CS146: Data Structures and Algorithms Lecture 6

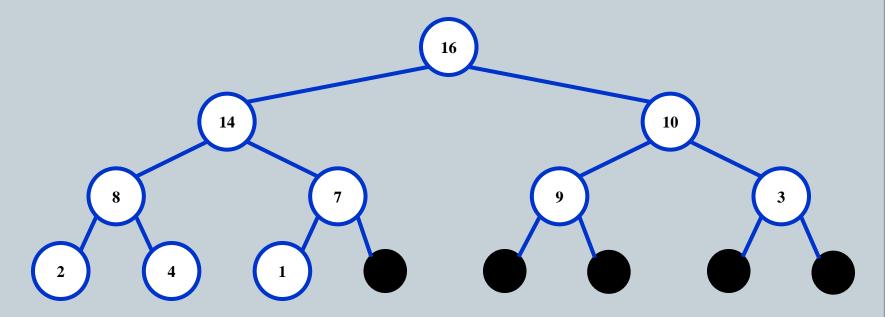
HEAPS - HEAPSORT

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Heaps (chapter 6)

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A heap can be seen as a complete binary tree:



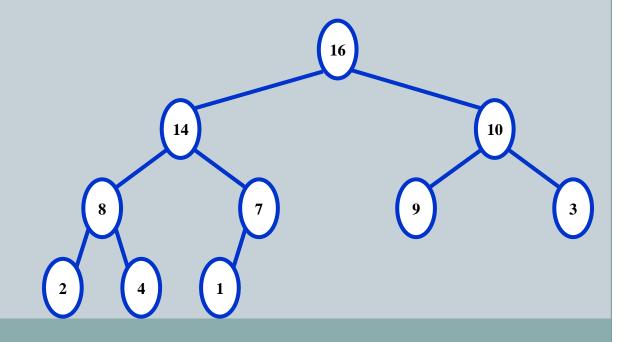
"nearly complete" binary trees: you can think of unfilled slots as null pointers

Heaps

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In practice, heaps are usually implemented as arrays:

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 \\ 16 & 14 & 10 & 8 & 7 & 9 & 3 & 2 & 4 & 1 & = \end{bmatrix}$$



Heaps



To represent a complete binary tree as an array:

The root node is A[1]

Node i is A[i]

The parent of node i is A[i/2] (note: integer divide)

The left child of node i is A[2i]

The right child of node i is A[2i + 1]



Referencing Heap Elements

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```
So...
```

```
parent(i) { return [i/2]; }
left(i) { return 2*i; }
right(i) { return 2*i + 1; }
```

How would you implement this most efficiently?

The Heap Property

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Heaps also satisfy the *heap property*:

 $A[parent(i)] \ge A[i]$ for all nodes i > 1

i.e., the value of a node is at most the value of its parent

In case of Max Heap

Where is the largest element in a heap stored?

- The *height* of a node in the tree = the number of edges on the longest downward path to a leaf
- The height of a tree = the height of its root

Self test

Is the array with values 23; 17; 14; 6; 13; 10; 1; 5; 7;12 a max-heap?

Heap Height



What is the height of an n-element heap?

This is nice property: all basic heap operations take at most time proportional to the height of the heap!

Heap Operations: Heapify()



Heapify(): maintain the heap property

- Input: a node i in the heap with children l and r
- **o**& two subtrees rooted at l and r, assumed to be heaps

The subtree rooted at *i* may violate the heap property (*Give an example...*)

• Output: the tree rooted at i is a heap

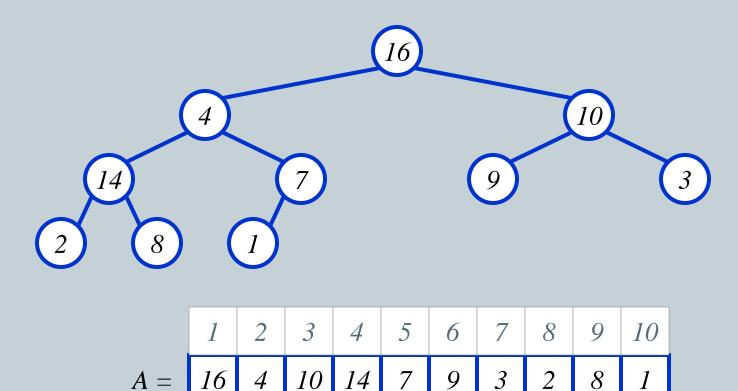
Action: let the value of the parent node "float down" so subtree at *i* satisfies the heap property

• What basic operation between i, l, and r must be used?

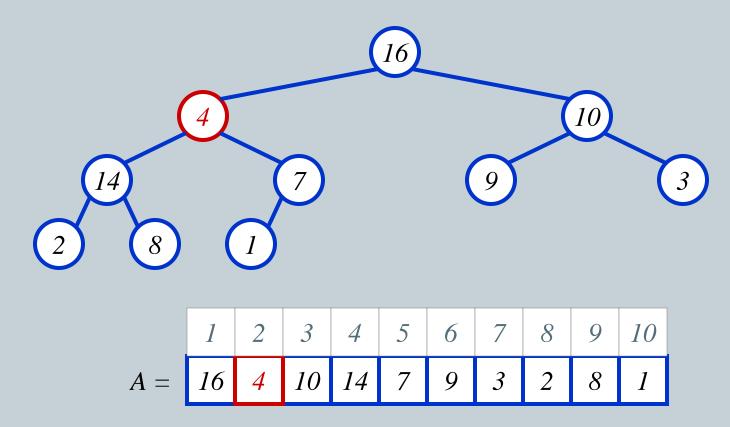
Heap Operations: Heapify()

```
Heapify(A, i)
  l = Left(i)
  r = Right(i)
  if (1 <= A.heap_size && A[1] > A[i])
   largest = 1
  else largest = i
  if (r <= A.heap_size && A[r] > A[largest])
   largest = r
  if (largest != i)
   Swap(A, i, largest);
   Heapify(A, largest);
```

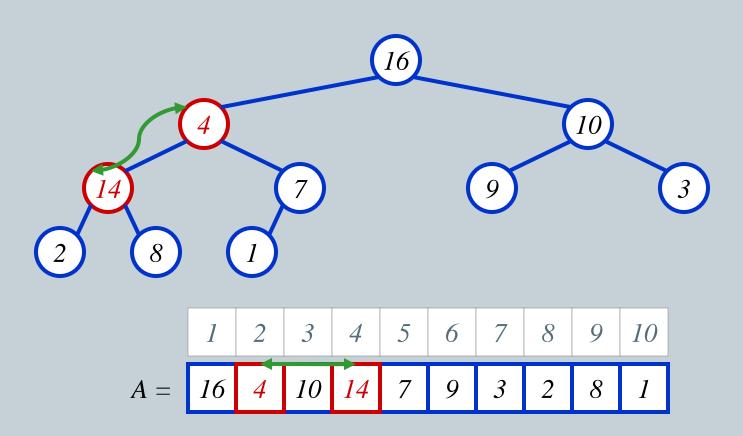




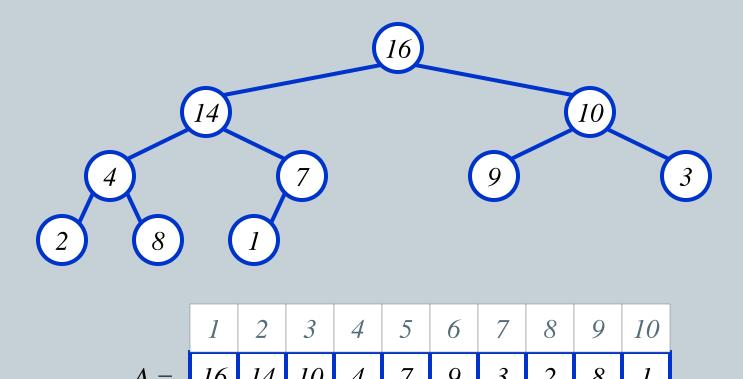
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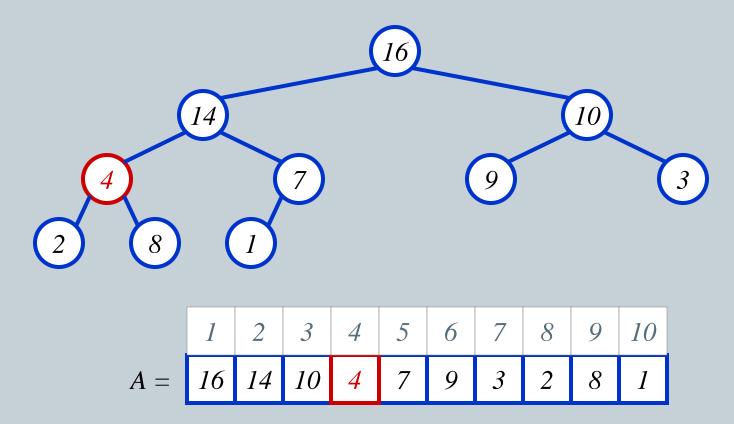




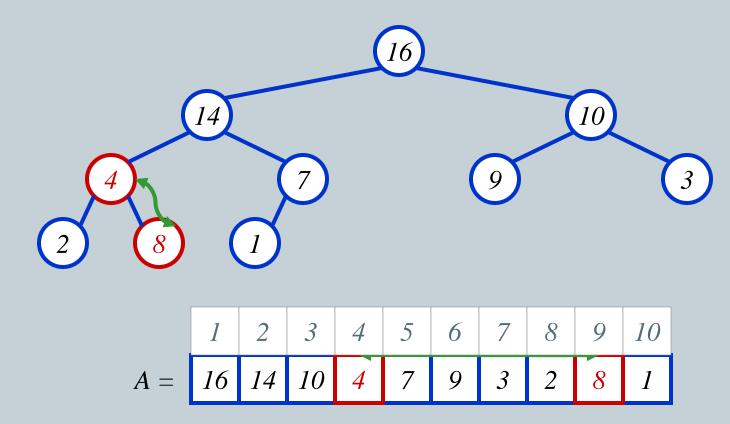
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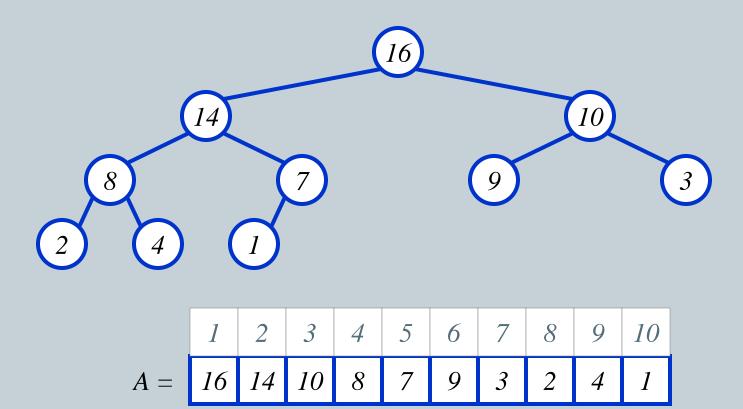
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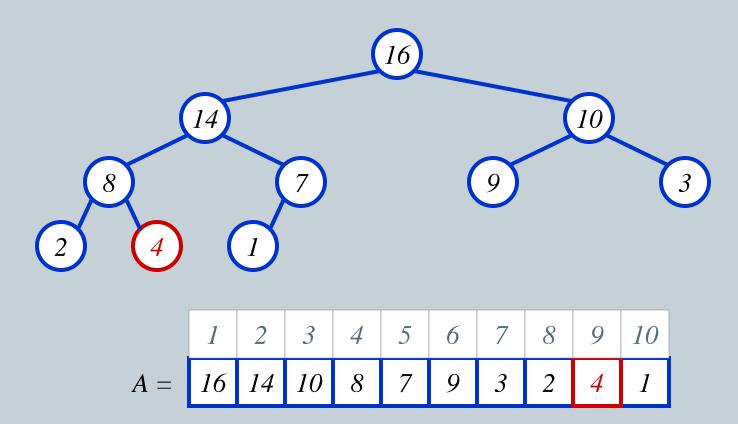
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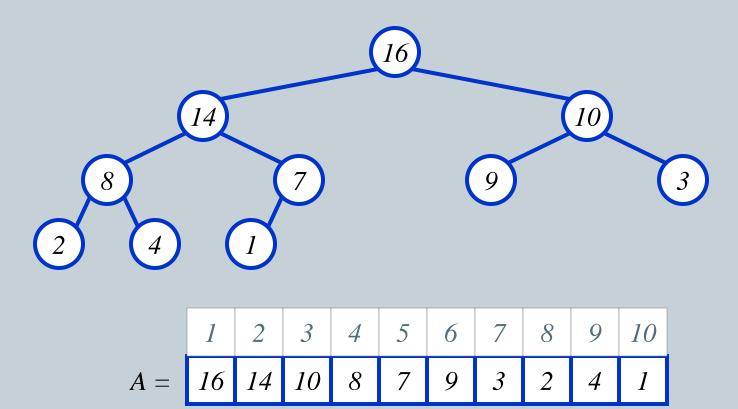




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Analyzing Heapify()

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Except the recursive call, what is the running time of **Heapify()**?

How many times can **Heapify()** recursively call itself?

What is the worst-case running time of **Heapify**() on a heap of size n?

Analyzing Heapify(): Formal



Fixing up relationships between i, l, and r takes $\Theta(1)$ time If the heap at i has n elements, how many elements can the subtrees at l or r have?

Draw it

Answer: 2n/3 (worst case: bottom row 1/2 full)

So time taken by **Heapify()** is given by

$$T(n) \le T(2n/3) + \Theta(1)$$

Analyzing Heapify(): Formal

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So we have

$$T(n) \le T(2n/3) + \Theta(1)$$

By case 2 of the Master Theorem,

$$T(n) = O(\lg n)$$

Thus, Heapify() takes logarthmic time

Heap Operations: BuildHeap()



We can build a heap in a *bottom-up* manner by running **Heapify()** on successive subarrays

Fact: for array of length n, all elements in range $A[\lfloor n/2 \rfloor + 1 ... n]$ are heaps (*Why is that?*) Key idea:

- Walk backwards through the array from n/2 to 1, calling **Heapify()** on each node.
- Order of processing guarantees that the children of node i are heaps when i is processed

BuildHeap()

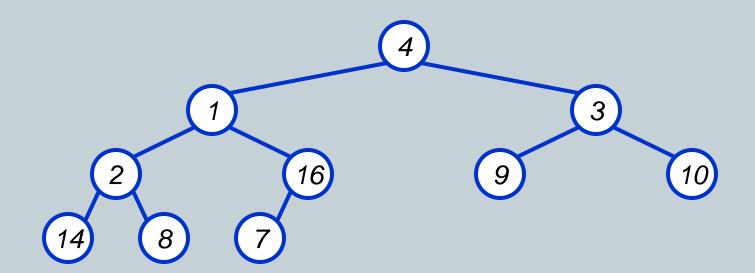
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```
// given an unsorted array A, make A a heap
BuildHeap(A)
{
   A.heap_size = A.length;  
   for (i = \[ A.length/2 \] downto 1)  
        Heapify(A, i);  
}
```

BuildHeap() Example

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Work through example $A = \{4, 1, 3, 2, 16, 9, 10, 14, 8, 7\}$



Analyzing BuildHeap()



Each call to **Heapify**() takes O(log *n*) time

There are O(n) such calls $(\lfloor n/2 \rfloor)$

Thus the running time is $O(n \log n)$

Is this a correct asymptotic upper bound?

Is this an asymptotically tight bound?

Can we do better?

A tighter bound is O(n)

Is there a flaw in the above reasoning? No more careful analysis

Analyzing BuildHeap(): Tight



To **Heapify()** a subtree takes O(h) time where h is the height of the subtree

 $h = O(\lg m)$, m = # nodes in subtree

The height of most subtrees is small

Fact: an n-element heap has at most $|n/2^{h+1}|$ nodes of height h

Uses this fact to prove that BuildHeap() takes O(n) time

BuildHeap() is O(n)!

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$$\sum_{h=0}^{\lfloor \lg n \rfloor} \left\lceil \frac{n}{2^{h+1}} \right\rceil O(h) = O\left(n \sum_{h=0}^{\lfloor \lg n \rfloor} \frac{h}{2^h}\right).$$

• Due X=1/2 it is

$$\sum_{h=0}^{\infty} \frac{h}{2^h} = \frac{1/2}{(1-1/2)^2}$$
$$= 2.$$

$$O\left(n\sum_{h=0}^{\lfloor \lg n\rfloor} \frac{h}{2^h}\right) = O\left(n\sum_{h=0}^{\infty} \frac{h}{2^h}\right)$$
$$= O(n).$$

Self Test

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• illustrate the operation of BUILD-MAX-HEAP on the array 5; 3; 17; 10; 84; 19; 6; 22; 9.

Heapsort!



Given **BuildHeap()**, an in-place sorting algorithm is easily constructed, key idea:

- Maximum element is at A[1]
- Discard by swapping with element at A[n]
 - Decrement heap_size[A]
 - A[n] now contains correct value
- Restore heap property at A[1] by calling Heapify()
- Repeat, always swapping A[1] for A[heap_size(A)]

Heapsort

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```
Heapsort(A)
BuildHeap(A);
for (i = A.length downto 2)
Swap(A[1], A[i]);
A.heap_size(A) -= 1;
Heapify(A, 1);
```

Example

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- 21, 14, 16, 12, 10, 4, 8
- HeapSort using min heap

Analyzing Heapsort



The call to **BuildHeap()** takes O(n) time

Each of the n-1 calls to **Heapify**() takes $O(\log n)$ time

Thus the total time taken by **HeapSort**()

- $= O(n) + (n 1) O(\lg n)$
- $= O(n) + O(n \lg n)$
- $= O(n \lg n)$

Priority Queues



Heapsort is a nice algorithm, but in practice Quicksort (coming up) usually wins

But the heap data structure is incredibly useful for implementing *priority queues*

A data structure for maintaining a set *S* of elements, each with an associated value or *key*

Supports the operations Insert(), Maximum(), and ExtractMax()

What might a priority queue be useful for?

Priority Queue Operations



Insert(S, x) inserts the element x into set S

Maximum(S) returns the element of S with the maximum key

ExtractMax(S) removes and returns the element of S with the maximum key

How could we implement these operations using a heap?

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Priority Queue Operations

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How could we implement these operations using a heap?

Maximum and ExtractMaximum

```
HeapMaximum(A)
   Return A[1]
HeapExtractMax(A)
    if (A.heap size < 1) { error }</pre>
    max = A[1]
    A[1] = A[A.heap size]
    A.heap size --
    Heapify (A, 1)
    return max
```

HeapExtractMax

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O(lgn) (same as Heapify)

IncreaseKey

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```
IncreaseKey(A,i,key)
 if key<A[i] error "new key is smaller than current"
 A[i]=key
 while (i>1 && A[parent(i)]<A[i])
  swap(A[i],A[parent(i)])
  i=parent(i)
```

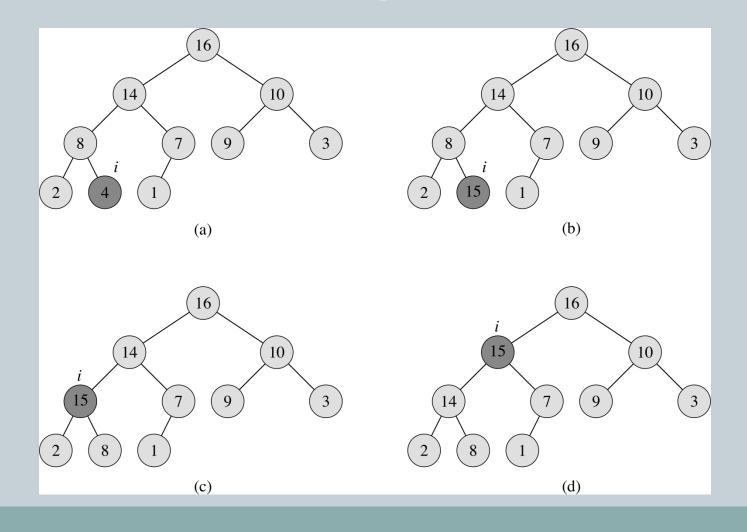
IncreaseKey complexity

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O(lgn) why?

example





Insert

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```
Insert(A, key)
  A.heap_size++
   A[A.heap size] = - infinity
   IncreaseKey(A,A.heap size, key)
O(lgn) complexity
```