

How do we learn about the value of others' advice



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Introduction

Leong & Zaki (2017)

Journal of Experimental Psychology: General

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Unrealistic Optimism in Advice Taking: A Computational Account

Yuan Chang Leong and Jamil Zaki
Stanford University

Expert advisors often make surprisingly inaccurate predictions about the future, yet people heed their suggestions nonetheless. Here we provide a novel, computational account of this unrealistic optimism in advice taking. Across 3 studies, participants observed as advisors predicted the performance of a stock. Advisors varied in their accuracy, performing reliably above, at, or below chance. Despite repeated feedback, participants exhibited inflated perceptions of advisors' accuracy, and reliably "bet" on advisors' predictions more than their performance warranted. Participants' decisions tightly tracked a computational model that makes 2 assumptions: (a) people hold optimistic initial expectations about advisors, and (b) people preferentially incorporate information that adheres to their expectations when learning about advisors. Consistent with model predictions, explicitly manipulating participants' initial expectations altered their optimism bias and subsequent advice-taking. With well-calibrated initial expectations, participants no longer exhibited an optimism bias. We then explored crowdsourced ratings as a strategy to curb unrealistic optimism in advisors. Star ratings for each advisor were collected from an initial group of participants, which were then shown to a second group of participants. Instead of calibrating expectations, these ratings propagated and exaggerated the unrealistic optimism. Our results provide a computational account of the cognitive processes underlying inflated perceptions of expertise, and explore the boundary conditions under which they occur. We discuss the adaptive value of this optimism bias.

Introduction

Task design

- Participant's Choice – Advisor's Prediction – Outcome



- How people learn to trust or not to trust the advisor?

Introduction

Original models (MAP method)

- Confirmation Bias model 
- Win-Stay-Lose-Switch model
- Bayesian updating model 
- Reinforcement model

- Each trial certain value is updated in Bayesian fashion.
- Each trial it calculates posterior distribution by grid approximation

Which means we need to put grid approximation in Stan code!



Introduction

Original models (MAP method)

- Confirmation Bias model



- Win-Stay-Lose-Switch model



- Bayesian updating model



- Reinforcement model



Methods

WSLS model

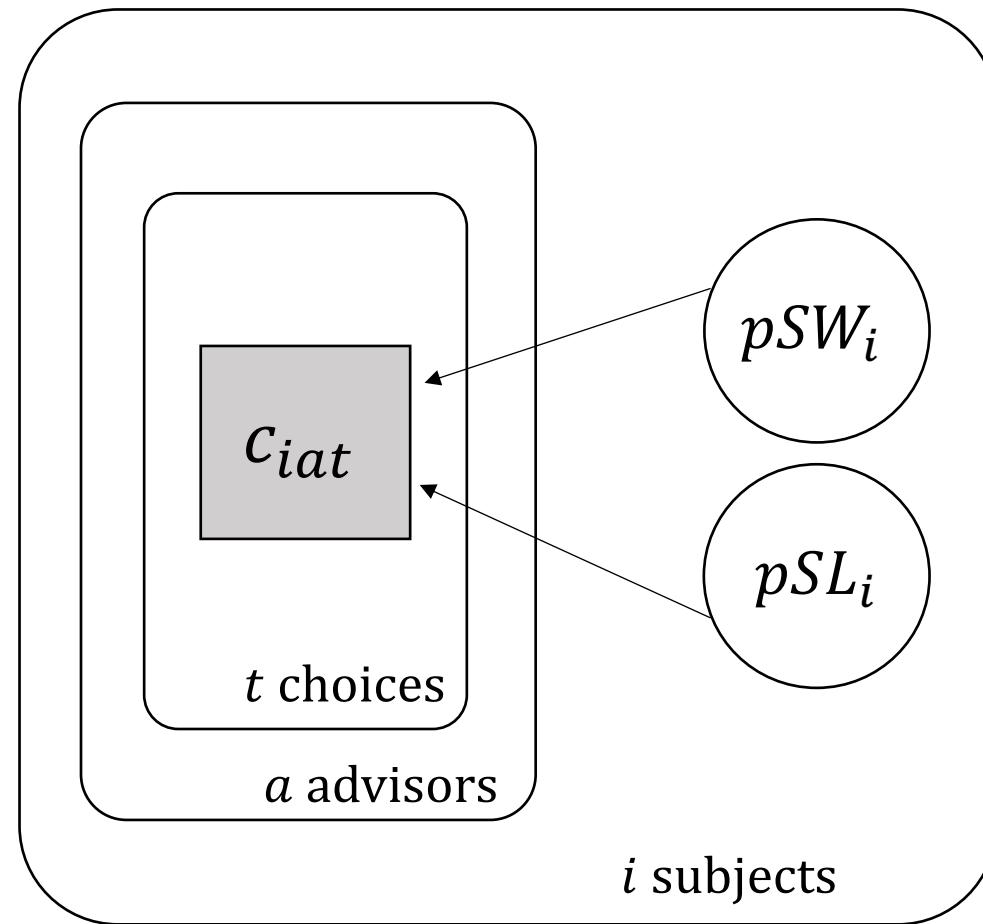
- Propensity to stay after win and shift after lose.
- Two parameters, each represents strength of these propensities.

$$P(stay|win)$$

$$P(shift|loss)$$

Methods

WSLS model



Methods

Reinforcement Learning model

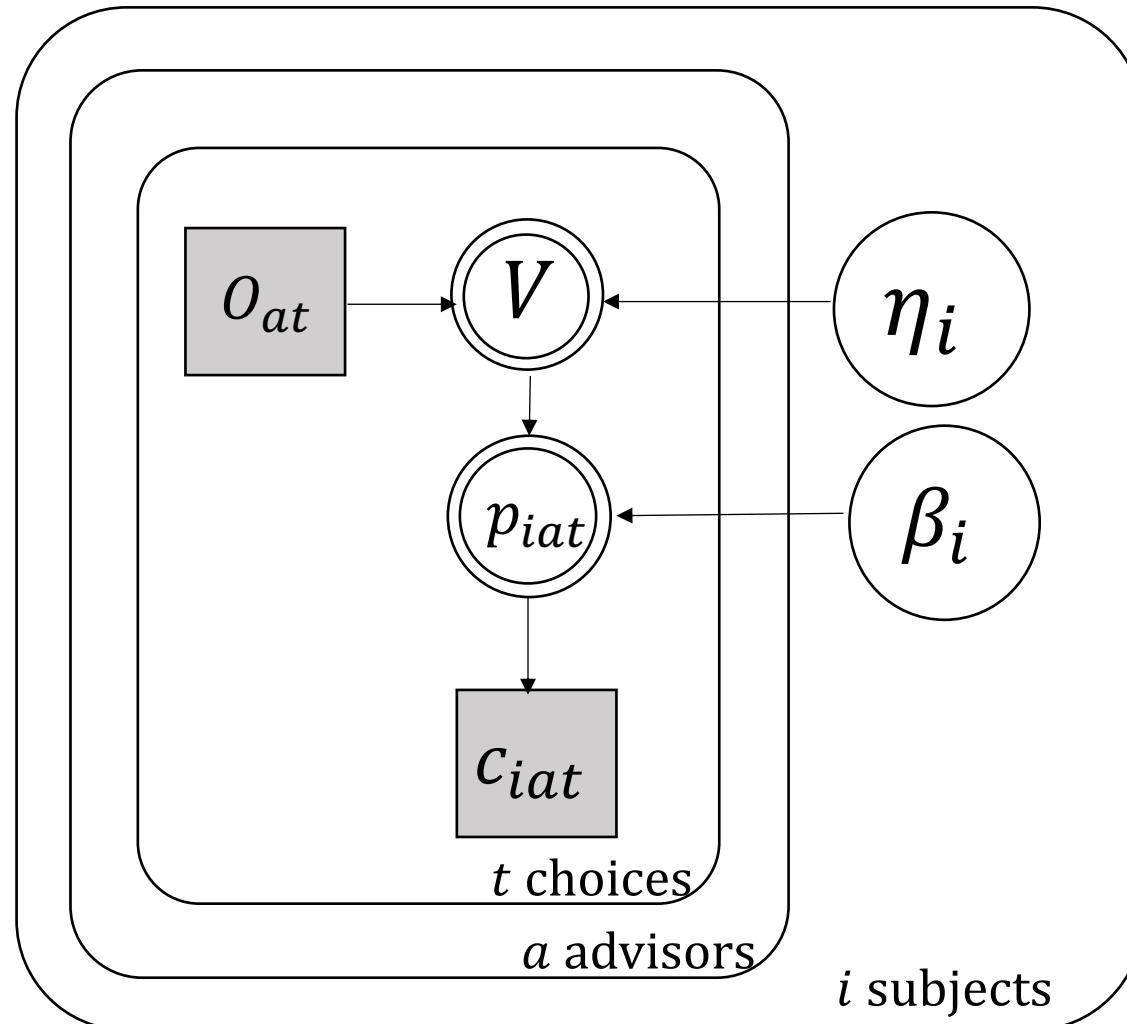
- Update the value of each advisor with prediction error
- Higher the value, higher the chance to trust the advisor

$$\delta_t = R_t - E(V_t)$$

$$E(V_{t+1}) = E(V_t) + \eta \delta_t$$

Methods

Reinforcement Learning model



Methods

Proposal for better models

A Comparison Model of Reinforcement-Learning and Win-Stay-Lose-Shift Decision-Making Processes: A Tribute to W.K. Estes

Darrell A. Worthy¹ and W. Todd Maddox²

¹Texas A&M University

²The University of Texas at Austin

Abstract

W.K. Estes often championed an approach to model development whereby an existing model was augmented by the addition of one or more free parameters, and a comparison between the simple and more complex, augmented model determined whether the additions were justified. Following this same approach we utilized Estes' (1950) own augmented learning equations to improve the fit and plausibility of a win-stay-lose-shift (WSLS) model that we have used in much of our recent work. Estes also championed models that assumed a comparison between multiple concurrent cognitive processes. In line with this, we develop a WSLS-Reinforcement Learning (RL) model that assumes that the output of a WSLS process that provides a probability of staying or switching to a different option based on the last two decision outcomes is compared with the output of an RL process that determines a probability of selecting each option based on a comparison of the expected value of each option. Fits to data from three different decision-making experiments suggest that the augmentations to the WSLS and RL models lead to a better account of decision-making behavior. Our results also support the assertion that human participants weigh the output of WSLS and RL processes during decision-making.



- WSL S learning model
- Transition RL model
 - version 1 / 2
- WSL S-RL model
 - version 1 / 2

Methods

WSLS learning model

- Updating the strength of propensity, trial by trial
 - Successive WIN increases pSW
 - Successive LOSS increases pSL
- Trend of the outcome, not the value itself!

$$P(stay|win)_{t+1} = P(stay|win)_t + \theta_{P(stay|win)} (1 - P(stay|win)_t)$$

$$P(shift|loss)_{t+1} = (1 - \theta_{P(lose|shift)}) P(shift|loss)_t \quad (8)$$

$$P(shift|loss)_{t+1} = P(shift|loss)_t + \theta_{P(lose|shift)} (1 - P(shift|loss)_t)$$

$$P(stay|win)_{t+1} = (1 - \theta_{P(stay|win)}) P(stay|win)_t \quad (10)$$

Methods

Transition RL model

- Learn the value of transition (Stay or Shift)
- Version 1 : EV is updated separately on Win / Loss trial
- Version 2 : EV is updated without distinction of Win/ Loss

$$EV_{i,t+1} = EV_{i,t} + \alpha \cdot [r(t) - EV_{i,t}]$$

$$P(a_t) = \frac{e^{[\gamma \cdot EV_{a,t}]}}{\sum_{j=1}^n e^{[\gamma \cdot EV_{j,t}]}}$$

Methods

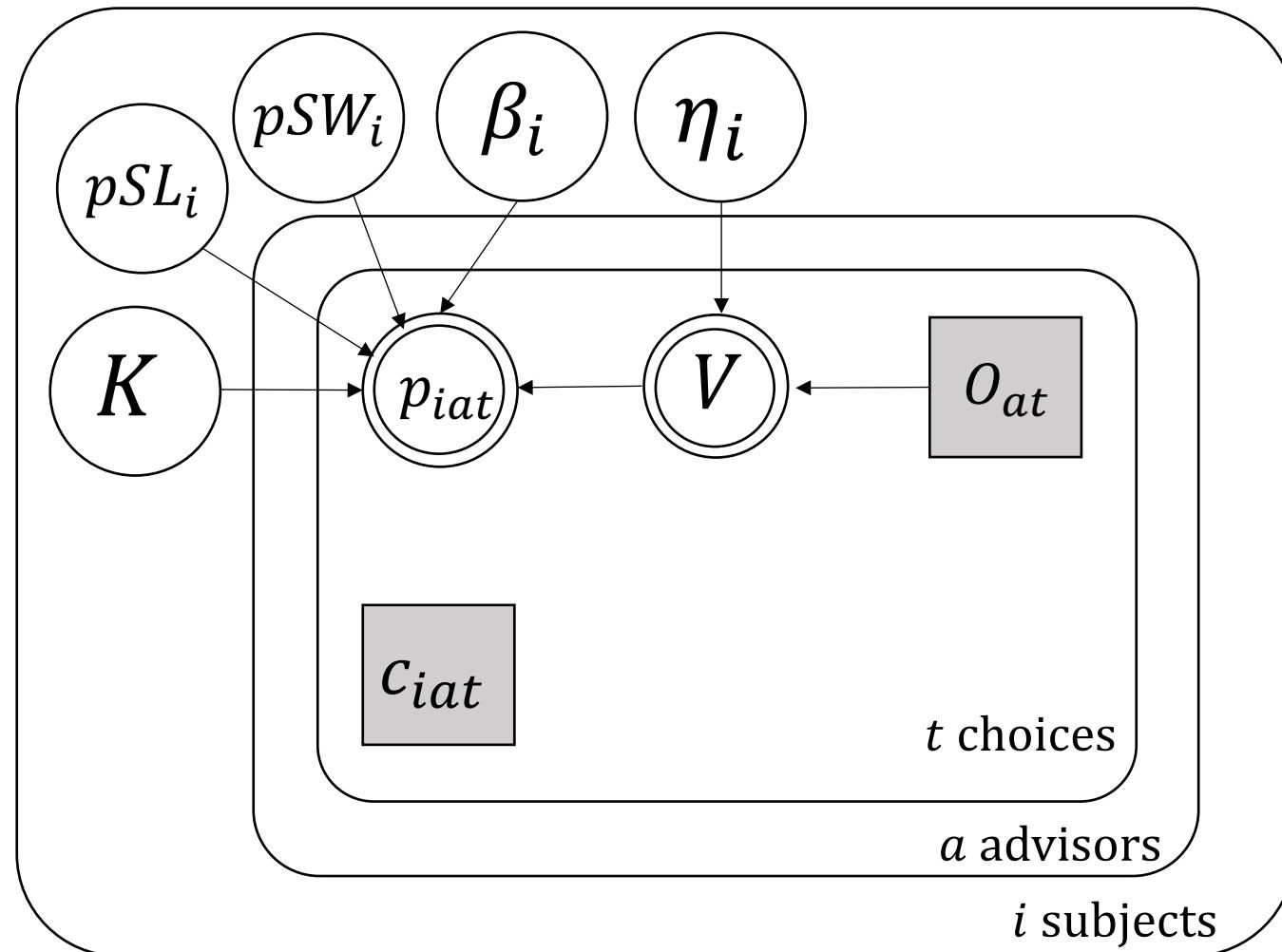
WSLS-RL hybrid model

- WSLs + Reinforcement learning
- Version 1 : WSLS learning + Reinforcement learning
- Version 2 : WSLS (classic) + Reinforcement learning
- People consider both the trend of the outcome and the value of the advisor

$$P(a_t) = P(a_t)_{WSLS_{Learning}} \cdot W_{WSLS_{Learning}} + P(a_t)_{RL} \cdot (1 - W_{WSLS_{Learning}})$$

Methods

WSLS-RL hybrid model (ver 2.)



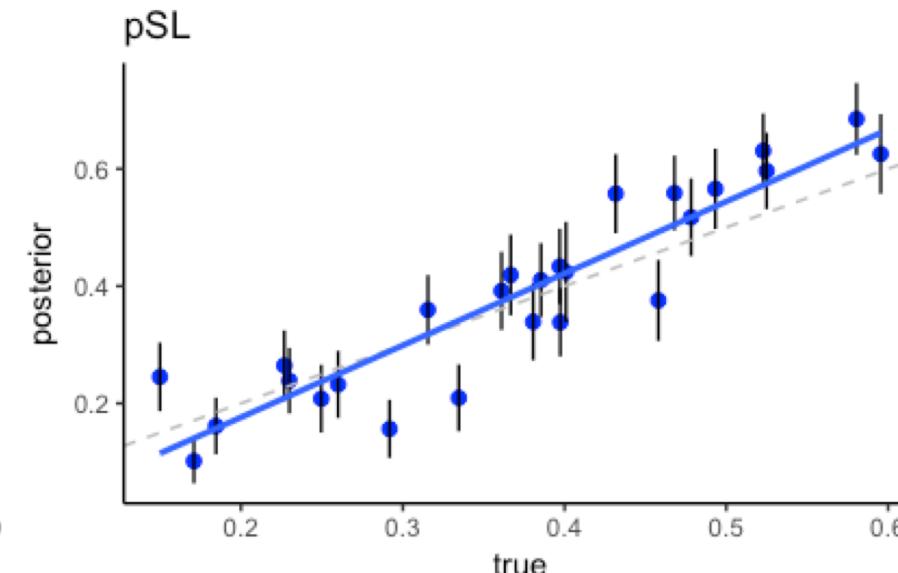
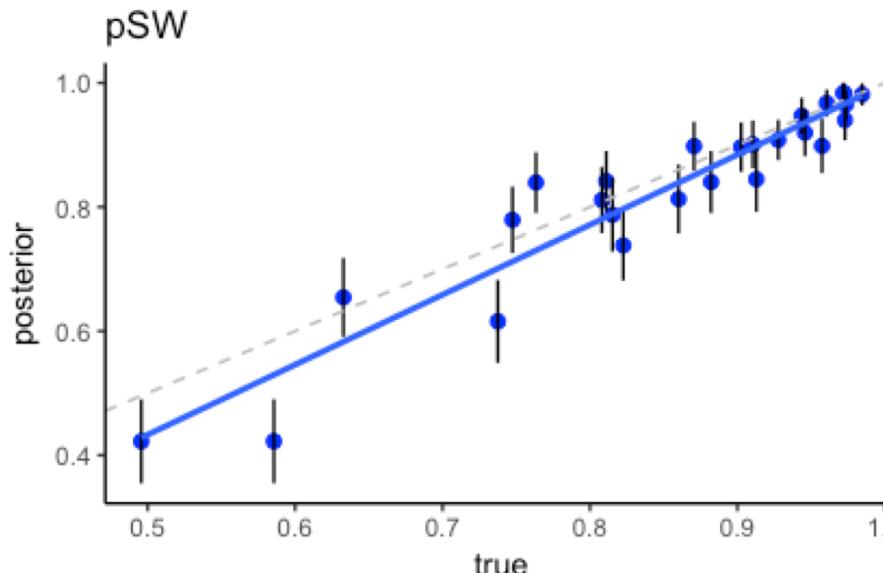
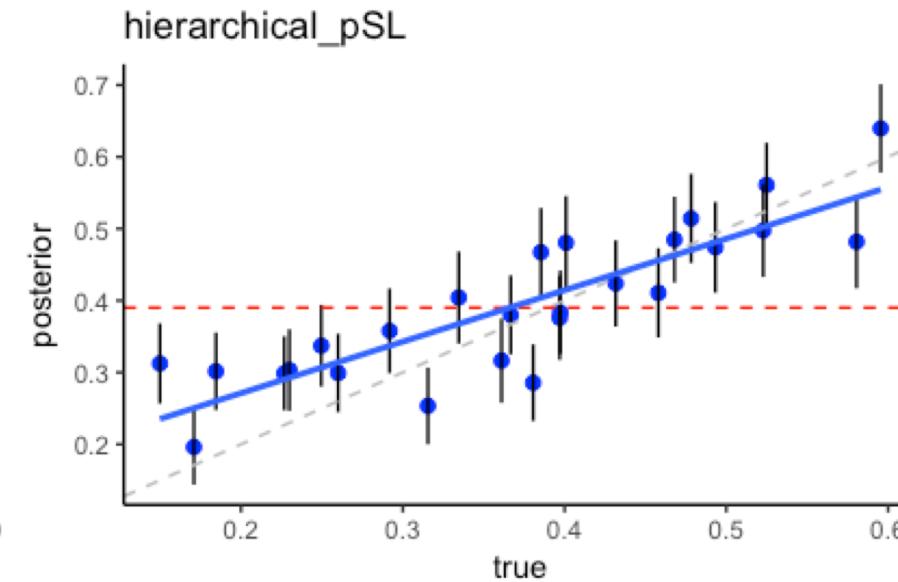
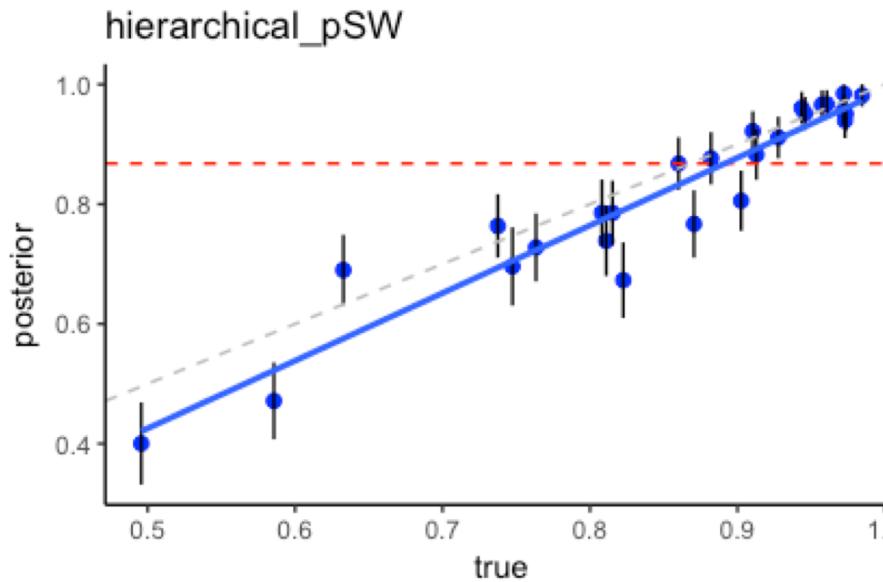
Results

Model Comparison

	LOOIC (full individual)	LOOIC (hierarchy)	
WSLS model	2644.4	2638.8	●
Reinforcement Learning model	2755.8	2697.8	●
WSLS learning model	2812.4	2662.3	●
WSLS transition model v1.	3305.6	3178.4	
WSLS transition model v2.	3309.1	3242.8	
WSLS-RL (hybrid) model	4260.5	3398.0	
WSLS-RL(Classic) model	2543.5	2450.6	●

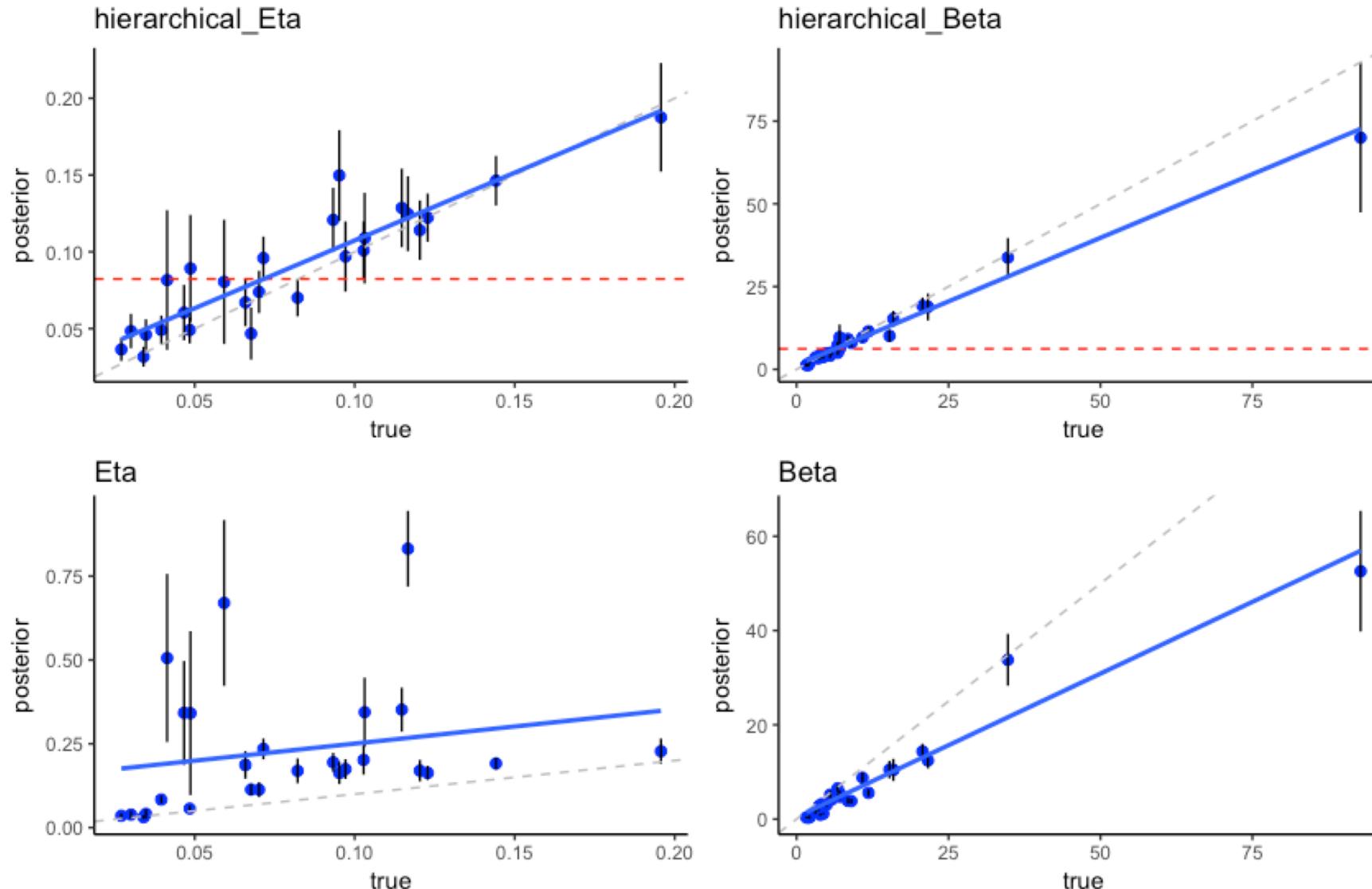
Results

WSLS_classic model : parameter recovery



Results

RL_classic model : parameter recovery

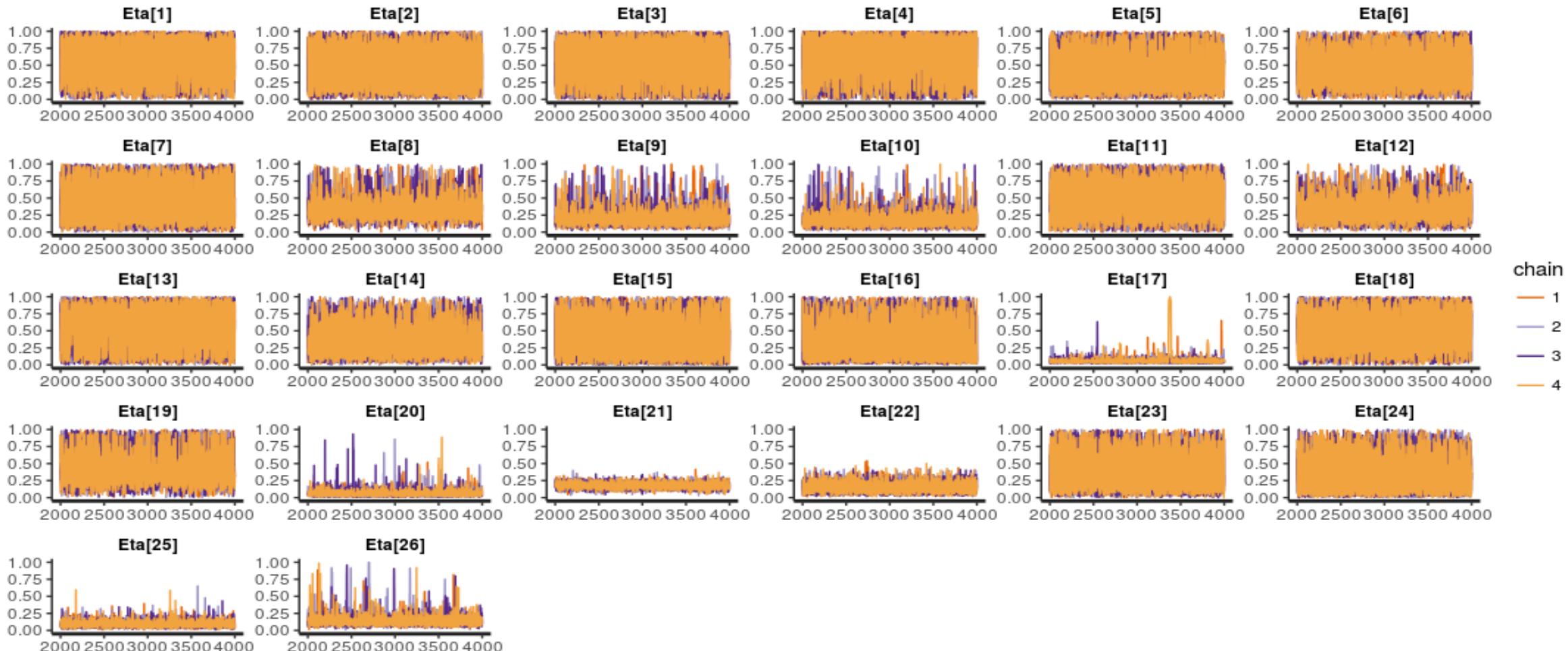


Results

Full Individual model

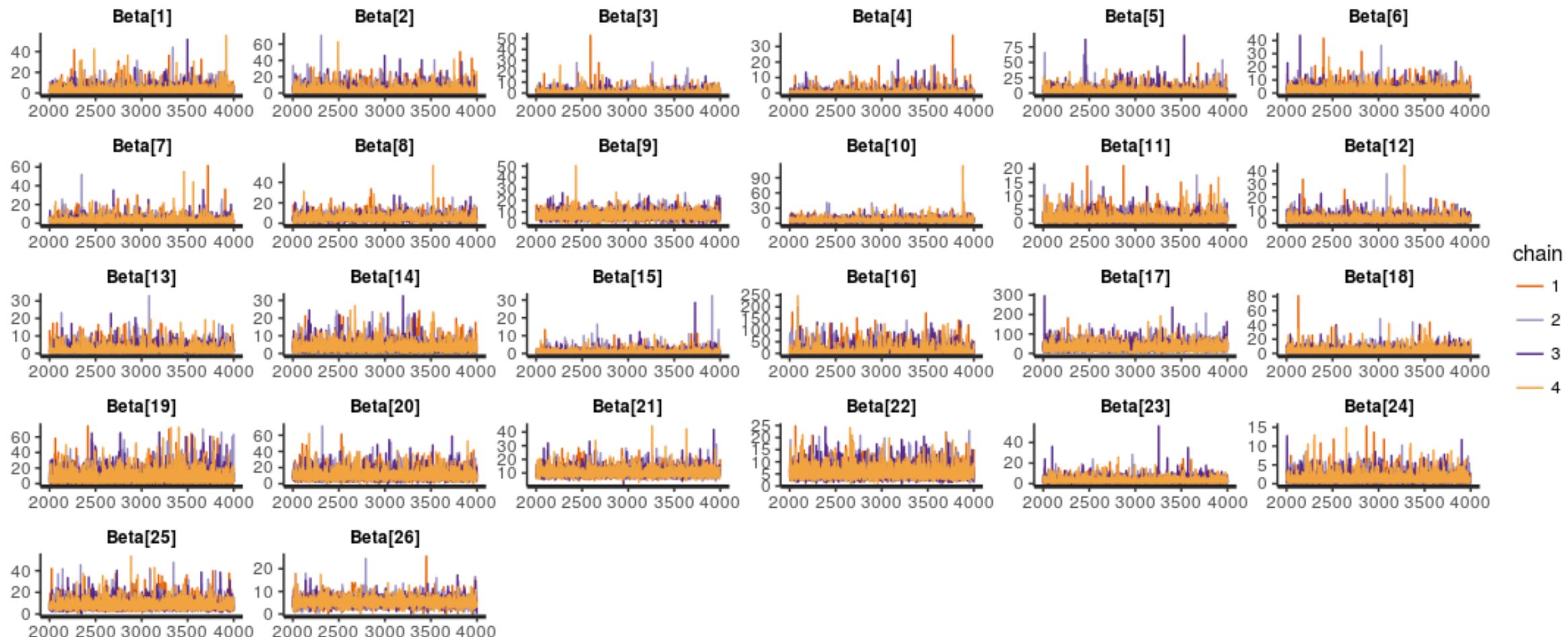
Results

Classic hybrid WSLS-RL model



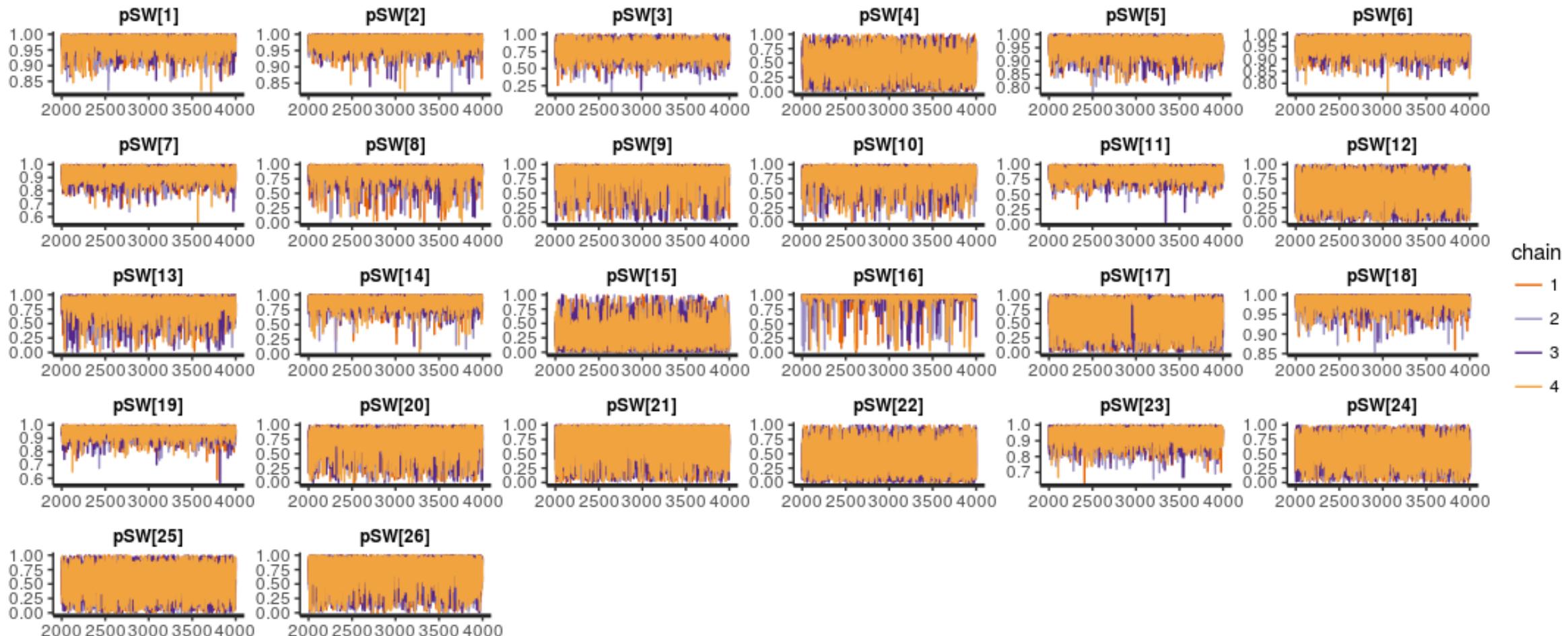
Results

Classic hybrid WSLS-RL model



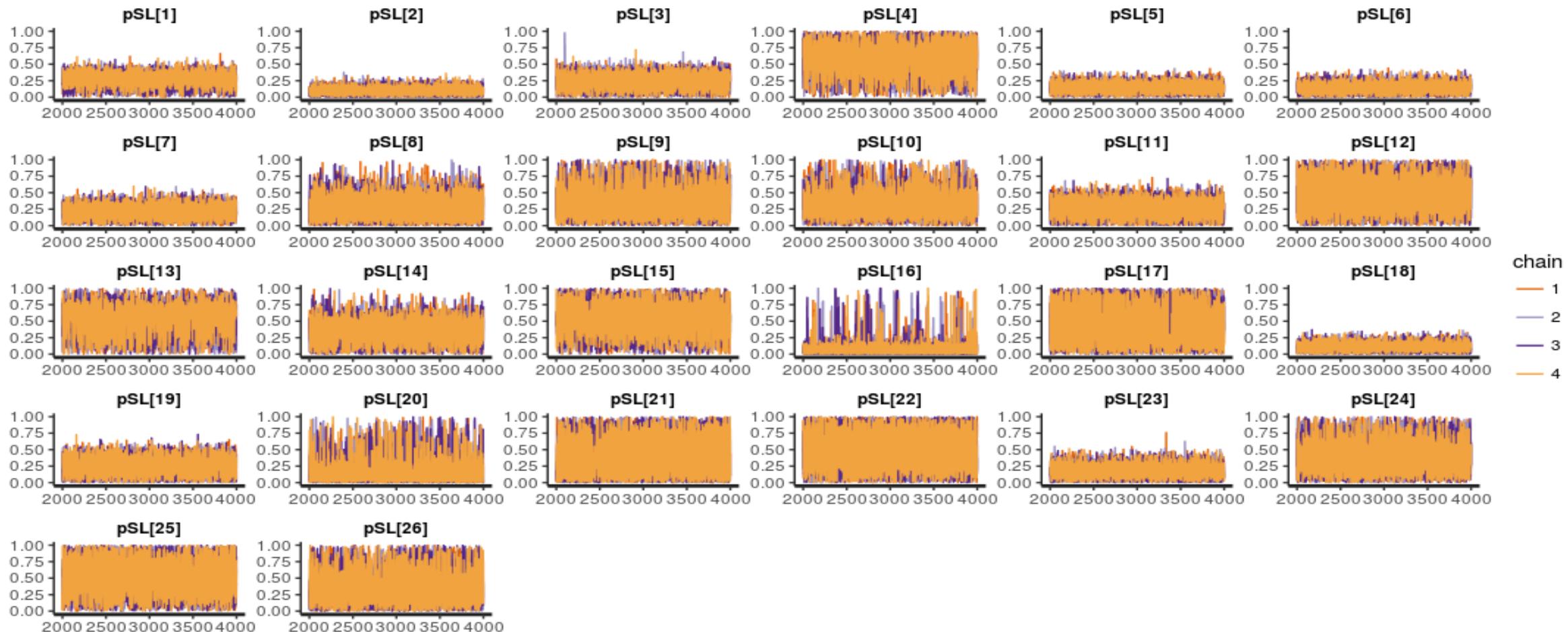
Results

Classic hybrid WSLS-RL model



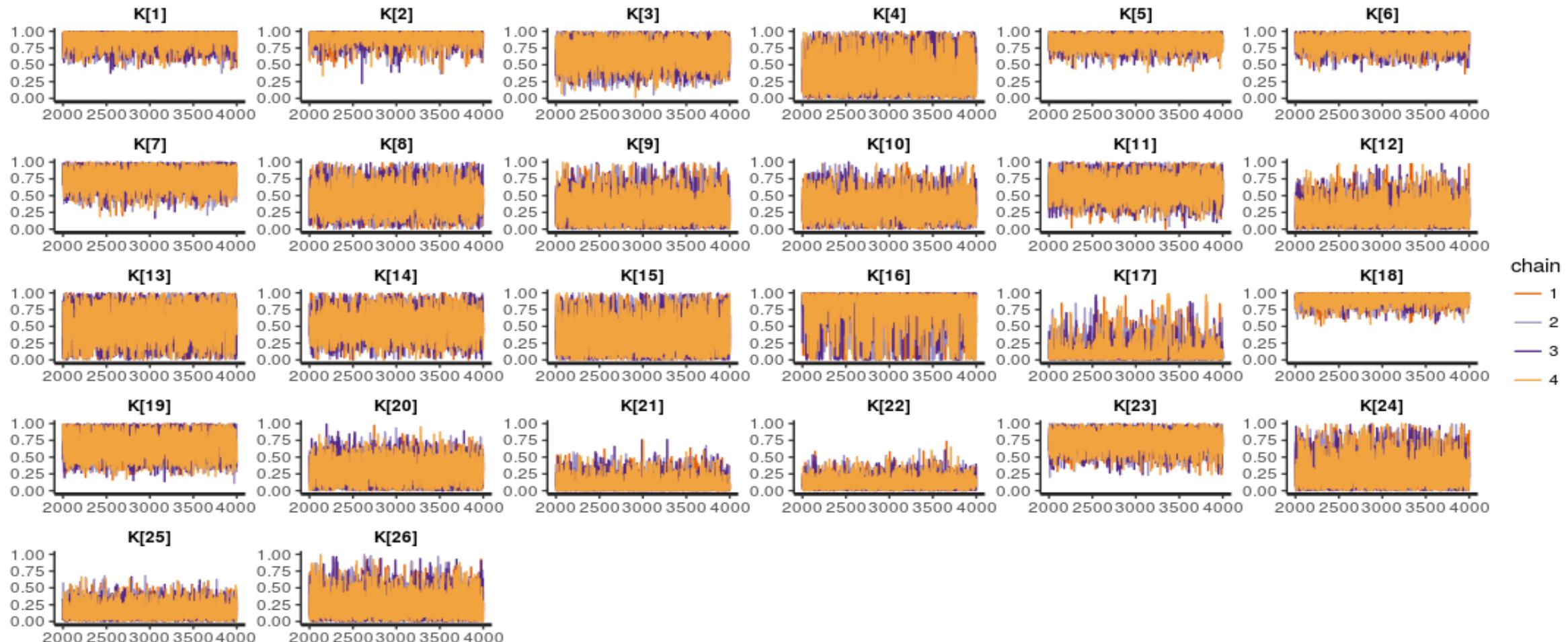
Results

Classic hybrid WSLS-RL model



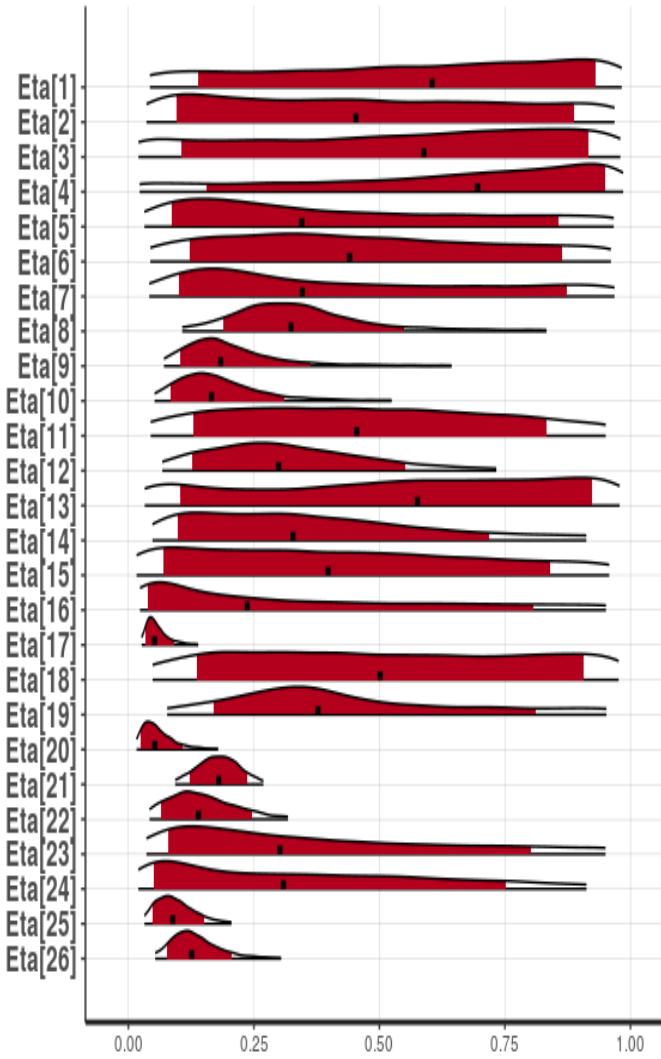
Results

Classic hybrid WSLS-RL model

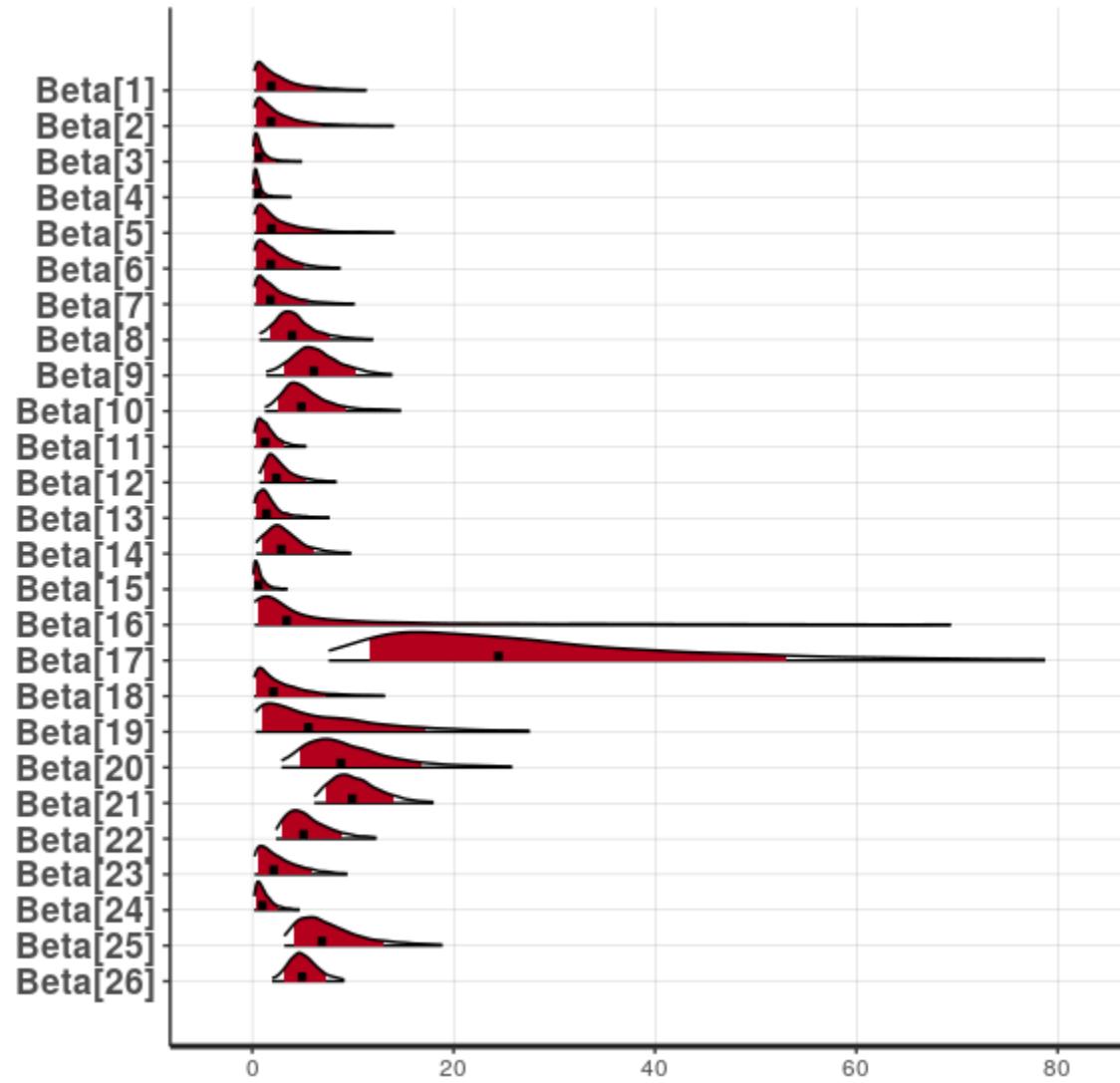


Results

Eta

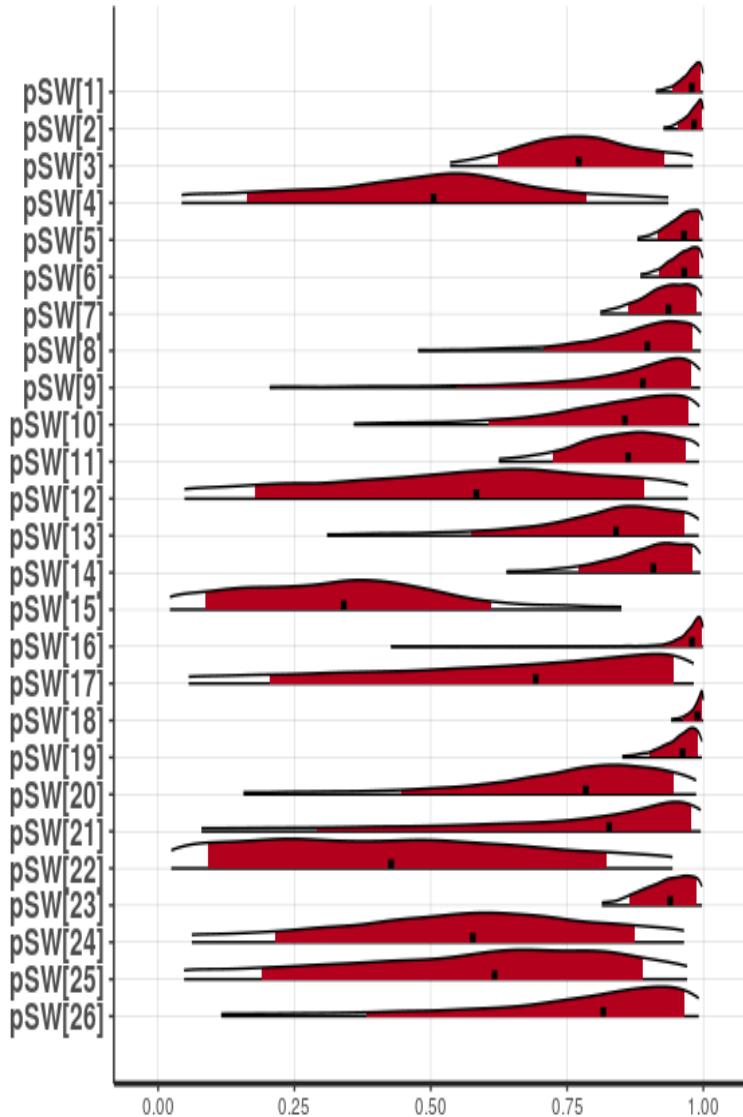


Beta

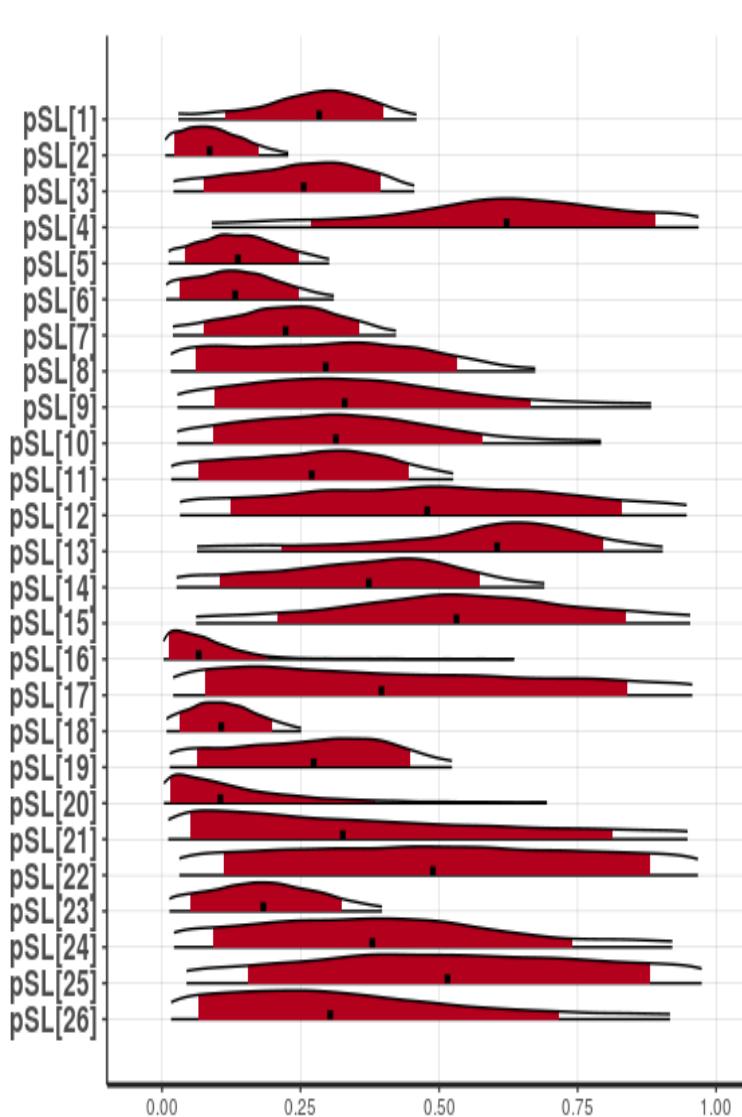


Results

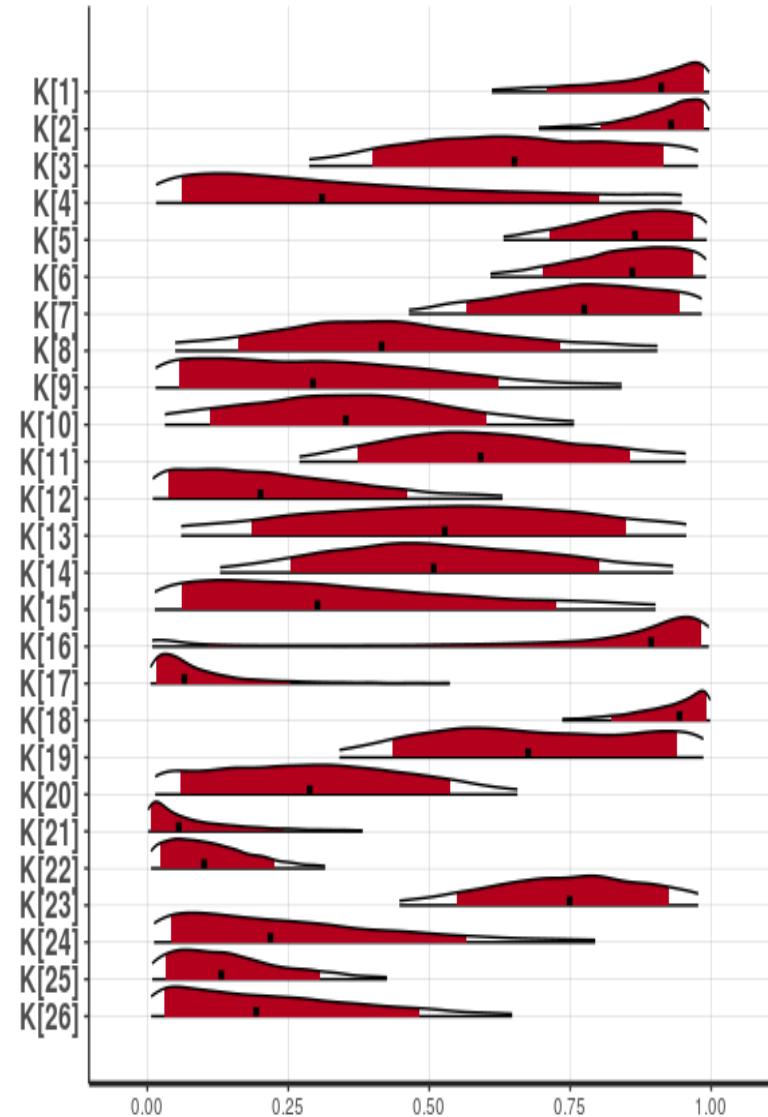
pSW



pSL



K

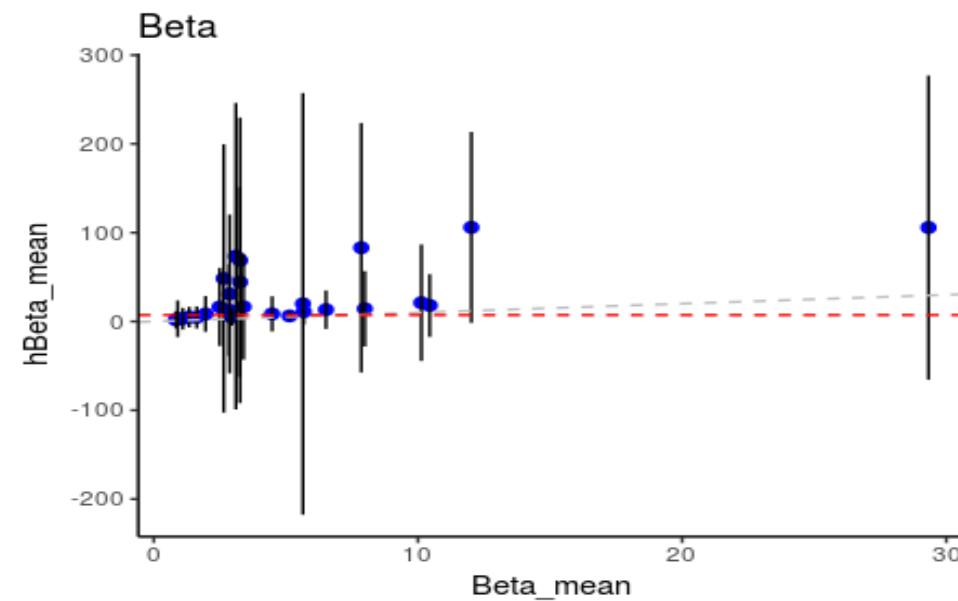
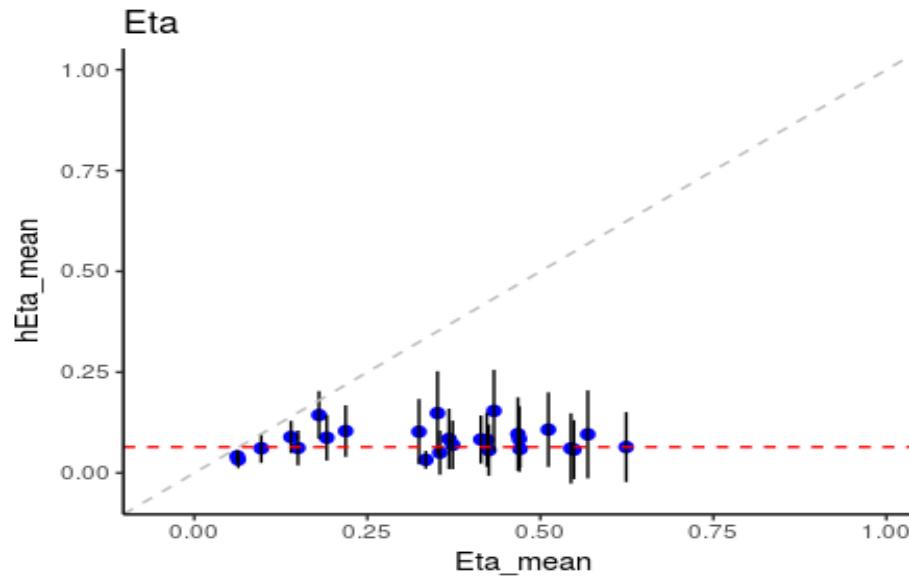


Results

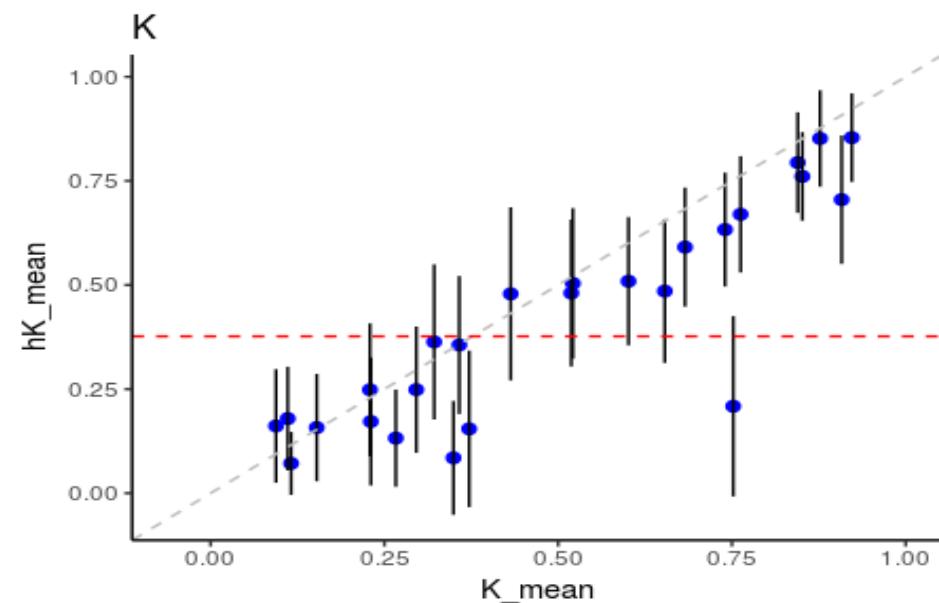
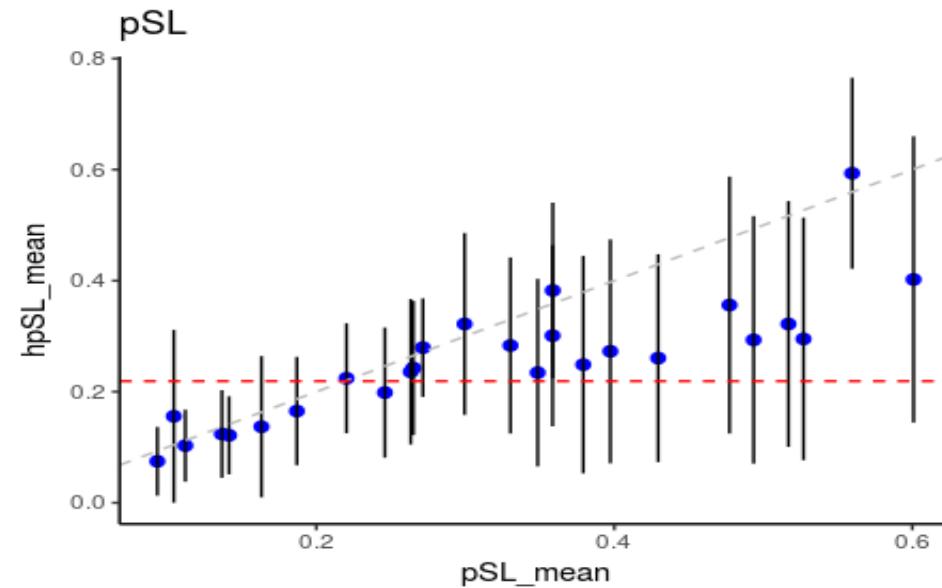
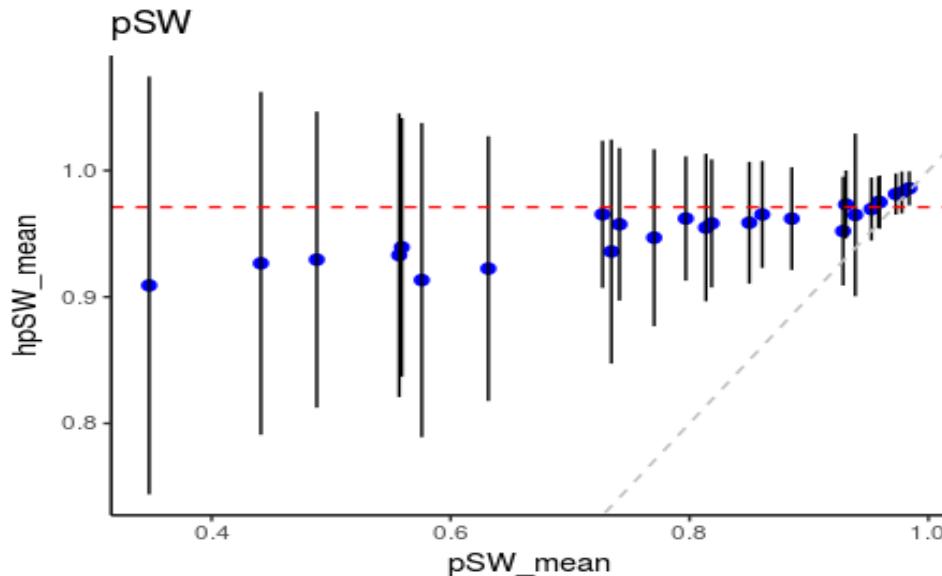
Hierarchical model

Results

WSLS_classic + RL model : Hierarchy - Nonhierarchy plot

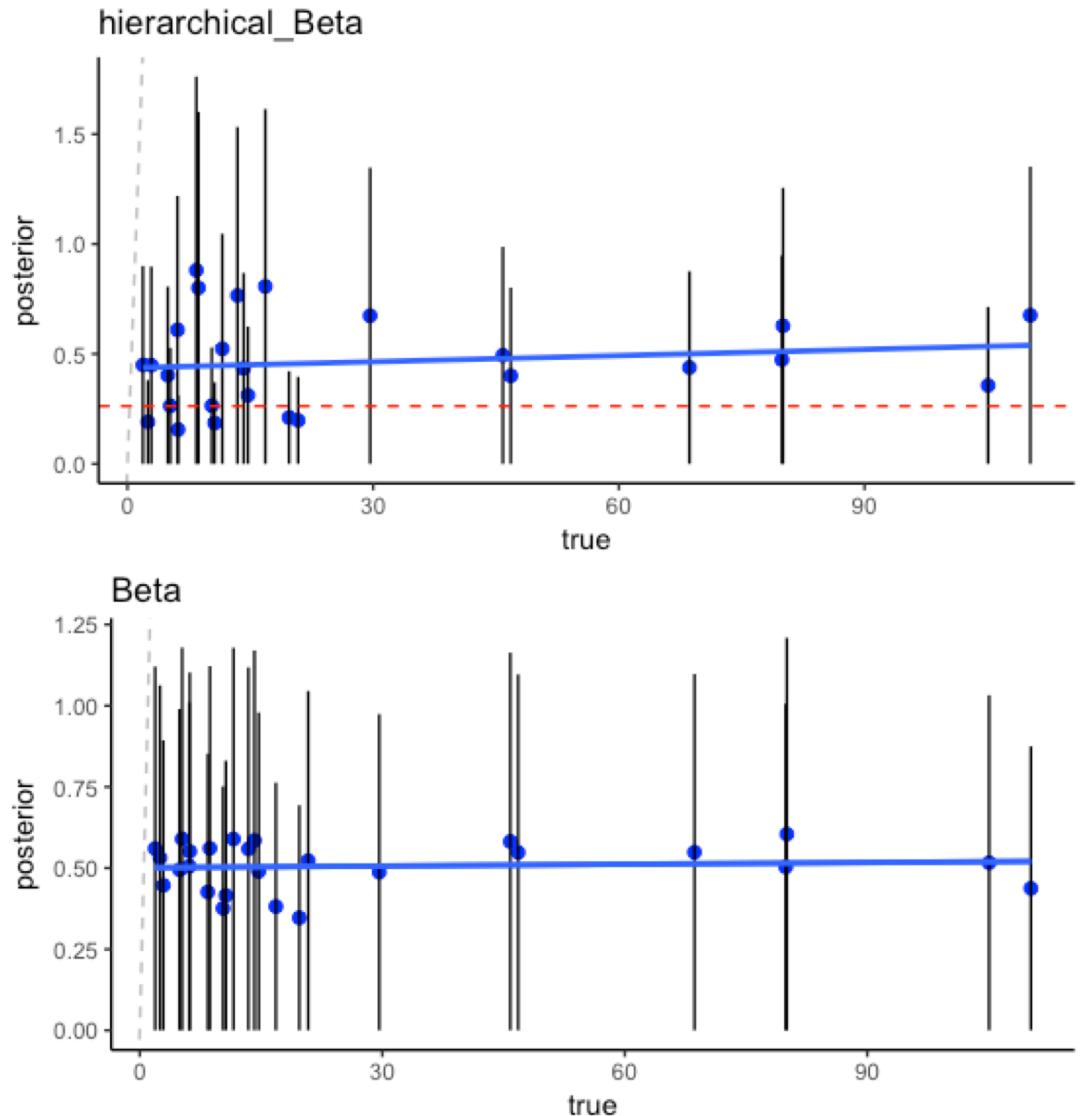
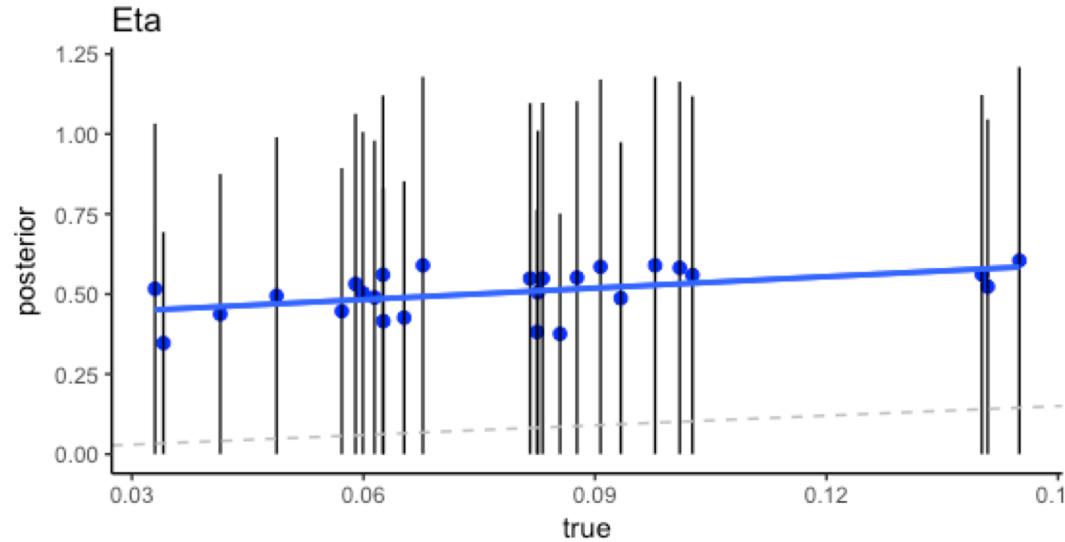
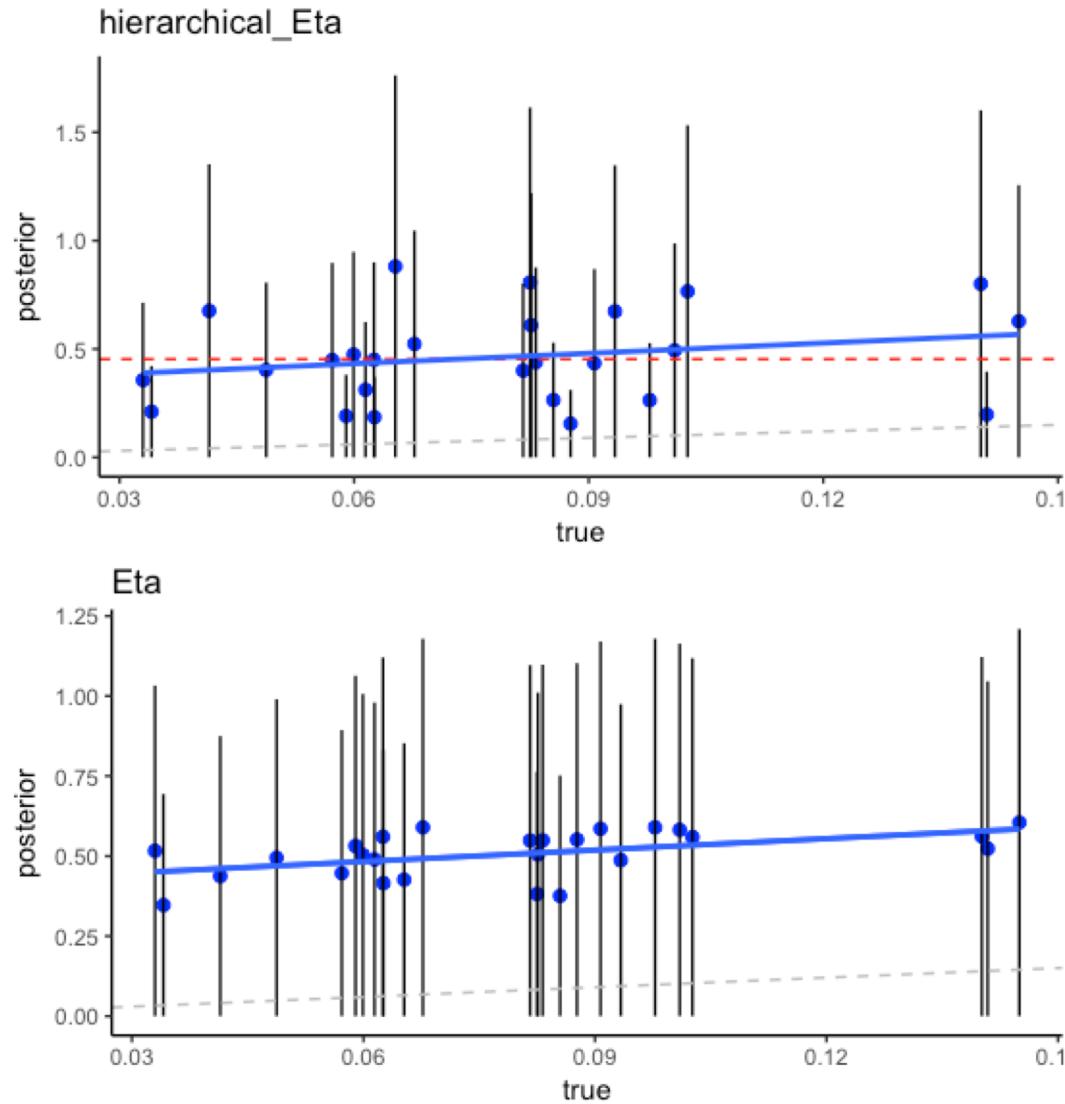


Results



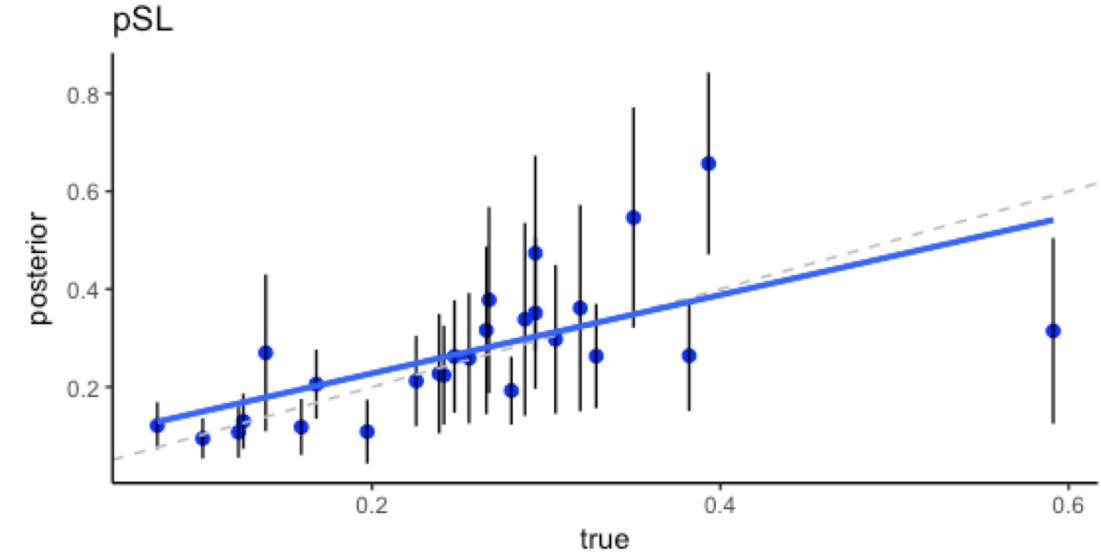
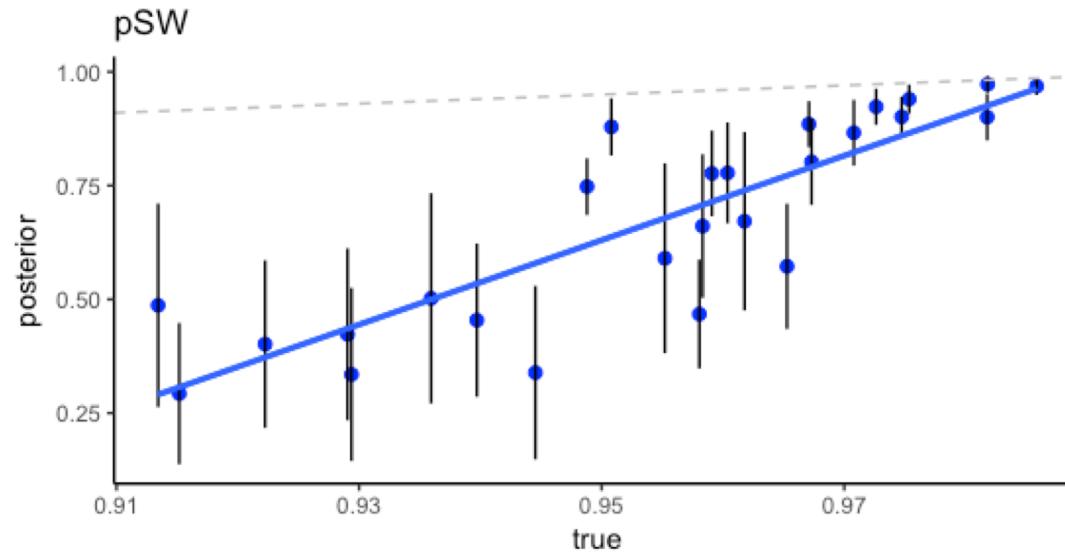
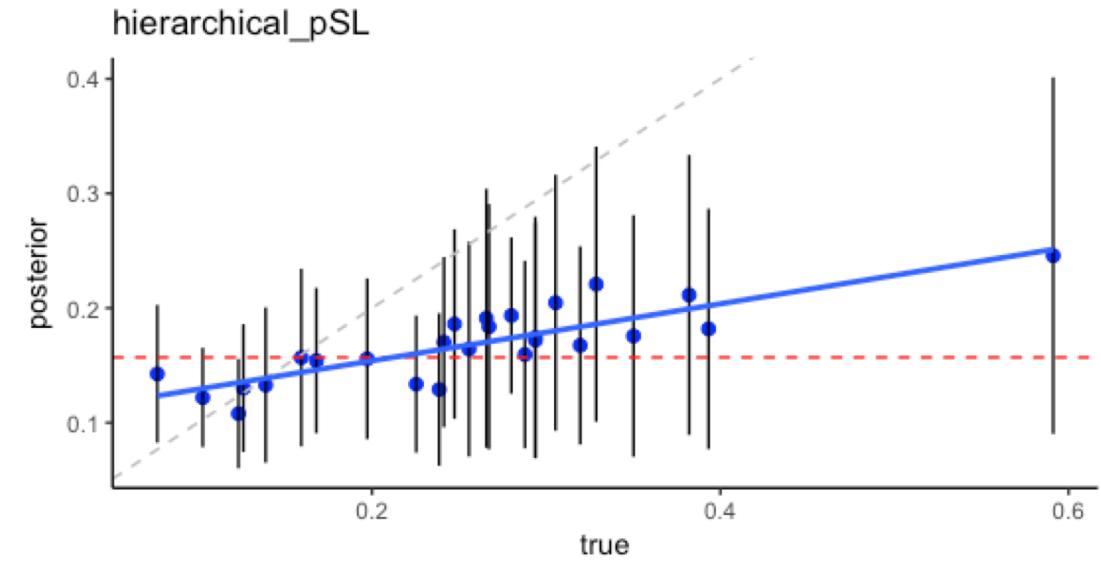
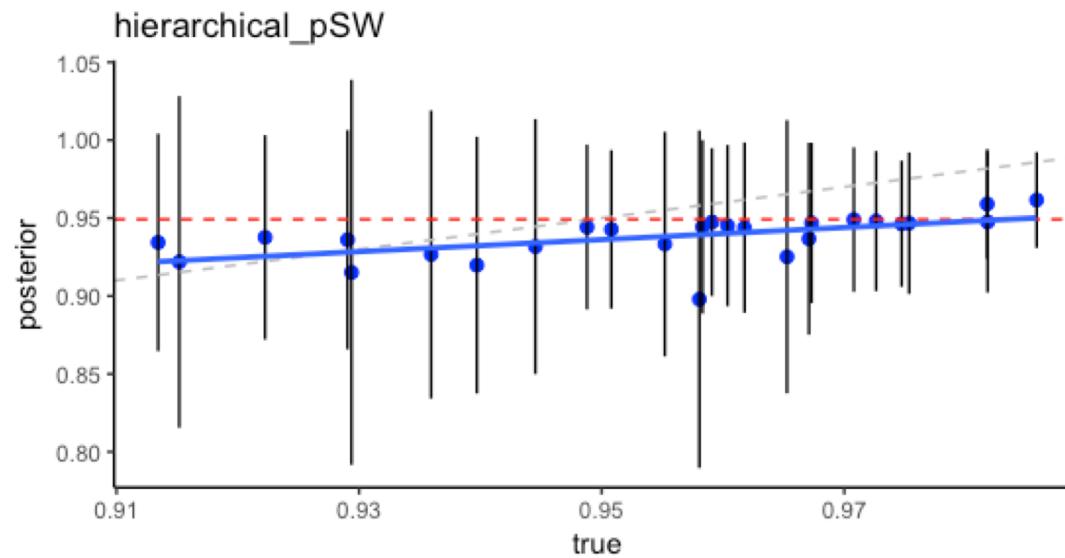
Results

WSLS_classic + RL model : parameter recovery



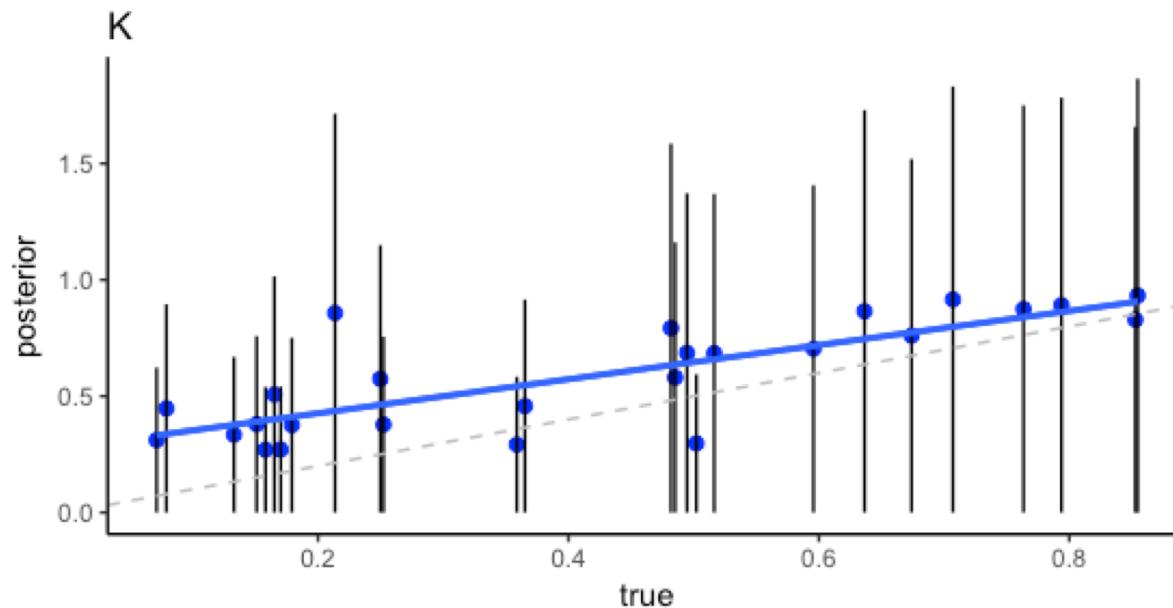
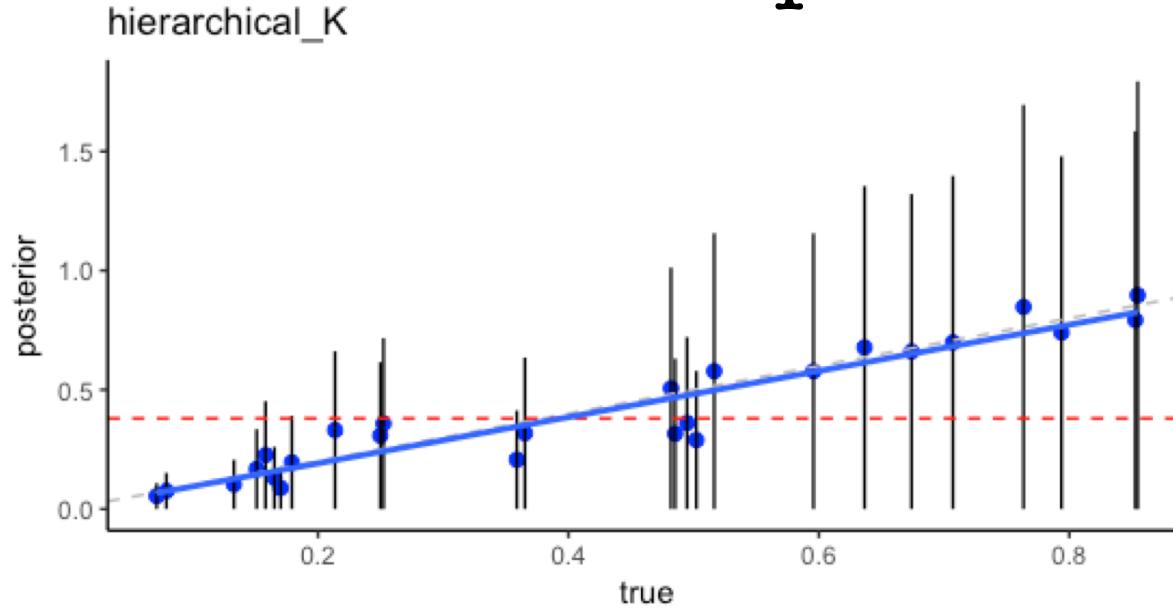
Results

WSLS_classic + RL model : parameter recovery



Results

WSLS_classic + RL model : parameter recovery



Results

Is this model okay?

Results

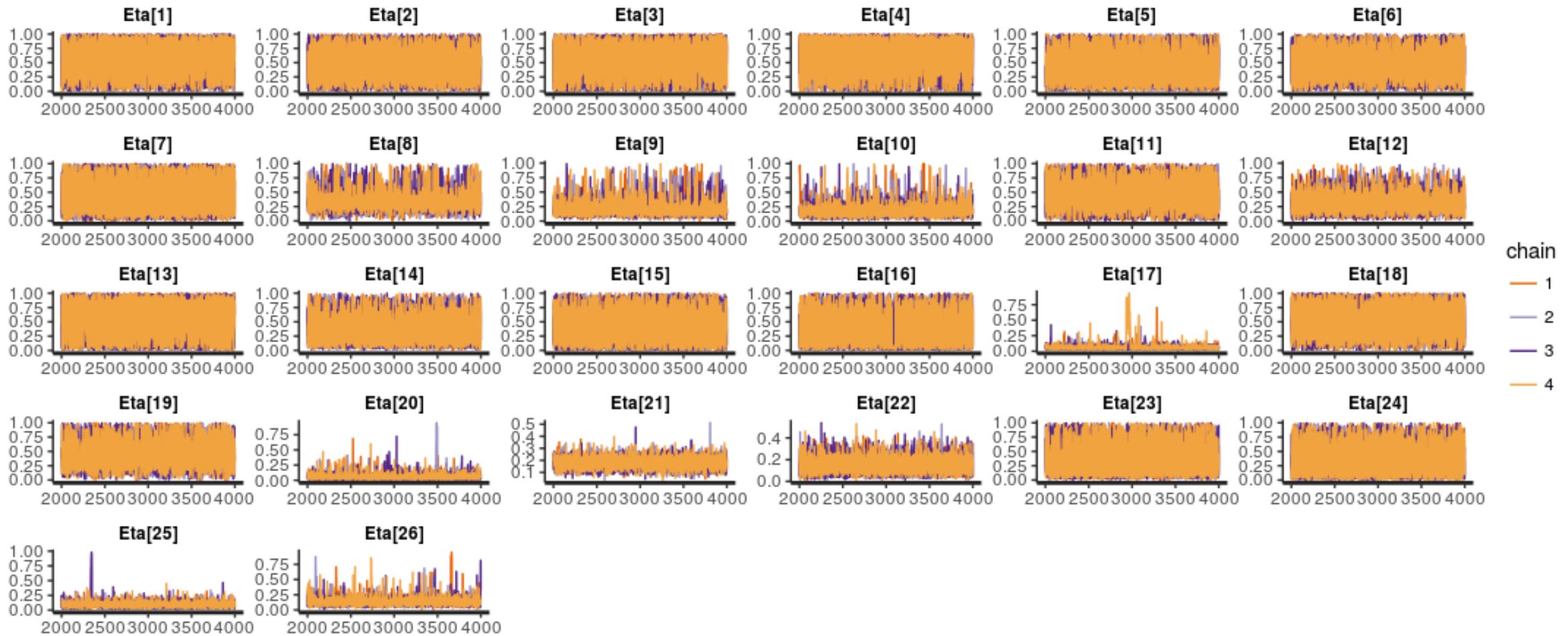
K (full individual)

0.877	0.908	0.653	0.372	0.851	0.845	0.763	0.432	0.322	0.358
0.601	0.231	0.521	0.519	0.349	0.752	0.111	0.923	0.683	0.296
0.094	0.116	0.740	0.266	0.153	0.229				

WSLS : 1,2,3,5,6,7,10,11,13,14,16,18,19,23

RL : 4,8,9,12,15,17,20,21,22,24,25,26

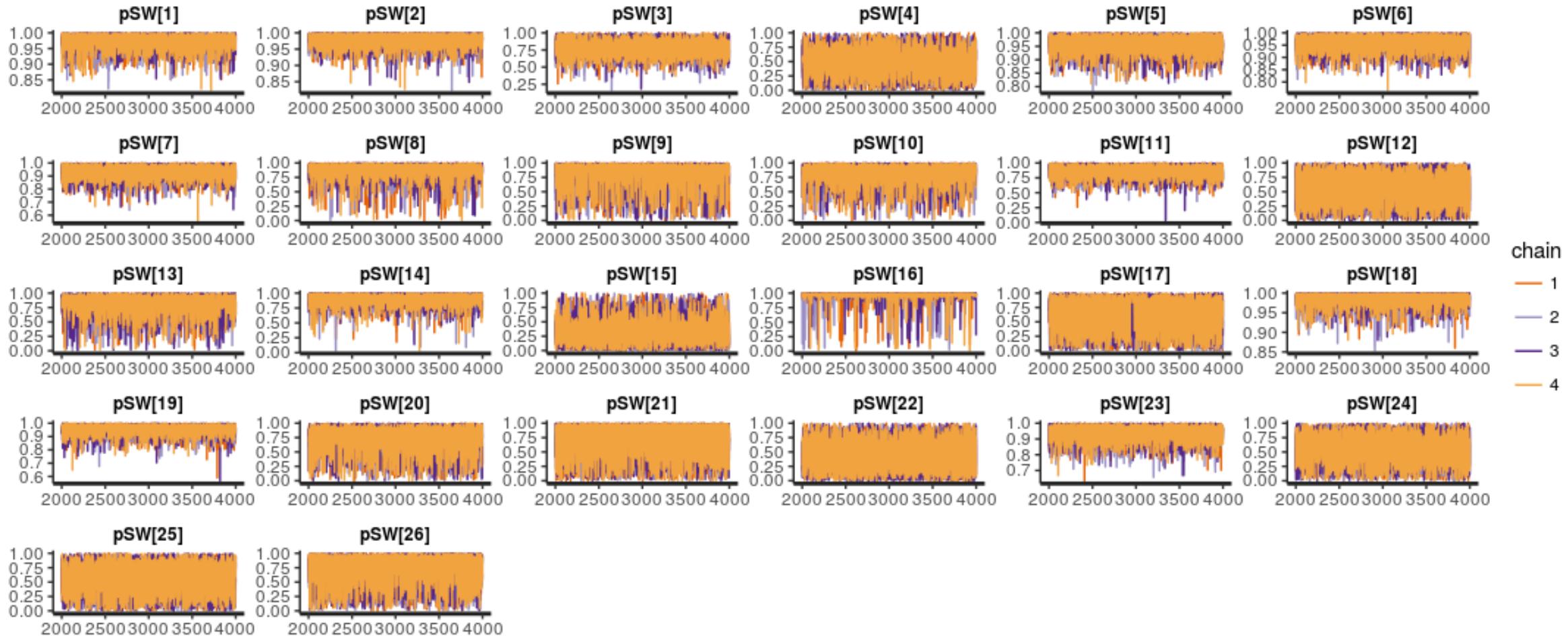
Results



WSLS: 1,2,3,5,6,7,10,11,13,14,16,18,19,23

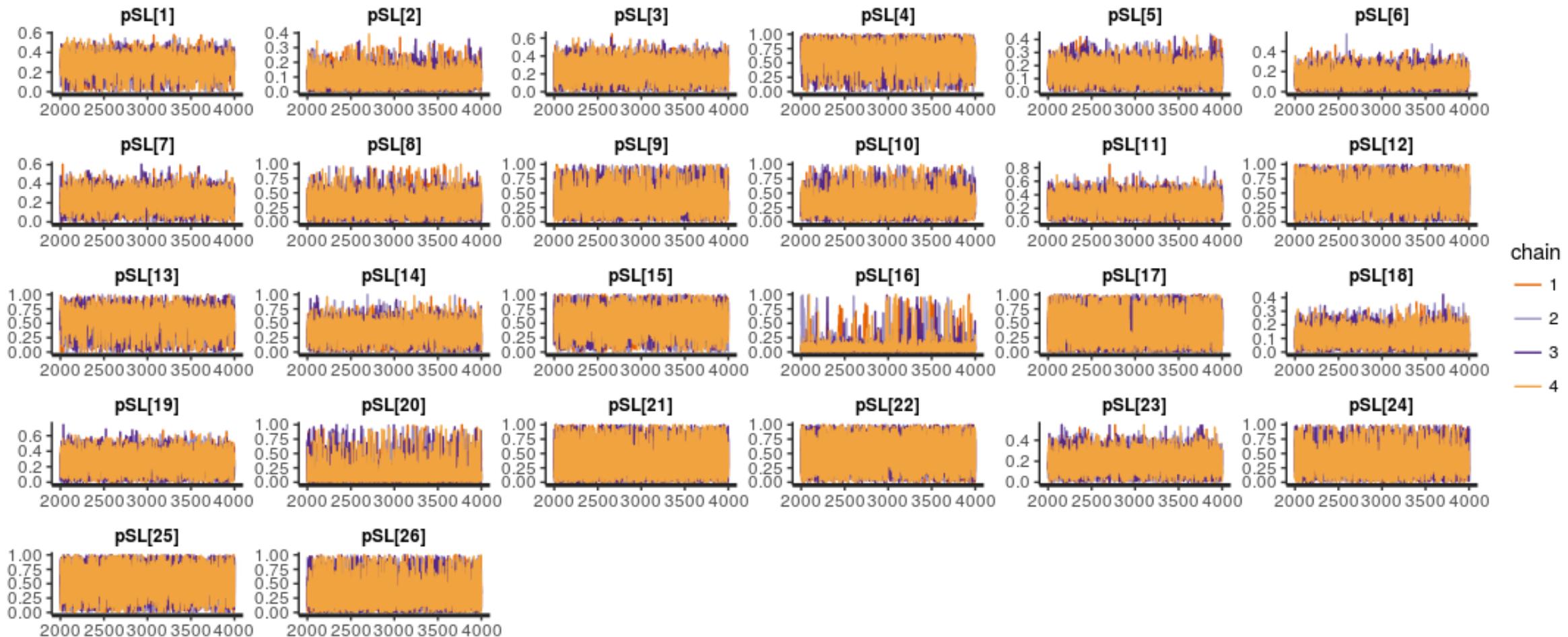
RL :4,8,9,12,15,17,20,21,22,24,25,26

Results



WSLS: 1,2,3,5,6,7,10,11,13,14,16,18,19,23
RL :4,8,9,12,15,17,20,21,22,24,25,26

Results



WSLS: 1,2,3,5,6,7,10,11,**13**,14,16,18,19,23
RL : **4,8,9,12,15,17,20,21,22,24,25,26**

Implication

WSLS_learning

+

RL model



VS

WSLS

+

RL model



Thank you ☺



Contribution

	Yoonseo Zoh	Hyeonjin Kim
Codes	Transition RL, hybrid v2	RL , hybrid v1
	Parameter recovery, posterior predictive	traceplot, posterior distribution check
	Everything else together	
PPT	First section	Second section
Presentatio n	First section	Second section

References

- Leong, Y. C., & Zaki, J. (2018). Unrealistic optimism in advice taking: A computational account. *Journal of Experimental Psychology: General*, 147(2), 170.
- Worthy, D. A., & Maddox, W. T. (2014). A comparison model of reinforcement-learning and win-stay-lose-shift decision-making processes: A tribute to WK Estes. *Journal of mathematical psychology*, 59, 41-49.

Supplementary

Posterior Predictive Check

