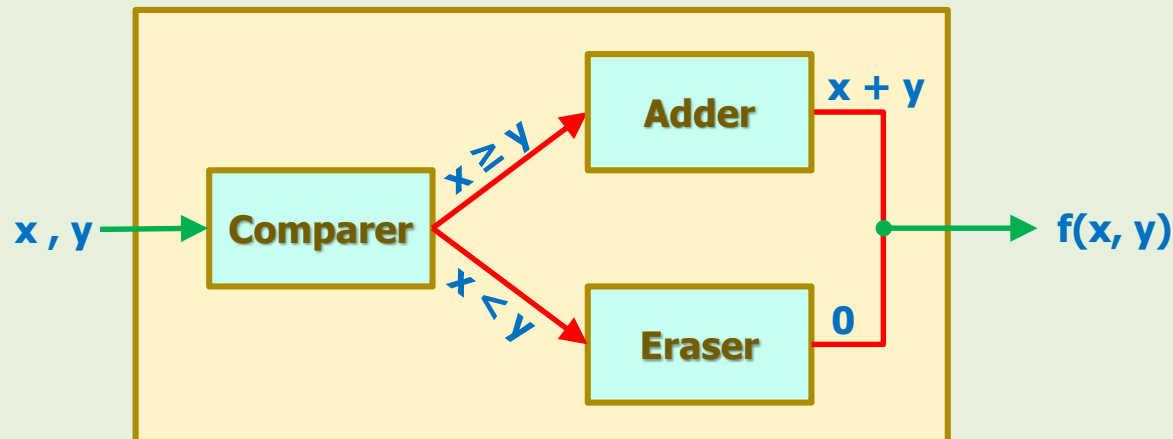
$$f(x, y) = \begin{cases} x + y & \text{if } x \geq y \\ 0 & \text{if } x < y \end{cases}$$



Combining TMs

Example 15 (cont'd)

- To implement this function, we would need the following routines:
 - a comparer
 - an adder
 - an eraser
- A **comparer** compares x and y ...
 - If $x \geq y$, then it activates the **adder** to compute $x + y$.
 - Else (i.e.: $x < y$), it activates the **eraser** to show zero.



Combining TMs



Example 15 (cont'd)

- This example shows that we can decompose any complex problem into simpler routines and implement each routine with a TM.
- Do the rest of this example as homework!



Homework

- Given two **positive integers** x and y , represented in **unary notation**, and separated by a zero.
- Design a TM to compute $x * y$.

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Other Models of TMs

Lecture 17 -2
Day 20/31

CS 154
Formal Languages and Computability
Spring 2018

Introduction

- We saw how adding memory could increase the computing power.
- Now the question is ...
- ... to make more powerful machines, can we add more memory, or different kind of memories?
- For example:
 - two or more stacks,
 - a queue and a stack,
 - two or more tapes
 - or ...
- How far can we go?
- What would be the most powerful automata?

Objective of This Lecture

- We are going to **check** some of those questions.
- We'll **add some extra capabilities** to the **standard TMs**.
- By any changes, we introduce a **new class** of automata.
- Then, **the very first question** would be:
 - Is this new class **more powerful** than the standard TMs?
- We've already saw how we compare the classes of automata **by simulation**.

TMs with Stay-Option

TMs with Stay-Option

- In standard TMs, the head can move "left (L)" or "right (R)".
- Now, we add a new movement to the head, ...
 - Stay (S), or no move
- Everything else would remain exactly the same as standard TMs.

Formal Definition

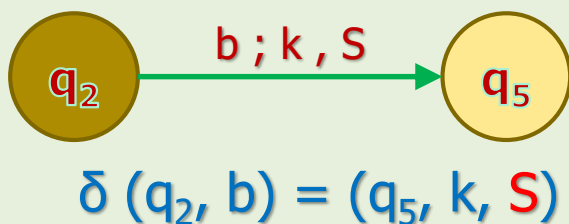
$$M = (Q, \Sigma, \Gamma, \delta, q_0, \square, F)$$

- Where:
 - ... (same as standard TM)
 - $\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, S\}$

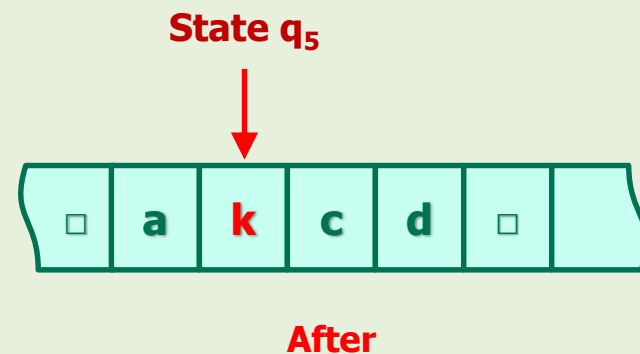
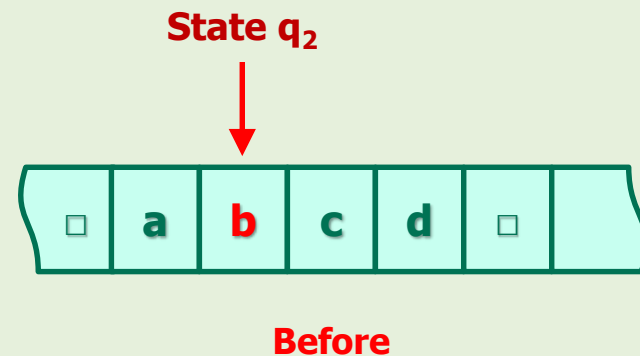
TMs with Stay-Option

Example 1

- Consider the following **transition**:



- The figures show the **content** of the tape and the **position** of the read-write-head before and after the transition.



Is this new class more powerful than standard TMs?

Theorem

- The class of TMs with stay-option is equivalent to the class of standard TMs.
- We need to prove two things:
 1. TMs with stay-option simulate standard TMs.
 2. Standard TMs simulate TMs with stay-option.

Proof of 1

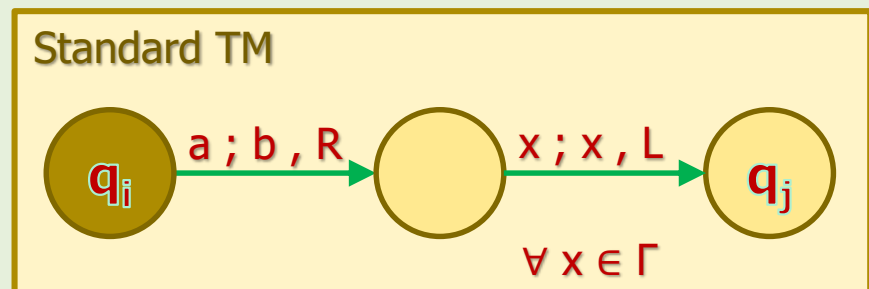
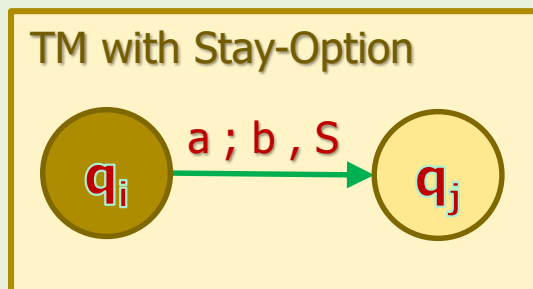
- Let's assume we've constructed a standard TM for an arbitrary language L.
- Can we always construct a TM with stay-option for L? How?
- Yes, just don't use "S" option!

Is this new class more powerful than standard TMs?

Proof of 2

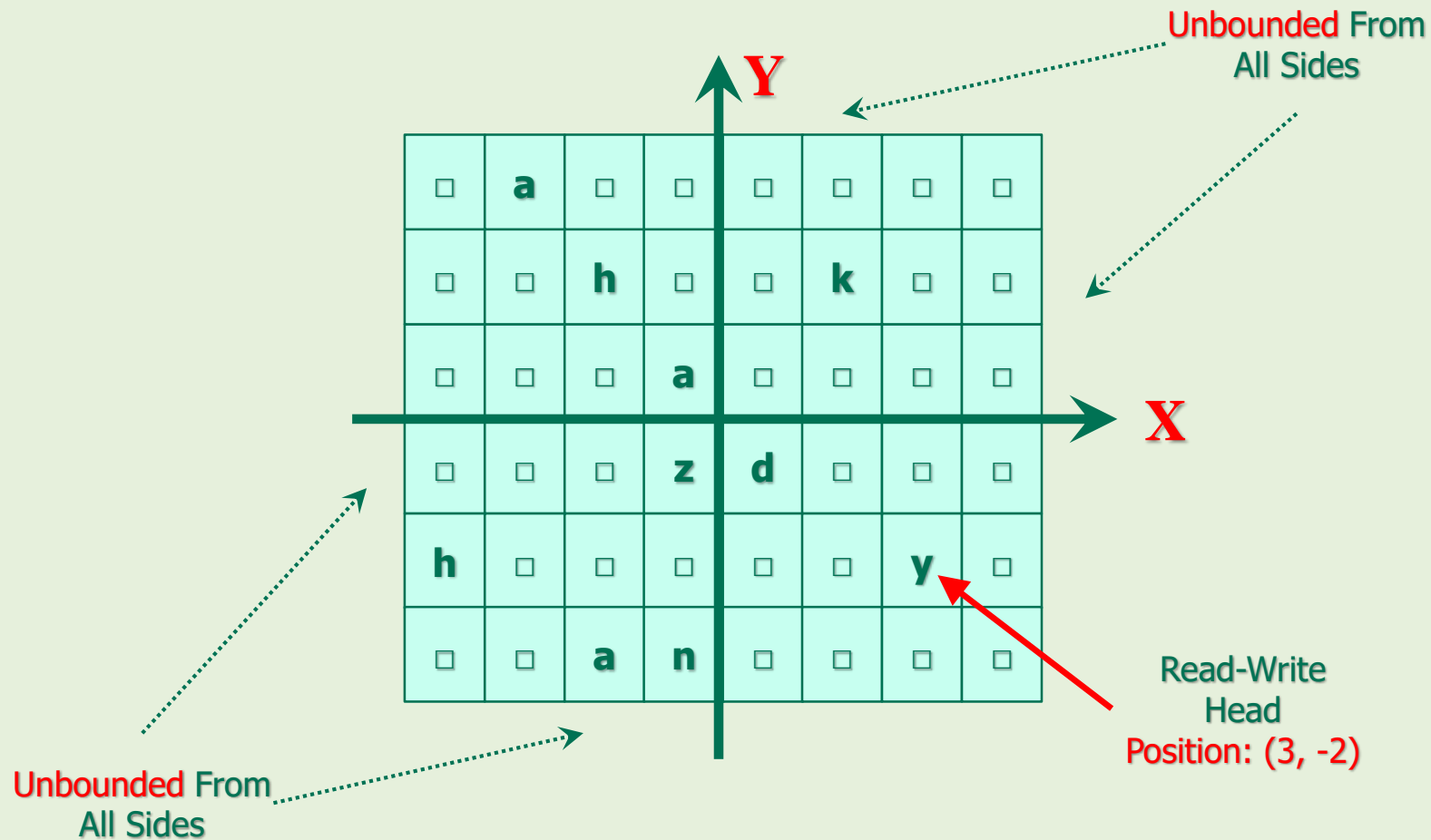


- Let's assume we've constructed a TM with stay-option for an arbitrary language L .
- Can we construct a standard TM for L ? **How?**
- The **only difference** is those transitions that use "**S**" option.
- So, we just need to **simulate "no move"** for those transitions.
- That can be simulated by **two moves** of the head: "left, then right" (or "right, then left") as the following figures show.



Multidimensional-Tape TMs

Multidimensional-Tape TMs



Multidimensional-Tape TMs

Definition

- A **multidimensional-tape TMs** M is defined by the septuple:

$$M = (Q, \Sigma, \Gamma, \delta, q_0, \square, F)$$

- Where:
 - ... (same as standard TM elements)

$$\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, U, D\}$$

- The new movements: **U**=Up and **D**=Down

Is this new class more powerful than standard TMs?

Theorem

- The class of multidimensional-tape TMs is equivalent to the class of standard TMs.
- We need to prove two things:
 1. Multidimensional-tape TMs simulate standard TMs.
 2. Standard TMs simulate multidimensional-tape TMs.

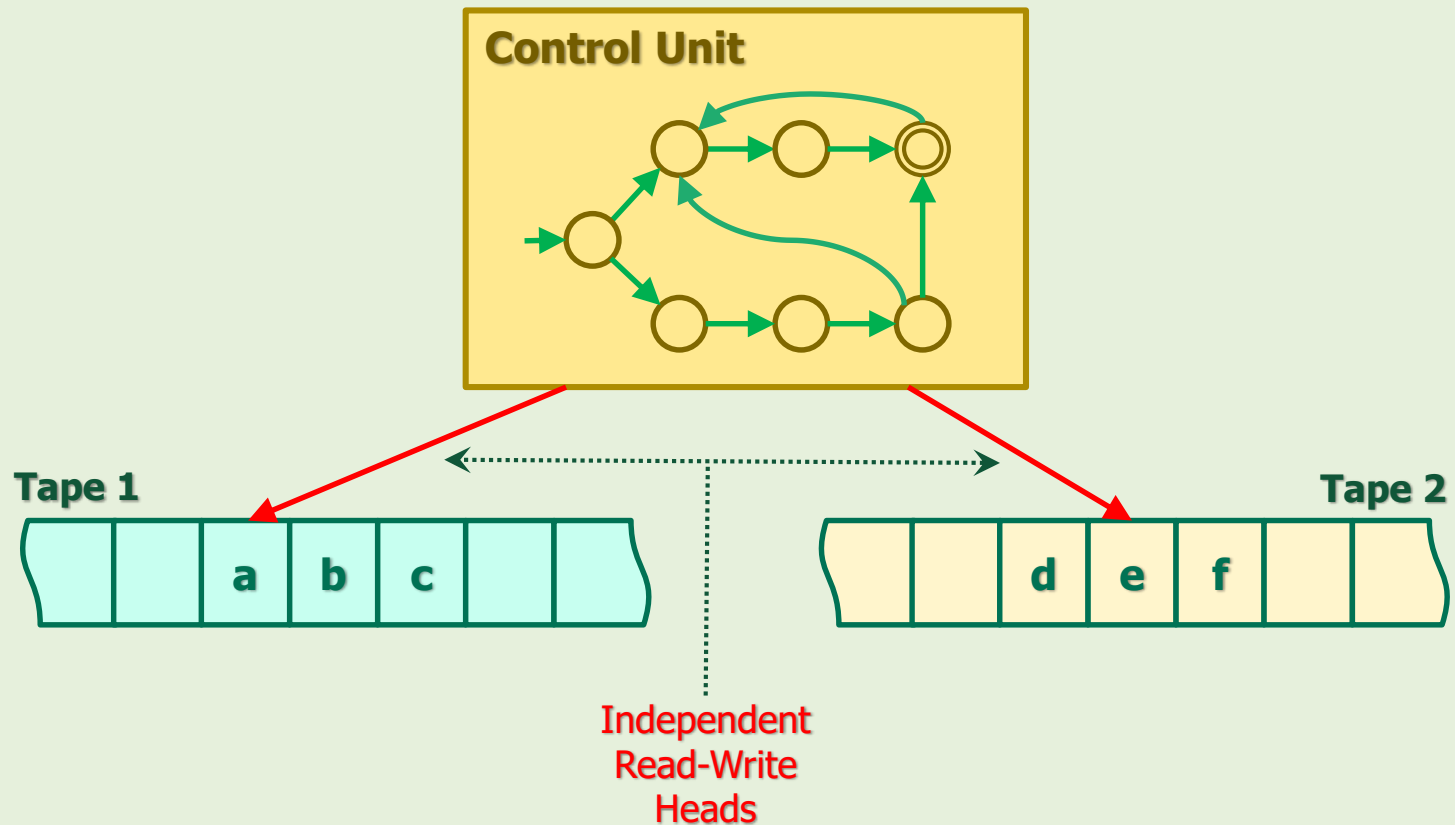
Proof

1. Multidimensional-tape TMs simulate standard TMs.
 - This step is trivial because if we just use one row of the tape, then we have standard TM.
2. Standard TMs simulate multidimensional-tape TMs.
 - Prove this as exercise!

⚠ Multi-Tape TMs

Multi-Tape TMs

- We can add **additional tapes with independent read-write head** to the standard TMs.
- For example, a **double-tape** TM looks like this:



Multi-Tape TMs

Formal Definition

- An n -tape TM M is defined by the septuple:

$$M = (Q, \Sigma, \Gamma, \delta, q_0, \square, F)$$

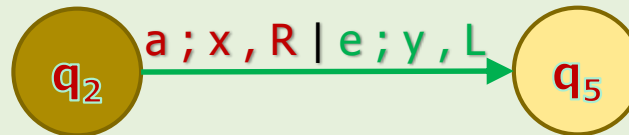
- Where:
 - ... (same as standard TM elements)

$$\delta: Q \times \Gamma^n \rightarrow Q \times \Gamma^n \times \{L, R\}^n$$

- Note that: $\Gamma^n = \Gamma \times \Gamma \times \dots \times \Gamma$ (Cartesian product)
- Therefore, the result is an n -tuple.

Formal Definition of Multi-Tape TMs

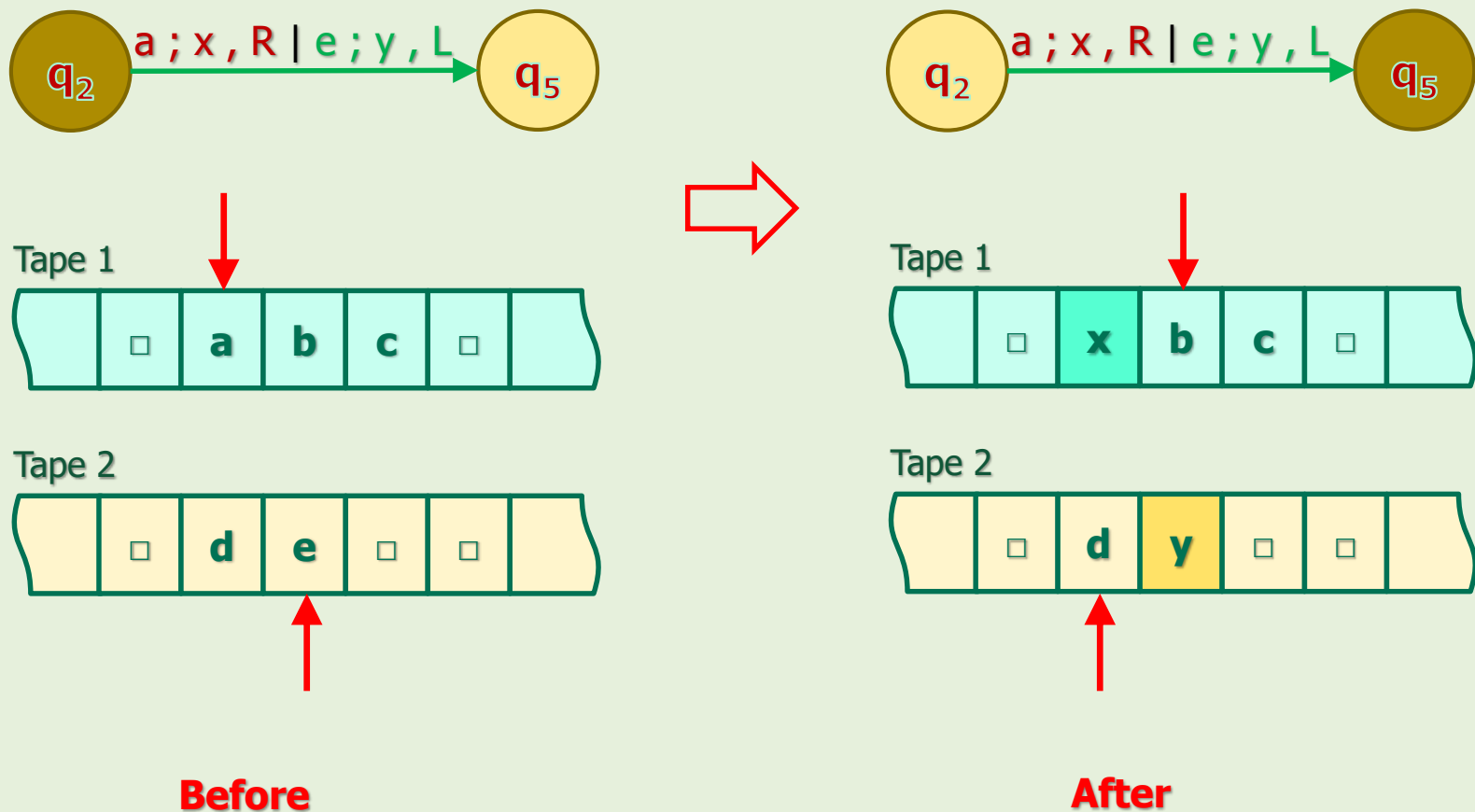
- **Example 2**



- This is a transition of a **double-tape TM**.
 - We **separate** the **labels** of different tapes with "|".
- The **transition condition** is both inputs:
input symbol of tape 1 = 'a'
AND
input symbol of tape 2 = 'e'.
- The **sub-rule** looks like this: $\delta(q_2, a, e) = (q_5, x, y, R, L)$

Formal Definition of Multi-Tape TMs

- Example 2 (cont'd) $\delta(q_2, a, e) = (q_5, x, y, R, L)$



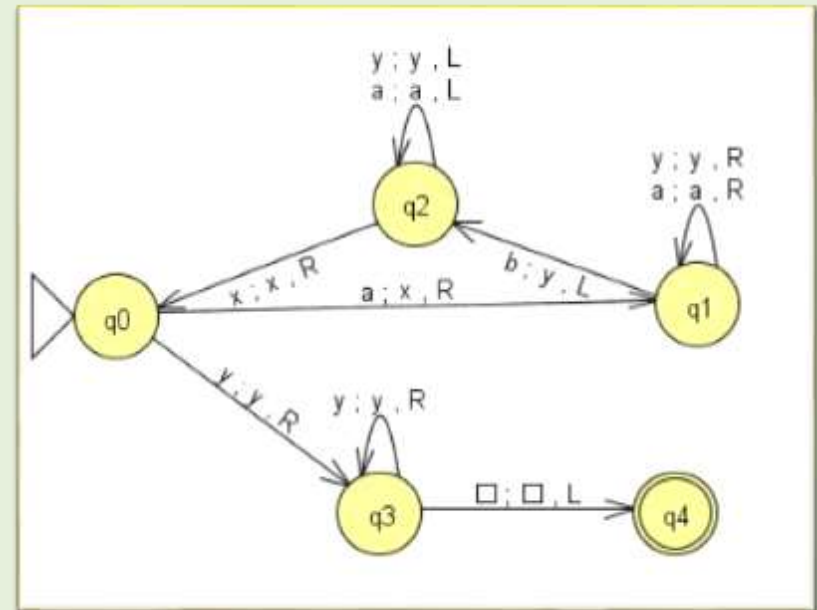


Multi-Tape TMs Example

Example 3

- Design a **double-tape** TM for accepting the language $L = \{a^n b^n : n \geq 1\}$ over $\Sigma = \{a, b\}$.
- Assume that the input is written on the **tape 1** and for simplicity, we can use "**stay-option**".

- Recall that we had **designed** a **standard TM** for L before as the figure shows.





Multi-Tape TMs Example

Example 3 (cont'd)

Strategy

- Read a's from tape 1 and write them on tape 2.
- When sensed the first 'b' on tape 1, match b's with the a's on tape 2.
- If all match, then accept,
- otherwise, reject.



- Do **double-tape** TMs facilitate our programming?



Homework

- Design a **double-tape TM** for accepting the following language:
 $L = \{a^n b^n c^n : n \geq 1\}$ over $\Sigma = \{a, b, c\}$
- Assume that **the input is written on the tape 1** and for simplicity, you can use "**stay-option**".

Is this new class more powerful than standard TMs?

Theorem

- The class of multi-tape TMs is equivalent to the class of standard TMs.
- We need to prove two things:
 1. Multi-tape TMs simulate standard TMs.
 2. Standard TMs simulate multi-tape TMs.

Proof

1. Multi-tape TMs simulate standard TMs.
 - This step is trivial because if we just use one tape, then we have standard TM.
2. Standard TMs simulate multi-tape TMs.



Nice Videos

1. Turing machines explained visually
https://www.youtube.com/watch?v=-ZS_zFg4w5k
2. A Turing machine – Overview
<https://www.youtube.com/watch?v=E3keLeMwfHY>

References

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