# CS146: Data Structures and Algorithms Lecture 14

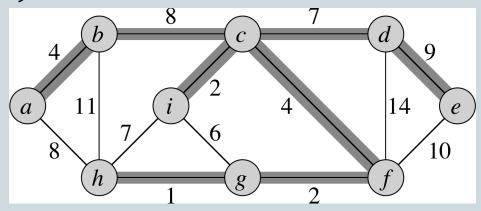
MINIMUM SPANNING TREE
PRIM'S AND KRUSKAL'S ALGORITHMS (CH 23)

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CS SJSU

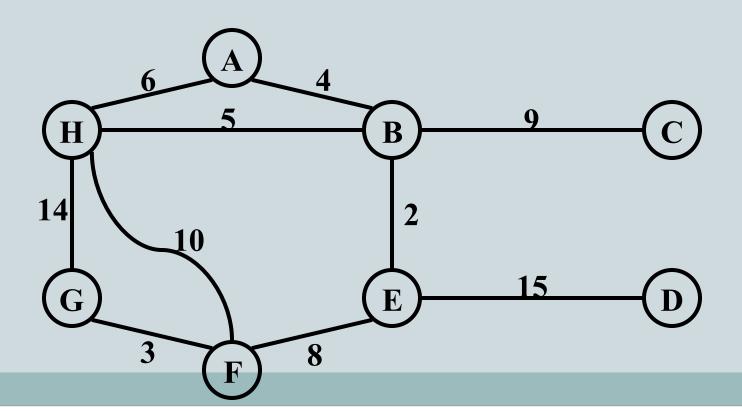
# Minimum Spanning Tree (Ch 23)

- 2
- Given: a connected, undirected, weighted graph with
- w: E-> R
- Output: a spanning tree T (spans all vertices)
- Goal: minimize the total weight of the selected edges  $w(T) = \sum (u,v) \in T \uparrow w(u,v)$

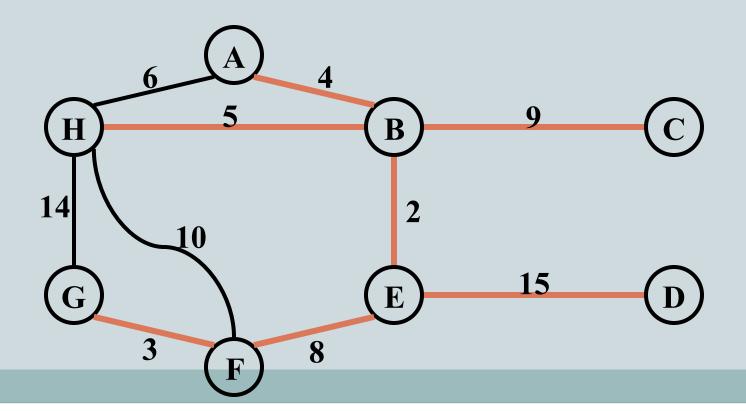




 Which edges form the minimum spanning tree (MST) of this graph?



• Solution: (not unique usually..), edges?, cycles?



- MSTs satisfy the *optimal substructure* property:
- an optimal tree is composed of optimal subtrees
  - $\Box$  Let T be an MST of G with an edge (u,v) in the middle
  - $\square$  Removing (u,v) partitions T into two trees  $T_1$  and  $T_2$
  - □ Claim:  $T_1$  is an MST of  $G_1 = (V_1, E_1)$ , and  $T_2$  is an MST of  $G_2 = (V_2, E_2)$  (Do  $V_1$  and  $V_2$  share vertices? Why?)
  - □ Proof:  $w(T) = w(u,v) + w(T_1) + w(T_2)$ (There can't be a better tree than  $T_1$  or  $T_2$ , or T would be suboptimal)

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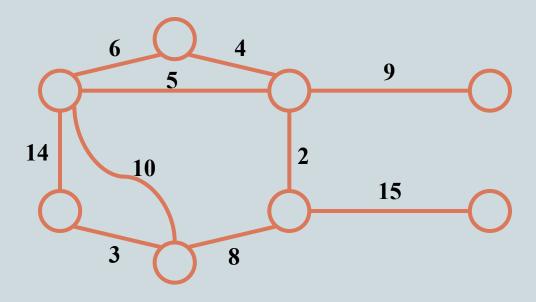
- Theorem:
  - $\circ$  Let T be MST of G, and let A  $\subseteq$  T be subtree of T
  - $\circ$  Let (u,v) be min-weight edge connecting A to V-A
  - o Then  $(u,v) \in T$
- Proof: in book (see Thm 23.1)

# Prim's algorithm (for MST)

- Start at an arbitrary vertex and grow until the tree spans all the vertices
- In each step add to the tree an edge with minimum weight

# Prim's vs Kruskal's Algorithm





```
\infty
MST-Prim(G, w, r)
                                                 \infty
     Q = G.V;
     for each u \in Q
                            14
                                     10
          u.key = \infty;
                                                         15
                                                 \infty
     r.key = 0;
                                   3
                                             8
                                        \infty
     u.\pi = NULL;
                                     Pick a start vertex r
     while (Q not empty)
          u = ExtractMin(Q);
          for each v \in Adj[u]
                if (v \in Q \text{ and } w(u,v) < v.\text{key})
                     v.\pi = u;
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                                        \infty
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                                         Black vertices have
     while (Q not empty)
                                        been removed from Q
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     r.key = 0;
                                    3
                                             8
     u.\pi = NULL;
                                       Black arrows indicate
     while (Q not empty)
                                           parent pointers
          u = ExtractMin(Q);
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```

# Review: Prim's Algorithm

```
How much time to build heap Q?
MST-Prim(G, w, r)
    Q = G.V;
                        How often is ExtractMin() called?
    for each u \in Q
                        |V| each cost log|V|
         u.key = \infty;
                        How often is DecreaseKey() called?
    r.key = 0;
                        |E| each cost log|V|
    u.\pi = NULL;
    while (Q not empty)
         u = ExtractMin(Q);
         for each v \in Adj[u]
             if (v \in Q \text{ and } w(u,v) < v.\text{key})
                  v.\pi = u;
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```

#### Review: Prim's Algorithm

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```
MST-Prim(G, w, r)
    Q = G.V;
                          What will be the running time?
    for each u \in Q
                          A: Depends on queue
        u.key = \infty;
                            binary heap: O(E lg V)
    r.key = 0;
                            Fibonacci heap: O(V \lg V + E)
    u.\pi = NULL;
    while (Q not empty)
        u = ExtractMin(Q);
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# **Greedy Algorithms**



- Used for optimization problems.
- *Idea*: When we have a choice to make
  - make the one that looks best right now.
  - make a *locally optimal choice* in hope of getting a *globally optimal solution*.
- Greedy algorithms don't always yield an optimal solution. But sometimes they do. We'll see a problem for which they do. Then we'll look at some general characteristics of when greedy algorithms give optimal solutions.
- Similar to dynamic programming (see later).

# Kruskal's Algorithm for MST



- Starts with each vertex being its own component.
- Repeatedly merges two components into one by choosing the light edge that connects them (i.e., the light edge crossing the cut between them).
- Scans the set of edges in monotonically increasing order by weight.
- Uses a disjoint-set data structure to determine whether an edge connects vertices in different components.

```
Kruskal()
   T = \emptyset;
   for each v \in V
      MakeSet(v);
   sort E by increasing edge weight w
   for each (u,v) \in E (in sorted order)
       if FindSet(u) ≠ FindSet(v)
          T = T \cup \{\{u,v\}\};
          Union(FindSet(u), FindSet(v));
```

```
Run the algorithm:
Kruskal()
                                 25
   T = \emptyset;
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                    83
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                                     192
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#### Correctness Of Kruskal's Algorithm



- Sketch of a proof that this algorithm produces an MST for T:
  - Assume algorithm is wrong: result is not an MST
  - Then algorithm adds a wrong edge at some point
  - If it adds a wrong edge, there must be a lower weight edge (cut and paste argument)
  - But algorithm chooses lowest weight edge at each step.
     Contradiction

(56)

```
What will affect the running time?
Kruskal()
   T = \emptyset;
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```

```
(57)
```

```
What will affect the running time?
Kruskal()
                                     O(ElgE) Sort Edges
                                    O(V) MakeSet() calls
   T = \emptyset;
                                     O(E) FindSet() calls
   for each v \in V
                                      O(V) Union() calls
                            (Exactly how many Union()s?)
       MakeSet(v);
   sort E by increasing edge weight w
   for each (u,v) \in E (in sorted order)
       if FindSet(u) ≠ FindSet(v)
           T = T U \{\{u,v\}\};
          Union(FindSet(u), FindSet(v));
```

#### Kruskal's Algorithm: Running Time



- To summarize:
  - Sort edges: O(E lg E)
  - o O(V) MakeSet()'s
  - o O(E) FindSet()'s
  - O(V) Union()'s
- So:
  - Best disjoint-set union algorithm makes above 3 operations take  $O(E \cdot \alpha(E,V))$ ,  $\alpha$  almost constant
  - Overall thus O(E lg E), almost linear w/o sorting

#### Disjoint-Set Union Problem (Ch 21)

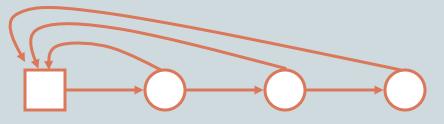


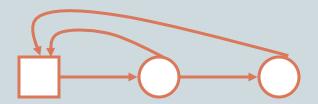
- Want a data structure to support disjoint sets
  - Collection of disjoint sets  $S = \{S_i\}, S_i \cap S_i = \emptyset$
- Need to support following operations:
  - MakeSet(x):  $S = S \cup \{\{x\}\}$
  - Union(S<sub>i</sub>, S<sub>j</sub>):  $S = S \{S_i, S_j\} \cup \{S_i \cup S_j\}$
  - FindSet(X): return  $S_i \in S$  such that  $x \in S_i$
- Application: MST (Kruskal's algorithm)

#### Disjoint Set Union (Ch 21.2)



- So how do we implement disjoint-set union?
  - Naïve implementation: use a linked list to represent each set:





- × MakeSet(): O(1) time
- x FindSet(): O(1) time
- ▼ Union(A,B): "copy" elements of A into B: O(A) time
- O How long can a single Union() take?
- Or How long will n Union()'s take?

#### Disjoint Set Union: Analysis

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Worst-case analysis: O(n²) time for n Union's

```
Union(S_1, S_2) "copy" 1 element Union(S_2, S_3) "copy" 2 elements ...

Union(S_{n-1}, S_n) "copy" n-1 elements O(n^2)
```

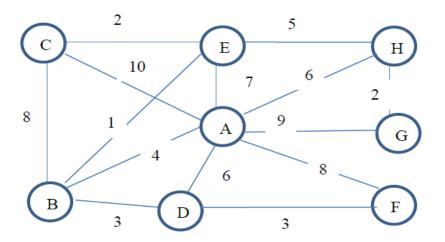
- Improvement: always copy smaller into larger
  - Why will this make things better?
  - What is the worst-case time of Union()?
- But now n Union's take only O(n lg n) time!

# practice



#### points each]

13. [18 pts] LuxuryForAll Construction is in the process of installing power lines to a large housing development. The owner wants to minimize the total length of wire used, which will minimize her costs. The housing development is shown as a graph in the next figure. Each house has been numbered, and the distance between the houses are given in hundreds of feet. What do you recommend? (Total length of wires and also which will be installed.) How would you solve it efficiently? Show all the steps.



#### Next: Single-Source Shortest Path (Ch 24)



- Input: given a weighted directed graph G,
- Output: find the path from a given source vertex s to another vertex v
- Goal: minimum-weight path
  - o "Shortest-path" = minimum weight
  - Weight of path is sum of weighted edges
  - E.g., a road map: what is the shortest path from San Jose to Palo Alto?