CS146: Data Structures and Algorithms Lecture 16

DYNAMIC PROGRAMMING
BRUTE FORCE
BACKTRACKING

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Algorithmic Paradigms

- Greed. Build up a solution incrementally, myopically optimizing some local criterion.
- Divide-and-conquer. Break up a problem into two subproblems, solve each sub-problem independently, and combine solution to sub-problems to form solution to original problem.
- **Dynamic programming**. Break up a problem into a series of overlapping sub-problems, and build up solutions to larger and larger sub-problems.
- Brute Force: Naïve, try all possible (slow)
- Backtracking: Consider sub-solutions.

Brute Force Algorithm

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- Based on trying all possible solutions
- Approach
 - Generate and evaluate possible solutions until
 - × Solution is found
 - Best solution is found (if can be determined)
 - All possible solutions found
 - Return best solution
 - Return false if no
- Generally the most expensive approach
- Example brute force sorting: try all permutations (n!) and check if any is sorted.

Backtracking Algorithm

- Based on depth-first recursive search of a tree
 - o easy case: consider for each variable take it or not take it
- Intuition: It is often possible to reject a solution by looking at just a small portion of it. Incrementally grow a tree of partial solutions.

Tree of alternatives → search tree

Steps of backtracking

- More abstractly, a backtracking algorithm requires a test that looks at a subproblem and quickly declares one of three outcomes:
 - 1. Failure: the subproblem has no solution.
 - 2. Success: a solution to the subproblem is found.
 - 3. Uncertainty, i.e. expand sub solution

Backtracking example: Sudoku



- 1. Find row, col of an unassigned cell
- 2. If there is none, return true
- 3. For digits from 1 to 9

_	_		l	ı '				
6			1	9	5			
	9	8					6	
8				6				3
8			8		3			1
7				2				6
	6					2	8	
			4	1	9			5
				8			7	9

- 4. a) If there is no conflict for digit at row,col assign digit to row,col and recursively try fill in rest of grid
- 5. b) If recursion successful, return true
- 6. c) Else, remove digit and try another
- If all digits have been tried and nothing worked, return false

Dynamic Programming History

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• Bellman. Pioneered the systematic study of dynamic programming in the 1950s.

- Etymology.
 - Dynamic programming = planning over time.
 - Secretary of Defense was hostile to mathematical research.
 - o Bellman sought an impressive name to avoid confrontation.
 - "it's impossible to use dynamic in a pejorative sense"
 - "something not even a Congressman could object to"

Reference: Bellman, R. E. Eye of the Hurricane, An Autobiography.

Dynamic Programming Applications

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Areas.

- Bioinformatics.
- Control theory.
- Information theory.
- Operations research.
- o Computer science: theory, graphics, AI, systems,

Some famous dynamic programming algorithms.

- Viterbi for hidden Markov models.
- Unix diff for comparing two files.
- o Smith-Waterman for sequence alignment.
- Bellman-Ford for shortest path routing in networks.
- Cocke-Kasami-Younger for parsing context free grammars.

Dynamic Programming – 3rd technique (Ch 15)

- Fibonacci numbers
- o-1 Knapsack Problem
- Longest Common Subsequence (LCS)
- All pairs shortest paths

Dynamic programming

- It is used, when the solution can be recursively described in terms of solutions to subproblems (optimal substructure)
- Algorithm finds solutions to subproblems and stores them in memory (table) for later use
- More efficient than Brute-Force, which solve the same subproblems over and over again

DP: three-step method

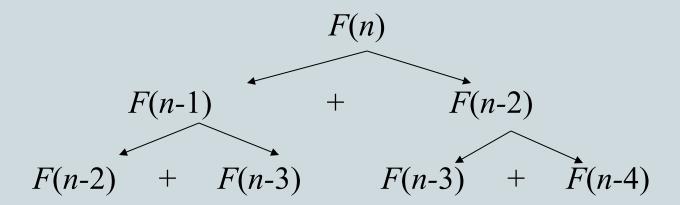
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- 1. Define subproblems
- 2. Write down the recurrence that relates subproblems
- 3. Recognize and solve the base cases

Example: Fibonacci numbers

$$F(n) = F(n-1) + F(n-2)$$

 $F(0) = 0$
 $F(1) = 1$

•Computing the n^{th} Fibonacci number recursively (top-down):



• • •

Example: Fibonacci numbers (cont.)

bottom-up iteration and recording results:

$$F(0) = 0$$

 $F(1) = 1$
 $F(2) = 1+0 = 1$

$$F(n-2) =$$
 $F(n-1) =$
 $F(n) = F(n-1) + F(n-2)$

0

F(n-2) F(n-1)

F(n)

Efficiency:

- time

- space

0-1 Knapsack problem (Ch 16.2): a picture

Items

n items with weight & benefit Pack knapsack:

- Holds up to W weight
- Maximum total benefit

Max weight: W = 20

$$W = 20$$

W	e ₁	g	ht

_i b

Benefit value

2

3

4 5

5

9 10

0-1 Knapsack problem

• Problem, in other words, is to find

$$\max \sum_{i \in T} b_i \text{ subject to } \sum_{i \in T} w_i \leq W$$

- The problem is called a "0-1" (or "discrete") problem, because each item must be entirely accepted or rejected.
- Just another version of this problem is the "Fractional Knapsack Problem", where we can take fractions of items.

The Knapsack Problem: Greedy Vs. Dynamic Programming



- ☐ The optimal solution to the fractional knapsack problem can be found with a greedy algorithm
 - oGreedy strategy: take in order of dollars/pound
- □ The optimal solution to the o-1 problem **cannot** be found with the same greedy strategy but by ad dynamic programming

Counter Example of greedy algorithm for

Consider the 0-1 knapsack problem. What is a good example, with 3 items and W=50, that shows that being greedy does not provide the optimum profit Take the ratio b/w and sort take the two highest (only these fit) is it the best you can do? Or can you choose another pair with higher b's?

- a. w=(10,20,30) and b=(40,100,150)
- b. w=(10,20,30) and b=(60,100,120)

The 0-1 Knapsack Problem And Optimal Substructure



- Consider the most valuable load with at most W pounds
 - If we remove item j from the load of the Knapsack, what do we know about the remaining load?
 - A: remainder must be the most valuable load weighing at most W w_i that was packed, excluding item j

0-1 Knapsack problem: brute-force approach



- Let's first solve this problem with a straightforward algorithm
- \square Since there are n items, there are 2^n possible combinations of items (possible subsets).
 - □ 1 BIT for each element: 1 take it or 0 don't take it.
- We go through all combinations and find the one with the most total value and with total weight less or equal to W
- \square Running time will be $O(2^n)$
- Is that fast?

0-1 Knapsack problem: subproblem



- Can we do better?
- Yes, with an algorithm based on dynamic programming
- We need to carefully identify the subproblems

Let's try this:

If items are labeled 1..n, then a subproblem would be to find an optimal solution for $S_k = \{items\ labeled\ 1,\ 2,\ ...\ k\}$

Defining a Subproblem



If items are labeled 1..n, then a subproblem would be to find an optimal solution for $S_k = \{items\ labeled\ 1, 2, ... k\}$

- This is a valid subproblem definition.
- The question is: can we describe the final solution (S_n) in terms of subproblems (S_k) ?
- Unfortunately, we <u>can't</u> do that. Explanation follows....

Defining a Subproblem

Max weight: W = 20

For S_{Δ} :

Total weight: 14;

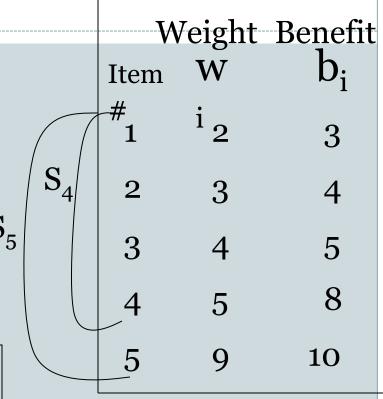
total benefit: 20

$W_1 = 2$	w ₂ =4	$w_3 = 5$	$W_4 = 9$
$b_1 = 3$	b ₂ =5	$b_3 = 8$	b ₄ =10

For S_5 :

Total weight: 20

total benefit: 26



Solution for S_4 is not part of the solution for $S_5!!!$

Defining a Subproblem (continued)

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- $lue{}$ As we have seen, the solution for S_4 is not part of the solution for S_5
- So our definition of a subproblem is flawed and we need another one!
- Let's add another parameter: w, which will represent the <u>exact</u> weight for each subset of items
- □ The subproblem then will be to compute B[k,w]

Recursive Formula for subproblems

■ Recursive formula for subproblems:

$$B[k, w] = \begin{cases} B[k-1, w] & \text{if } w_k > w \\ \max\{B[k-1, w], B[k-1, w-w_k] + b_k\} & \text{else} \end{cases}$$

- It means, that the best subset of S_k that has total weight w is one of the two:
- 1) the best subset of S_{k-1} that has total weight w, or
- 2) the best subset of S_{k-1} that has total weight w- w_k plus the item k

☐ Recursive Formula



$$B[k, w] = \begin{cases} B[k-1, w] & \text{if } w_k > w \\ \max\{B[k-1, w], B[k-1, w-w_k] + b_k\} & \text{else} \end{cases}$$

- \square The best subset of S_k that has the total weight w, either contains item k or not.
- First case: $w_k > w$. Item k can't be part of the solution, since if it was, the total weight would be > w, which is unacceptable
- Second case: $w_k <= w$. Then the item k can be in the solution, and we choose the case with greater value

0-1 Knapsack Algorithm (Exer 16.2-3)

for w = 0 to WB[o,w] = ofor i = 0 to nB[i,o] = ofor w = 0 to Wif $w_i \le w$ // item i can be part of the solution $if (b_i + B[i-1,w-w_i] > B[i-1,w])$ $B[i,w] = b_i + B[i-1,w-w_i]$ else B[i,w] = B[i-1,w]

else $B[i,w] = B[i-1,w] // w_i > w$

Running time

O(W)

for
$$w = 0$$
 to W

$$B[o,w] = o$$

for
$$i = 0$$
 to n

$$B[i,o] = o$$

for
$$w = 0$$
 to W

Repeat *n* times

< the rest of the code > What is the running time of this algorithm?

$$O(n*W)$$

Remember that the brute-force algorithm takes O(2ⁿ)

Knapsack Problem by DP (example)

Example: Knapsack of capacity W = 5

_		
item	weight	profit
1	2	\$12
2	1	\$10
3	3	\$20
4	2	\$15

capacity j

	O	U	U	U			
$v_1 = 2, v_1 = 12$			0				
$v_2 = 1, v_2 = 10$	2	0	10	12	22	22	22
$v_2 = 3, v_2 = 20$	3	0	10	12	22	30	32

Backtracing finds the actual optimal subset, i.e. solution.

 $w_4 = 2, v_4 = 15$ 4 0 10 15 25 30 37

Example Knapsack

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• Let B = [1, 4, 3] and W = [1, 3, 2] be the array of profits and weights the 3 items respectively. Total Weight of knapsack is 4

Longest Common Subsequence (LCS)

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• A subsequence of a sequence/string *S* is obtained by deleting zero or more symbols from *S*. For example, the following are some subsequences of "president": pred, sdn, predent. In other words, the letters of a subsequence of *S* appear in order in *S*, but they are not required to be consecutive.

 The longest common subsequence problem is to find a maximum length common subsequence between two sequences.

LCS

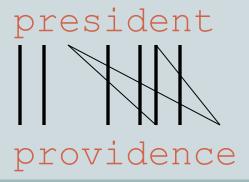


For instance,

Sequence 1: president

Sequence 2: providence

Its LCS is priden.



LCS

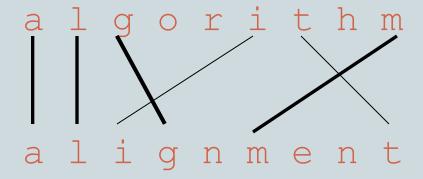


Another example:

Sequence 1: algorithm

Sequence 2: alignment

One of its LCS is algm.



How to compute LCS?

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- Let $A = a_1 a_2 ... a_m$ and $B = b_1 b_2 ... b_n$.
- len(i, j): the length of an LCS between $a_1a_2...a_i$ and $b_1b_2...b_j$
- With proper initializations, len(i, j) can be computed as follows.

$$len(i, j) = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0, \\ len(i-1, j-1) + 1 & \text{if } i, j > 0 \text{ and } a_i = b_j, \\ \max(len(i, j-1), len(i-1, j)) & \text{if } i, j > 0 \text{ and } a_i \neq b_j. \end{cases}$$

procedure LCS-Length(A, B)

- 1. **for** $i \leftarrow 0$ **to** m **do** len(i, 0) = 0
- 2. **for** $j \leftarrow 1$ **to** n **do** len(0,j) = 0
- 3. for $i \leftarrow 1$ to m do
- 4. **for** $j \leftarrow 1$ **to** n **do**

6. else if $len(i-1, j) \ge len(i, j-1)$

9. **return** *len* and *prev*

i		j ()	1		2	3	4	4	5	Ć	5	7		8		9	1	10
				p		r	0	١	V	i	C	l	e		n		\mathcal{C}		e
0			0	0		0	0	()	0	()	0		0		0		0
1	p		0	\ 1	•	← 1	← 1	← 1	1	← 1	← j	1	← 1	lacksquare	1	←	1	lacksquare	1
2	r		0	1		2	4 2	← 2	2	← 2	← 2	2	← 2	lack	- 2	←	2	lacksquare	2
3	e		0	1		2	2	† 2	2	2	1 2	2	3	lacksquare	3	•	3	X	3
4	S		0	1		2	2	† 2	2	2	1 2	2	3		3	1	3	^ :	3
5	i		0	1	4	2	1 2	1 2	2	3	← 3	3	1 3		3	lack	3		3
6	d		0	1		2	1 2	1 2	2	3		1	← 4	lacksquare	4	←	4	lacksquare	4
7	e		0	1	4	2	1 2	2	2	3	<u> </u>	1	5	lacksquare	5	←	5	K	5
8	n		0	1		2	1 2	2	2	3		1	5		6	•	6	•	6
9	t		0	1		2	2	1 2	2	3	1 4	1	5		6	^	6		6

```
procedure Output-LCS(A, prev, i, j)
```

- *I* if i = 0 or j = 0 then return
- 2 **if** prev(i, j) =" **then** $\begin{bmatrix} Output LCS(A, prev, i-1, j-1) \\ print & a_i \end{bmatrix}$
- 3 else if prev(i, j) =" $\stackrel{\wedge}{\uparrow}$ " then Output-LCS(A, prev, i-1, j)
- 4 **else** Output-LCS(A, prev, i, j-1)

i		j (0	Î	7	2	3		4	5	5	6	,	7	8		9	د	10
				ľ	2	r	0		ν	i	į	d	(2	n		\mathcal{C}		e
0			0	()	0	0		0	0)	0	()	0		0		0
1	p		0	X 1	1	← 1	← 1	\	1	← 1	•	← 1	←	1	← 1	←	1	lacksquare	1
2	r		0	1	L	2	← 2	←	2	4 2	2	← 2	← 2	2	← 2	←	2	+	2
3	e		0	1	l	\uparrow 2	2		2	2	2	2	X 3	3	← 3	•	3	K	3
4	S		0	1	l	$\frac{1}{2}$	2		2	\uparrow 2	2	2	1 3	3	3		3	1	3
5	i		0	<u>1</u>	l	1 2	<u>2</u>	<u></u>	2	3	}	⊢ 3	1 3	3	1 3	1	3	lacktriangle	3
6	d		0	<u> </u>	l	1 2	1 2	1	2	3	×	4	← ∠	4	← 4	←	4	lacksquare	4
7	e		0	<u>†</u> 1	<u> </u>	1 2	1 2	<u> </u>	2	3		4		5	← 5	—	5	K	5
8	n		0	1	ĺ	2	1 2		2	3		4	<u> </u>	5	6	•	6	•	6
9	t		0	1	1	2	2		2	3	3	4	1 :	5	6		6		6

Output: priden

In class activity

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16.1-4

Suppose that we have a set of activities (lectures) to schedule among a large number of lecture halls, where any activity can take place in any lecture hall. We wish to schedule all the activities using as few lecture halls as possible (minimization problem).

Give an efficient greedy algorithm to determine which activity should use which lecture hall. (This problem is also known as the *interval-graph coloring problem*).

We can create an interval graph whose vertices are the given activities and whose edges connect incompatible activities. Draw an example...

The smallest number of colors required to color every vertex so that no two adjacent vertices have the same color corresponds to finding the fewest lecture halls needed to schedule all of the given activities.)

1st attempt



- Use repeated calls to the solution of activity selection algorithm
 - Find a maximum-size set S1 of compatible activities from S for the first lecture hall starting from the beginning,
 - o then using it again to find a maximum-size set S2 of compatible activities from S -S1 for the second hall,
 - o (and so on until all the activities are assigned), requires $\Theta(n^2)$ time in the worst case.
- Is that the optimal (=min #halls)?
- Counterexample: Consider activities with the intervals (1, 4), (2, 5), (6, 7), (4, 8).
 - o 1st hall choose the activities (1, 4) and (6, 7) for the first lecture hall, and then each of the activities with intervals
 - Each of (2, 5) and (4, 8) would have to go each into its own hall, for a total of three halls used.
- But optimal solution would put activities (1, 4) and (4, 8) into one hall and the activities with intervals (2, 5) and (6, 7) into another hall, for only two halls used.

2nd attempt



There is a correct algorithm, however, whose asymptotic time is just the time needed to sort the activities by time

- O(n lg n) time for arbitrary times, or
- possibly as fast as O(n) if the times are small integers.

The general idea is to go through the activities in order of start time, assigning each to any hall that is available at that time. To do this, move through the set of events consisting of activities starting and activities finishing, in order of event time.

Maintain two lists of lecture halls:

- 1. Halls that are busy at the current event time t (because they have been assigned an activity i that started at s_i <t but won't finish until f_i > t) and
- 2. halls that are free at time t.

How many halls in a optimal solution?

Continue solution



- Sort the 2n activity-starts/activity-ends events. (In the sorted order, an activity ending event should precede an activity-starting event that is at the same hall.)
 - o O(n lg n) time for arbitrary times, possibly O(n) if the times are restricted (e.g., to small range).
- Process the events in O(n) time: Scan the 2n events, doing O(1) work for each (moving a hall from one list to the other and possibly associating an activity with it).
- Total: O(n + time to sort)